A STUDY OF THE PHYSIOLOGICAL COSTS OF SMMETRICAL AND SIMULTANEOUS MOTIONS

## by

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## INTRODUCTION

Motion study had its beginning in the early 1900's when Frank B. Qulbreth (1911) observed the methods by which work was performed in a given task situation. These Pirst observations gradually developed into a set of "rules for motion econory and efficiency." These rules relating to motion study were used throughout industry until R. M. Barnes (1940) reviewed these rules and others that were being used at that time and formulated what is known as the "Principles of Motion Economy." Since that time, these rules have been the basis for evaluation and improvement of given work sttuations.

The evaluation of these principles of motion economy has been done largely with the criterion of time. The set of motions required to perform a given task situation that results in the least amount of time required to accomplish the task is defined as "best." It has been the opinion of some persons that least time may or may not be the best eriterion from the standpoint of physiological cost to the worker.

If the shortest time doesn't necessarily determine the optimum set of motions, what eriterion does? Several investigations have been made along this line using some physiological properties related to time as the criteria. Examples of these are: Oxygen consumption per unit of time, pulse rate and the increase in body teraperature.

The investigations have been successful in demonstrating that to a certain degree, i.e. under strained work conditions, that physiological variations do arise as a result of task variation. Recently, a now moasuring device of the physiological cost to the worker has come from the work begun by Lueien Lauru (1957). Lauru developed a force platform to
be used as a moans of recording physical effort resulting from the performance of light tasks. Greeno (1957) ingroved and aallbratod the platform. The data obtained from the instrument correlates significantly with the physical definition of work, 1.e. foree acting through a distance.

It is therefore, the purpose of this paper to investigate the prine ciple of notion oconony establiahed by Barnes that states, "motions of the arms should be perforwed symenotrically and simultaneously." Physiological cost as measured by a force platform will be the oriterion.

## LITERATURE REVI®N

Symotrical and Simultaneous Motions.
Frank B. Gilbreth (1911) revolutionized the fleld of scientific management by presenting his ideas on motion economy. His now famous bricklayer illustration was the basis of his studies. Mr. Gilbreth stated that When work is done with both hands simultaneously, it can be done quickest and with least mental effort if the work is done by both hands in a similar manner; that is to say, when one hand makes the same motions to the right as the other does to the left." This was the beginning of organized thought on the subject of related am motions. Mr. Gilbreth, however, did not specifically demonstrate this to be true in the bricklaying illustration. Mr. Gilbreth's laws of motion economy were not imediately accepted. It took some time before they were understood and put to use.

Later, Hartson (1932) spoke of putting special emphasis on the idea that "elements of movements occur simultaneousiy." It wasn't until 1937 that Bernes reviewed the original laws of motion economy by Gilbreth and developed what is known and used today as the "Principles of Motion Beonomy." As one of his principles, Barnes (1940) states "Motions of the arms should be made in opposite and symotrical directions and should be made simultaneously." He further says, "There is apparently less body strain when the hands move symmetrically than when they make non-symmetrical motions, because of this matter of balance." This statement was illustrated by the use of a bolt and washer assembly task. The old method of performance was improved by 538 using time as the eriterion. Barnes and Mundel (1939) made an investigation of the effect of
the angle in the horizontal frontal plane upon the efficiency with which the subject moved his hands in a simultaneous, symmetrical fashion. The results of the study showed that when visual direction of the hands was required to perform the task, the $90^{\circ}$ position was best for both hands. The "three o'clock" position was defined as zero. For the task where visual direction was not required, the $60^{\circ}$ and $120^{\circ}$ angle was best for the right and left hands respectively. These angles were also measured from the three o'clock position. Time was used as the eriterion.

Briggs (1955) also investigated the effect of angle in the design of work areas. He had ten right handed male students from the psychology classes of Purdue Oniversity perform a simple motor task of moving a stylus from one position to another with their right hand. The angles investigated were $0^{\circ}, 30^{\circ}, 60^{\circ}, 90^{\circ}$ and $120^{\circ}$ with varying distances. All angles were measured at the three o'clock position. The effect of angles was significant. The criterion used was the number of correct hits on a target per 20 seconds. From the results, Briggs plotted a curve of score versus angle as shown in Fig. 1. The plot shows that the score is marimum when the angle is $57.2^{\circ}$ and that the maximum average response score is between angles of $62.8^{\circ}$ and $52.7^{\circ}$.

It may be noted from Fig. I that a higher score was obtained per 20 seconds for outward motions than for inward motions. Wu (1965) investigated the effect of angle and work table height for ten right-handed subjects. He found that the amount of work exerted was dependent on angle. It can also be shown from Wu's data that there is a difference in the amount of work required of invard and outward motions of the arms. This can be explained from Flg. 2 which was reproduced from an investigation by Dudek and Petruno (1965). The mechanical advantage of the arm is best when the
arm is contracted as at the beginning of an outward motion. The mechanical advantage changes to a "least" value when the am is extended as at the beginning of an inward movement. This causes differences in the am mount of energy the subject must expend to move his arm in to and out from his body. From this it may be concluded that when the amp is considered to be a lever, it will requirs more onergy expenditure to move the arm in toward the body than to move it away from the body.

From this discussion, the question arises; Does the shortest time represent the smallest amount of work done by the operator? H. L. Gantt in Gilbreth (1911) related the story of the time that Mr. Gilbreth applied his laws of motion economy to a task that was already being performed with exceptional speed. At the time, it was considered that the task was at a point of maximus production, beyond which it was almost impossible for anyone to achieve. Although this was the general opinion, Mr. Gilbreth improved the job by analyzing its component notions. The results were a easier method by which the task could be performed and increased output. From this story, the question of the shortest time representing the smallest amount of work done by the operator may be answered by concluding that the shorter time does not necessamily represent least work. This was demonstrated by the elimination of the extra motions of the task in the story to obtain a task that could be performed easier and faster.

There have been a few atterapts to evaluate Barnes' principles; however, they have used time as the criterion. The problem of finding the best eriterion on which to base decisions about physical work has plagued scientists. Schmidtke and Stier (1961) investigated the possibility of a physiologically optimum motion time. The experiment required
the subject to nove her hands between fixed points to the beat of a metronome. In order to avoid static muscular work, her aras were sus. pended by two flexible loops. A gas meter measured the expired air and analyzed its content of $\mathrm{O}_{2}$ and $\mathrm{CO}_{2}$. The energy expended in the task performance was calculated from the $\mathrm{CO}_{2}$ value. The results of the experiment showed the optimum time values to be dependent on distance traveled, motion pattern and weight transported. The conclusions were good only for continuousiy swinging motions. Oreene, Morris and Wiebers (1959) mentioned three methods of determining energy expenditure. The first two methods dealt with moasurement of caloric consumption as the eriteria. These methods are difficult to perform; consequently, they are not used except under laboratory conditions. The third is based on the oxygen consumed during the performance of the task. This method is used because of its portability for use in the shop as well as the laboratory situation. One problew is the time lag before the body actually begins to absorb $\mathrm{O}_{2}$ and expell the $\mathrm{CO}_{2}$. The $\mathrm{O}_{2}$ is used in a "burning" process of the stored carbohydrates in the body. Therefore, the results of this method do not give a precise account of the work being done by the operator in perforring the task.

