

STRENGTH OF BEAMS WITH
ECCENTRIC, REINFORCED, RECTANGULAR

WEB OPENINGS

by

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CHAPTER I INTRODUCTION

1.1 Problem Statement

In the design of high-rise steel building frames, the structural engineer is faced with the challenge of designing a structure which is safe as well as economical. When all other factors are approximately equal, the design which results in the lowest cost will usually be considered to be the best design. One method of achieving economy in a steel building frame is to reduce the total building height by locating wiring, piping and heating and air-conditioning ducts in the same space that is occupied by the floor beams and girders, thus reducing the height of each story compared with that of an alternate system where the utilities are located below the floor beams and girders. Thus it has become fairly common practice to cut openings in beams to permit the passage of utilities.

Cutting an opening in the web of a beam leads to a variety of problems. The strength of the beam in the vicinity of the opening can be considerably reduced, depending on the size of the member and the opening. This reduction in strength may or may not be critical, depending on the location of the opening on the span. It may be economical to use straight, horizontal duct work, and this results in openings which are not centered on the mid-depth of the floor members if floor beams and girders of different depth

have been selected. In many cases, the beam will have to be reinforced in the vicinity of an opening to avoid using a heavier member. Reinforcement will probably be required if the opening is located at a section subjected to high shear forces, and almost certainly be required at sections where both high moments and high shear forces are present.

The objective of this thesis is to present and discuss the development of an ultimate strength analysis of steel beams with reinforced, eccentric web openings, which is the most general problem encountered when web openings are used. The results of the analysis are compared with the strength of uncut beams, and presented in the form of interaction diagrams relating shear strength and bending strength. Some numerical examples are also presented to illustrate the analysis, and to show the effects of the parameters involved in the problem.

1.2 Literature Review

Ultimate strength analyses of beams with web openings have been formulated by several investigators in recent years. In 1968, Bower published an ultimate strength analysis of concentric, unreinforced rectangular openings in the webs of beams (1). His analysis was based on the assumption that points of contraflexure are located in the tee-sections above and below the center of the openings, and that the stress distributions are the same at the high and low moment

edges of the openings. Since the effect of strain hardening was neglected, experimental results showed that the ultimate loads were somewhat conservatively predicted by the lower-bound solution.

Redwood presented an ultimate strength analysis of the same problem in 1968 (2). He assumed that points of contraflexure occur somewhere along the length of the opening, not necessarily at the center. In the analysis, a four-hinge mechanism was assumed in which bending, shear and direct force resultants were considered at each hinge. Only one tee-section was dealt with, and it was assumed that half of the total shear force is carried by each tee-section because of symmetry.

In 1969, Congdon presented in her M.S. thesis an ultimate strength analysis of beams with concentric, reinforced web openings (3). Basically, the assumptions used by Congdon were the same as Redwood's. An approximate method of analysis was also developed. Correlation with previous experimental work indicated that the theoretical results were conservative for large shear forces because the strain-hardening effect was neglected.

In 1971, Richard presented a M.S. thesis on the analysis of beams with eccentric, unreinforced rectangular web openings (4). His assumptions were primarily the same as Redwood's except that he assumed that points of contraflexure occur at the centers of the tee-sections above and below the opening.

From his analysis the variation of moment carrying capacity with different opening locations and dimensions was investigated. Shear forces were unequally distributed to the web areas above and below the eccentric openings, with the larger area carrying the larger shear force.

In 1973, Frost presented a method of predicting the ultimate strength of I-shaped beams with web holes that are not centered at the middepth of the beam and also not reinforced (5). The analysis was based on the assumption that the points of contraflexure occurred somewhere along the length of the opening, not necessarily at the center. Comparison with experimental results showed that the ultimate loads were conservatively predicted by the approximate interaction formulas developed, and thus it was concluded that the formulas are satisfactory for design purpose.

In all the papers reviewed, no theoretical analysis was discovered which treats the subject of eccentric, reinforced rectangular openings.

1.3 Scope of the Investigation

The investigation presented in this thesis was limited to an analytical, ultimate strength analysis of steel W shape beams containing reinforced, eccentric rectangular openings in their webs. The general type of reinforcement used herein is pairs of steel bars of rectangular cross section welded on both sides of the web, parallel to the opening edge and with

equal area for both top and bottom reinforcement. In the investigation the effects of variable opening lengths, opening eccentricities and reinforcing areas were considered.

CHAPTER II ULTIMATE STRENGTH ANALYSIS

2.1 Nomenclature

The symbols adopted in this thesis are defined where they first appear, and are summarized for convenient reference at the end of the thesis in the section "Nomenclature".

2.2 Assumptions

The following assumptions were made to facilitate the solution of the problem :

- a. The failure of the member will occur by the formation of a four-hinge mechanism with hinges located at the corners of the opening. The assumed failure mechanism of the beam is shown in Fig. 1.
- b. Points of contraflexure occur somewhere within the sections above and below the opening, but not necessarily at the center of the opening. The location of the points of contraflexure is the same above and below the opening. This assumption permits the calculation of secondary bending due to shear (the so-called "Vierendeel action").
- c. Shear stresses are assumed to be carried only by the webs of the tee-sections and are uniformly distributed across those webs at hinge locations when hinges are fully formed.

- d. Yielding in the flanges and reinforcing bars is in direct tension or compression.
- e. Yielding in the webs at each of the four hinge locations under combined bending and shear must satisfy the Von-Mises yield criterion.
- f. Reinforcing areas are assumed to be the same for the top and bottom tee-sections (see Fig. 2).
- g. To simplify the derivation of formulas, the yield stresses of the material either in tension or compression for flanges, webs and reinforcing bars are assumed to be the same and equal to f_y . That is, $f_y = f_{yf} = f_{yw} = f_{yr}$.
- h. For the purpose of this analysis, the opening will always be considered to be eccentric toward the top flange (or compression flange) of the beam. Eccentricity in that direction will be assumed positive and all derivations and examples will be based on positive eccentricity. If the eccentricity is toward the other direction (or bottom flange), it is taken as negative. However, the shape of the interaction curve will be exactly the same as that for positive eccentricity.

2.3 Equilibrium Equation

Free body diagrams of the tee-sections above and below the opening are shown in Fig. 3a. With an opening length of $2a$, an opening depth of $2h$ and an eccentricity of e with respect to the center line of the beam, the opening is located

a distance $L=M/V$ from the near reaction. Horizontal equilibrium of the top tee requires that $Q_{1T}=Q_{2T}$. Similarly, for the bottom tee, $Q_{1B}=Q_{2B}$. Furthermore, horizontal equilibrium of sections one and two yields $Q_{1T}=Q_{1B}$ and $Q_{2T}=Q_{2B}$, respectively. Thus

$$Q = Q_{1T} = Q_{1B} = Q_{2T} = Q_{2B} \dots \dots \dots \dots \dots \quad (1)$$

Referring to Fig. 3b, moment equilibrium at section one (the high-moment edge of the opening) yields

$$M = Q_{1T}(y_{1T} + y_{1B} + 2h) - Va \dots \dots \dots \dots \dots \quad (2)$$

and from Fig. 3c moment equilibrium at section two (the low-moment edge of the opening) gives

$$M = Q_{2T}(y_{2T} + y_{2B} + 2h) + Va \dots \dots \dots \dots \dots \quad (3)$$

Moment equilibrium for the top tee-section yields

$$V_T = Q(y_{1T} - y_{2T})/2a \dots \dots \dots \dots \dots \quad (4)$$

while for the bottom tee-section,

$$V_B = Q(y_{1B} - y_{2B})/2a \dots \dots \dots \dots \dots \quad (5)$$

Using Eqs. 4 and 5, and eliminating Q and a to find the shear distribution between the upper and lower tee-sections, the following relationship for V_T and V_B can be obtained :

$$\frac{V_T}{V_B} = \frac{y_{1T} - y_{2T}}{y_{1B} - y_{2B}} \dots \dots \dots \dots \dots \quad (6)$$

of the points of stress reversal at section one can be located in the stubs (web between reinforcing bars and opening edge), in the reinforcing bars or in the clear webs (between reinforcing bars and flange); therefore, there are nine possible combinations of the locations of stress reversal for the low shear case. The six stress distributions which are possible at section one for the low shear case and positive eccentricities are shown in Fig. 4. For low shear stress at section two, the points of stress reversal are assumed to be always in the flanges (see Fig. 5). The different locations of the points of stress reversal under low shear conditions at both sections one and two are shown in Table 1. The relationship between the low shear cases at section one is shown in Fig. 6 and will be discussed later.

Equations for the low shear Case SS are derived in the following section, and similar equations for other locations of stress reversal for low shear conditions are summarized in Appendix A .

2.6 Low Shear Case SS

Considering the first case of low shear in Fig. 4a, the assumed locations of stress reversal occur in the stubs at distances $k_{1T}S_T$ and $k_{1B}S_B$ from the opening edges for the top and bottom tee-sections at the high-moment edge of the opening (section one), respectively, and $k_{2T}t$ and $k_{2B}t$ from the outermost flange surfaces at the low-moment edge of the opening (section two) for the top and bottom tee-sections, respec-

CHAPTER III COMPUTER PROGRAM

3.1 Introduction

Using the procedure described previously, the computer programs shown in Appendix B were written to solve for the coordinates of points on the interaction diagram, V/V_p and M/M_p . Examples of the output from these programs are presented in Appendix C.

Programs were written separately for each case instead of one complete program involving all the cases, because the use of separate programs facilitated debugging, permitted monitoring the transition from one stress reversal case to the next, and helped to isolate special problems which are discussed later.

3.2 Initial Stress Reversal Locations

At the beginning of the program, it is necessary to determine the locations of the points of stress reversal when $V = 0$. From experience, the stress reversal in the top tee, Section 1, is always in the web stub initially, and stress reversals occur in the flanges for both the top and bottom tees at Section 2. In the bottom tee at Section 1, the initial location of the point of stress reversal is the plastic neutral axis of the cut, reinforced section. The plastic neutral axis can occur in the web stub, in the reinforcing bars or in the clear web. Therefore, it can be concluded that Case SS, SR or SW should be used to start with

at Section 1 and Case FF at Section 2.

The eccentricity is the determining factor in selecting the initial case at Section 1, and the three possibilities can be summarized as follows :

- a. For $e \leq u$, the plastic neutral axis is located in the web stub between the opening edge and reinforcing bars in the bottom tee. This limit was derived by equating the compression web area to the tension web area, since flange areas and reinforcing areas are the same for the top and bottom tee-sections. In this case, the problem is solved starting with Case SS, but from the viewpoint of practical design, it is not a common case since for such small values of e , the eccentricity could be neglected and the problem treated as a concentric opening.
- b. For $u < e \leq u+q+\frac{A_r}{w}$, the plastic neutral axis is located within the reinforcing bars in the bottom tee. The upper limit for this case is derived by setting the plastic neutral axis at the lower edge of the reinforcing bars in the bottom tee-section and equating the total area including all the reinforcing area above the plastic neutral axis to the total area below it. Under such circumstances, the problem is solved starting with Case SR.
- c. For $e > u+q+\frac{A_r}{w}$, the plastic neutral axis is located in the clear web between the reinforcing bars and the flange in the bottom tee, and the problem is solved starting with Case SW. This is a practical case only for small

reinforcing area, otherwise such large eccentricities would leave no room for reinforcement in the top tee-section.

3.3 Roots of the Quadratic

An important step in the program involves solving for the roots of k_{2T} from the quadratic equation in order to evaluate the other k-values. Since there is only one root of the quadratic equation which will result in the other k-values being less than the limits (for example, for Case SS, k_{1T} and k_{1B} must be less than u/S_T and u/S_B , respectively, and k_{2T} and k_{2B} must be less than 1), the problem is to choose the right root. When the problem starts with a very small (or zero) value of V , one of the roots will be positive and less than 1 and the other root will be negative but close to zero. In this case the other k-values can not be evaluated within their limits from the former. Therefore, the technique adopted is to set the latter equal to zero in order to obtain a solution. This assumption can be checked numerically by comparing the M/M_P value obtained from the computer solution for $V=0$ with the ratio of plastic moment capacity of the cut, reinforced section to the plastic moment capacity of the gross cross section. Comparison of the two M/M_P values has shown in all cases that setting the small root equal to zero for small values of V yields correct results.

An interesting result from the numerical examples presented

CHAPTER IV NUMERICAL EXAMPLES AND DISCUSSION OF RESULTS

4.1 Introduction

Some numerical examples are presented in this Chapter to explain how the computer program works, to show the effect of varying parameters on the interaction diagram and to check if the solution reduces to that of Congdon when $e=0$ (3) and to that of Frost when $A_r=0$ (5).

A W16x45 beam was used in all the numerical examples since this section had been tentatively selected for a proposed test program. Other properties and dimensions selected with the W16x45 section to serve as the basic case for the numerical examples are : $f_y = 36 \text{ ksi}$, $a = 4\frac{1}{2}''$, $h = 3''$, $e = 2''$, $u = q = \frac{1}{4}''$ and $c-w = 4''$.

Using these properties as the basic case, the effects of varying parameters a , e and A_r (actually, q was kept constant, varying $c-w$ only) were investigated, while u , q , h and f_y were not varied. The values of the parameters investigated are shown in Table 2. An interaction diagram for the basic case is shown in Fig. 8, while the effects of varying parameters are shown in the interaction diagrams of Figs. 9 through 11.

4.2 Varying Eccentricity

The first parameter investigated was eccentricity. It is the most important one involved in the problem from the point of view that the eccentricity determines the correct

stress reversal case to start the computations, as discussed in Section 3.2. Five different eccentricities were investigated, and they can be divided into three groups. The first group involves $e=0"$, and the solution obtained is the same as that of Congdon (3). Case SS was the first case in the solution. The second group includes $e=0.3"$, $1"$ and $2"$. Here, Case SR was the first case encountered in the solution. The third group involves $e=3.5"$, and Case SW was selected to start the solution (see Table 2). The interaction diagrams for these examples are plotted in Fig. 9, from which it can be concluded:

- a. With small eccentricity (say, $e \leq u$), the problem could be treated as a concentric opening, without any significant loss of accuracy.
- b. As the eccentricity increases, the moment carrying capacity of the beam decreases for low shear forces and increases for high shear forces.
- c. For the eccentricities included in group 2, the sensitivity problem was encountered when V approached V_{max} .

4.3 Varying Reinforcing Area

The second parameter investigated was $c-w$. With q kept constant, $c-w$ was the term selected to vary the reinforcing area. There were five different $c-w$ values investigated; the first case was $c-w=0"$, which yielded results identical to Frost's solution (5). The remaining cases were $c-w=1"$ through $4"$ in $1"$ increments. The results are plotted in Fig. 10, from which it can be concluded :

- a. The moment carrying capacity is almost linearly proportional to the reinforcing area where the shear force is low, but this relationship becomes non-linear when the shear force is larger.
- b. When $c-w=0"$, the program terminated because it entered a region where low shear is "mixed" with high shear, i.e., Case FW was encountered at Section 1, and this case was not included in the present analysis.
- c. When the reinforcing area provided was less than the minimum area given by Eq. 38 (min. $A_r = 0.899 \text{ in}^2$), V_{\max} was not reached (see Fig. 10; $c-w=1"$, $2"$ and $3"$).
- d. When $c-w=4"$, the problem was sensitive when V approached V_{\max} .

4.4 Varying Opening Length

The last parameter investigated was a . There were three different values investigated, $a=3"$, $4\frac{1}{2}"$ and $6"$. The results are shown in Fig. 11, and conclusions can be formulated as follows :

- a. When $V=0$, the moment carrying capacity does not vary with opening length.
- b. As a increases, the moment carrying capacity decreases while V increases.
- c. The curve for $a=6"$ was terminated at $V < V_{\max}$, because the opening length exceeds the maximum length given by Eq. 37 (max. $a=5.006"$).

- d. For the other two curves the sensitivity problem was encountered when V approached V_{\max} .

4.5 Sequence of Stress Reversal Cases

The purpose of this section is to show by example how much of the interaction diagram is covered by each stress reversal case. The first example is the basic case, shown in Fig. 8, where there were only two stress reversal cases (Cases SR and RR) involved in the solution. In the second example there were five cases (Cases SW, SR, RR, RW and WW) included in the problem as shown in Fig. 12. The data for these two examples is presented in Appendix C. All of the sequences of stress reversal cases encountered in the numerical examples of this Chapter are shown in Fig. 6 by arrows between cases.

CHAPTER V CONCLUSIONS

An ultimate strength analysis of steel W shape beams containing eccentric, reinforced rectangular openings in their webs has been formulated for the low shear case. From a study of the parameters involved in the problem the following major conclusions can be made :

- a. Eccentricity does not affect the maximum opening length and the minimum reinforcing area, hence Eqs. 36,37 and 38 are the same as obtained by Congdon (3).
- b. With small eccentricity (say, $e \leq u$), the problem could be treated as a concentric opening without any significant loss of accuracy.
- c. As the eccentricity increases, the moment carrying capacity of the beam decreases for low shear forces and increases for high shear forces.
- d. The moment carrying capacity is almost linearly proportional to the reinforcing area when the shear force is low, but this relationship becomes non-linear when the shear force is larger.
- e. As opening length increases, the moment carrying capacity decreases while shear force increases.

CHAPTER VI RECOMMENDATIONS FOR FURTHER STUDY

From the present analysis, the following recommendations are suggested for further investigation of the problem of eccentric, reinforced web openings :

- a. All the computer programs shown in Appendix C should be combined into one program so that a complete interaction curve could be obtained in one calculation.
- b. The same procedures described in this thesis could be used to analyze the high shear case at section one (i.e., Case FF) as well as those cases where low and high shear are " mixed ", i.e., Cases RF,FR,WF and FW (In the present analysis Case FW was found to be the next case for $c-w=0"$).
- c. An approximate solution should be formulated for design use.
- d. An experimental study of beams with eccentric, reinforced rectangular openings in their webs would be helpful to check the analytical results presented here.

