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COMPUTATIONAL TECHNIQUES FOR THE ANALYSIS OF
THE GENERAL LINEAR MODEL

by

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Chapter 1

Introduction

1.1 Statement of the Problem

For the general linear statistical model there are two areas of interest, estimating the parameters of the model and testing hypotheses about some linear functions of the parameters. The computational techniques have been obtained for the standard linear statistical models and have been incorporated into many computer programs. However, there are experimental situations, where the corresponding linear models are different from the standard statistical linear models. Hence, the experimenter would be unable to properly analyze the model or test the desired hypothesis by utilizing the standard programs.

One of the problems inherent with the use of standard programs, arises when a design matrix is less than full rank (singular design matrix). The usual procedure to alleviate the problem in computer programs, is to impose a set of restrictions upon a subset of the parameters of the model and equating their sum to zero. In some experimental situations, these restrictions are not meaningful for the linear model which may require a different set of restrictions or none at all. In this case, it is difficult or impossible to achieve the desired restrictions (or lack of them), particularly for less than full rank designs because the design matrix must be inverted in order to estimate its parameters.

The other problem at hand is the inability to test varied hypotheses

in the standard programs. For a given model, the programs test the same hypothesis. Again, experimental situations arise which require one or more different testable hypotheses for the corresponding linear statistical model. The major problem of interest involves translating theoretical techniques of analyzing a general linear model with the desired restrictions and testable hypothesis into a computational procedure suitable for programming.

The primary motivation for this study came from Dr. G. A. Milliken, who realized a need in his consulting for a program which would statistically analyze any linear model with uncorrelated error structure, provide flexibility in the restrictions, and test the desired testable hypothesis about linear combinations of the parameters of the model. The problem of creating a program which will eliminate some of the standard programs' limitations is to be investigated herein.

1.2 Goals and Contents of This Report

The ultimate goal of this report is to implement algorithms which will statistically analyze the general linear model with any choice of restrictions and test the desired testable hypothesis. To obtain this goal, a study of generalized inverse computational procedures is necessary (generalized inverses enables one to deal with a less than full rank model without reparameterizing the model to a new full rank model). The theoretical techniques of parameter estimation and hypothesis testing are to be examined and transformed into procedures suitable for programming.

Chapter 2 discusses the theoretical techniques of generalized inverses, parameter estimation of the general linear model and hypothesis testing of linear combinations of the parameters and develops these theoretical techniques into computational procedures which are appropriate for implementation. Notations and definitions are defined in Section 2.1 and important theorems relating to the properties of generalized inverses are stated in Section 2.2. A technique developed by Rust, Burrus, and Schunburger, and expanded by Albert, for computing the generalized inverse of a matrix is presented in Section 2.3. In Section 2.4, the computational technique of generalized inversion is demonstrated by an example. The discussion of the linear statistical model is begun in Section 2.5 which also states an equivalent restricted linear model. The conditions for estimability of the restricted linear model are stated in Section 2.6. In the final section of Chapter 2 computational procedures for testing hypotheses that are estimable functions of the unknown parameters are developed by the use of Principle of Conditional Error. Chapter 3 provides some examples which are carried out in detail to present the internal computations of the program as well as the final output. The remaining examples illustrate the flexibility features of the restrictions used and the hypotheses that are tested. The Appendix contains the program and its documentation.

Chapter 2

THEORY AND DEVELOPMENT OF COMPUTATIONAL TECHNIQUES

This chapter consists of a review of the basic results and definitions from the theory of the Gramm-Schmidt orthogonalization for computing the generalized inverse of a matrix and the theory of parameter estimation and hypothesis testing procedures for less than full rank statistical models. The proofs of the theorems involving generalized inverses can be found in Graybill [3] and Albert [1]. The theory of parameter estimation, estimability and their computational procedures were developed by Milliken [5].