A fow months later, Nichols and Arrine (1959) inveatigated simultaneous and symetrical use of the hands using as their criterion, ninimum increase in heart rate. Aecording to their results, simultaneous and symutrical motions, in addition to accomplishing twice as much work, are physiologically better than non-simultaneous and non-symmetrical motions. The criterion used, however, must be questioned. Michols and Amrine do not state for what length of time the operators performed
the task. Fahnostock, Doys, Sergent, Springer and Siler (1963) performed an coxperiment involving an operator pedaling a bicyele. Mgure 3 (reproduced from their regort) indleates that for the ilrst thirty minutes of physical aotivity, the hoart rato incroased. After that the body adjustod to the conditions it was being subjected to and the heart rate maintained a constant level. Any conclusions based on less than thirty minutes continuous work are $11 k \operatorname{ly}$ to be orronoous if heart rate is used as a eriterion. The study done by NEAols and Amerine assumes that the increase in hosrt rate as a result of worlc is a stratight 14 ne relation ship. It doesn't take into account the ability of the body to investigate tho constraints it is operating under and adjust its physiologieal functions accordingly. Therefore, it still rarains to ilnd an appropriate eriterion to evaluate bodily motions.

The writer of the paper was unable to find any other publishod papers that evaluated the principles ostablished by Giloreth and Barnos. The next section will review the Literature obtained on the force plate forma.

Foree Platform. The force platfor, was built by Iauru (Greens, 1957) as a moans of obtaining a record of an oporator's motion pattern. The best method to perform the task was detemuined by the "smoothest" foree trace. Lauru intorpeted "smoothest" as msaning that the suallest force-time trace obtained frov taak porfomance (elimination of poaks from the trace) was a representation of least physical work.

Later Greme, Morris and Wlebers (1359) developed a new platforv design. It was constructed in the shape of a triangle resting on a frame with the frane supported by ball bearings resting on oantilever beams. Merian (1961) tells ns that the dorlection of a cantilever bema
is proportional to the applied force. Beceuse of this relationship, the beam deilection may be used to measure the applied force. Greene's (1757) platform used three linear variable differential transformers (IVDT) to detect the bodily forces in three directions. Hill (1961) axplains that the LVIF consists of three coils surrounding a moveable iron core. With the core centered in the coil, the alternating current In the primary winding induces equal voltages in the two secondaries. These produce soro output when the colls are connected in phase opposition as shown in Mg. 4. However, wion the core is moved either to the left or the right, the systern is thrown out of balance and an output voltage occurs. The linearity of the response indicates that the instrunent is useable for measuring large displacements, i.e. the increasing voltage being proportional to the distance moved.

The platfora uses three of these IVDT's to obtain output voltages In the three co-ordinate planes. The output voltages of the LJDI's may be resopded on a atrip chart recorder. This results in a reoord of the bodily forces exerted in performing a task. The recording may be made for the three force planes. Greene points out that the foree-time trace shouldn't be confused with Arginse which is a force-time value. Even though the platform measures force on a time axis, it does not represent iapluse. Impluse is a measure of only dynamic forces whereas the force-time value obtained from the platform included static forces $2 s$ well as dynanic forces for a measure of the total forces exerted in performing a task. Greane demonstrated that the data obtained from the platform can indicate differences in arsount of work due to the high correlation with the physical concept of work, i.e. force moved through a distance.

Barany and Whetsel (1962) developed another platform with a National Science Foundation grant. The new platform, Pig. S. a redesigned version of Greene's platform, utilized the same geometrical properties of its predecessor and the bature of the LVDT's but it was also portable and less expensive. It is this design that was used in this experiment.

In summary, the prinoiples of motion economy as established by Barnes have been investigated using the criteria of time and heart rate. Physiological cost has also been investigated from the standpoint of oxygen consumption. The question arises, however, from the evidence presented: Are these valid critoria? It is the purpose of this paper, therefore, to investigate the symmetrical and simultaneous motions versus non-symetrical and non-simultaneous motions on the basis of a fourth criteria, foree exerted. For the purpose of this investigation, physiological cost will be defined as the amount of force exerted for a given period of time in units of pound-seconds.

## Hypothesis:

1. Motions of the amms which are made symmetrically and simultaneously will result in a significantly smaller amount of physiological cost to the worker than non-symetrical but simultaneous motions.
2. Notions which are made symmetrically and simultaneously will result in a significantly smaller amount of physiological cost to the worker than those made symetrically and non-simultaneously.
3. Ama motions made toward the body will result in significantly larger amounts of physiological cost to the worker than motions made away fron the body.

Experimental Task. The experimental task was designed so that the subjects moved a two pound weight in each hand botween two specified points. Two basic moverent pattern designs were used for this research. See Flg. 6. In condition $A$, the subject's hands moved simultaneously from points $A$ eind $B$ to points $C$ and $D$. The motions were made symmetrically in that the path of the hands was made at an angle of $53^{\circ}$ and $127^{\circ}$ (zero is three o'elock). Fifty-throe degrees was determined to be the angle that required the smallest amount of physiological cost to the worker in the study done by Wu (1965). Condition B required the hands to move along paths simultaneously but not symmetrically to perform the task. In condition $B$, the left hand was rotated counter-clockwise to a new angle of 1430. Condition $C$ was the same as condition $A$ with the exception that the hands did not move simultaneously. In all three conditions, the distance moved was oighteen inches.

Bach subject performed each condition fifteen times. The experimental cycle began with the subject's hands at the starting point (positions A and B) and ended after the hands had traveled to points $C$ and D (E for condition B) and returned to the starting position, i.e, each cycle consisted of one "out" and one "in" motion of each arm. Each subject performed a condition five times in succession. Readings were taken of the forces exerted in each of the three planes. A reading was taken each time the subject "touched down" on each black circle. Each subject performed each set of five trials three times for a total of fifteen sample readings per subject per condition. The experimental tasks were ordered according to the arrangement of Fig. 7 in an offort to counter-
balance any fatigue or learning. In order to eliminate time as a variable, the subjects were paced by a metronome at a rate of 66 clicks per minute. The metronome periditted the subject to use either the visual or auditory stimuli for pacing or both.

The experimental task was performed in the Industrial Engineering Department's hwan engineering laboratory at Kansas State University. Bquiprent. The experimental equipment utilized a table that could be adjusted to different heights. The subjects were seated on a non-padded stool. There was no back on the stool as it was believed that this would interfere with the free motion of the body. The stool was placed on the force platform.

The primary windings of the LVDT's in the platform were provided with a 2000 cps current from the oscillator stages of three Sanborn recording amplifiers. The LVDT outputs were fed to the two Heathicit Model EC-1 analog coadputers shown in $\mathrm{PM}_{\mathrm{g}}$. 8. Using the ability of the computer to integrate the area under a curve when wired according to the schematic diagram of Fig. 9. a numerical value of the force-time trace for a particular set of motions was obtained. The inverter show in Fig. 9 was used so that work in one direction was not subtracted from work in the other direction. Fig. 10 was recorded by a Texas Instruments Oscilloriter recorder. This gave the experimenter a permanent paper record of the integration from which the experimental data was taken. The readings were obtained simultaneously for the three recording channels. Previous work had utilized the planimeter as a method of obtaining a numerical value of the area under the force trace. The orror in the reading obtained from a planimeter is on the order of $12 \%$. The error of the
cormuter is of the order of $5 \%$. The computer also reduced the amount of time required of the experinenter to obtain numerical values of the forcetime relationship. Thus the experimenter was able to take more readings with a smaller amount of error in the readings.