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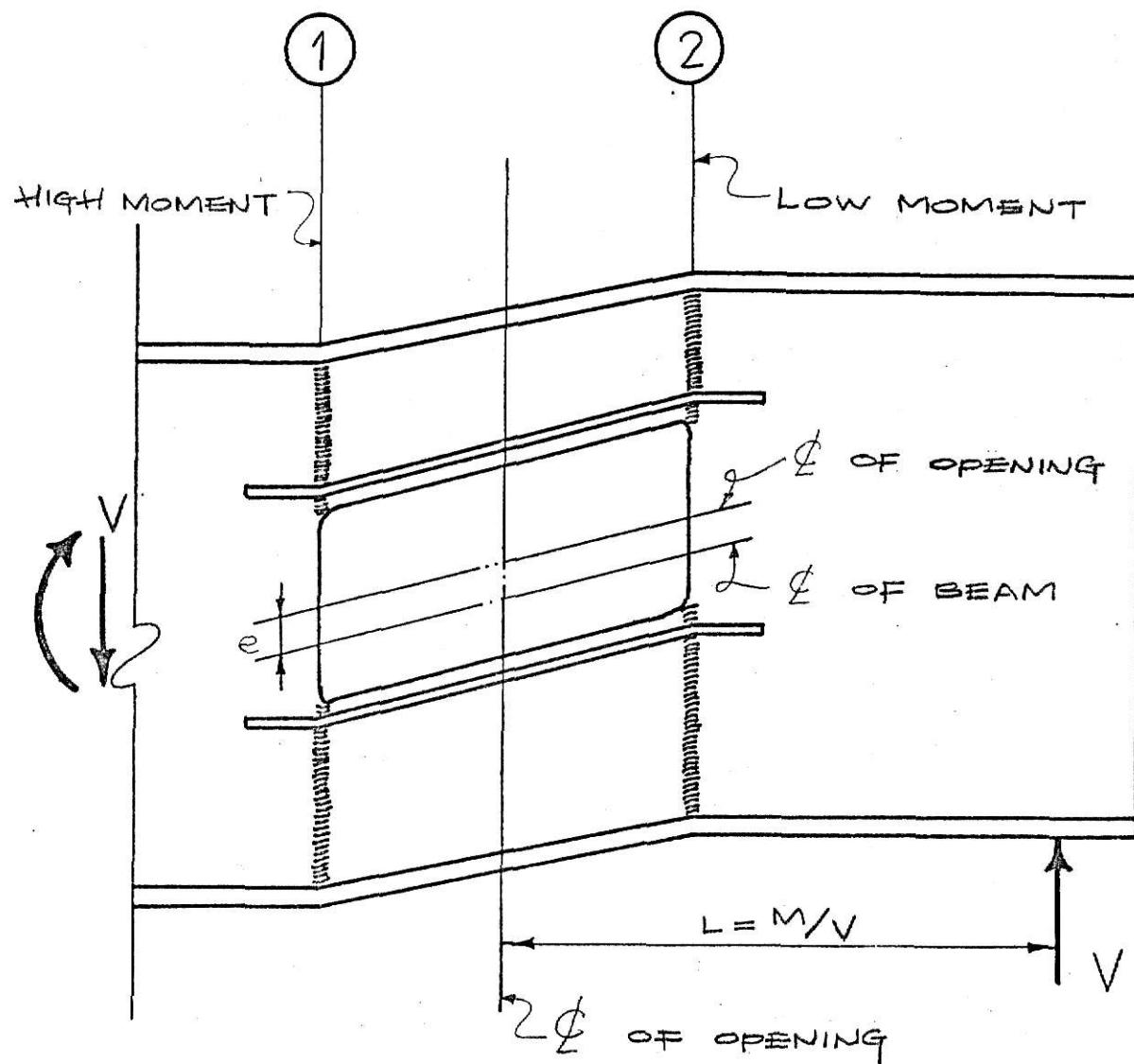


Fig 3 : Equilibrium of Tee-Sections

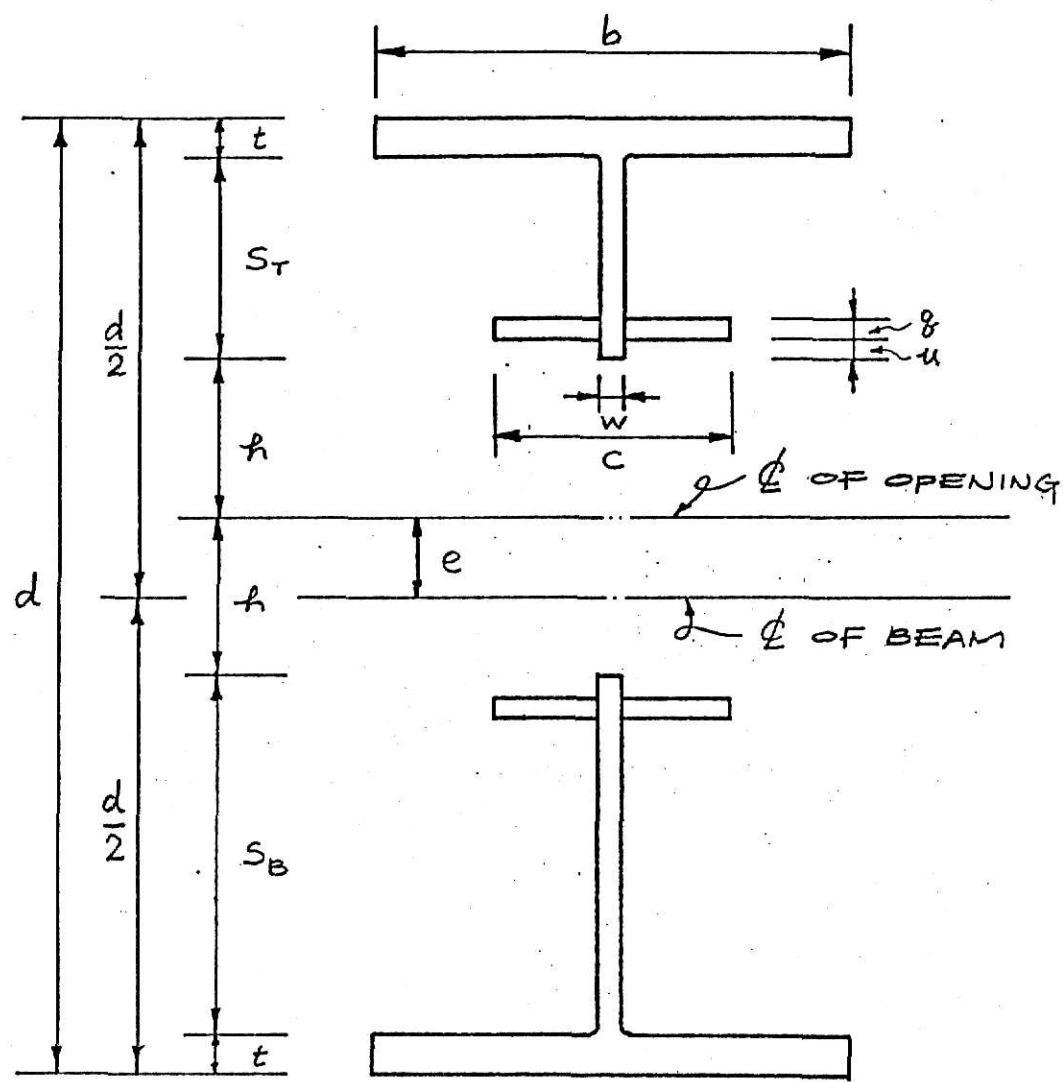


Fig. 2 : Beam Cross Section

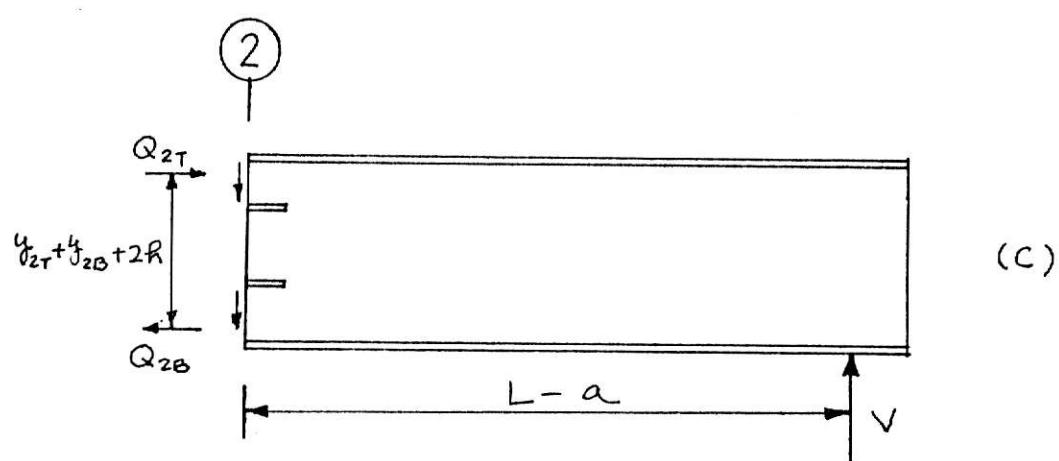
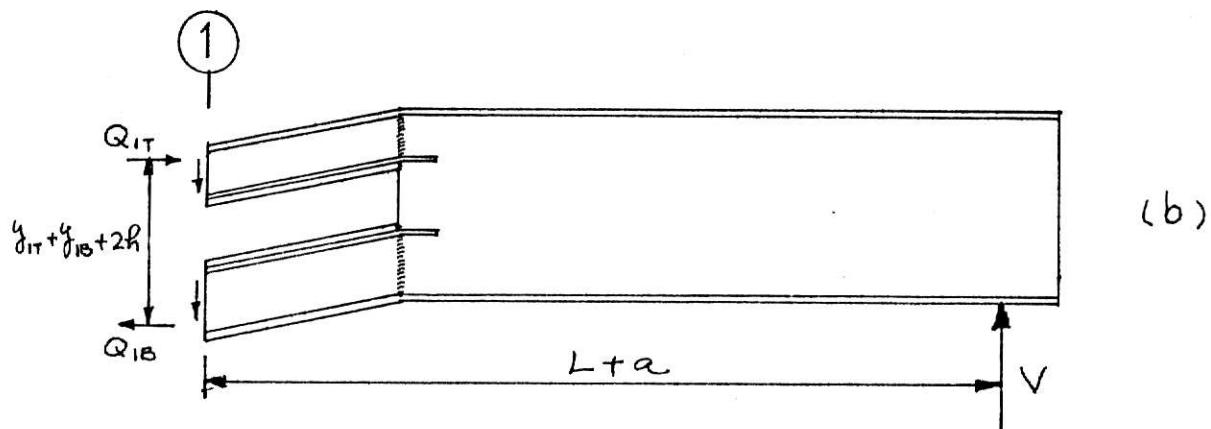
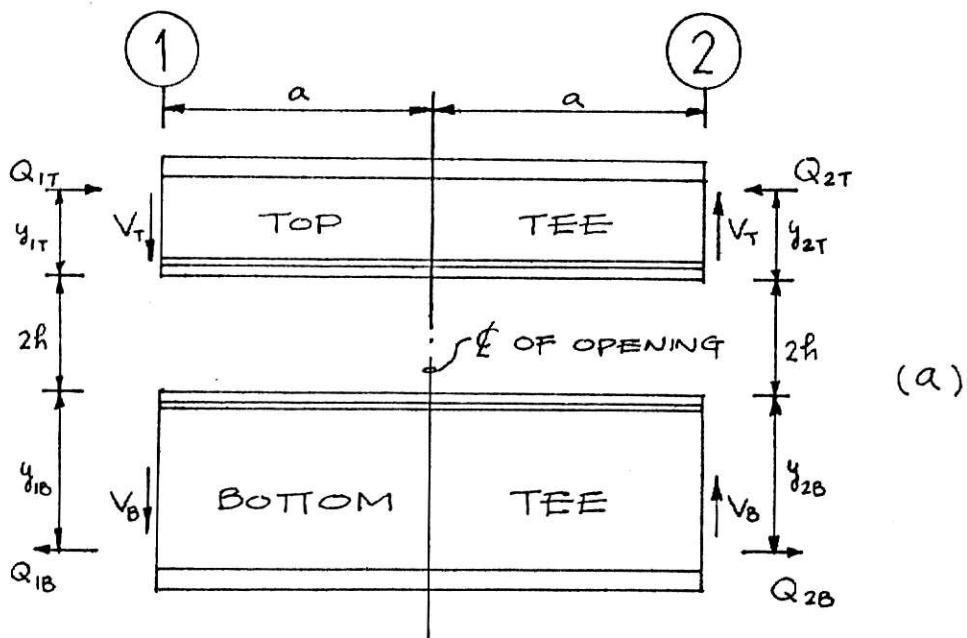


Fig. 3 : Free Body Diagrams

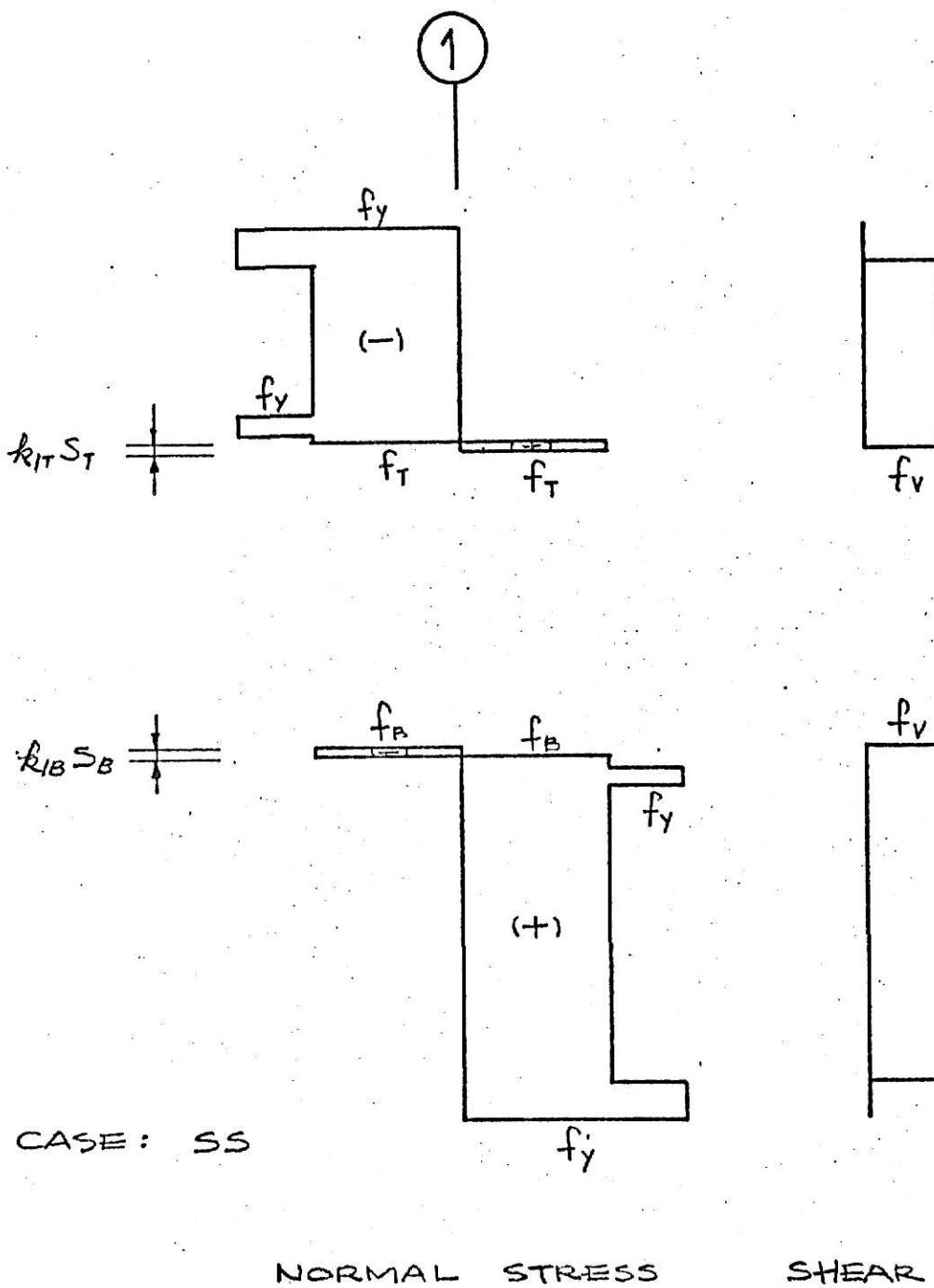


Fig. 4a : Stress Distribution at Section 1
for Low Shear Cases

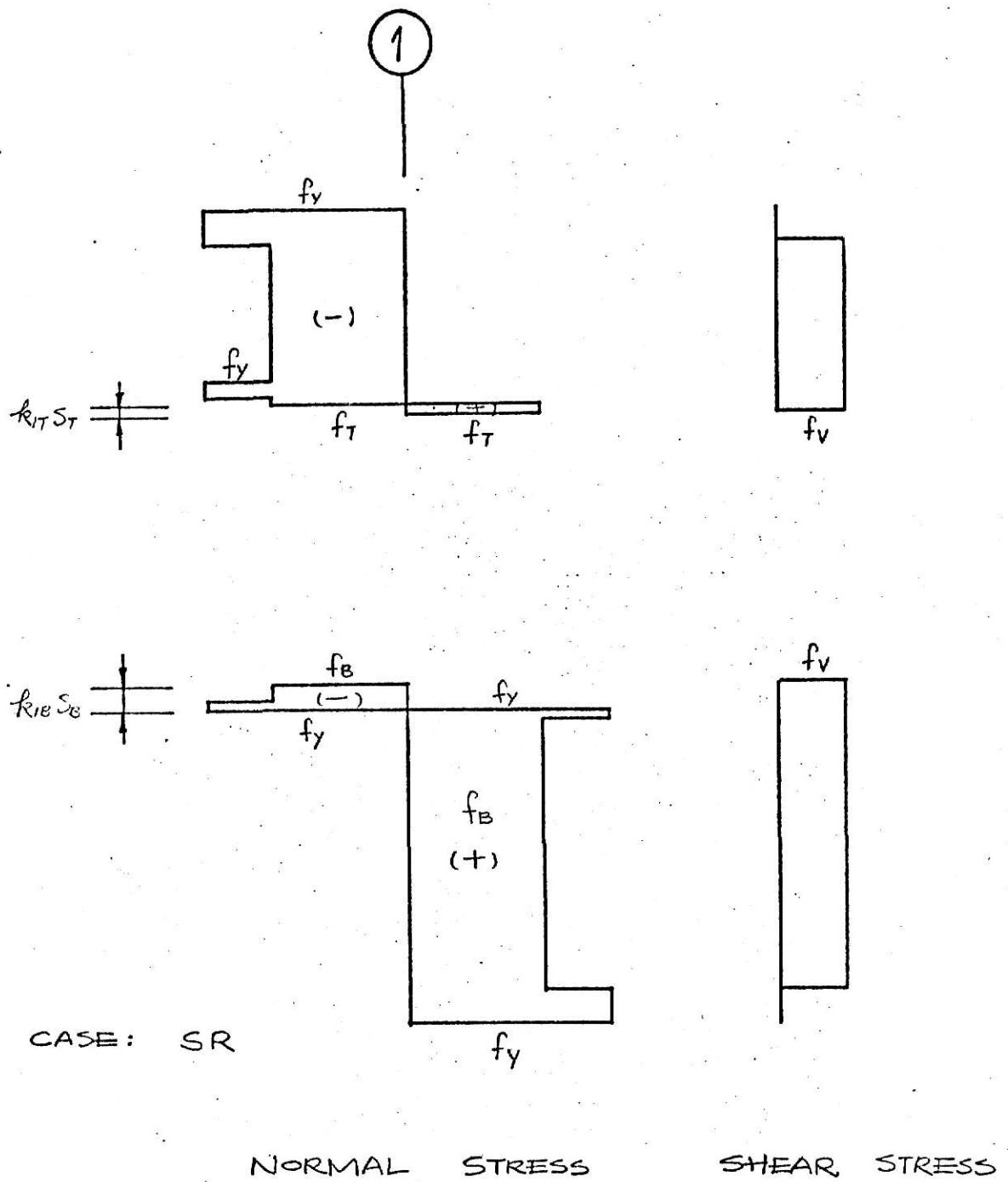


Fig. 4b : Stress Distribution at Section 1
for Low Shear Cases (cont'd)