2.1 Notations and Definitions

The notation used consists mainly of matrices and vectors, hence underlined uppercase letters represent matrices; for example, $\underline{A}, \underline{U}, \underline{X}$. Column vectors are represented by underlined smallcase letters, such as $\underline{a}, \underline{x}, \underline{y}$. The transpose of a $n \times m$ matrix $\underline{A}$ is denoted by $\underline{A}'$, a $m \times n$ matrix. Smallcase letters which are not underlined represent scalars or constants, that is; c, d, y , are scalars or constants.

Now, we will define a generalized inverse as it is an essential part of parameter estimation of less than full rank models when we do not wish to impose the usual restrictions.

DEFINITION 2.1.1

Let $\underline{A}$ be any $n \times m$ matrix of rank $k \leq \min(n, m)$. There exists a unique $\underline{A}^-$ a $m \times n$ matrix called the generalized inverse (Moore-Penrose

Pseudoinverse) of $\underline{A}$ which satisfies the following four conditions:

1. $\underline{A}\underline{A}^-\underline{A} = \underline{A}$
2. $\underline{A}^-\underline{A}\underline{A}^+ = \underline{A}^+$
3. $\underline{A}\underline{A}^+$ is symmetric
4. $\underline{A}^-\underline{A}$ is symmetric.

The special case where $n=m=k$, i.e., where $\underline{A}$ is nonsingular, this generalized inverse is the ordinary inverse, $\underline{A}^{-1}$.

2.2 Theorems

This section consists of important theorems relating to the properties of generalized inverses and the Gramm-Schmidt orthogonalization (abbreviated GSO).

THEOREM 2.2.1 (Graybill [3]) If $\underline{A}'\underline{A} = \underline{I}$ ($\underline{I}$ is an identity matrix) or $\underline{B}\underline{B}' = \underline{I}$ or $\underline{B} = \underline{A}'$ or $\underline{B} = \underline{A}^+$ then $(\underline{A}\underline{B})^- = \underline{B}^-\underline{A}^-$.

THEOREM 2.2.2 (Graybill [2]) The $\text{rk}(\underline{A}) = \text{rk}(\underline{A}'\underline{A}) = \text{rk}(\underline{A}')$ where $\text{rk}(\cdot)$ denotes the rank operator.

THEOREM 2.2.3 (Graybill [3]) If $\underline{A}$ is a $n \times r$ matrix and $\underline{B}$ is a $r \times m$ matrix and $\text{rk}(\underline{A}) = \text{rk}(\underline{B}) = r$ then $(\underline{A}\underline{B})^- = \underline{B}^-\underline{A}^-$.

THEOREM 2.2.4 (Graybill [3]) If the rows of $\underline{A}$ are linearly independent then $\underline{A}^- = \underline{A}'(\underline{A}\underline{A}')^{-1}$.

The next theorem involves the use of the GSO. The GSO (Gramm-Schmidt orthogonalization) is a procedure which takes an arbitrary set of vectors $\underline{h}_1, \underline{h}_2, \dots, \underline{h}_n$ and generates a corresponding set of mutually orthogonal vectors $\underline{u}_1, \underline{u}_2, \dots, \underline{u}_n$ having the properties that

1. the column space of $(\underline{u}_1, \underline{u}_2, \dots, \underline{u}_n)$ equals the column space of $(\underline{h}_1, \underline{h}_2, \dots, \underline{h}_n)$
2. $\underline{u}_j' \underline{u}_i = 0 \quad i \neq j, i = 1, 2, \dots, n.$

THEOREM 2.2.5 (Albert [1]) Let $\underline{U}$ be a $k \times r$ matrix. If a GSO and then a normalization (inner product of a normalized vector is one) is performed on the columns of the matrix

$$\begin{pmatrix} \underline{U} \\ \underline{I} \\ \underline{I} \end{pmatrix}$$

generating the matrix of the orthonormal vectors

$$\underline{V} = \begin{pmatrix} \underline{V}_1 & k \times r \\ \underline{V}_2 & r \times r \end{pmatrix}$$

then

$$\underline{V}_2 \underline{V}_2' = (\underline{I} + \underline{U}'\underline{U})^{-1}$$

and

$$\underline{I} - \underline{V}_1 \underline{V}_1' = (\underline{I} + \underline{U}\underline{U}')^{-1}.$$

The following section involves a technique for computing the generalized inverse of a matrix. This technique was developed by Rust, Burrus, and Schnuburger [9] and expanded by Albert [1].