Calibration of the equipment was performed by applying a two pound force along each orthogonal axis for five seconds. The force-time integration performed by the computer was noted by pen deflection on the Texas Instruments recorders in volts. The following calibration values were obtained for each axls: $X=.33$ volts/ X .-sec. $\mathrm{I}=.19$ volts/ lb.-sec., $Z=.39$ volts/lb.-500. All calculations of experimental data were done in volts except total force values. These tol forces were the sum of the $x, y$ and $z$ forces after these forces had been adjusted.

With the subject seated on the stool which was on the platform, the necessary corrections were made on the recording equipment to readjust the equipment to an initial zero point, i.e. to balance out the effect of the subject's waight on the platform. The gain settings on the recorders wore increasod until large deflections on the three recording channels were obtained. Large deflections were obtained to reduce the percentage of error that would be obtained since the same absolute asount of error would be divided by a larger base. When these conditions had been obtained, the positions of the calibration leval on the Toxas Instruments reeorders were noted on the subject's data sheet. This adjustment provided the experimenter with very reliable integration recordings. After the data was taken, each reading was nultiplied by its appropriate callbration level to determane the energy exerted. The computer output in volts for each of the three force planes represented the total force
exerted by the motion of the body in each of the three planes. To determine the total voltage or total amount of work for the task, the values obtained in each of the planes were arithmetically swmed to find the "total" cost for the task (1.e. "total" is not a vector). Subjects. The eighteen fomsle subjects were members of the freshman women's dormitories, the home oconomics home management houses and patronizers of Kansas State University's student union. They ranged in height from $5^{\prime \prime} 2^{\prime \prime}$ to $5^{\prime 8} 8^{\prime \prime}$ and in weight from 107 pounds to 160 pounds. The age range was from 18 yrs . to 28 yrs . Each subject was paid at the rate of $\$ 1.00$ per hr . for participating in the experiment. The Experimental Procedure. Upon entering the experimental room, the data of name, age, height, weight and length of the upper arm was collected from each subject. Length was measured from the tip of the elbow to the top of the shoulder. The measurement was obtained by instructing the subject to place her arm so that the upper and lower arm were at right angles with the elbow at the subject's side. A tape measure was then placed between the two measurement points to obtain the length of the upper arm. The subject was then instructed to seat herself on the stool positioned on the force platform. With the subject in position, worktable height was adjusted to a position of two inches above the elbow. This was found to be the best work-table height by Wu.

Next the subject was given the following instructions and allowed to ask questions pertaining to them as they wore explained.

> "You are about to perform a series of simple motor tasks. The purpose of this experiment is to determine the energy you expend in the perforrance of three experimental task conditions. In Condition A, you are to move a two pound weight, held in each hand, simultaneously from the black circles, A and B, in front of you to the circles C and D returning to the starting position. Condition B requires you
to move the same weights simultaneously to circles C and E returning to the starting position. Condition C requires you to move the two pound weight in your right hand from circle B to circle D returning it to the starting position. Then after the right hand is in its original position, you move the weight in your left hand from circle A to circle C and back to circle A. Note that in condition $C$, the hands do not move simultaneously but in sequence.

All three conditions are performed to the rhythm of a metronome. Each time the metronome clicks, your hands should be placing the weight(s) on the appropriate circles for the condition you are performing.

You will be told which of the three conditions to perform and when to begin. Keep repeating the task until told to stop.

You are about to begin the task.
Put your feet on the rung of the stool on which you are sitting. Grasp the weights by placing the second finger of each hand through the ring on top.

The experimenter will say 'Ready' and then 'Start'. At the signal 'Start' begin to perform the task.

Now position yourself as if you are ready to begin."
After answering any questions, the subject was allowed to practice moving the weights between points so that she could learn the rhythm of the metronome. When the experimenter felt the subject could reproduce the rhythm, the subject was instructed to begin a particular condition.

When the subject had completed two cycles, the readings were taken from the next five eycles.

Statistical Model. The analysis of variance of the "physiological cost" is based on Snedecor's (1962) "Model I" design. It is a subject by treatment analysis with a single case for each factor combination. The model being tested in each hypothesis was

$$
\begin{aligned}
& x_{1, j}=u+A_{i}+B_{j}+\epsilon_{i, j} \\
& i=1 \ldots \ldots a_{i} \quad j=1 \ldots \ldots b \\
& \epsilon_{i, j}=N(0, \sigma)
\end{aligned}
$$

Where

$$
\begin{aligned}
& A_{i}=\text { method effects } \\
& B_{j}=\text { subject offects } \\
& \epsilon_{1, j}=\text { random variable of sample variation }
\end{aligned}
$$

For those comparisons where signiflcance was found, the Duncan's Multiple Range test (Hicks, 1964) was used to test for differences between means.

## RESULTS

A Model I analysis of variance was performed on the data of Table I. The first hypothesis tested was the foree requirements for conditions A, B, and C for "out" motions and for "in" motions. Tables 2, 3, and 4 show the analysis of variance for the outward direction by force plane while tables 5, 6, and 7 are for the inward direction. Next the average forces recorded in the $x, y$ and $z$ planes were adjusted by the appropriate calibration factors so they could be added. The planes were then added arithmetically to obtain the "total force" values for each condition. These values are the total amount of force required to perform the task. For both inward and outward motions conditions are shown to be significant in the $x$ and $y$ planes at an alpha risk of .01 but not in the $z$ plane. Table 8 shows that conditions were significant at an alpha risk of . 01.

The results of the Duncan Multiple-Range Test on the means are show in table 9. Conditions A, B and C are significantly different ( $\alpha<.05$ ) from each other in the $x$ plane for both the inward and outward movements. Howover, for the $\bar{y}$ plane, with inward motion, $B$ was significantly $(\alpha<.05)$ less than $C$ but not significantly less than A. A was not significantly lower than C. B was significantly lower than A and C for outward motion but A was not significantly lower than C. Tables 4 and 7 indicated that conditions were not significant for the $z$ plane. $A, B$ and $C$ were significantly different from each other when $x, y$ and $z$ were added.

On the basis of these calculations, hypothesis I was rejected since condition B (simultaneous and non-symmetrical) was significantly smaller than condition A (simultaneous and symmetrical). Hypothesis II was
accopted since condition A (simultaneous and symetrical) was found to be significantly smaller than condition C (non-simultaneous and symetrical).

The third hypothesis was tested by comparisons of the inward and outward data. Table 22 gives the mean values for conditions $A, B$ and $C$ in the $x, y$ and $z$ planes. The value for each subject's in motion was compared versus the value for his out motion for condition A (simultaneous and symmetrical) in Tables 10, 11 and 12, for condition B (simultaneous and non-symetrical) in Tables 13, 14 and 15, and for condition C (non-simultaneous and symetrical) in Tables 16,17 and 18. The offect of in versus out was significant $(\alpha<.01)$ in the $z$ plane for condition $A$, in the $x$ and 2 planes for condition $B$ and the $x, y$ and $z$ planes for condition $C$. It is also shown in Tables $10-18$, that for conditions $A, B$ and $C$, subjects within sequence were consistently significant in the $x, y$ and $z$ planes except for the $x$ and $y$ planes of condition $A$ (Tables 10 and 11) where subjocts within sequence were not significant. The effect of sequence was significant only in the $x$ plane of condition C (Table 11). Tables 19, 20 and 21 show the analysis of variance of total $(x+y+z)$ inward and total outward motions for conditions A, B and C. In was not different from out for condition A or C but was signiflcant for condition B. Subjects were significant for condition $B$ and $C$ but not for A. From the significant values obtained from analysis of the $x, y$ and $z$ planes and the total of these planes for condition $B$, hypothesis III is rejected. Outward motions require more force than inward motions which is the converse of hypothesis III.