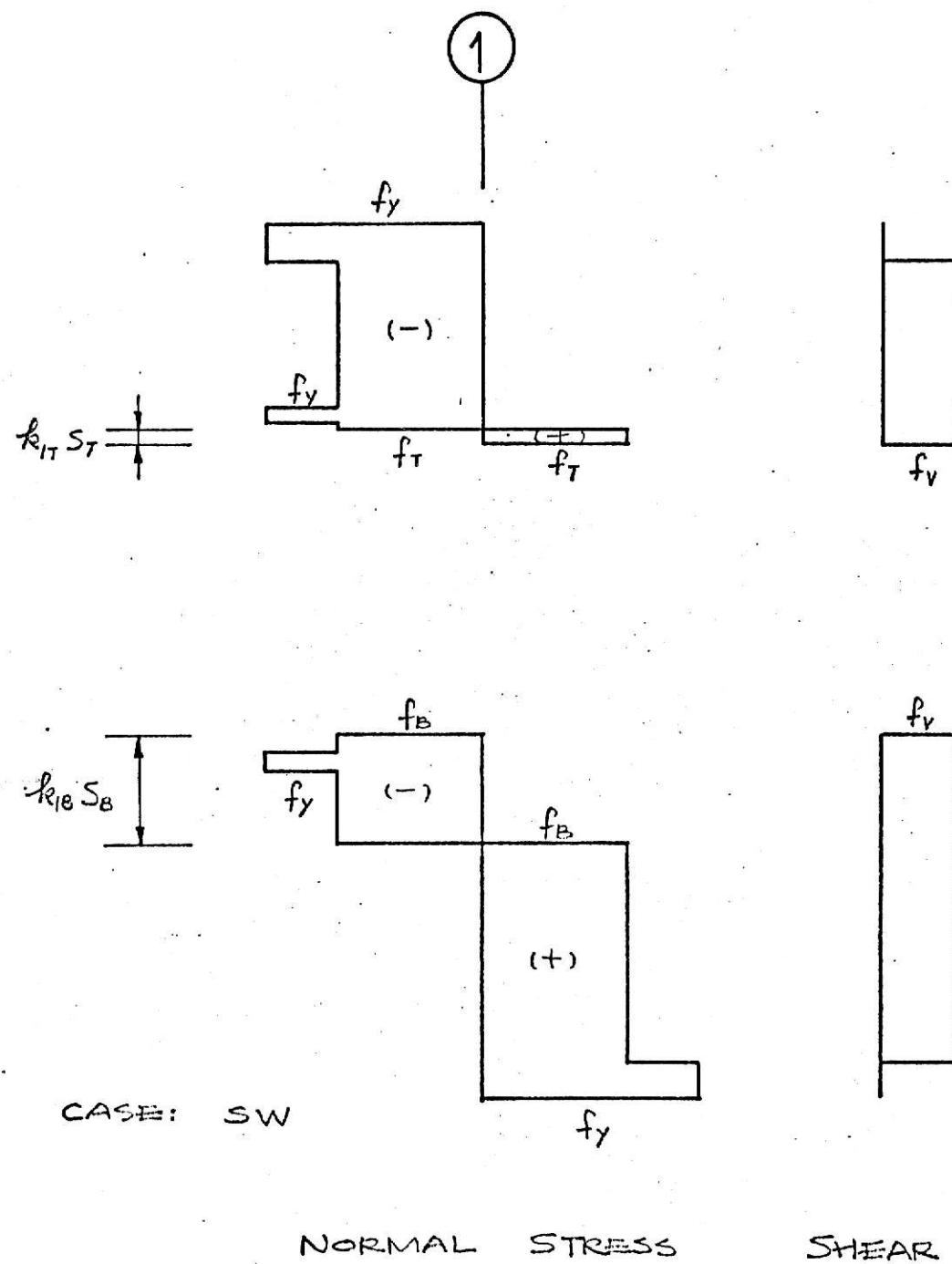


Fig. 4c : Stress Distribution at Section 1
for Low Shear Cases (cont'd)

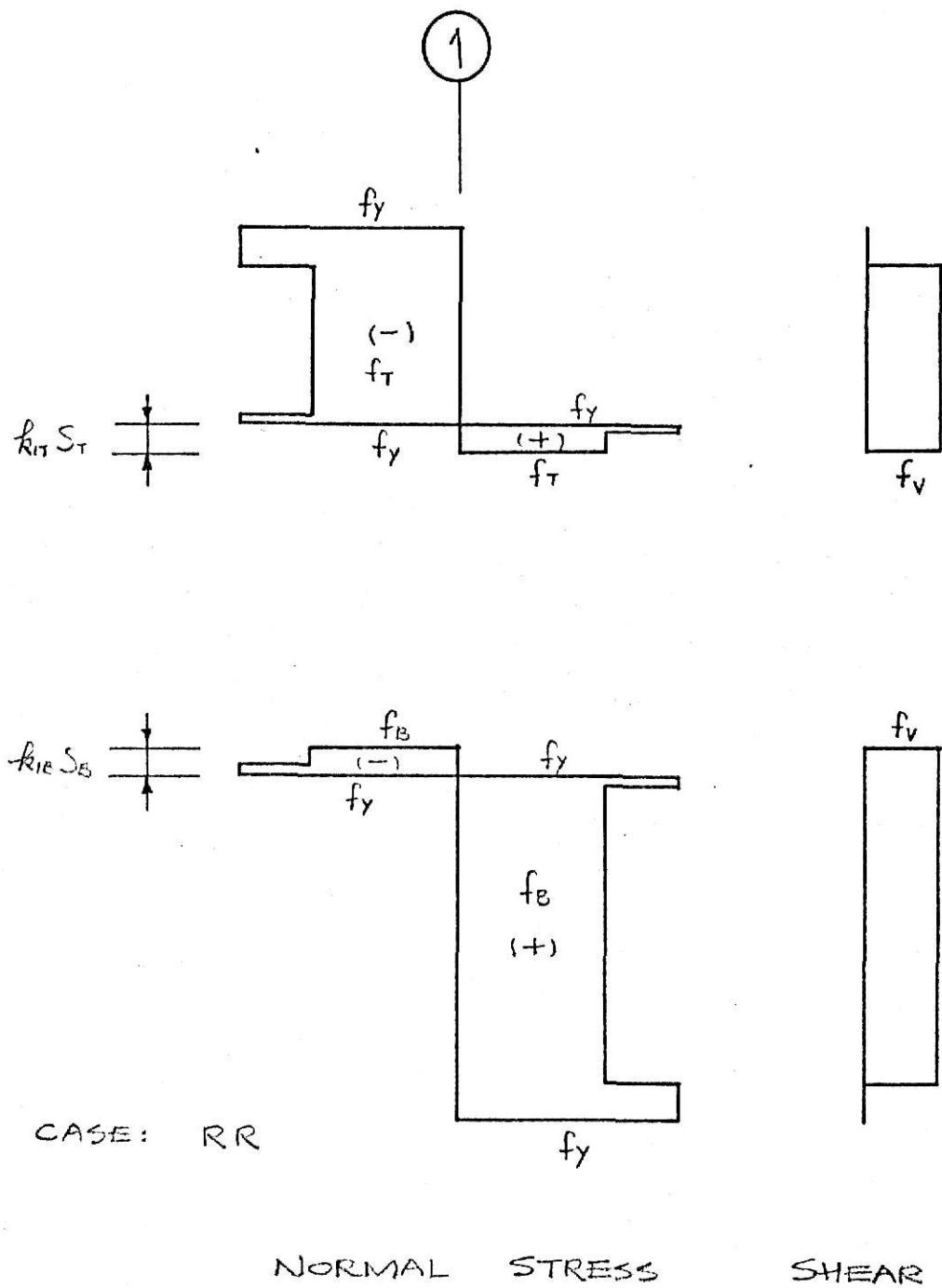


Fig. 4d : Stress Distribution at Section 1
for Low Shear Cases (cont'd)

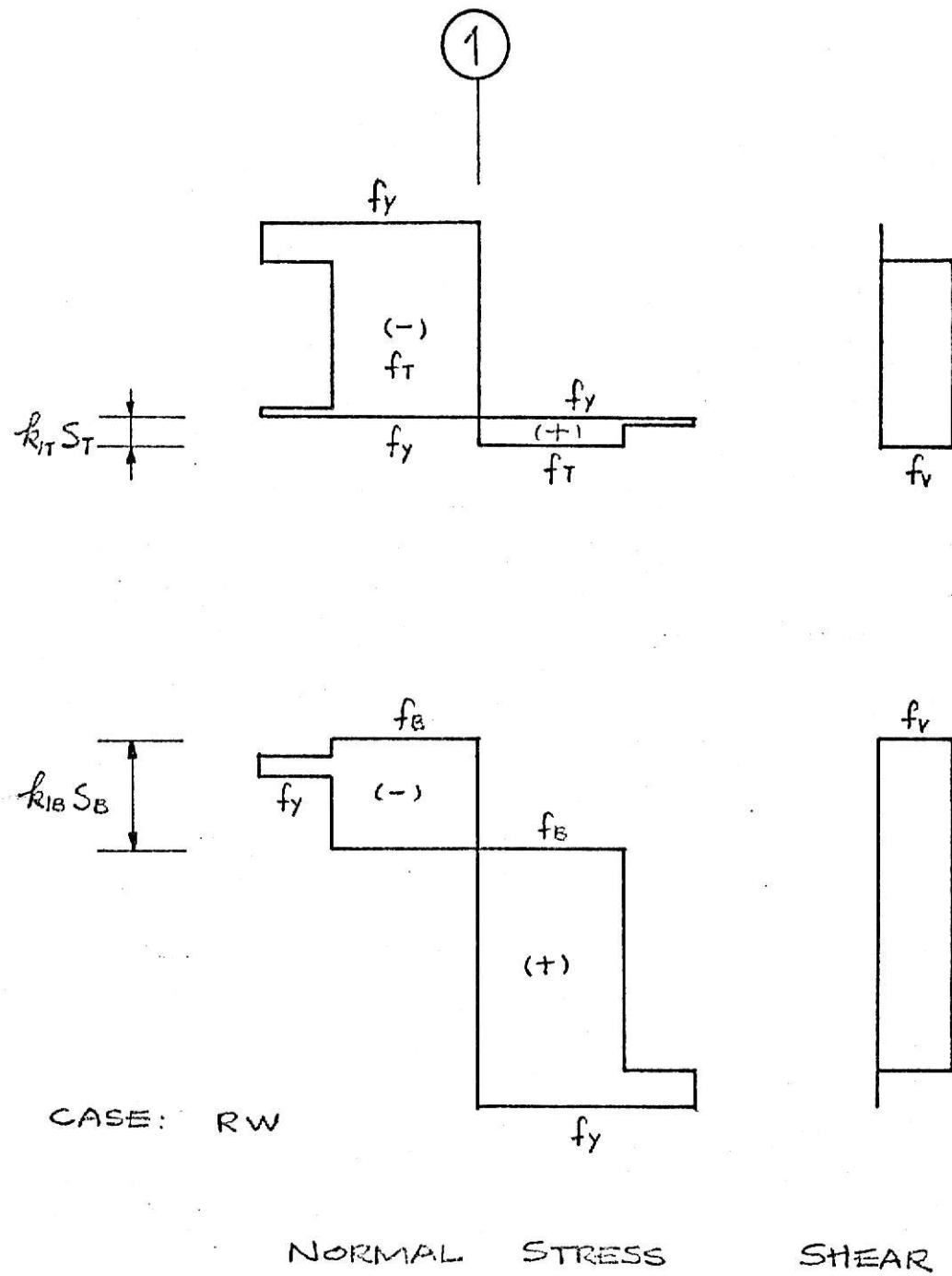
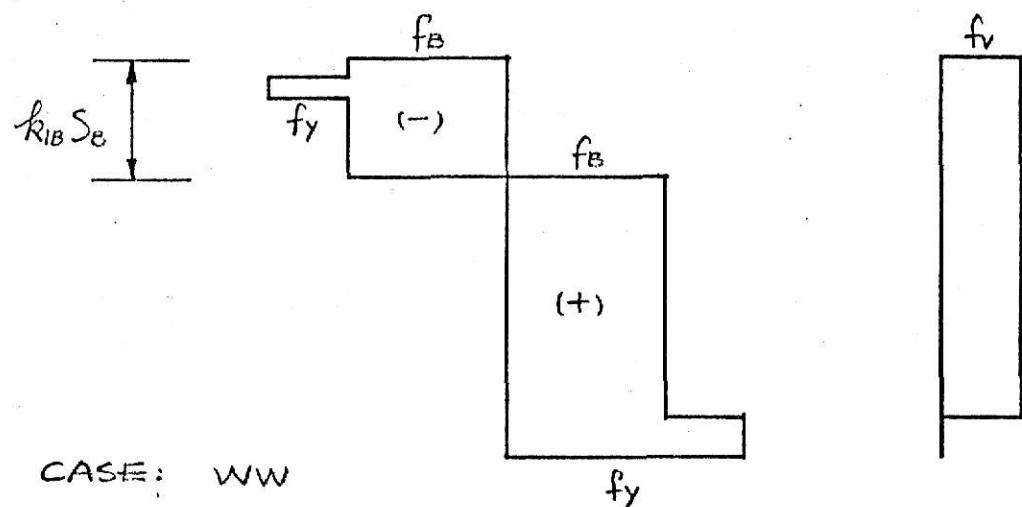
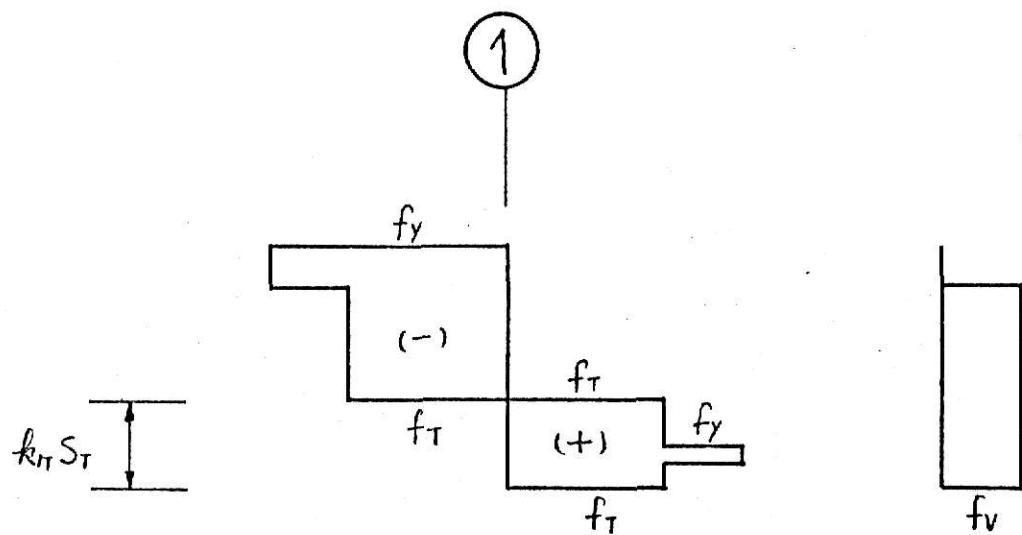


Fig. 4e : Stress Distribution at Section 1
for Low Shear Cases (cont'd)

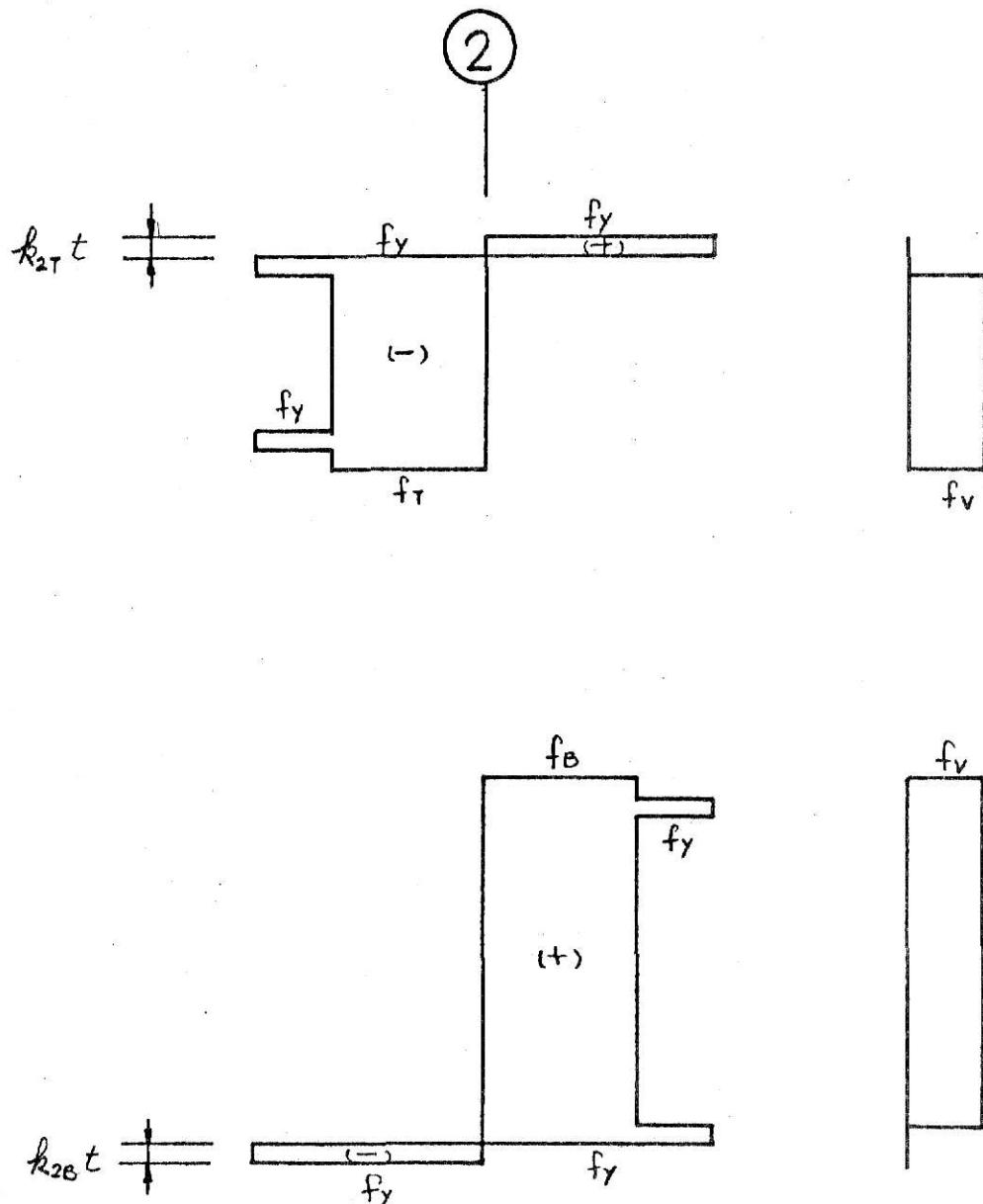


CASE: WW

NORMAL STRESS

SHEAR STRESS

Fig. 4f : Stress Distribution at Section 1
for Low Shear Cases (cont'd)