2.3 Computing the Generalized Inverse

Let $\underline{A}$ be any $n \times m$ matrix of rank $k \leq \min(n, m)$. There exists a permutation matrix (a square matrix of zeros and ones with exactly one nonzero entry in each row and column) $\underline{P}$ $m \times m$ such that

$$\underline{AP} = (\underline{R}, \underline{S})$$

where $\underline{R}$ is a $n \times k$ matrix of rank k (all columns of $\underline{R}$ are linearly independent) and $\underline{S}$ is a $n \times (m-k)$ matrix whose columns are orthogonal to those of $\underline{R}$. Hence there exists a $k \times (m-k)$ matrix $\underline{U}$ such that

$$\underline{S} = \underline{RU}.$$

Since $\underline{P}$ is an orthogonal matrix, $\underline{P}^{-1} = \underline{P}'$ thus

$$\underline{A} = (\underline{R}, \underline{S})\underline{P}' = (\underline{R}, \underline{RU})\underline{P}'$$

by applying Theorem 2.2.1, we see that

$$\underline{A}^- = \underline{P}[\underline{R}(\underline{I}, \underline{U})]^-$$

and from Theorem 2.2.2

$$\text{rk}(\underline{I}, \underline{U}) = \text{rk}[(\underline{I}, \underline{U})(\underline{I}, \underline{U})'] = \text{rk}(\underline{I} + \underline{UU}') = k.$$

This implies the rows of $(\underline{I}, \underline{U})$ are linearly independent so that by

Theorem 2.2.3

$$\begin{aligned}
[\underline{R}(\underline{I}, \underline{U})]^- &= (\underline{I}, \underline{U})^- \underline{R}^- \\
&= (\underline{I}, \underline{U})' [\underline{I}(\underline{I}, \underline{U}) (\underline{I}, \underline{U})']^{-1} \underline{R}^- \quad (\text{Theorem 2.2.4}) \\
&= (\underline{I}, \underline{U})' (\underline{I} + \underline{U}\underline{U}')^{-1} \underline{R}^-
\end{aligned}$$

Putting the above relationships together we observe that

$$\underline{A}^- = \underline{P}(\underline{I}, \underline{U})' (\underline{I} + \underline{U}\underline{U}')^{-1} \underline{R}^-.$$

The following are the steps (Albert [1]) involved in solving for $\underline{P}$, $\underline{R}^-$ and $\underline{U}$ by use of the GSO procedure. Note that by Theorem 2.2.5, $(\underline{I} + \underline{U}\underline{U}')^{-1}$ can be obtained by reapplying the GSO on $\begin{bmatrix} \underline{U} \\ \underline{I} \end{bmatrix}$.

Step 1: Evaluation of $\underline{P}$

Perform the GSO on the columns of $\underline{A}$ where $\underline{A} = (\underline{a}_1, \underline{a}_2, \dots, \underline{a}_n)$.

The GSO is defined by

$$\begin{aligned}
c_1^* &= a_1 \\
c_2^* &= a_2 - \frac{c_1^* a_2}{c_1^* c_1^*} c_1^* \\
&\vdots \\
c_m^* &= a_m - \frac{c_1^* a_m}{c_1^* c_1^*} c_1^* - \frac{c_2^* a_m}{c_2^* c_2^*} c_2^* - \dots - \frac{c_{m-1}^* a_m}{c_{m-1}^* c_{m-1}^*} c_{m-1}^*
\end{aligned}$$