An additional analysis was made in Table 23 of the left versus right hand of condition C. It shows that there was a significant difference
$(\alpha<.01)$ in the "physiological cost" required of the right and left hand movenents with the right hand being lower.

The results of the present experiment failed to show that the "physiological cost" is Lower for simultaneous and symmetrical ary motions than for simultaneous and non-symmetrical arn motions. In fact, for the situation studied, Condition B (simultaneous and non-symmetrical) required a significantly smaller amount of force than oondition A (simultaneous and symmetrical).

This result contradicts the "principle of motion econory" established by Barnes. The difference ritght be explained by what Barnes called "this matter of balance." He is not referring to the belance of am movement patterms but to the balance of the body during arm motions. In the performance of the axperimental tasks, the subject's center of gravity is constantly being moved along the frontal plane between two extreme points caused by the extreme points of arm motion. When the ams are extended to the farthest point away from the subject's body, the subject is off balance. In the cese of symmetrical motions, the arms are fully extended causing the body center of gravity to move forward to the farthest extreme point. When one arm, the left in this experiment, is rotated in the horizontal plane; the body's center of gravity is moved closer to the centerline of the body. This helps the subject to regain some of his balance. This greater degree of body balance is one explanation for the small force values of condition B. Another explanation is the effect of the angle at which the movements were performed. It can be thenm from the work done by Wu, that as the right hand moved in the horizontal plane a "physiologieal optimun" angle was reached. It's possible that as the left hand rotated counterelocknise to its new position for
condition $B$, that it moved toward an optimum angle. If this occourred, the forces would have been lower for condition B than A.

The rosults obtained for the $x$ plane of condition $A$ should not be thought of as the total force exerted in that plane. It is actually a measure of the non-simultaneity of the arm movements. The subjects were instructed to move their arms simultaneously, but it is diffloult to perform amm movements that are perfectly simultaneous. If the arms performed in perfect unison, the forces one would expect to be exerted would mulify each other and a zero reading would be obtained for the $x$ plane. If the subject moves one apm before the other, the body will be throw in the opposite direction of the unbalaneed force associated with the motion causing force to be exerted in the lateral plane. The foree in the $x$ plane is then not only an indicator of foree but also an indication of the simultaneity of the motion.

The second hypothesis was accepted on the basis of the data in Table 9 that condition $C$ was significantiy different from $A$ or $B$. This was expected because of the replication of body movement in each individual hand movement. It is interesting that when asked which experimental condition was easiest, sixteen of the eighteen subjects chose condition $C$. In condition $C$, the subject had the reinforcement of auditory pacing with visual direction of each hand. W1th condition $A$ and $B$, the subject's attention was divided between her hands making it more difficult to place the weights directly on the black circles.

Hypothesis III was tested for signiflcance in the inward and outward motions. Wu found that inward motions exerted more force than outward motions for the right hand at angles varying from $0^{\circ}$ to $180^{\circ}$ in the
horizontal plans. It can be shown from Wu's data that the greatest anount of force is in the vertical plane. It is unusual that it is not in the plane of greatest motion, the $y$ plane. The results of this experiment contradict those of Wu's. First, this author found that motions of the arms made away from the body exert more force than those made toward the body, although the differences were not statistically significant. Purther, this author found the plane of greatest movement (y plane) contained the greatest total force exertion. This could be the result of the horizontal movement of the subject's center of gravity along the frontal plane to a greater degree than the vertical plane or the fact that a weight was in each hand while Wu's subjects used the right hand only.

The results obtained showing that the outward motions exerted more force than inward motions may be explained from FIg. 2. When the arm is at the position of best mechanical advantage, the brachialis muscle is in a contracted status and its "ability to develop tension is least" (Fig. 2). This would mean that the muscles' ability to aid in moving the arm forward would be reduced to a minimum. Consequently, for a forward movement of the arm other muscles in the arm will have to respond in order to move the limb along its path. An inward movement of the arm, however, would be initiated with the armextended to a point approaching the point of maxdmum ability of the brachialis muscle to develop tension. The movement may be acoomplished by a single contraction of the brachialis muscle. If the movement of the arm forward and backward requires two different sets of muscles, the set being used is dependent on direction of movement. Unequal amounts of force may be exerted by the in and out arm
motions since it requires only one muscle to contract the amp where it might take several to extend it.

The difference between the right and leitt hand motions was expected since all subjects were right handed. This is because the right arm is more coordinated than the left. Since it is used more frequently than the left arm, the muscular action of the right arm is smoother resulting in a smaller amount of physical effort to use it.

## CONCLJSIONS

Trom the results of this experiment, and the tasks studied, we may conclude (1) It is easior to perform simultaneous and non-symmetrical motions than simultaneous and symetrical motions. (2) Simultaneous motions are easier to perform than non-simultaneous or sequential motions. (3) Outward motions of the amm may be considered to require more force than Inward am motions. (4) When the force platform is used to measure simultaneous and symmetrical hand motions, the x or lateral plane is a measure of the simultaneity of the movement. (5) Minally, for Mighthended women, the left hand exerts more force than the right hand when both hands are working at an "equal" task.

Bxtension of these conclusions to motion patterns not yot studied should be made with caution until additional studies are made.

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Mg. 1. Speed and accuracy of movement related to direction of movement in the investigations done by Briggs.


Mechanical advantage of lever systers is best. wuscle shortened-ability to develop


Mochanical advantage of lever system is least, muscle lengthened-ability to develop tension is best.

Fig. 2. Illustration of lever mechanism at the elbow.


Fig. 3. grfect of time on heart beat rate under constant levels on energy exertion.


Fig. 4. LVDT wiring diagram.


Fig. 5. The force platform.


Ag. 6. The task layout of the three experimental conditions.

Subjects
Set of
$\begin{array}{lllllllllllllllllll}\text { Trials } & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 & 10 & 11 & 12 & 13 & 14 & 15 & 16 & 17 & 18\end{array}$


 $\begin{array}{lllllllllllllllllll}\text { 4th } & C & A & B & B & C & A & C & A & B & B & C & A & C & A & B & B & C & A\end{array}$


 $\begin{array}{lllllllllllllllllll}\text { 8th } & \text { C } & \text { A } & \text { B } & \text { B } & \text { C } & \text { A } & \text { C } & \text { A } & \text { B } & \text { B } & \text { C } & \text { A } & \text { C } & \text { A } & \text { B } & \text { B } & \text { C } & \text { A }\end{array}$ $\begin{array}{lllllllllllllllll}9 \text { th } & \text { A B C A B }\end{array}$


PMg. 8. Model EC-1 analog computers and oscilloriter recorders.
AREA SUMMING COMPUTER



Fig. 10. Computer integrations for Subject No. 14
for the x and $\bar{y}$ planes


Mig. 11. Subject performing experimental task.

Table 1. Sumary sheet of experimental data in volts.