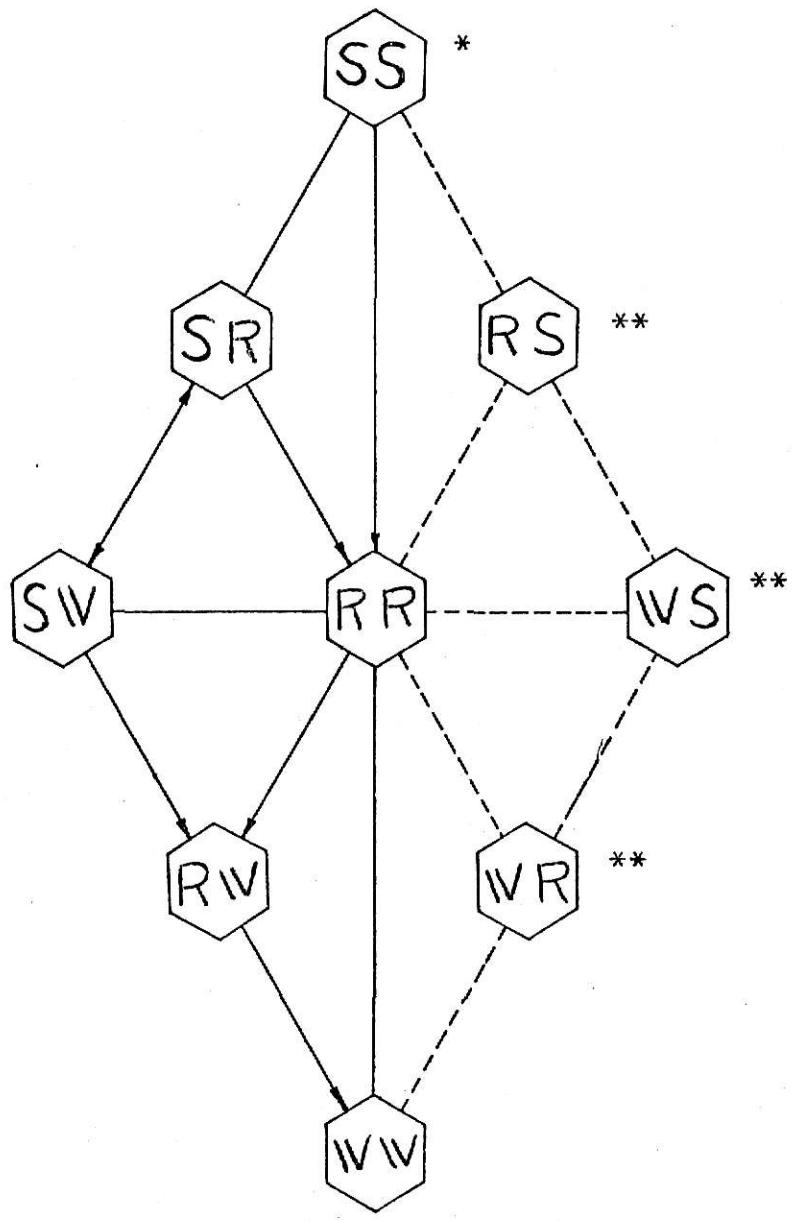
CASE: FF

NORMAL STRESS

SHEAR STRESS

Fig. 5 : Stress Distribution at Section 2

for Low Shear Case



*. Notation defined in TABLE 1.