Condition A
Condition B
Subj.

| No | $X_{0}$ | $X_{1}$ | Yo | $Y_{1}$ | 20 | $z_{i}$ | X | $\mathrm{X}_{1}$ | $Y_{0}$ | $\mathrm{r}_{1}$ | 2 。 | $z_{1}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | .26 | . 15 | 1.14 | 1.07 | 1.04 | .79 | .23 | . 11 | . 88 | . 91 | . 81 | . 68 |
| 2 | . 50 | . 26 | 1.55 | 1.54 | 1.44 | 1.26 | . 41 | . 28 | 1.30 | 1.25 | . 84 | . 63 |
| 3 | . 22 | . 14 | 1.15 | 1.28 | 1.42 | 1.10 | . 22 | . 18 | . 96 | 1.26 | 1.47 | 1.18 |
| 4 | . 09 | . 10 | 1.47 | 1.6 | 1.39 | 1.69 | . 10 | . 08 | 1.35 | 1.27 | .76 | . 97 |
| 5 | . 23 | . 11 | 1.97 | 2.06 | 1.26 | .87 | . 24 | . 20 | 1.81 | 1.96 | 1.33 | . 89 |
| 6 | .76 | .76 | . 59 | 1.36 | 1.08 | 2.54 | 2.39 | . 72 | . 58 | . 92 | 2.55 | 2.46 |
| 7 | . 21 | . 14 | .69 | . 63 | . 83 | . 82 | .26 | . 23 | . 41 | . 41 | 1.22 | . 98 |
| 8 | .21 | . 16 | 1.21 | 1.15 | .99 | . 80 | . 27 | . 22 | 1.01 | 1.10 | 1.16 | . 88 |
| 9 | .23 | . 15 | 2.29 | 2.08 | 2.36 | 2.03 | . 27 | . 21 | 2.30 | 2.14 | 2.27 | 1.89 |
| 10 | . 42 | . 25 | 1.81 | 1.81 | 1.70 | 1.93 | . 39 | . 26 | 1.55 | 1.53 | 2.05 | 1.94 |
| 11 | . 18 | . 10 | 1.36 | 1.19 | .40 | . 33 | . 18 | . 13 | .97 | .97 | . 39 | . 29 |
| 12 | . 20 | . 06 | 1.35 | 1.05 | 1.00 | . 77 | . 12 | . 07 | 1.20 | 1.03 | 1.13 | .78 |
| 13 | . 50 | . 43 | 1.17 | 1.45 | 2.07 | 1.81 | .47 | . 42 | .93 | 1.03 | 2.14 | 1.86 |
| 14 | . 44 | . 33 | 1.71 | 1.83 | 1.62 | 1.43 | . 46 | . 30 | 1.55 | 1.64 | 1.73 | 1.58 |
| 15 | .13 | . 05 | 1.94 | 1.91 | .72 | . 69 | . 11 | . 04 | 1.69 | 1.71 | . 71 | . 66 |
| 16 | . 27 | . 21 | 1.23 | 1.29 | 1.46 | 1.21 | . 31 | . 31 | 1.04 | 1.11 | 1.25 | . 78 |
| 17 | . 28 | . 15 | 1.31 | 1.13 | .74 | . 66 | . 28 | . 20 | 1.19 | 1.01 | . 70 | .67 |
| 118 | . 25 | . 13 | 2.18 | 2.01 | 1.46 | 1.33 | . 22 | . 12 | 1.77 | 1.95 | 1.29 | 1.29 |

$\bar{X}_{0}$ is the outward force in the X plane.
$X_{1}$ is the inward force in the $X$ plane.
$Y_{0}$ is the outward force in the $Y$ plane.
$I_{i}$ is the inward force in the I plane.
$Z_{0}$ is the outward force in the $Z$ plane.
$z_{1}$ is the inward force in the $z$ plane.

Table 1 (cont.). Sumary sheet of experimental data in volts. Subj. No. $\begin{array}{llllllllllllll} & X_{o r} & X_{o l} & X_{1 r} & X_{11} & Y_{o r} & Y_{o 1} & I_{i r} & Y_{11} & Z_{\text {or }} & Z_{o 1} & Z_{i r} & Z_{i 1}\end{array}$

| 1 | .09 | .27 | .12 | .17 | .46 | .50 | .55 | .58 | .20 | .38 | .16 | .24 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| 2 | .26 | .32 | .20 | .28 | .81 | .88 | .81 | .62 | .25 | .34 | .18 | .13 |
| 3 | .18 | .14 | .14 | .16 | .53 | .41 | .99 | .70 | .45 | .64 | .61 | .56 |
| 4 | .09 | .07 | .11 | .06 | .70 | .73 | .91 | .85 | .66 | .66 | .62 | .86 |
| 5 | .21 | .24 | .05 | .20 | 1.35 | 1.63 | 1.51 | 1.95 | .69 | .69 | .54 | .65 |
| 6 | .64 | .57 | .57 | .52 | .50 | .42 | .56 | .51 | 1.78 | 1.76 | 1.56 | 1.73 |
| 7 | .08 | .13 | .05 | .17 | .54 | .29 | .41 | .28 | .30 | .41 | .11 | .30 |
| 8 | .18 | .27 | .17 | .24 | .50 | .41 | .49 | .45 | .50 | .58 | .34 | .51 |
| 9 | .16 | .21 | .10 | .32 | 1.16 | 1.19 | 1.40 | 1.41 | 1.91 | 1.05 | .84 | .62 |
| 10 | .30 | .34 | .23 | .31 | .76 | .63 | .88 | .81 | 1.31 | 1.41 | 1.23 | 1.48 |
| 11 | .19 | .22 | .15 | .22 | .79 | .88 | .76 | .90 | .18 | .18 | .12 | .20 |
| 12 | .11 | .08 | .06 | .12 | 1.07 | .31 | .83 | 1.09 | .44 | .45 | .35 | .37 |
| 13 | .35 | .32 | .45 | .39 | .88 | .60 | .80 | .68 | 1.29 | 1.43 | 1.07 | 1.25 |
| 14 | .43 | .35 | .26 | .35 | 1.14 | 1.13 | 1.17 | 1.13 | 1.01 | .92 | .88 | .92 |
| 15 | .12 | .11 | .08 | .13 | 1.02 | 1.36 | 1.01 | 1.34 | .17 | .23 | .17 | .25 |
| 16 | .21 | .51 | .23 | .24 | .66 | .50 | .63 | .50 | .65 | .51 | .56 | .34 |
| 17 | .25 | .24 | .17 | .18 | .80 | .80 | .71 | .79 | .12 | .13 | .18 | .12 |
| 18 | .19 | .24 | .19 | .25 | .99 | 1.11 | 1.01 | 1.27 | .56 | .60 | .41 | .49 |

[^0]$X_{01}^{0 r}$ is outward force in $X$ plane caused by the left hand.
$X_{\text {Ir }}^{01}$ is inward force in $X$ plane caused by the right hand.
$X_{i 1}^{1 r}$ is inward force in $X$ plane caused by the left hand.
The same notation applies to the $Y$ and $Z$ planes for condition $C$.

Table 2. Analysis of variance of outward work in X plane.

| Soures | d.f. | M.S. | F |
| :--- | ---: | ---: | ---: |
| Subjects | 17 |  |  |
| $\quad$Sequence <br> Subject $\times$ Sequence | 12 | .356 | $356.00 * *$ |
| Conditions | 2 | .001 | .02 |
| Residual Error | 34 | .210 | $42.00 * *$ |
| Totsl | 53 | .005 |  |
| ** Signifleant at one percent level |  |  |  |

Table 3. Analysis of varianee of outward work in $Y$ plane.

| Source | d.f. | M.S. | F |
| :--- | ---: | ---: | :---: |
| Subjects | 17 |  |  |
| Sequence <br> Subjoct $x$ Sequence | 12 | .728 | 1.183 |
| Conditions | 2 | .515 | $11.826^{* *}$ |
| Residual Eror | 34 | .535 | $10.29 * *$ |
| Total | 53 | .052 |  |

** Significant at one percent level

Table 4. Analysis of variance of outward work in 2 plane.

| Source | d.f. | M. S. | F |
| :---: | :---: | :---: | :---: |
| Subjocts | 17 |  |  |
| Sequence | 5 | 1.028 | . 683 |
| Subject $x$ Sequence | 12 | 1.505 | 17.705** |
| Conditions | 2 | . 005 | . 058 |
| Residual Error | 34 | . 085 |  |
| Total | 53 |  |  |

Table 5. Analysis of variance of inward work in X plane.

| Source | d.f. | M.S. | F |
| :---: | :---: | :---: | :---: |
| Subjocts | 17 |  |  |
| Sequence | 5 | . 034 | 1.05 |
| Subject $x$ Sequence | 12 | . 030 | 20.00** |
| Conditions | 2 | . 285 | 71.25** |
| Residual Freor | 34 | . 004 |  |
| Total | 53 |  |  |

** Slgnificant at one percent level

Table 6. Analysis of variance of imard work in $Y$ plane.

| Source | d.f. | M.S. | F |
| :---: | :---: | :---: | :---: |
| Subjects | 17 |  |  |
| Sequence | 5 | . 804 | 1.10 |
| Subject x Sequence | 12 | . 730 | 3.90** |
| Conditions | 2 | . 955 | 5.106** |
| Residual Error | 34 | . 187 |  |
| Total | 53 |  |  |

** Significant at one percent level

Table 7. Analysis of variance of inward work in 2 plane.


Table 8. Analysis of veriance of "Total" Porce.

| Source | d.f. | M.S. | F |
| :--- | ---: | ---: | ---: |
| Subjects | 17 |  |  |
| $\quad$Sequence  <br> Subject $x$ Sequence | 12 | 8.51 | .484 |
| Conditions | 2 | 17.57 | $20.430^{* *}$ |
| Residual Error | 34 | 14.91 | $17.337^{\text {** }}$ |
| Total | 53 | .86 |  |
| ** Signifleant at one percent level |  |  |  |


| Plane | Direction | Condition and Mean Force |  |  |
| :---: | :---: | :---: | :---: | :---: |
|  |  | A | B | c |
| X | Inward | . 20 | . 22 | . 42 |
|  |  | B | A | c |
| I | Inward | 2.22 | 2.53 | 3.02 |
|  |  | B | c. | A |
| 2 | Inward | . 955 | . 981 | 1.03 |
|  |  | B | A | c |
| $\chi$ | Outward | . 29 | . 30 | . 48 |
|  |  | B | A | C |
| $Y$ | Outward | 2.19 | 2.58 | 2.77 |
|  |  | c | B | A |
| $z$ | Outward | 1.12 | 1.13 | 1.15 |
|  |  | B | A | c |
| $X+Y+Z$ | $\mathrm{In}+\mathrm{Out}$ | 6.98 | 2.77 | 8.79 |

Table 10. Analysis of variance for condition $A$ in the $X$ plane of the in and out motions.

| Source | d.f. | M.S. | F |
| :--- | ---: | :--- | :--- |
| Subjects | 17 |  |  |
| Sequence  <br> Subject $x$ Sequence | 12 | .033 | .687 |
| Conditions | 1 | .043 | .369 |
| Residual Error | 17 | .097 | $.7^{4} 6$ |
| Total | 35 | .130 |  |
| **Significant at one percent level |  |  |  |

Table 11. Analysis of variance for condition A in the I plane of the in and out motions.

| Source | d. ${ }_{\text {r }}$. | M.S. | $F$ |
| :---: | :---: | :---: | :---: |
| Subjects | 17 |  |  |
| Sequence | 5 | . 360 | 1.100 |
| Subject $x$ Sequence | 12 | . 327 | 1.224 |
| Conditions | 1 | . 013 | . 048 |
| Residual Exror | 17 | . 267 |  |
| Total | 35 |  |  |

** Significant at one percent level

Table 12. Analysis of variance for condition $A$ in the $A$ plane of the in and out motions.


Table 13. Analysis of varianoa for condition 3 in the $X$ plane of the in and out motions.

| Source | d.f. | M. 3. | \% |
| :---: | :---: | :---: | :---: |
| Subjects | 17 |  |  |
|  |  |  | $.416$ |
| Subject $x$ Sequence | 12 | . 048 | $480.000 \text { * }$ |
| Conditions | 1 | . 048 | 430.000** |
| Residual Ereop | 17 | . 0001 |  |
| Total | 35 |  |  |

Table 14. Analysis of variance for condition $B$ in the $Y$ plane of the in and out motions.

| Source | d.f. | M.S. | F |
| :---: | :---: | :---: | :---: |
| Subjecta | 17 |  |  |
| Sequence | 5 | . 514 | 1.472 |
| Subject x Sequence | 12 | .349 | 45.921** |
| Conditions | 1 | . 0016 | . 210 |
| Residual mroor | 17 | . 0076 |  |
| Total | 35 |  |  |

Table 25. Analysis of variance for condition $B$ in the $Z$ plane of the in and out motions.

| Source | d.f. | M.S. | F |
| :--- | :---: | :---: | :---: |
| Subjects | 17 |  |  |
| $\quad$ Sequence | 5 | .552 | .725 |
| $\quad$ Subject $x$ Sequence | 12 | .761 | $63.416^{* *}$ |
| Conditions | 1 | .380 | $31.666 * *$ |
| Residual Brror | 17 |  |  |
| Total | 35 |  |  |
| * Significant at one percent level |  |  |  |

Table 1.6. Analysi.s of variance for condition $C$ in the $X$ plane of the in and out motions.

| Source | d.f. | M.S. | F |
| :---: | :---: | :---: | :---: |
| Subjects | 17 |  |  |
| Sequence <br> Subject x Sequence | 5 12 | $\begin{aligned} & .256 \\ & .060 \end{aligned}$ | $\begin{array}{r} 4.26 * * \\ 12.00^{*} * \end{array}$ |
| Conditions | 1 | . 029 | 5.80** |
| Residual Brer | 17 | . 005 |  |
| Total | 35 |  |  |

Table 17. Analysis of variance for condition $C$ in the $Y$ plane of the in and out motions,

| Source | d.f. | M.S. | F |
| :--- | :---: | :---: | :---: |
| Subjects | 17 |  |  |
| $\quad$ Sequence | 5 | .893 | 1.10 |
| Subjects $x$ Sequence | 12 | .816 | $25.50 * *$ |
| Conditions | 1 | .160 | $5.00 * *$ |
| Residual Error | 17 | .032 |  |
| Total | 35 |  |  |
| ** Significant at one percent level |  |  |  |