**. Cases not possible for positive eccentricity.

Fig. 6 : Possible Combinations for Low Shear Case
at Section 1

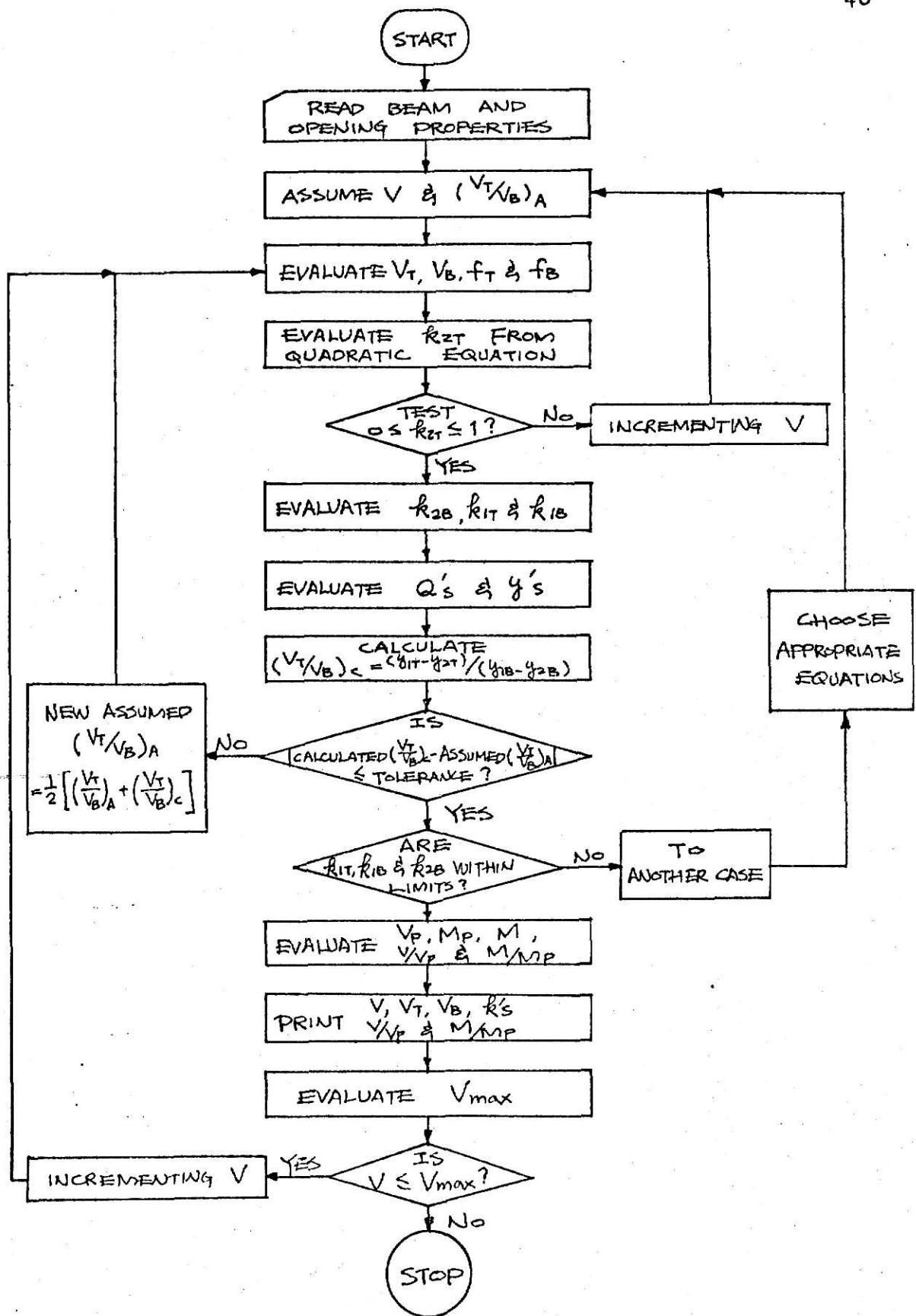


Fig. 7 : Flow Chart for Evaluating the Interaction Diagram

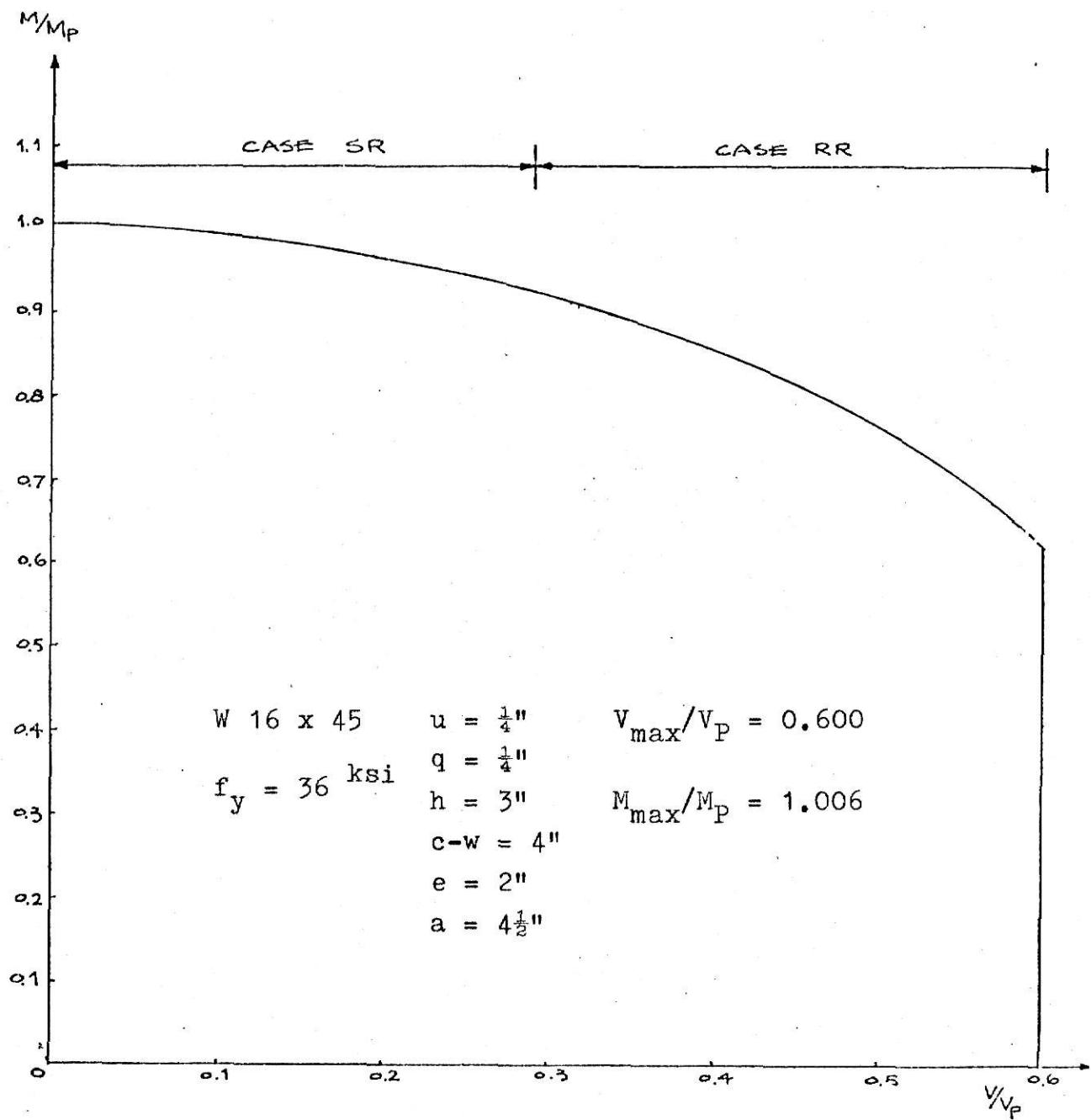


Fig. 8 : Interaction Curve for the Basic Case

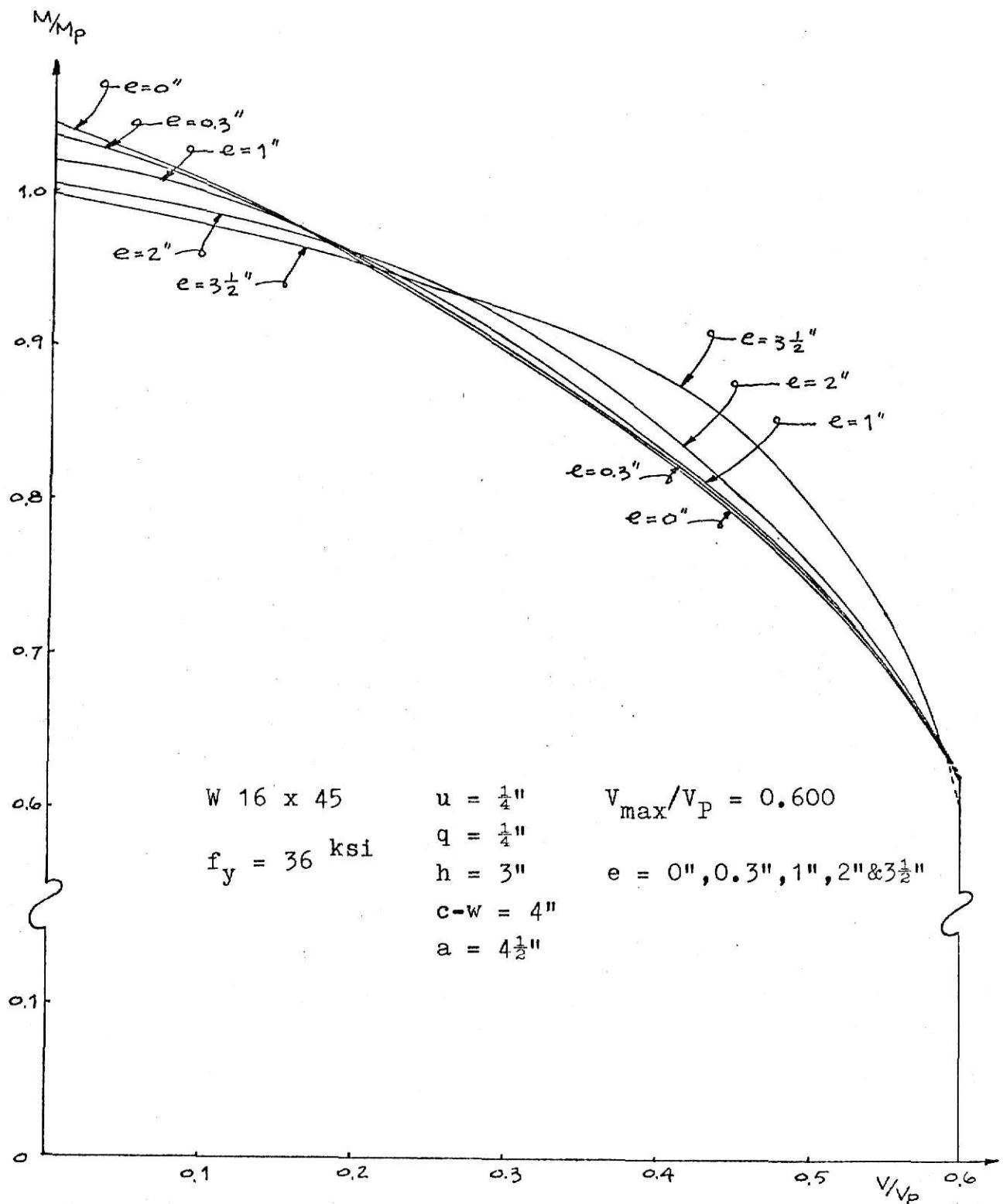


Fig. 9 : Interaction Curve with Varying Eccentricities

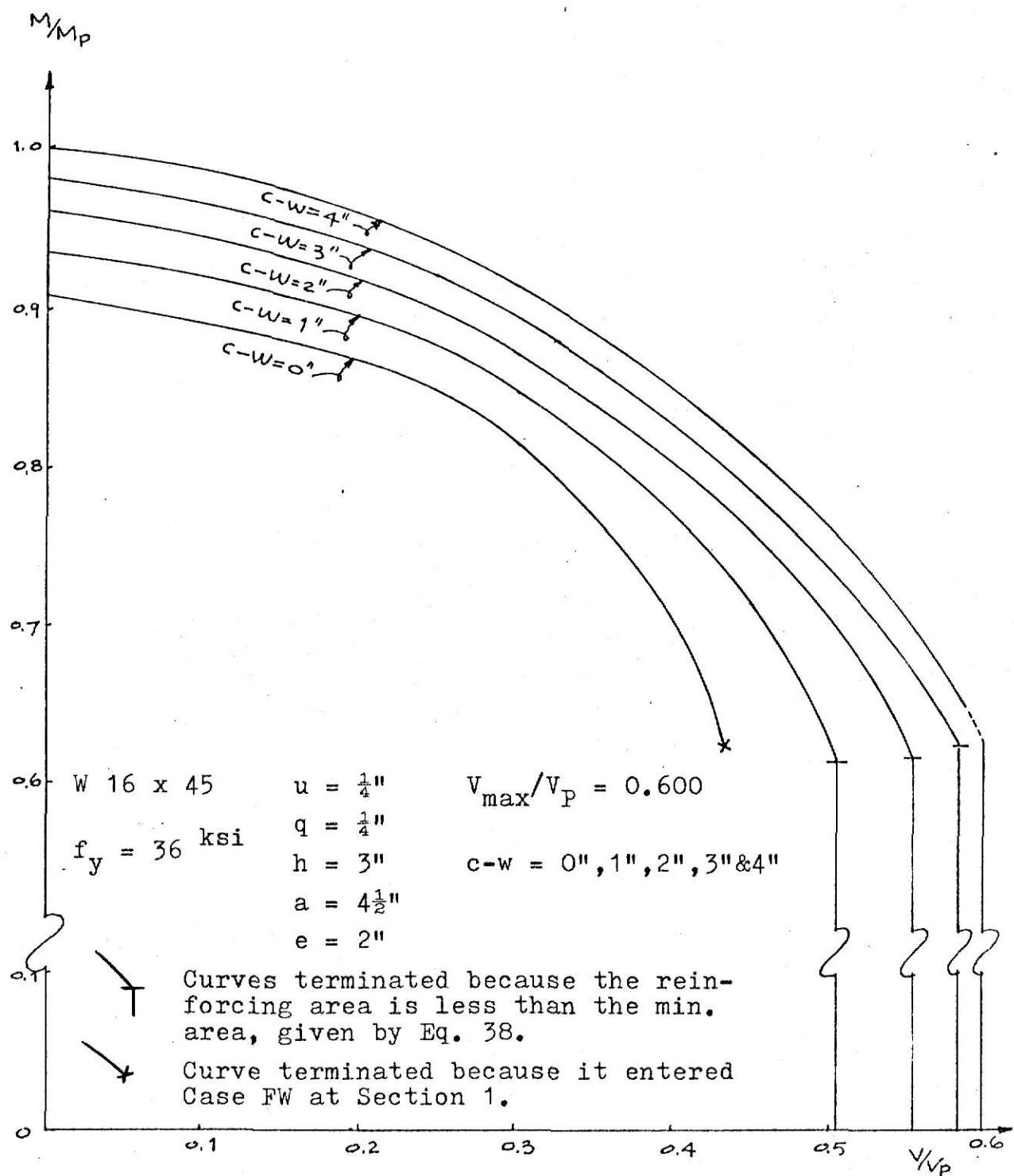


Fig. 10 : Interaction Curve with Varying Reinforcing Areas

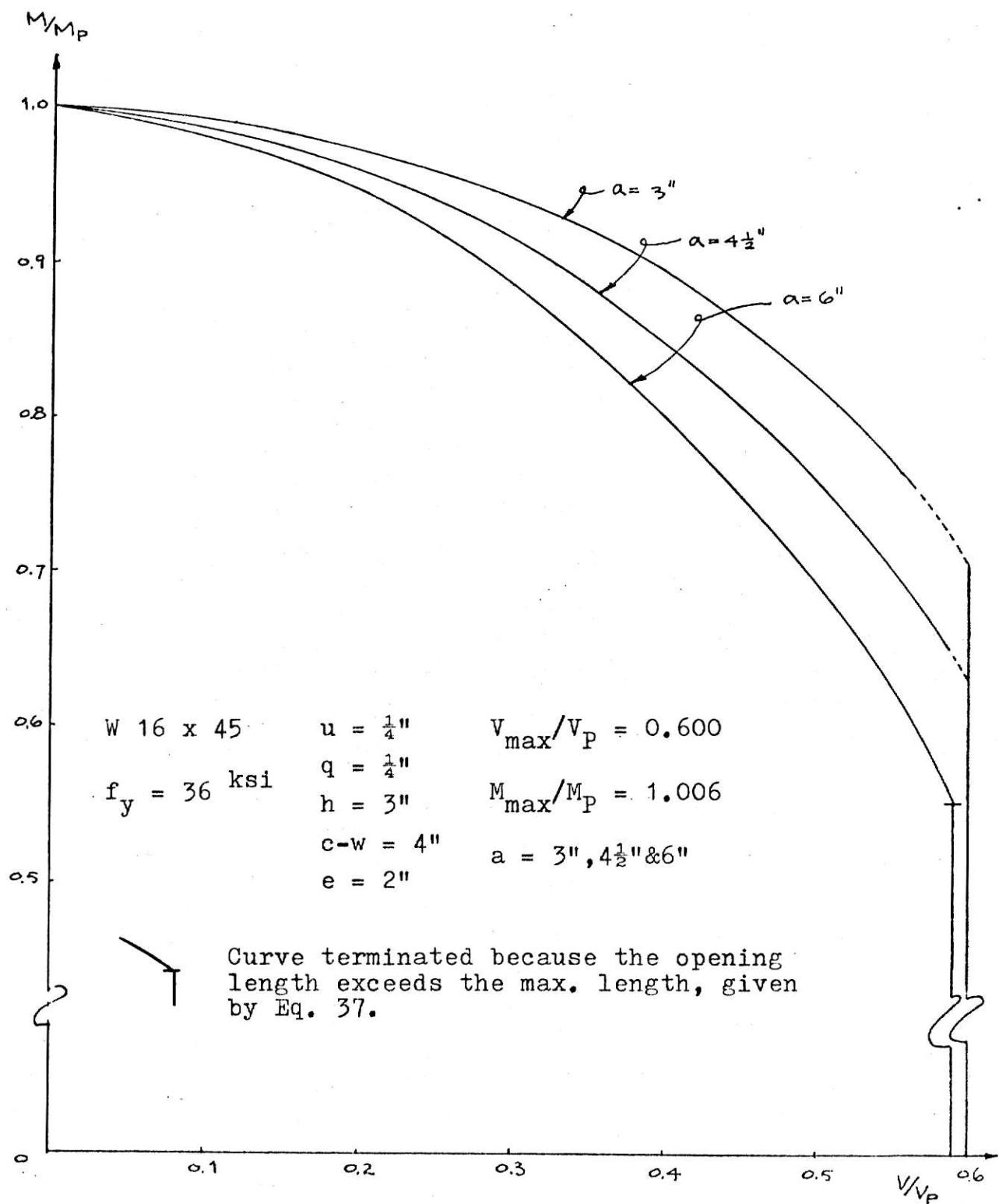


Fig. 11 : Interaction Curve with Varying Opening Lengths

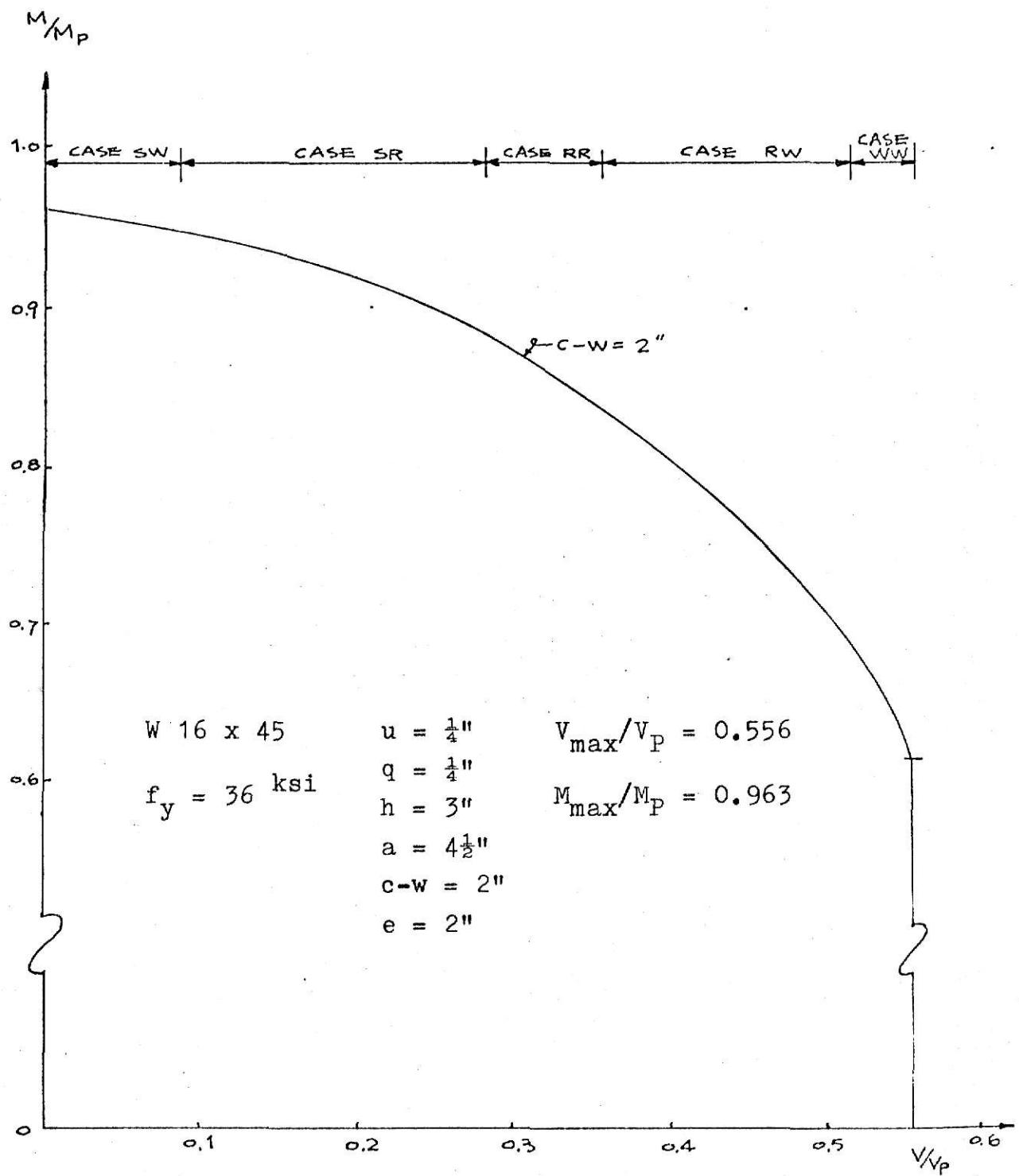


Fig. 12 : Interaction Curve for Illustrating
Stress Reversal Cases

TABLE 1. Locations of Points of Stress Reversal

Section	Case	Stress reversal at top T-section in :	Stress reversal at bottom T-section in:
1	SS (L) ¹	Stub ²	Stub
1	SR (L)	Stub	Reinforcing
1	SW (L)	Stub	Clear Web
1	RS*(L)	Reinforcing	Stub
1	RR (L)	Reinforcing	Reinforcing
1	RW (L)	Reinforcing	Clear Web
1	WS*(L)	Clear Web ³	Stub
1	WR*(L)	Clear Web	Reinforcing
1	WW (L)	Clear Web	Clear Web
2	FF (L)	Flange	Flange

1. (L) - Low Shear Case.
2. Stub - Web between Reinforcing Bars and Opening Edge.
3. Clear Web - Web between Reinforcing Bars and Flange.
- *. Cases not possible for Positive Eccentricity.

TABLE 2. Values of Parameters Investigated

a. Varying Parameter " e " :

($f_y = 36 \text{ ksi}$, $u=q=\frac{1}{4}''$, $h=3''$, $a=4\frac{1}{2}''$ and $c-w=4''$)

e (in)	Group	Complete Solution ?	Cases Involved
0	I ¹	Yes	(SS) ⁴ , RR
0.3	II ²	Yes*	(SR), RR
1	II	Yes*	(SR), RR
2	II	Yes*	(SR), RR
$3\frac{1}{2}$	III ³	Yes	(SW), RR, RW

b. Varying Parameter " c-w " :

($f_y = 36 \text{ ksi}$, $u=q=\frac{1}{4}''$, $h=3''$, $a=4\frac{1}{2}''$ and $e=2''$)

$c-w$ (in)	Group	Complete Solution ?	Cases Involved
0	III	$V=0-47^k$ ⁵	(SW), RW, WW
1	III	$V=0-54.5^k$ ⁶	(SW), RW, WW
2	III	$V=0-60.0^k$ ⁶	(SW), SR, RR, RW, WW
3	II	$V=0-63.0^k$ ⁶	(SR), RR, RW, WW
4	II	Yes*	(SR), RR

TABLE 2. (cont'd)

c. Varying Parameter " a " :

($f_y = 36 \text{ ksi}$, $u = q = \frac{1}{4} \text{ in}$, $h = 3 \text{ in}$, $e = 2 \text{ in}$ and $c - w = 4 \text{ in}$)

$a(\text{in})$	Group	Complete Solution ?	Cases Involved
3	II	Yes *	(SR), RR
$4\frac{1}{2}$	II	Yes *	(SR), RR
6	II	$V=0-63.7^k$ 7	(SR), RR, RW, WW

1. Group I - For $e \leq u$, Starting with Case SS.
2. Group II - For $u < e \leq u + q + A_r/w$, Starting with Case SR.
3. Group III - For $e > u + q + A_r/w$, Starting with Case SW.
4. The Case in parenthesis is the first case in the solution.
5. The program terminated because it entered Case FW at Section 1.
6. The program terminated because the reinforcing area is less than the minimum area, given by Eq. 38.
7. The program terminated because the opening length exceeds the maximum length, given by Eq. 37.
- *. The program terminated because of the sensitivity problem when V approached V_{\max} .

NOMENCLATURE

- a Half length of opening
- A_f Flange area ($b \times t$)
- A_r Reinforcing area ($c - w$) q
- b Flange width
- c Total width of the reinforcing bars (including web thickness)
- d Depth of beam
- e Opening eccentricity
- h Half height of opening
- f_b Bending stress
- f_B Normal stress, bottom tee-section
- f_T Normal stress, top tee-section
- f_v Shear stress
- f_y Yield stress
- f_{yf} Yield stress for flange
- f_{yr} Yield stress for reinforcing area
- f_{yw} Yield stress for web
- k_{1B} Stress reversal coefficient, section one (bottom)
- k_{1T} Stress reversal coefficient, section one (top)
- k_{2B} Stress reversal coefficient, section two (bottom)
- k_{2T} Stress reversal coefficient, section two (top)
- L Horizontal distance from opening center line to closest support
- q Reinforcing bar thickness

Q_{1B}	Total normal force, section one (bottom)
Q_{1T}	Total normal force, section one (top)
Q_{2B}	Total normal force, section two (bottom)
Q_{2T}	Total normal force, section two (top)
M	Moment at center line of opening
M_p	Plastic moment capacity, uncut section
s_B	Web depth, bottom tee-section
s_T	Web depth, top tee-section
t	Flange thickness
u	Distance between opening and reinforcing bar
V	Total shear force ($v_T + v_B$)
v_B	Shear force, bottom tee-section
v_p	Plastic shear capacity, uncut section
v_T	Shear force, top tee-section
w	Web thickness
y_{1B}	Distance from opening edge to Q_{1B}
y_{1T}	Distance from opening edge to Q_{1T}
y_{2B}	Distance from opening edge to Q_{2B}
y_{2T}	Distance from opening edge to Q_{2T}
Case F	Stress reversal in the flange
Case R	Stress reversal in the reinforcing bars
Case S	Stress reversal in the web stub between reinforcing bars and opening edge
Case W	Stress reversal in the clear web between flange and reinforcing bars

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APPENDIX A

SUMMARY OF EQUATIONS FOR LOW AND HIGH SHEAR CASES

1. Low Shear Case SR :

a. Stress resultants :

$$Q_{1T} = A_f f_y + S_T w (1 - 2k_{1T}) f_T + A_r f_y$$

$$Q_{1B} = A_f f_y + S_B w (1 - 2k_{1B}) f_B + (c - w) (2u + q - 2k_{1B} S_B) f_y$$

$$Q_{2T} = A_f f_y (1 - 2k_{2T}) + S_T w f_T + A_r f_y$$

$$Q_{2B} = A_f f_y (1 - 2k_{2B}) + S_B w f_B + A_r f_y$$

$$Q_{1T} y_{1T} = A_f f_y (S_T + 0.5t) + 0.5 S_T^2 w f_T (1 - 2k_{1T}^2)$$

$$+ A_r f_y (u + \frac{q}{2})$$

$$Q_{1B} y_{1B} = A_f f_y (S_B + 0.5t) + 0.5 S_B^2 w f_B (1 - 2k_{1B}^2)$$

$$+ (c - w) [u^2 + uq + \frac{q}{2} - (k_{1B} S_B)^2] f_y$$

$$Q_{2T} y_{2T} = A_f f_y [(S_T + 0.5t) - 2k_{2T} (S_T + t) + tk_{2T}^2]$$

$$+ 0.5 S_T^2 w f_T + A_r f_y (u + \frac{q}{2})$$

$$Q_{2B} y_{2B} = A_f f_y [(S_B + 0.5t) - 2k_{2B} (S_B + t) + tk_{2B}^2]$$

$$+ 0.5 S_B^2 w f_B + A_r f_y (u + \frac{q}{2})$$

b. Stress reversal coefficients :

$$k_{1T} = \frac{A_f f_y}{S_T w f_T} k_{2T}$$

$$k_{1B} = \frac{1}{S_B w f_B + S_B (c-w) f_y} \left[A_f f_y k_{2T} + u(c-w) f_y + \frac{w}{2} (S_B f_B - S_T f_T) \right]$$

$$k_{2B} = \frac{w(S_B f_B - S_T f_T)}{2A_f f_y} + k_{2T}$$

c. Quadratic equation :

$$A_{SR} k_{2T}^2 + B_{SR} k_{2T} + C_{SR} = 0$$

$$A_{SR} = \frac{A_f f_y}{w f_T} + \frac{A_f f_y S_B}{S_B w f_B + S_B (c-w) f_y} + 2t$$

$$B_{SR} = -2(d-2h) + \frac{2u(c-w) f_y S_B}{S_B w f_B + S_B (c-w) f_y} + \frac{w(S_B f_B - S_T f_T) S_B}{S_B w f_B + S_B (c-w) f_y}$$

$$+ \frac{tw(S_B f_B - S_T f_T)}{A_f f_y}$$

$$C_{SR} = \frac{2Va}{A_f f_y} - \frac{u^2(c-w)}{A_f} + \frac{u^2(c-w)^2 f_y S_B}{A_f [S_B w f_B + S_B (c-w) f_y]}$$

$$+ \frac{w^2(S_B f_B - S_T f_T)^2 S_B}{4A_f f_y [S_B w f_B + S_B (c-w) f_y]} + \frac{wu(c-w) S_B (S_B f_B - S_T f_T)}{A_f [S_B w f_B + S_B (c-w) f_y]}$$

$$- \frac{w(S_B f_B - S_T f_T)(S_B + t)}{A_f f_y} + \frac{tw^2(S_B f_B - S_T f_T)^2}{4A_f^2 f_y^2}$$

2. Low Shear Case SW :

a. Stress resultants :

$$Q_{1T} = A_f f_y + S_T w(1-2k_{1T}) f_T + A_r f_y$$

$$Q_{1B} = A_f f_y + S_B w(1-2k_{1B}) f_B - A_r f_y$$

$$Q_{2T} = A_f f_y (1-2k_{2T}) + S_T w f_T + A_r f_y$$

$$Q_{2B} = A_f f_y (1-2k_{2B}) + S_B w f_B + A_r f_y$$

$$Q_{1T}y_{1T} = A_f f_y (S_T + 0.5t) + 0.5 S_T^2 w f_T (1 - 2k_{1T}^2)$$

$$+ A_r f_y (u + \frac{q}{2})$$

$$Q_{1B}y_{1B} = A_f f_y (S_B + 0.5t) + 0.5 S_B^2 w f_B (1 - 2k_{1B}^2)$$

$$- A_r f_y (u + \frac{q}{2})$$

$$Q_{2T}y_{2T} = A_f f_y [(S_T + 0.5t) - 2k_{2T}(S_T + t) + tk_{2T}^2]$$

$$+ 0.5 S_T^2 w f_T + A_r f_y (u + \frac{q}{2})$$

$$Q_{2B}y_{2B} = A_f f_y [(S_B + 0.5t) - 2k_{2B}(S_B + t) + tk_{2B}^2]$$

$$+ 0.5 S_B^2 w f_B + A_r f_y (u + \frac{q}{2})$$

b. Stress reversal coefficients :

$$k_{1T} = \frac{A_f f_y}{S_T w f_T} k_{2T}$$

$$k_{1B} = \frac{1}{2} - \frac{S_T f_T}{2 S_B f_B} - \frac{A_r f_y}{S_B w f_B} + \frac{A_f f_y}{S_B w f_B} k_{2T}$$

$$k_{2B} = \frac{w(S_B f_B - S_T f_T)}{2 A_f f_y} + k_{2T}$$

c. Quadratic equation :

$$A_{SW} k_{2T}^2 + B_{SW} k_{2T} + C_{SW} = 0$$

$$A_{SW} = \frac{A_f f_y}{w} \left(\frac{1}{f_T} + \frac{1}{f_B} \right) + 2t$$

$$B_{SW} = -2(d - 2h) + \frac{t}{A_f f_y} (S_B f_B - S_T f_T) \left(w + \frac{bf_y}{f_B} \right) - \frac{2 A_r f_y}{w f_B}$$

$$C_{SW} = \frac{2Va}{A_f f_y} + \frac{w(S_B f_B - S_T f_T)^2}{4A_f f_y} \left(\frac{1}{f_B} + \frac{w}{bf_y} \right) + \frac{A_r}{A_f} (2u+q) \\ - \frac{w}{A_f f_y} (S_B f_B - S_T f_T) (S_B + t) + \frac{A_r^2 f_y}{A_f w f_B} - \frac{A_r}{A_f f_B} (S_B f_B - S_T f_T)$$