Table 13. Analysis of variance for condition $C$ in the $Z$ plane of the in and out motions.

| Souree | d.f. | M.S. | F |
| :---: | :---: | :---: | :---: |
| Subjects | 17 |  |  |
| Sequence | 5 | 1.159 | . 648 |
| Subject $x$ Sequenes | 12 | 1.787 | 111.687** |
| Conditions | 1 | .240 | 15.00** |
| Rostdual Brror | 17 | . 015 |  |
| Total | 35 |  |  |

Table 19. Analysis of variance for total in and out motions of condition A .

| Source | d.f. | M.S. | F |
| :--- | :---: | :---: | :---: |
| Subjects | 17 |  |  |
| $\quad$Sequence <br> Subject $x$ | Sequence | 12 | 1.17 |
| Conditions | 1 | 1.68 | 1.183 |
| Residual Erxor | 17 | .73 | .514 |
| Total | 35 | 1.42 |  |
| ** Significant at one percent level |  |  |  |

Table 20. Analysis of variance for totnl in and out motions of conclition 3.

| Souroe | d.f. | M.s. | $F$ |
| :--- | :---: | :---: | :---: |
| Subjeots | 17 |  |  |
| $\quad$ Sequence | 5 | 1.05 | .600 |
| Subject $x$ Sequance | 12 | 1.75 | $145.830 * *$ |
| Conditions | 1 | .63 | $53.500 * 0$ |
| Residual Jrror | 17 | .012 |  |

Total 35
** Stgnificant at one porcont lovel.

Table 21. Analysis of variance for total in and out motions of condition C .

| Source | d.f. | M.S. | F |
| :---: | :---: | :---: | :---: |
| Subjects | 17 |  |  |
| Sequence | 5 | 1.02 | $.262$ |
| Subjoct $x$ Sequence | 12 | $3.89$ | $77.600$ |
| Conditions | 1 | . 07 | 1.400 |
| Restdual limror | 17 | . 05 |  |
| Total | 35 |  |  |

Table 22. Summary of mean values for in and out motions in the $x, y$ and $z$ planes.

| Plane | Direction of Movernent |  |
| :---: | :---: | :---: |
|  | Condition A |  |
|  | In | Out |
| X | . 20 | .30 |
| I | 2.53 | 2.58 |
| 2 | 1.03 | 1.15 |
| Total | 3.76 | 4.03 |
|  | Condition B |  |
| X | . 22 | . 29 |
| 1 | 2.22 | 3.92 |
| 2 | 1.80 | 1.13 |
| Total | 4.24 | 5.34 |
|  | Condition C |  |
| X | . 42 | .48 |
| $Y$ | 3.02 | 2.79 |
| 2 | . 98 | 1.12 |
| Total | 4.42 | 4.39 |

Table 23. Anslysis of variance for right and left hand movements.

EXPERIMENTAL DATA SHEET

EXPERIMENTAL DATA SHEET


> Reading No.


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EXPERIMENTAL DATA SHEET

| Table Height $41 \frac{1}{2}$ | in. |
| :--- | :--- |
| Upper Arm Length |  |
| Dist. from Table | $\frac{12}{2} \frac{1}{2}$ |
| in. |  |
| in. |  |



Reading No.


$\qquad$

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| 13 | 14 | 15 |
| :---: | :---: | :---: |
| .30 | .40 | .24 |
| .12 | .19 | .19 |
| 2.38 | 1.86 | 2.45 |
| 2.09 | 2.18 | 1.85 |
| 2.10 | 2.25 | 2.35 |
| 1.85 | 2.15 | 1.86 |


 वूलूजन


| 0 | 11 | 12 |
| :---: | :---: | :---: |
| 28 | .50 | .40 |
| 08 | .21 | .10 |
| 88 | 2.50 | 2.30 |
| 85 | 2.42 | 2.15 |
| 30 | 2.38 | 2.30 |
| 99 | 2.28 | 2.10 |


| Honm |
| :---: |
|  |  |





$$
\begin{aligned}
& \text { Date November 23, } 1965 \\
& \text { Subject No. } \quad 9 \\
& \text { Weight } 135 \quad 1 \text { ibs. }
\end{aligned}
$$

| Table Height $40 \frac{1}{2}$ |
| :--- |
| Upper Arm Length |
| in |
| Dist. from Table $6 \frac{1}{2}$ |
| $\frac{1}{4}$ |
| ine |
| ine |

EXPERIMENTAL DATA SHEET

| Table | Height | In. |
| :---: | :---: | :---: |
| Upper | Arm Length | in. |
| Dist. | from Table | 1n. |



## 1 volts/cm



จ иотътpuos
EXPERIMENTAL DATA SHEET


## Calibration: X__ volts/cm

$$
\mathrm{z} 1 \mathrm{volts} / \mathrm{cm}
$$

Reading No.



EXPERIMENTAL DATA SHEET

| Janet Suboter |  |  | Date | November | . 23 | 1965 | Table | Height | 40 | in. |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 18 yrs. |  |  | Subje | ct No. | 12 |  | Upper | Arm Length | 14 | in. |
| Height $5 \mathrm{ft}$.7 in. |  |  | Weigh | 121 |  | lbs. | Dist. | from Table | $6 \frac{1}{2}$ | in. |
| Calibration: ${ }^{\mathrm{X}} \mathrm{Y} \frac{1}{} \frac{\mathrm{l}}{}$ volts $/ \mathrm{cm}$ |  |  |  |  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |  |  |  |  |
| $21 \mathrm{volts} / \mathrm{cm}$ |  |  | Reading No. |  |  |  |  |  |  |  |