3. Low Shear Case RR :

a. Stress resultants :

$$Q_{1T} = A_f f_y + S_T w (1 - 2k_{1T}) f_T + (c-w)(2u+q-2k_{1T}S_T) f_y$$

$$Q_{1B} = A_f f_y + S_B w (1 - 2k_{1B}) f_B + (c-w)(2u+q-2k_{1B}S_B) f_y$$

$$Q_{2T} = A_f f_y (1 - 2k_{2T}) + S_T w f_T + A_r f_y$$

$$Q_{2B} = A_f f_y (1 - 2k_{2B}) + S_B w f_B + A_r f_y$$

$$Q_{1T} y_{1T} = A_f f_y (S_T + 0.5t) + 0.5 S_T^2 w f_T (1 - 2k_{1T}^2) \\ + (c-w) [u^2 + uq + \frac{q^2}{2} - (k_{1T} S_T)^2] f_y$$

$$Q_{1B} y_{1B} = A_f f_y (S_B + 0.5t) + 0.5 S_B^2 w f_B (1 - 2k_{1B}^2) \\ + (c-w) [u^2 + uq + \frac{q^2}{2} - (k_{1B} S_B)^2] f_y$$

$$Q_{2T} y_{2T} = A_f f_y [(S_T + 0.5t) - 2k_{2T} (S_T + t) + tk_{2T}^2] \\ + 0.5 S_T^2 w f_T + A_r f_y (u + \frac{q}{2})$$

$$Q_{2B} y_{2B} = A_f f_y [(S_B + 0.5t) - 2k_{2B} (S_B + t) + tk_{2B}^2] \\ + 0.5 S_B^2 w f_B + A_r f_y (u + \frac{q}{2})$$

b. Stress reversal coefficients :

$$k_{1T} = \frac{1}{S_T w f_T + S_T (c-w) f_y} \left\{ A_f f_y k_{2T} + u(c-w) f_y \right\}$$

$$k_{1B} = \frac{1}{S_B w f_B + S_B (c-w) f_y} \left[A_f f_y k_{2T} + u(c-w) f_y + \frac{w}{2} (S_B f_B - S_T f_T) \right]$$

$$k_{2B} = \frac{w(S_B f_B - S_T f_T)}{2A_f f_y} + k_{2T}$$

c. Quadratic equation :

$$A_{RR} k_{2T}^2 + B_{RR} k_{2T} + C_{RR} = 0$$

$$A_{RR} = \frac{A_f f_y S_T}{S_T w f_T + S_T (c-w) f_y} + \frac{A_f f_y S_B}{S_B w f_B + S_B (c-w) f_y} + 2t$$

$$B_{RR} = -2(d-2h) - \frac{2u(c-w) f_y S_T}{S_T w f_T + S_T (c-w) f_y} + \frac{2u(c-w) f_y S_B}{S_B w f_B + S_B (c-w) f_y}$$

$$+ \frac{w(S_B f_B - S_T f_T) S_B}{S_B w f_B + S_B (c-w) f_y} + \frac{tw(S_B f_B - S_T f_T)}{A_f f_y}$$

$$C_{RR} = \frac{2Va}{A_f f_y} - \frac{2u^2(c-w)}{A_f} + \frac{u^2(c-w)^2 f_y S_T}{A_f [S_T w f_T + S_T (c-w) f_y]}$$

$$+ \frac{u^2(c-w)^2 f_y S_B}{A_f [S_B w f_B + S_B (c-w) f_y]} + \frac{w^2(S_B f_B - S_T f_T)^2 S_B}{4A_f f_y [S_B w f_B + S_B (c-w) f_y]}$$

$$+ \frac{wu(c-w) S_B (S_B f_B - S_T f_T)}{A_f [S_B w f_B + S_B (c-w) f_y]} - \frac{w(S_B + t)(S_B f_B - S_T f_T)}{A_f f_y}$$

$$+ \frac{tw^2(S_B f_B - S_T f_T)^2}{4A_f^2 f_y^2}$$

4. Low Shear Case RW :

a. Stress resultants :

$$Q_{1T} = A_f f_y + S_T w (1 - 2k_{1T}) f_T + (c - w) (2u + q - 2k_{1T} S_T) f_y$$

$$Q_{1B} = A_f f_y + S_B w (1 - 2k_{1B}) f_B - A_r f_y$$

$$Q_{2T} = A_f f_y (1 - 2k_{2T}) + S_T w f_T + A_r f_y$$

$$Q_{2B} = A_f f_y (1 - 2k_{2B}) + S_B w f_B + A_r f_y$$

$$Q_{1T} y_{1T} = A_f f_y (S_T + 0.5t) + 0.5 S_T^2 w f_T (1 - 2k_{1T}^2)$$

$$+ (c - w) [u^2 + uq + \frac{q^2}{2} - (k_{1T} S_T)^2] f_y$$

$$Q_{1B} y_{1B} = A_f f_y (S_B + 0.5t) + 0.5 S_B^2 w f_B (1 - 2k_{1B}^2)$$

$$- A_r f_y (u + \frac{q}{2})$$

$$Q_{2T} y_{2T} = A_f f_y [(S_T + 0.5t) - 2k_{2T} (S_T + t) + t k_{2T}^2]$$

$$+ 0.5 S_T^2 w f_T + A_r f_y (u + \frac{q}{2})$$

$$Q_{2B} y_{2B} = A_f f_y [(S_B + 0.5t) - 2k_{2B} (S_B + t) + t k_{2B}^2]$$

$$+ 0.5 S_B^2 w f_B + A_r f_y (u + \frac{q}{2})$$

b. Stress reversal coefficients :

$$k_{1T} = \frac{1}{S_T w f_T + S_T (c - w) f_y} [A_f f_y k_{2T} + u (c - w) f_y]$$

$$k_{1B} = \frac{1}{2} - \frac{S_T f_T}{2 S_B f_B} - \frac{A_r f_y}{S_B w f_B} + \frac{A_f f_y}{S_B w f_B} k_{2T}$$

$$k_{2B} = \frac{w (S_B f_B - S_T f_T)}{2 A_f f_y} + k_{2T}$$

c. Quadratic equation :

$$A_{RW} k_{2T}^2 + B_{RW} k_{2T} + C_{RW} = 0$$

$$A_{RW} = \frac{A_f f_y}{w f_B} + \frac{A_f f_y S_T}{S_T w f_T + S_T (c-w) f_y} + 2t$$

$$B_{RW} = -2(d-2h) + \frac{2u(c-w)f_y S_T}{S_T w f_T + S_T (c-w) f_y} - \frac{2A_r f_y}{w f_B}$$

$$+ \frac{t(S_B f_B - S_T f_T)}{A_f f_y} \left(\frac{bf_y}{f_B} + w \right)$$

$$C_{RW} = \frac{2Va}{A_f f_y} - \frac{(c-w)(u^2 - 2qu - q^2)}{A_f} + \frac{w(S_B f_B - S_T f_T)^2}{4 A_f f_y f_B}$$

$$+ \frac{u^2(c-w)^2 f_y S_T}{A_f [S_T w f_T + S_T (c-w) f_y]} + \frac{A_r^2 f_y}{A_f w f_B} - \frac{A_r (S_B f_B - S_T f_T)}{A_f f_B}$$

$$- \frac{(S_B + t)w(S_B f_B - S_T f_T)}{A_f f_y} + \frac{tw^2(S_B f_B - S_T f_T)^2}{4A_f^2 f_y^2}$$

5. Low Shear Case WW :

a. Stress resultants :

$$Q_{1T} = A_f f_y + S_T w (1 - 2k_{1T}) f_T - A_r f_y$$

$$Q_{1B} = A_f f_y + S_B w (1 - 2k_{1B}) f_B - A_r f_y$$

$$Q_{2T} = A_f f_y (1 - 2k_{2T}) + S_T w f_T + A_r f_y$$

$$Q_{2B} = A_f f_y (1 - 2k_{2B}) + S_B w f_B + A_r f_y$$

$$Q_{1T} y_{1T} = A_f f_y (S_T + 0.5t) + 0.5 S_T^2 w f_T (1 - 2k_{1T}^2)$$

$$- A_r f_y (u + \frac{q}{2})$$

$$Q_{1B}y_{1B} = A_f f_y (S_B + 0.5t) + 0.5 S_B^2 w f_B (1 - 2k_{1B}^2)$$

$$- A_r f_y (u + \frac{q}{2})$$

$$Q_{2T}y_{2T} = A_f f_y [(S_T + 0.5t) - 2k_{2T}(S_T + t) + tk_{2T}^2]$$

$$+ 0.5 S_T^2 w f_T + A_r f_y (u + \frac{q}{2})$$

$$Q_{2B}y_{2B} = A_f f_y [(S_B + 0.5t) - 2k_{2B}(S_B + t) + tk_{2B}^2]$$

$$+ 0.5 S_B^2 w f_B + A_r f_y (u + \frac{q}{2})$$

b. Stress reversal coefficients :

$$k_{1T} = \frac{1}{S_T w f_T} (A_f f_y k_{2T} - A_r f_y)$$

$$k_{1B} = \frac{1}{2} - \frac{S_T f_T}{2 S_B f_B} - \frac{A_r f_y}{S_B w f_B} + \frac{A_f f_y}{S_B w f_B} k_{2T}$$

$$k_{2B} = \frac{w(S_B f_B - S_T f_T)}{2 A_f f_y} + k_{2T}$$

c. Quadratic equation :

$$A_{WW} k_{2T}^2 + B_{WW} k_{2T} + C_{WW} = 0$$

$$A_{WW} = \frac{A_f f_y}{w} \left(\frac{1}{f_T} + \frac{1}{f_B} \right) + 2t$$

$$B_{WW} = -2(d - 2h) + \frac{t}{A_f f_y} (S_B f_B - S_T f_T) \left(w + \frac{bf_y}{f_B} \right)$$

$$- \frac{2A_r f_y}{w} \left(\frac{1}{f_T} + \frac{1}{f_B} \right)$$

$$\begin{aligned}
 C_{WW} = & \frac{2Va}{Af^f_y} + \frac{w(S_B f_B - S_T f_T)^2}{4Af^f_y} \left(\frac{1}{f_B} + \frac{w}{bf_y} \right) \\
 & - \frac{w}{Af^f_y} (S_B f_B - S_T f_T) (S_B + t) + \frac{A_r^2 f_y}{w Af} \left(\frac{1}{f_T} + \frac{1}{f_B} \right) \\
 & - \frac{A_r (S_B f_B - S_T f_T)}{Af^f_B} + \frac{2A_r}{Af} (2u + q)
 \end{aligned}$$

APPENDIX B**COMPUTER PROGRAMS**

ILLEGIBLE DOCUMENT

**THE FOLLOWING
DOCUMENT(S) IS OF
POOR LEGIBILITY IN
THE ORIGINAL**

**THIS IS THE BEST
COPY AVAILABLE**

APPENDIX B

C THIS IS THE FIRST PACKAGE OF THE COMPUTER PROGRAM TO BE PUT IN
C FRONT OF EACH CASE.

C ****
C THIS IS A PROGRAM FOR SOLVING THE INTERACTION DIAGRAM OF V/VP AND
C N/MP FOR THE LOW SHEAR CASES :
C ****

```

READ(5,20) B,D,T,W,U,O,C,H,A,FY,ECCTRY,ROK2T,HIK2T,RIK2B,HIK2B
20 FORMAT(8F10.3)
ST=D/2.0-T-ECCTRY-H
SB=D/2.0-T+ECCTRY-H
WRITE(6,21) B,D,T,ST,SB
21 FORMAT(//,1F10.3)
WRITE(6,22) W,U,O,C
22 FORMAT(//,1F10.3)
WRITE(6,23) H,A,FY,ECCTRY
23 FORMAT(//,1F10.3)
AF=B*T
AR=(C-W)*O
VP=W*(D-2.0*T)*FY/SQRT(3.)
VMAX=H*(D-2.0*T-2.0*H)*FY/SQRT(3.)
PM=FY*(AF*(D-T)+H*(D-2.0*T)**2/4.0)
HIVMP=VMAX/VP
WRITE(6,24) VP,VMAX,PM,HIVMP
24 FORMAT(//,1F10.5)
12.5,F10.5)
WRITE(6,25) ROK2T,HIK2T,RIK2B,HIK2B
25 FORMAT(//,1F10.5)
      ROK2T      HIK2T      RIK2B      HIK2B      FOR ALL THE
      FOLLOWING CASES!/,4F10.5)
```

C ****
C THIS SPACE IS RESERVED FOR THE APPROPRIATE CASE TO BE RUN.
C ****

C THE FOLLOWING PACKAGE IS THE LAST ONE TO BE PUT AT THE END OF THE
C PROGRAM.
C ****

```

1990 WRITE(6,1991)
1991 FORMAT(//,1F10.5)
      V IS GREATER THAN VMAX!
      GO TO 2000
1992 WRITE(6,1993)
1993 FORMAT(//,1F10.5)
      VFT OR FV IS TOO SMALL!
2000 STOP
      END
```

C
C *****
C CASE : SS (THAT MEANS BOTH KIT AND K1B ARE LOCATED IN THE WEB BE
C LOW THE REINFORCING BARS.)
C *****

```

R0K1T=0.0
HIK1T=U/ST
R0K1B=0.0
HIK1B=U/SB
WRITE(6,28) R0K1T,HIK1T,R0K1B,HIK1B
28 FORMAT(/,1      L0K1T      HIK1T      L0K1B      HIK1B      FOR THE FULL)
LING CASE SS /,4F10.5)
WRITE(6,29)
29 FORMAT(//,1      V           VT          VR          V1          V2
        1K1T      K1B          K2T         K2B         V/VP       M/MP //)
C
C       THIS SPACE IS RESERVED FOR ARBITRARY VALUE OF V AND V1 .
C
V1NCR=1.0
30 VR=V/(1.0+V1)
VT=V-VR
FTEX=FY**2-3.0*VT**2/(ST**2*W**2)
IF (FTEX .GT. 0.0) GO TO 35
WRITE(6,32) FTEX
32 FORMAT(/,1      FTEX =1,F10.5)
GO TO 2000
35 FBEX=FY**2-3.0*VR**2/(SB**2*W**2)
IF (FBEX .GT. 0.0) GO TO 40
WRITE(6,37) FBEX
37 FORMAT(/,1      FBEX =1,F10.5)
GO TO 2000
40 FT=SORT(FTEX)
FR=SORT(FBEX)
IF (FT .LT. 0.1) GO TO 1992
IF (FR .LT. 0.1) GO TO 1992
ASS=AF*FY*(1.0/FT+1.0/FR)/W+2.0*T
BSS=-2.0*(D-2.0*H)+T*(SB*FB-ST*FT)*(W+H*FY/FR)/(AF*FY)
CSS=2.0*A*V/(AF*FY)+W*(SB*FB-ST*FT)**2*(1.0/FR+W/(B*FY))/(4.0*A*F-
Y)-W*(SB*FB-ST*FT)*(SB+T)/(AF*FY)
DO=BSS**2-4.0*ASS*CSS
IF (DO .GT. 0.0) GO TO 50
WRITE(6,45) DO
45 FORMAT(5H DO =F15.5)
GO TO 2000
50 R2T1=(-BSS+SORT(DO))/(2.0*ASS)
R2T2=(-BSS-SORT(DO))/(2.0*ASS)
IF (R2T1 .LT. 0.0) GO TO 52
IF (R2T1 .LE. 1.0) GO TO 60
52 IF (R2T2 .LT. 0.0) GO TO 57
IF (R2T2 .LE. 1.0) GO TO 61
WRITE(6,55) R2T1,R2T2
55 FORMAT(/,1      R2T1      R2T2 //,2F10.5//)
GO TO 2000
57 R2T=0.0
K=1

```

```

      GO TO 65
60 R2T=R2T1
  K=0
  GO TO 65
61 R2T=R2T2
  K=1
65 R2B=H*(SB*FB-ST*FT)/(2.0*AF*FY)+R2T
  R1T=AF*FY*R2T/(ST*W*FT)
  R1B=AF*FY*R2B/(SB*W*FB)
  Q1T=AF*FY+ST*W*FT*(1.0-2.0*R1T)+AR*FY
  Q1B=AF*FY+SB*W*FB*(1.0-2.0*R1B)+AR*FY
  Q2T=AF*FY*(1.0-2.0*R2T)+ST*W*FT+AR*FY
  Q2B=AF*FY*(1.0-2.0*R2B)+SB*W*FB+AR*FY
  Y1T=(AF*FY*(ST+0.5*T)+0.5*ST**2*W*FT*(1.0-2.0*R1T**2)+AR*FY*(1+Q/1.0))/Q1T
  Y1B=(AF*FY*(SB+0.5*T)+0.5*SB**2*W*FB*(1.0-2.0*R1B**2)+AR*FY*(1+Q/1.0))/Q1B
  Y2T=(AF*FY*((ST+0.5*T)-2.0*R2T*(ST+T)+T*R2T**2)+0.5*ST**2*W*FT+AR*FY*(U+Q/2.0))/Q2T
  Y2B=(AF*FY*((SB+0.5*T)-2.0*R2B*(SB+T)+T*R2B**2)+0.5*SB**2*W*FB+AR*FY*(U+Q/2.0))/Q2B
  V2=(Y1T-Y2T)/(Y1B-Y2B)
  IF (V2 .LT. 0.0) GO TO 85
  IF (V2 .GT. 1.0) GO TO 85
  R=V2-V1
  IF (ABS(R) .LE. 0.001) GO TO 66
  V1=(V1+V2)/2.0
  GO TO 30
66 IF (R1T .GT. HIK1T) GO TO 86
  IF (R1B .GT. HIK1B) GO TO 88
  Z=Q1T*(Y1T+Y1B+2.0*H)-V*A
  VVP=V/VP
  PMM=Z/PM
  IF (PMM .GT. 0.0) GO TO 80
  WRITE(6,70) PMM
70 FORMAT(/, ' PMM = ', F10.5)
  GO TO 2000
80 WRITE(6,81) V,VT,VB,V1,V2,R1T,R1B,R2T,R2B,VVP,PMM
81 FORMAT(11F10.5)
  V=V+VI*CR
  IF (V .GT. VMAX) GO TO 1990
  GO TO 30
85 IF (K .EQ. 0) GO TO 52
  GO TO 2000
86 IF (K .EQ. 0) GO TO 52
  WRITE(6,87)
87 FORMAT(//, ' TO NEXT CASE ES! ')
  GO TO 2000
88 IF (K .EQ. 0) GO TO 52
  WRITE(6,89)
89 FORMAT(//, ' TO NEXT CASE SR! ')
  GO TO 2000