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EXPERIMENTAL DATA SHEET


* uoţт̣puod g uoţtpuod
EXPERIMENTAL DATA SHEET

| Kathy Webb |  |  |  |  |  |  |  | November 23, 1965 |  |  |  | Table Height |  | 41 |  | in. |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Age | 18 |  | rs. |  |  | Sub | ject |  |  |  |  | Upper | Arm Length <br> from Table |  | 13 | in. |
| ght 5 ft .5 |  |  |  |  |  | Weight |  | 115 |  | lbs. |  |  |  |  |  | in. |
| Calibration:X volts $/ \mathrm{cm}$ <br>  $\mathrm{Y}-\frac{1}{1}$ volts $/ \mathrm{cm}$ <br> Z volts $/ \mathrm{cm}$ |  |  |  |  |  | Reading No. |  |  |  |  |  |  |  |  |  |  |
|  |  | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 | 13 | 14 | 5 |
|  | Xo | 38 | 29 | 30 | 30 | 35 | 65 | 5 | 5 | 58 | 55 | 60 | 42 | 47 | 40 | 42 |
|  | Xi | 16 | 20 | 25 | 22 | 23 | 47 | 48 | 45 | 48 | 40 | 21 | 30 | 35 | 35 | 36 |
|  | Yo | 1.94 | 1.42 | 1.65 | 1.70 | 1.85 | 1.80 | 1.39 | 1.65 | 1.71 | 1.85 | 2.30 | 1.95 | 1.39 | 1.20 | 1.80 |
|  | Yi | 1.79 | 2.10 | 1.59 | 1.94 | 1.50 | 1.50 | 2.10 | 1.58 | 1.94 | 1.50 | 2.15 | 1.89 | 1.68 | 2.10 | 2.02 |
|  | Zo | 1.75 | 1.10 | 1.09 | 1.29 | 1.50 | 2.10 | 1.75 | 1.65 | 1.79 | 1.62 | 2.15 | 1.51 | 1.70 | 1.65 | 1.67 |
|  | 2 Z | 1.25 | 1.20 | 1.28 | 1.19 | 1.49 | 1.50 | 1.60 | 1.30 | 1.49 | 1.66 | 1.60 | 1.53 | 1.55 | 1.25 | 1.50 |
|  | Xo | 55 | 39 | 31 | 34 | 40 | 62 | 42 | 50 | . 50 | 49 | 52 | 50 | 50 | 43 | $4+$ |
|  | Xi | 10 | 2 | 24 | 32 | 31 | 28 | 45 | 32 | 32 | 49 | 30 | 30 | . 32 | 25 | 35 |
|  | Yo | 1.49 | 1.70 | 1.45 | 1.50 | 1.75 | 2.10 | 1.30 | 1.65 | 1.50 | 1.49 | 1.51 | 1.70 | 1.15 | 1.44 | 1.50 |
|  | Yi | 1.42 | 1.73 | 1.59 | 2.15 | 1.55 | 1. 4.4 | 2.20 | 1.90 | 1.55 | 2.00 | 1.65 | 1.40 | 1.28 | 1.15 |  |
|  | 20 | 2.01 | 1.08 | 1.50 | 1.42 | 1.50 | 2.15 | 1.64 | 1.66 | 1.55 | 1.70 | 2.10 | 1.75 | 1.90 | 1.65 | 1.65 |
|  | 2 i | 1.25 | 1.49 | 1.45 | 1.52 | 1.59 | 1.69 | 1.65 | 1.67 | 1.22 | 11.60 | 1.65 | 7.66 | 1.85 | 1.66 | 1.76 |
|  | Xo-rh | 48 | .40 | 35 | 35 | 34 | 51 | 40 | 47 | 40 | 46 | 48 | . 45 | . 60 | 45 | 40 |
|  | Xo-1h | 26 | . 32 | 30 | 34 | . 28 | . 35 | . 22 | 32 | 47 | 48 | 45 | . 38 | . 35 | 4.4 | , |
|  | Xi-rh | . 24 | 26 | 22 | 79 | 26 | . 20 | . 13 | 29 | 20 | 29 | 30 | . 28 | 30 | 32 | 88 |
|  | Xi-1h | 20 | 24 | 31 | 32 | 29 | 36 | 40 | 34 | 42 | 35 | 41 | 50 | 36 | 40 | 42 |
|  | Yo-rh | 1.74 | 1.21 | . 90 | 1.12 | 1.10 | 1.30 | 1.00 | 82 | 80 | . 88 | 1.48 | 1.45 | 7.00 | . 95 | 1.39 |
|  | Yo-1h | . 8.8 | 1.30 | 1.32 | 1.40 | . 94 | 1.14 | . 85 | 70 | 1.20 | 12.42 | . 90 | 1.70 | 1.25 | 1.40 | 1.30 |
|  | Yi-rh | 1.00 | 1.45 | 1.28 | 1.26 | . 95 | . 61 | 1.06 | 1.00 | 1.02 | 1.21 | 1.25 | 1.50 | 1.20 | 1.55 | 1.25 |
|  | Yi-1h | 1.30 |  | 1.05 | 1.02 | .70 | 7. 78 | 1.32 | -. .90 | 1.10 | . 95 | 1.29 | 1.72 | 1. 2.24 | 1.25 | 1.05 |
|  | Zo-rh | . .85 | . 65 | . 61 | . 72 | . 75 | 2.25 | . 96 | . 99 | 1.10 | 1.17 | 1,40 | 1.15 | . 2.15 | 1.25 | 1.15 |
|  | 20-1h | . 66 | . 61 | . 70 | . 80 | . 85 | 1.09 | 1.10 | 1.01 | 1.08 | 1.01 | . 75 | 1.05 | 7.14 | 1.01 | . 88 |
|  | Zi-rh | . 65 | . 70 | . 58 | . 60 | . 80 | . 82 | . 75 | . 95 | . 75 | . .90 | 1.10 | . 95 | 1.25 | 7.12 | 1.30 |
|  | 2i-1h | . 77 | . 75 | . 80 | . 95 | . 82 | . 95 | . 90 | . 90 | . 80 | 1.00 | 1.09 | 1.10 | . 95 | 1.00 | 1.01 |

EXPERIMENTAL DATA SHEET


EXPERIMENTAL DATA SHEET

| Table Height 41 | in. |
| :--- | :--- |
| Upper Arm Length $\frac{13}{}$ in. |  |
| Dist. from Table $6 \frac{1}{2}$ | in. |


 Calibration: X 1 volts/cm
Reading No.


$\qquad$


$\qquad$





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EXPERIMENTAL DATA SHEET

$$
\text { Name } \frac{\text { Pat laggard }}{\text { Age }}
$$

| Table Height $40 \frac{1}{2}$ | in. |
| :--- | :--- |
| Upper Arm Length $\frac{13 \frac{1}{2}}{}$ | ine |
| Dist. from Table $6 \frac{1}{3}$ | in. |

$$
\begin{aligned}
& \text { Date November } 23,1965 \\
& \text { Subject No. } \frac{17}{} \\
& \text { Weight } 122 \quad 1 \text { bs. }
\end{aligned}
$$

EXPERIMENTAL DATA SHEET

| Table Height 41 | in. |
| :--- | :--- |
| Upper Arm Length | 13 in |
| Dist. from Table | $6 \frac{1}{2}$ |
| in. |  |



 volts/cm | Name | Betty L. Jeans |  |
| :---: | :---: | :---: |
|  | 26 |  |
| Age | yrs. |  |
| Height 5 ft. $4 \frac{1}{2}$ | in. |  |

Calibration: X
Reading No.




$\qquad$
8
.12
.08
1.59
2.28
1.15
1.46 두구우N



$$
1-7
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1- 05

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# A STUDY OF THE PHYSIOLOGICAL COSTS OF SMMETRICAL AND SIMULTANBOUS MOTIONS 

by

CARL EVERETT JEANS<br>B. S., Kansas State University, 1964

AN ABSTRACT OF A MASTER'S THESIS
submitted in partial fulfillment of the
requirements for the degree

MASTER OF SCIBNCE

Department of Industrial Engineering

KANSAS STATE UNIVERSITY<br>Manhattan, Kansas

The prineiples of motion econony established by $R$. M. Barnes in 1937 state, "motions of the arms should be perforned symuetrically and simultaneously" was investigated using physiological cost as measured by a foree platform as a criterion. Three tak conditions presented the combinations of symotrical and sluultaneous amp motions.

Bighteen femalo subjects performed in each of the three experimental conditions. The order of the task presentation vas countorbalanced within each subject.

A subjects by conditions analysis of varianee was calculated. Mean values were tested by the Dunean Multiple Range test.

It was concluded that for the task studied:

1) It is easier to perform shmitaneous and non-symmetrical motions than simultaneous and symsetrical motions.
2) Simultaneous motions are easier to perform than nonmsimultaneous or sequential motions.
3) Outward mottions of the ara require more fore than imverd motions.
4) Finally, for rightwhanded women, the loft hand exerts more foree than the might hand when both hands aro working at an "equal" task.

[^0]:    $X$ is outward force in $X$ plane caused by the right hand.