```

```

C
C
C ****
C CASE : SR (THAT MEANS KIT IS LOCATED IN THE WER BELOW THE REIN-
C FORCING BARS AND K1B IS LOCATED IN THE REINFORCING
C BARS. )
C ****
C
C ROKIT=0.0
C HIKIT=U/ST
C ROKIB=U/SB
C HIKIB=(U+0)/SB
C WRITE(6,190) ROKIT,HIKIT,ROKIB,HIKIB
C 190 FORMAT(/,1 LOKIT HIKIT LOKIB HIKIB FOR THE FOLLOW-
C ING CASE SR ! / .4E10.5)
C WRITE(6,200)
C 200 FORMAT(//,1 V VT VB V1 V2
C 1K1T K1B K2T K2B V/VP M/MP //)
C
C THIS SPACE IS RESERVED FOR ARBITRARY VALUE OF V AND V1 .
C
C VINCR=1.0
C 210 VB=V/(1.0+V1)
C VT=V-VB
C FTEX=FY**2-3.0*VT**2/(ST**2*W**2)
C IF (FTEX .GT. 0.0) GO TO 214
C WRITE(6,213) FTEX
C 213 FORMAT(/,1 FTEX =!,F10.5)
C GO TO 2000
C 214 FBEX=FY**2-3.0*VB**2/(SB**2*W**2)
C IF (FBEX .GT. 0.0) GO TO 217
C WRITE(6,216) FBEX
C 216 FORMAT(/,1 FBEX =!,F10.5)
C GO TO 2000
C 217 FT=SORT(FTEX)
C FB=SORT(FBEX)
C IF (FT .LT. 0.1) GO TO 1992
C IF (FB .LT. 0.1) GO TO 1992
C PARA1=SB*W*FB+SB*(C-W)*FY
C PARA2=W*(SB*FB-ST*FT)
C PARA3=U*(C-W)*FY
C ASR=AF*FY/(W*FT)+AF*FY*SB/PARA1+2.0*T
C BSR=-2.0*(D-2.0*H)+2.0*PARA3*SB/PARA1+PARA2*SB/PARA1+T*PARA2/(AF*
C 1Y)
C CSR=2.0*W*V/(AF*FY)-U*PARA3/(AF*FY)+SB*PARA3**2/(AF*FY*PARA1)+SB*
C 1ARA2**2/(4.0*AF*FY*PARA1)+SB*PARA2*PARA3/(AF*FY*PARA1)-(SB+1)*PAR
C 22/(AF*FY)+T*PARA2**2/(4.0*AF**2*FY**2)
C D1=BSR**2-4.0*ASR*CSR
C IF (D1 .GT. 0.0) GO TO 220
C WRITE(6,219) D1
C 219 FORMAT(5H D1 =F15.5)
C GO TO 2000
C 220 R2T1=(-BSR+SORT(D1))/(2.0*ASR)
C R2T2=(-BSR-SORT(D1))/(2.0*ASR)
C IF (R2T1 .LT. 0.0) GO TO 230
C IF (R2T1 .LE. 1.0) GO TO 250
C 230 IF (R2T2 .LT. 0.0) GO TO 243

```

```

    IF (R2T2 .LE. 1.0) GO TO 251
    WRITE(6,240) R2T1,R2T2
240 FORMAT(2F10.5)
    GO TO 2000
243 R2T=0.0
    K=1
    GO TO 260
250 R2T=R2T1
    K=0
    GO TO 260
251 R2T=R2T2
    K=1
260 R2B=PARA2/(2.0*AF*FY)+R2T
    R1T=AF*FY*R2T/(ST*N*FT)
    R1B=(AF*FY*R2T+PARA3+PARA2/2.0)/PARA1
    O1T=AF*FY+ST*N*FT*(1.0-2.0*R1T)+AR*FY
    O1B=AF*FY+SB*N*FB*(1.0-2.0*R1B)+(C-H)*(2.0*IU+0-2.0*R1B*SB)*FY
    O2T=AF*FY*(1.0-2.0*R2T)+ST*N*FT+AR*FY
    O2B=AF*FY*(1.0-2.0*R2B)+SB*N*FB+AR*FY
    Y1T=(AF*FY*(ST+0.5*T)+0.5*ST**2*N*FT*(1.0-2.0*R1T**2)+AR*FY*(U+Q/
    1.0))/O1T
    Y1B=(AF*FY*(SB+0.5*T)+0.5*SB**2*N*FB*(1.0-2.0*R1B**2)+(C-H)*(1**2*
    IU+0**2/2.0-(R1B*SB)**2)*FY)/O1B
    Y2T=(AF*FY*((ST+0.5*T)-2.0*R2T*(ST+T)+T*R2T**2)+0.5*ST**2*N*FT+AR*
    1FY*(U+Q/2.0))/O2T
    Y2B=(AF*FY*((SB+0.5*T)-2.0*R2B*(SB+T)+T*R2B**2)+0.5*SB**2*N*FB+AR*
    1FY*(U+Q/2.0))/O2B
    V2=(Y1T-Y2T)/(Y1B-Y2B)
    R=V2-V1
    IF (V2 .LT. 0.0) GO TO 269
    IF (V2 .GT. 1.0) GO TO 269
    IF (ABS(R) .LE. 0.001) GO TO 261
    V1=(V1+V2)/2.0
    GO TO 210
261 IF (R1T .GT. HIK1T) GO TO 270
    IF (R1B .LT. ROK1B) GO TO 272
    IF (R1B .GT. HIK1B) GO TO 274
    Z=O1T*(Y1T+Y1B+2.0*H)-V*A
    VVP=V/VP
    PMM=Z/PN
    IF (PMM .GT. 0.0) GO TO 267
    WRITE(6,266) PMM
266 FORMAT(1,1 M/MP =1E10.5)
    GO TO 2000
267 WRITE(6,268) V,VT,VB,V1,V2,R1T,R1B,R2T,R2B,VVP,PMM
268 FORMAT(11E10.5)
    V=V+VINCR
    IF (V .GT. VMAX) GO TO 1990
    GO TO 210
269 IF (K .EQ. 0) GO TO 230
    GO TO 2000
270 IF (K .EQ. 0) GO TO 230
    WRITE(6,271)
271 FORMAT(1,1 TO NEXT CASE RR1)
    GO TO 2000
272 IF (K .EQ. 0) GO TO 230
    WRITE(6,273)
273 FORMAT(1,1 TO NEXT CASE SS1)
    GO TO 2000
274 IF (K .EQ. 0) GO TO 230

```

WRITE(6,275)

275 FORMAT(//,1 TO NEXT CASE SW!)
GO TO 2000

67

```

C
C
C ****
C CASE : SH (THAT MEANS K1T IS LOCATED IN THE WEB BELOW THE REIN-
C FORCING BARS AND K1B IS LOCATED IN THE CLEAR WEB. )
C
C ****
C
C ROK1T=0.0
C HIK1T=U/ST
C ROK1B=(U+0)/SB
C HIK1B=1.0
C WRITE(6,401) ROK1T,HIK1T,ROK1B,HIK1B
C 401 FORMAT(/, ' LOK1T      HIK1T      LOK1B      HIK1B      FOR THE FULL
C LING CASE SH',4F10.5)
C WRITE(6,402)
C 402 FORMAT(//, ' V          VT          VB          V1          V2
C 1K1T      K1B      K2T      K2B      V/VP      M/MP //)
C
C THIS SPACE IS RESERVED FOR ARBITRARY VALUE OF V AND V1 .
C
C VINCR=1.0
C 410 VB=V/(1.0+V1)
C VT=V-VB
C FTEX=FY**2-3.0*VT**2/(ST**2*W**2)
C IF (FTEX .GT. 0.0) GO TO 413
C WRITE(6,412) FTEX
C 412 FORMAT(/, ' FTEX =',F10.5)
C GO TO 2000
C 413 FBEX=FY**2-3.0*VB**2/(SB**2*W**2)
C IF (FBEX .GT. 0.0) GO TO 420
C WRITE(6,415) FBEX
C 415 FORMAT(/, ' FBEX =',F10.5)
C GO TO 2000
C 420 FT=SORT(FTEX)
C FB=SORT(FBEX)
C IF (FT .LT. 0.1) GO TO 1992
C IF (FB .LT. 0.1) GO TO 1992
C PARA2=W*(SB*FB-ST*FT)
C ASH=AF*FY*(1.0/FT+1.0/FB)/W+2.0*T
C BSM=-2.0*(D-2.0*H)+T*(SB*FB-ST*FT)*(W+B*FY/FB)/(AF*FY)-2.0*AR*FY/
C 1W*FB)
C CSW=2.0*V*A/(AF*FY)+(1.0/FT+H/(B*FY))*PARA2**2/(4.0*W*AF*FY)-PARA
C 1*(S4+T)/(AF*FY)+AR*(2.0*U+0)/AF+AR**2*FY/(AF*W*FB)-AR*PARA2/(H*F
C 2AF)
C D2=BSh**2-4.0*ASH*CSH
C IF (D2 .GT. 0.0) GO TO 432
C WRITE(6,430) D2
C 430 FORMAT(5H D2 =F16.5)
C GO TO 2000
C 432 R2T1=(-BSH+SORT(D2))/(-2.0*ASH)
C R2T2=(-BSH-SORT(D2))/(-2.0*ASH)
C IF (R2T1 .LT. 0.0) GO TO 434
C IF (R2T1 .LE. 1.0) GO TO 439
C 434 IF (R2T2 .LT. 0.0) GO TO 439
C IF (R2T2 .LE. 1.0) GO TO 440
C WRITE(6,435) R2T1,R2T2
C 435 FORMAT(2F10.5)

```

```

      GO TO 2000
438 R2T=0.0
      K=1
      GO TO 441
439 R2T=R2T1
      K=0
      GO TO 441
440 R2T=R2T2
      K=1
441 R2B=PARA2/(2.0*AF*FY)+R2T
      R1T=AF*FY*R2T/(ST*W*FT)
      R1B=(AF*FY*R2B-AR*FY)/(SB*W*FB)
      O1T=AF*FY+ST*W*FT*(1.0-2.0*R1T)+AR*FY
      O1B=AF*FY+SB*W*FB*(1.0-2.0*R1B)-AR*FY
      O2T=AF*FY*(1.0-2.0*R2T)+ST*W*FT+AR*FY
      O2B=AF*FY*(1.0-2.0*R2B)+SB*W*FB+AR*FY
      Y1T=(AF*FY*(ST+0.5*T)+0.5*ST**2*W*FT*(1.0-2.0*R1T**2)+AR*FY*(U+0)/
1.0))/O1T
      Y1B=(AF*FY*(SB+0.5*T)+0.5*SB**2*W*FB*(1.0-2.0*R1B**2)-AR*FY*(U+0)/
1.0))/O1B
      Y2T=(AF*FY*((ST+0.5*T)-2.0*R2T*(ST+T)+T*R2T**2)+0.5*ST**2*W*FT+AR*
1FY*(U+0/2.0))/O2T
      Y2B=(AF*FY*((SB+0.5*T)-2.0*R2B*(SB+T)+T*R2B**2)+0.5*SB**2*W*FB+AR*
1FY*(U+0/2.0))/O2B
      V2=(Y1T-Y2T)/(Y1B-Y2B)
      R=V2-V1
      IF (V2 .LT. 0.0) GO TO 470
      IF (V2 .GT. 1.0) GO TO 470
      IF (ABS(R) .LE. 0.001) GO TO 450
      V1=(V1+V2)/2.0
      GO TO 410
450 IF (R1T .GT. HIK1T) GO TO 480
      IF (R1B .LT. ROK1B) GO TO 482
      IF (R1B .GT. HIK1B) GO TO 484
      Z=O1T*(Y1T+Y1B+2.0*H)-V*A
      VVP=V/VP
      PMM=Z/PM
      IF (PMM .GT. 0.0) GO TO 460
      WRITE(6,459) PMM
459 FORMAT(/, ' M/MP ='F10.5)
      GO TO 2000
460 WRITE(6,461) V,VT,VB,V1,V2,R1T,R1B,R2T,R2B,VVP,PMM
461 FORMAT(11F10.5)
      V=V+VINCR
      IF (V .GT. VMAX) GO TO 1990
      GO TO 410
470 IF (K .EQ. 0) GO TO 434
      GO TO 2000
480 IF (K .EQ. 0) GO TO 434
      WRITE(6,481)
481 FORMAT(//, ' TO NEXT CASE RW1')
      GO TO 2000
482 IF (K .EQ. 0) GO TO 434
      WRITE(6,483)
483 FORMAT(//, ' TO NEXT CASE SR1')
      GO TO 2000
484 IF (K .EQ. 0) GO TO 434
      WRITE(6,485)
485 FORMAT(//, ' TO NEXT CASE SF1')
      GO TO 2000

```

C
C
C ****
C CASE : RR (THAT MEANS BOTH KLT AND K1B ARE LOCATED IN THE REIN-
C FORCING BARS.)
C
C ****

ROK1T=U/ST

HIK1T=(U+Q)/ST

ROK1B=U/SB

HIK1B=(U+Q)/SR

WRITE(6,278) ROK1T,HIK1T,ROK1B,HIK1B

278 FORMAT(/,1 LOK1T HIK1T LOK1B HIK1B FOR THE FOLLOWING CASE RR /,4F10.5)

WRITE(6,279)

279 FORMAT(/,1 V VT VB V1 V2
1K1T K1B K2T K2B V/VP M/MP //)

C
C THIS SPACE IS RESERVED FOR ARBITRARY VALUE OF V AND V1 .
C

VINCR=1.0

IND=0

280 VB=V/(1.0+V1)

VT=V-VB

FTEX=FY**2-3.0*VT**2/(ST**2*W**2)

IF (FTEX .GT. 0.0) GO TO 284

IF (ABS(R) .LE. 0.0005) GO TO 282

GO TO 286

282 WRITE(6,283) FTEX

283 FORMAT(/,1 FTEX =1,F10.5)

GO TO 2000

284 FBEX=FY**2-3.0*VB**2/(SB**2*W**2)

IF (FBEX .GT. 0.0) GO TO 291

IF (ABS(R) .LE. 0.0005) GO TO 289

286 IF (IND .EQ. 1) GO TO 287

IND=1

VVNCR=VINCR/2.0

GO TO 288

287 VVNCR=VVNCR/2.0

288 V=V+VVNCR

V1=VV1

GO TO 280

289 WRITE(6,290) FBEX

290 FORMAT(/,1 FBEX =1,F10.5)

GO TO 2000

291 FT=SORT(FTEX)

FB=SORT(FBEX)

IF (FT .LT. 0.1) GO TO 1992

IF (FB .LT. 0.1) GO TO 1992

PARA1=SB*W*FB+SB*(C-W)*FY

PARA2=W*(SB*FB-ST*FT)

PARA3=U*(C-W)*FY

PARA4=ST*W*FT+ST*FY*(C-W)

ARR=AF*FY*ST/ PARA4+AF*FY*SB/ PARA1+2.0*FT

BRR=-2.0*(D-2.0*H)+2.0*PARA3*ST/ PARA4+2.0*PARA3*SB/ PARA1+PARA2*

1PARA1*FT*PARA2/(AF*FY)

CRR=2.0*V*A/(AF*FY)-2.0*U*PARA3/(AF*FY)+PARA3**2*ST/(AF*FY*PARA4)

1 PARA3**2*SB/(AF*FY*PARA1)+PARA2**2*SB/(4.0*AF*FY*PARA1)+PARA2*PAR
 23*SB/(AF*FY*PARA1)-PARA2*(SB+T)/(AF*FY)+T*PARA2**2/(4.0*AF**2*FY*
 32)
 D3=BRR**2-4.0*ARR*CRR
 IF (D3 .GT. 0.0) GO TO 294
 WRITE(6,293) D3
 293 FORMAT(5H D3 =F15.5)
 GO TO 2000
 294 R2T1=(-BRR+SORT(D3))/(2.0*ARR)
 R2T2=(-BRR-SORT(D3))/(2.0*ARR)
 IF (R2T1 .LT. 0.0) GO TO 300
 IF (R2T1 .LE. 1.0) GO TO 320
 300 IF (R2T2 .LT. 0.0) GO TO 310
 IF (R2T2 .LE. 1.0) GO TO 321
 310 WRITE(6,311) R2T1,R2T2
 311 FORMAT(2F10.5)
 GO TO 2000
 320 R2T=R2T1
 K=0
 GO TO 325
 321 R2T=R2T2
 K=1
 325 R2B=PARA2/(2.0*AF*FY)+R2T
 R1T=(AF*FY*R2T+PARA3)/PARA4
 R1B=(AF*FY*R2T+PARA3+PARA2/2.0)/PARA1
 Q1T=AF*FY+ST*W*FT*(1.0-2.0*R1T)+(C-W)*(2.0*U+0-2.0*R1T*ST)*FY
 Q1B=AF*FY+SB*W*FB*(1.0-2.0*R1B)+(C-W)*(2.0*U+0-2.0*R1B*SB)*FY
 Q2T=AF*FY*(1.0-2.0*R2T)+ST*W*FT+AR*FY
 Q2B=AF*FY*(1.0-2.0*R2B)+SB*W*FB+AR*FY
 Y1T=(AF*FY*(ST+0.5*T)+0.5*ST**2*W*FT*(1.0-2.0*R1T**2)+(C-W)*(1**2
 1U*0+0**2/2.0-(R1T*ST)**2)*FY)/Q1T
 Y1B=(AF*FY*(SB+0.5*T)+0.5*SB**2*W*FB*(1.0-2.0*R1B**2)+(C-W)*(1**2
 1U*0+0**2/2.0-(R1B*SB)**2)*FY)/Q1B
 Y2T=(AF*FY*((ST+0.5*T)-2.0*R2T*(ST+T)+T*R2T**2)+0.5*ST**2*W*FT+AR
 1FY*(U+0/2.0))/Q2T
 Y2B=(AF*FY*((SB+0.5*T)-2.0*R2B*(SB+T)+T*R2B**2)+0.5*SB**2*W*FB+AR
 1FY*(U+0/2.0))/Q2B
 V2=(Y1T-Y2T)/(Y1B-Y2B)
 IF (V2 .LT. 0.0) GO TO 349
 IF (V2 .GT. 1.0) GO TO 349
 R=V2-V1
 IF (IND .EQ. 1) GO TO 330
 IF (ABS(R) .LE. 0.001) GO TO 331
 V1=(V1+V2)/2.0
 GO TO 280

C
 C THE TOLERANCE FOR THE FOLLOWING STATEMENT MUST BE CHOSEN VERY CAR
 C FULLY WHEN IT APPROACHES VMAX IN THIS CASE.
 C

330 IF (ABS(R) .LE. 0.025) GO TO 331
 V1=(V1+V2)/2.0
 GO TO 280
 331 IF (R1T .LT. ROK1T) GO TO 350
 IF (R1T .GT. HIK1T) GO TO 352
 IF (R1B .LT. ROK1B) GO TO 354
 IF (R1B .GT. HIK1B) GO TO 356
 Z=Q1T*(Y1T+Y1B+2.0*H)-V*A
 VVP=V/VP
 PNM=Z/ZPM
 IF (PNM .GT. 0.0) GO TO 346

```
      WRITE(6,340) PMM
340 FORMAT(/, ' M/MR = F10.5')
      GO TO 2000
345 WRITE(6,346) V,VT,VB,V1,V2,R1T,R1B,R2T,R2B,VVP,PMM
346 FORMAT(11F10.5)
      VV=V
      VV1=V1
      V=V+VINCR
      IND=0
      IF (V .GT. VMAX) GO TO 1990
      GO TO 280
349 IF (K .EQ. 0) GO TO 300
      GO TO 2000
350 IF (K .EQ. 0) GO TO 300
      WRITE(6,351)
351 FORMAT(//, ' TO NEXT CASE SR')
      GO TO 2000
352 IF (K .EQ. 0) GO TO 300
      WRITE(6,353)
353 FORMAT(//, ' TO NEXT CASE WR')
      GO TO 2000
354 IF (K .EQ. 0) GO TO 300
      WRITE(6,355)
355 FORMAT(//, ' TO NEXT CASE RS')
      GO TO 2000
356 IF (K .EQ. 0) GO TO 300
      WRITE(6,357)
357 FORMAT(//, ' TO NEXT CASE RW')
      GO TO 2000
```

C
C
C
C

CASE : RH (THAT MEANS K1T IS LOCATED IN THE REINFORCING AND K1R
IS LOCATED IN THE CLEAR WEB.)

ROK1T=U/ST

HIK1T=(U+0)/ST

ROK1R=(U+0)/SB

HIK1R=1.0

WRITE(6,501) ROK1T,HIK1T,ROK1R,HIK1R

501 FORMAT(7,1 LOK1T HIK1T ROK1R HIK1R FOR THE FOLLOWING CASE RW1/,4F10.5)

WRITE(6,502)

502 FORMAT(7,1 V VT VB VI V2
1KIT K1B K2T K2B V/VP M/MP1//)

C
C
C

THIS SPACE IS RESERVED FOR ARBITRARY VALUE OF V AND VI .

VINCR=1.0

IND=0.

510 VB=V/(1.0+VI)

VT=V-VB

FTEX=FY**2-3.0*VT**2/(ST**2*H**2)

IF (FTEX .GT. 0.0) GO TO 514

IF (ABS(R) .LE. 0.0005) GO TO 512

GO TO 516

512 WRITE(6,513) FTEX

513 FORMAT(7,1 FTEX =1,F10.5)

GO TO 2000

514 FBEX=FY**2-3.0*VB**2/(SB**2*H**2)

IF (FBEX .GT. 0.0) GO TO 521

IF (ABS(R) .LE. 0.0005) GO TO 519

516 IF (IND .EQ. 1) GO TO 517

IND=1

VVNCR=VINCR/2.0

GO TO 518

517 VVNCR=VVNCR/2.0

518 V=V+VVNCR

VI=VV1

GO TO 510

519 WRITE(6,520) FBEX

520 FORMAT(7,1 FBEX =1,F10.5)

GO TO 2000

521 FT=SORT(FTEX)

FB=SORT(FBEX)

IF (FT .LT. 0.1) GO TO 1992

IF (FB .LT. 0.1) GO TO 1992

PARA2=U*(SB*FB-ST*FT)

PARA3=U*(C-H)*FY

PARA4=ST*U*FT+ST*FY*(C-H)

ARW=A*FY*ST/ PARA4+A*FY/(U*FB)+2.0*FT

BRW=-2.0*(D-2.0*H)+2.0*PARA3*ST/ PARA4+PARA2/(W*FB)-2.0*ARW*FY/(W*FB)
1+T*PARA2/(A*FY)

CRW=2.0*W*A/(A*FY)-(C-H)*(U*2-2.0*0.01-U*0.02)/A*F+PARA3*2*ST/(A*FY)
1*PARA4)+PARA2*2/(4.0*A*FY*FB)+ARW*2*FY/(A*W*FB)-W*PARA2/(A*

$2 * W * F B) - P A R A 2 * (S B + T) / (A F * F Y) + T * P A R A 2 * * 2 / (4 . 0 * A F * * 2 * F Y * * 2)$
 $D 4 = B R W * * 2 - 4 . 0 * A R W * C R W$
 IF (D4 .GT. 0.0) GO TO 524
 522 WRITE(6,523) D4
 523 FORMAT(5H D4 =F15.5)
 GO TO 2000
 524 R2T1=(-BRW+SORT(D4))/(2.0*ARW)
 R2T2=(-BRW-SORT(D4))/(2.0*ARW)
 IF (R2T1 .LT. 0.0) GO TO 530
 IF (R2T1 .LE. 1.0) GO TO 550
 530 IF (R2T2 .LT. 0.0) GO TO 540
 IF (R2T2 .LE. 1.0) GO TO 551
 540 WRITE(6,541) R2T1,R2T2
 541 FORMAT(2F10.5)
 GO TO 2000
 550 R2T=R2T1
 K=0
 GO TO 555
 551 R2T=R2T2
 K=1
 555 R2B=PARA2/(2.0*AF*FY)+R2T
 $R1T=(A F * F Y * R 2 T + P A R A 3) / P A R A 4$
 $R1B=(A F * F Y * R 2 B - A R * F Y) / (S B * W * F B)$
 $Q1T=A F * F Y + S T * W * F T * (1 . 0 - 2 . 0 * R 1 T) + (C - W) * (2 . 0 * U + 0 - 2 . 0 * R 1 T * S T) * F Y$
 $Q1B=A F * F Y + S B * W * F B * (1 . 0 - 2 . 0 * R 1 B) - A R * F Y$
 $Q2T=A F * F Y * (1 . 0 - 2 . 0 * R 2 T) + S T * W * F T + A R * F Y$
 $Q2B=A F * F Y * (1 . 0 - 2 . 0 * R 2 B) + S B * W * F B + A R * F Y$
 $Y1T=(A F * F Y * (S T + 0 . 5 * T) + 0 . 5 * S T * * 2 * W * F T * (1 . 0 - 2 . 0 * R 1 T * * 2) + (C - W) * (U * * 2 -$
 $1 U * 0 + 0 * * 2 / 2 . 0 - (R 1 T * S T) * * 2) * F Y) / Q1T$
 $Y1B=(A F * F Y * (S B + 0 . 5 * T) + 0 . 5 * S B * * 2 * W * F B * (1 . 0 - 2 . 0 * R 1 B * * 2) - A R * F Y * (U + 0 /$
 $1 . 0)) / Q1B$
 $Y2T=(A F * F Y * ((S T + 0 . 5 * T) - 2 . 0 * R 2 T * (S T + T) + T * R 2 T * * 2) + 0 . 5 * S T * * 2 * W * F T + A R *$
 $1 F Y * (U + 0 / 2 . 0)) / Q2T$
 $Y2B=(A F * F Y * ((S B + 0 . 5 * T) - 2 . 0 * R 2 B * (S B + T) + T * R 2 B * * 2) + 0 . 5 * S B * * 2 * W * F B + A R *$
 $1 F Y * (U + 0 / 2 . 0)) / Q2B$
 $V2=(Y1T-Y2T)/(Y1B-Y2B)$
 IF (V2 .LT. 0.0) GO TO 579
 IF (V2 .GT. 1.0) GO TO 579
 R=V2-V1
 IF (IND .EQ. 1) GO TO 560
 IF (ABS(R) .LE. 0.001) GO TO 561
 V1=(V1+V2)/2.0
 GO TO 510

C

THE TOLERANCE FOR THE FOLLOWING STATEMENT MUST BE CHOSEN VERY CAREFULLY WHEN IT APPROACHES VMAX IN THIS CASE.
 C

560 IF (ABS(R) .LE. 0.015) GO TO 561
 $V1=(V1+V2)/2.0$
 GO TO 510
 561 IF (R1T .LT. ROK1T) GO TO 580
 IF (R1T .GT. HIK1T) GO TO 582
 IF (R1B .LT. ROK1B) GO TO 584
 IF (R1B .GT. HIK1B) GO TO 586
 $Z=Q1T*(Y1T+Y1B+2.0*H)-V*A$
 $VVP=V/VP$
 $PMM=Z/PM$
 IF (PMM .GT. 0.0) GO TO 575
 WRITE(6,570) PMM
 570 FORMAT(7,1 PMM =E10.5)

```
      GO TO 2000
575 WRITE(6,576) V,VT,VB,V1,V2,R1T,R1B,R2T,R2B,VVP,PMM
576 FORMAT(11F10.5)
      VV=V
      VV1=V1
      V=V+VINCR
      IND=0
      IF (V .GT. VMAX) GO TO 1990
      GO TO 510
579 IF (K .EQ. 0) GO TO 530
      GO TO 2000
580 IF (K .EQ. 0) GO TO 530
      WRITE(6,581)
581 FORMAT(//,' TO NEXT CASE SWI')
      GO TO 2000
582 IF (K .EQ. 0) GO TO 530
      WRITE(6,583)
583 FORMAT(//,' TO NEXT CASE HWI')
      GO TO 2000
584 IF (K .EQ. 0) GO TO 530
      WRITE(6,585)
585 FORMAT(//,' TO NEXT CASE RR')
      GO TO 2000
586 IF (K .EQ. 0) GO TO 530
      WRITE(6,587)
587 FORMAT(//,' TO NEXT CASE RF')
      GO TO 2000
```

```

C
C
C
C ****
C CASE : WW ( THAT MEANS BOTH K1T AND K1B ARE LOCATED IN THE CLEAR
C WEBS. )
C ****
C
C ROK1T=(U+0)/ST
C HIK1T=1.0
C ROK1B=(U+0)/SB
C HIK1B=1.0
C WRITE(6,602) ROK1T,HIK1T,ROK1B,HIK1B
C 602 FORMAT(/,!, LOK1T HIK1T LOK1B HIK1B FOR THE FOLLOWING CASE WW!,4F10.5)
C WRITE(6,603)
C 603 FORMAT(//,! V VT VB VI V2
C 1K1T K1B K2T K2B V/VP M/MP !//)
C
C THIS SPACE IS RESERVED FOR ARBITRARY VALUE OF V AND VI .
C
C VINCR=1.0
C IND=0
C 610 VB=V/(1.0+VI)
C VT=V-VB
C FTEX=FY**2-3.0*VT**2/(ST**2*W**2)
C IF (FTEX .GT. 0.0) GO TO 614
C IF (ABS(R) .LE. 0.0005) GO TO 612
C GO TO 616
C 612 WRITE(6,613) FTEX
C 613 FORMAT(/,! FTEX =!,F10.5)
C GO TO 2000
C 614 FBEX=FY**2-3.0*VB**2/(SB**2*W**2)
C IF (FBEX .GT. 0.0) GO TO 621
C IF (ABS(R) .LE. 0.0005) GO TO 619
C 616 IF (IND .EQ. 1) GO TO 617
C IND=1
C VVNCR=VINCR/2.0
C GO TO 618
C 617 VVNCR=VVNCR/2.0
C 618 V=VV+VVNCR
C VI=VV1
C GO TO 610
C 619 WRITE(6,620) FBEX
C 620 FORMAT(/,! FBEX =!,F10.5)
C GO TO 2000
C 621 FT=SORT(FTEX)
C FB=SORT(FBEX)
C IF (FT .LT. 0.1) GO TO 1992
C IF (FB .LT. 0.1) GO TO 1992
C PARA2=H*(SB*FB-ST*FT)
C AHW=AF*FY*(1.0/FT+1.0/FB)/U+2.0*T
C BHW=-2.0*(D-2.0*H)+T*PARA2/(AF*FY)+PARA2/(W*FB)-2.0*AR*FY*(1.0/FT)
C CHW=2.0*V*A/(AF*FY)+PARA2**2*(1.0/FT+W/(B*FY))/(4.0*H*AF*FY)-PARA2
C 1*(SB+T)/(AF*FY)+AR**2*FY*(1.0/FT+1.0/FB)/(W*AF)-AR*PARA2/(AF*FY)
C +2.0*AR*(2.0*U+1)/AF
C D5=(H*U**2-4.0*AH*U+C1H

```

```

      IF (D5 .GT. 0.0) GO TO 624
      WRITE(6,623) D5
  623 FORMAT(5H D5 =F15.5)
      GO TO 2000
  624 R2T1=(-BWW-SORT(D5))/(2.0*AWW)
      R2T2=(-BWW+SORT(D5))/(2.0*AWW)
      IF (R2T1 .LT. 0.0) GO TO 630
      IF (R2T1 .LE. 1.0) GO TO 650
  630 IF (R2T2 .LT. 0.0) GO TO 640
      IF (R2T2 .LE. 1.0) GO TO 651
  640 WRITE(6,641) R2T1,R2T2
  641 FORMAT(2F10.5)
      GO TO 2000
  650 R2T=R2T1
      K=0
      GO TO 655
  651 R2T=R2T2
      K=1
  655 R2B=PARA2/(2.0*AF*FY)+R2T
      R1T=(AF*FY*R2T-AR*FY)/(ST*W*FT)
      R1B=(AF*FY*R2B-AR*FY)/(SB*W*FB)
      O1T=AF*FY+ST*W*FT*(1.0-2.0*R1T)-AR*FY
      O1B=AF*FY+SB*W*FB*(1.0-2.0*R1B)-AR*FY
      O2T=AF*FY*(1.0-2.0*R2T)+ST*W*FT+AR*FY
      O2B=AF*FY*(1.0-2.0*R2B)+SB*W*FB+AR*FY
      Y1T=(AF*FY*(ST+0.5*T)+0.5*ST**2*W*FT*(1.0-2.0*R1T**2)-AR*FY*(U+0/
      1.0))/O1T
      Y1B=(AF*FY*(SB+0.5*T)+0.5*SB**2*W*FB*(1.0-2.0*R1B**2)-AR*FY*(U+0/
      1.0))/O1B
      Y2T=(AF*FY*((ST+0.5*T)-2.0*R2T*(ST+T)+T*R2T**2)+0.5*ST**2*W*FT+AR*
      1FY*(U+0/2.0))/O2T
      Y2B=(AF*FY*((SB+0.5*T)-2.0*R2B*(SB+T)+T*R2B**2)+0.5*SB**2*W*FB+AR*
      1FY*(U+0/2.0))/O2B
      V2=(Y1T-Y2T)/(Y1B-Y2B)
      IF (V2 .LT. 0.0) GO TO 679
      IF (V2 .GT. 1.0) GO TO 679
      R=V2-V1
      IF (IND.EQ. 1) GO TO 660
      IF (ABS(R) .LE. 0.001) GO TO 661
      V1=(V1+V2)/2.0
      GO TO 610

```

C
C THE TOLERANCE FOR THE FOLLOWING STATEMENT MUST BE CHOSEN VERY CAREFULLY WHEN IT APPROACHES VMAX IN THIS CASE.
C

```

  660 IF (ABS(R) .LE. 0.025) GO TO 661
      V1=(V1+V2)/2.0
      GO TO 610
  661 IF (R1T .LT. ROK1T) GO TO 680
      IF (R1T .GT. HIK1T) GO TO 682
      IF (R1B .LT. ROK1B) GO TO 684
      IF (R1B .GT. HIK1B) GO TO 686
      Z=O1T*(Y1T+Y1B+2.0*H)-V*A
      VVP=V/VP
      PMM=Z/PM
      IF (PMM .GT. 0.0) GO TO 675
      WRITE(6,670),PMM
  670 FORMAT(1,14H P = F10.5)
      GO TO 2000
  675 WRITE(6,676) V,VT,VH,V1,V2,R1T,R1B,R2T,R2B,VVP,PMM

```

```
676 FORMAT(11F10.5)
    VV=V
    VV1=V1
    V=V+V1NCR
    IND=0
    IF (V .GT. VMAX) GO TO 1990
    GO TO 610
679 IF (K .EQ. 0) GO TO 630
    GO TO 2000
680 IF (K .EQ. 0) GO TO 630
    WRITE(6,681)
681 FORMAT(//,' TO NEXT CASE RW')
    GO TO 2000
682 IF (K .EQ. 0) GO TO 630
    WRITE(6,683)
683 FORMAT(//,' TO NEXT CASE FW')
    GO TO 2000
684 IF (K .EQ. 0) GO TO 630
    WRITE(6,685)
685 FORMAT(//,' TO NEXT CASE WR')
    GO TO 2000
686 IF (K .EQ. 0) GO TO 630
    WRITE(6,687)
687 FORMAT(//,' TO NEXT CASE RF')
    GO TO 2000
```

APPENDIX C

SAMPLE COMPUTER PRINTOUT

STRENGTH OF BEAMS WITH
ECCENTRIC, REINFORCED, RECTANGULAR
WEB OPENINGS

by

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AN ABSTRACT OF A MASTER'S THESIS

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ABSTRACT

An analytical method of determining the moment carrying capacity of steel W shape beams with eccentric, reinforced rectangular web openings is developed. Using this method, the effects of varying the opening eccentricities and lengths and the reinforcing areas were investigated. From this analysis, the following conclusions are drawn :

- a. Eccentricity does not affect the maximum opening length and the minimum reinforcing area (see Eqs. 36, 37 and 38).
- b. With small eccentricity (say, $e \leq u$), the problem could be treated as a concentric opening, without any significant loss of accuracy.
- c. As the eccentricity increases, the moment carrying capacity of the beam decreases for low shear forces and increases for high shear forces.
- d. The moment carrying capacity is almost linearly proportional to the reinforcing area when the shear force is low, but this relationship becomes non-linear when the shear force is larger.
- e. As opening length increases, the moment carrying capacity decreases while shear force increases.