If the vectors c_1^* , c_2^* , ..., c_m^* are permuted so that the k nonzero vectors come first, the same permutation matrix $\underline{P}$, applied to the vectors of a_1 , a_2 , ..., a_m will rearrange them so that the first k are linearly independent, while the last $m-k$ vectors are linear combinations of the

first k . This is true since $\underline{c}_i^* = \underline{0}$ if and only if $\underline{a}_i$ is a linear combination of the preceding $\underline{a}$'s. So, if $\underline{P}$ is any matrix for which

$$(\underline{c}_1^*, \underline{c}_2^*, \dots, \underline{c}_m^*) \underline{P} = (\underline{c}_1, \underline{c}_2, \dots, \underline{c}_m) \text{ where}$$

$$\underline{c}_i' \underline{c}_i \begin{cases} > 0 & i = 1, 2, \dots, k \\ = 0 & i = k+1, \dots, m \end{cases}$$

then

$$\underline{A} \underline{P} = (\underline{a}_1, \underline{a}_2, \dots, \underline{a}_m) \underline{P} = (\underline{R}, \underline{S})$$

Step 2: Computation of $\underline{R}^-$

The (nonzero) vectors $\underline{c}_1, \underline{c}_2, \dots, \underline{c}_k$ represent a GSO of the columns of $\underline{R}$. If we let

$$(2.3.1) \quad \underline{Q} = \left(\frac{\underline{c}_1}{\sqrt{\underline{c}_1' \underline{c}_1}}, \frac{\underline{c}_2}{\sqrt{\underline{c}_2' \underline{c}_2}}, \dots, \frac{\underline{c}_k}{\sqrt{\underline{c}_k' \underline{c}_k}} \right)$$

(this orthonormalizes each column of $\underline{Q}$, that is, if q is any column of $\underline{Q}$ then q is orthonormal if $q_i' q_j$ equals one when $i = j$ and equals zero when $i \neq j$)

then the column space of $\underline{Q}$ is the same as the column space of $\underline{R}$.

Hence there exists a $k \times k$ matrix $\underline{B}$ such that

$$\underline{R} \underline{B} = \underline{Q}.$$

Since the $\text{rk}(\underline{R}) = k$

$$\underline{B} = (\underline{R}' \underline{R})^{-1} \underline{R}' \underline{Q}$$

and

$Q'Q = I$ since the columns of Q are orthonormal

$Q'RB = I$ implies B is nonsingular

hence

$$R = QB^{-1} \text{ and by Theorem 2.2.1}$$

$$R^{-} = BQ^{-} \text{ which is expressed as}$$

$$R^{-} = B(Q'Q)^{-1}Q' \text{ by Theorem 2.2.4}$$

$$R^{-} = BQ'.$$

Step 3: Computation of B and U .

Let the columns of R be $r_1, r_2, \dots, r_k$ and the columns of S be $s_1, s_2, \dots, s_{m-k}$. The vectors $(c_1, c_2, \dots, c_k, c_{k+1}, \dots, c_m)$ represent the nonnormalized GSO of $(r_1, r_2, \dots, r_k, s_1, s_2, \dots, s_{m-k})$ then

$$c_1 = r_1$$

$$(2.3.2) \quad c_j = r_j - \sum_{i=1}^{j-1} \frac{r_j' c_i}{c_i' c_i} c_i \quad j = 2, \dots, k$$

and

$$(2.3.3) \quad 0 = c_{k+j} = s_j - \sum_{i=1}^k \frac{s_j' c_i}{c_i' c_i} c_i \quad j = 1, \dots, m-k$$

From equation (2.3.2) it is easy to deduce (by induction on j) that

$$(2.3.4) \quad c_j = \sum_{i=1}^j g_{ij} r_i \quad j = 1, 2, \dots, k$$

where

$$(2.3.5) \quad g_{ij} = \begin{cases} 0 & i > j \\ 1 & i = j \\ -\sum_{\ell=1}^{j-1} \frac{r_j c_{j-\ell}}{c_{\ell} c_{j-\ell}} g_{i\ell} & i < j \end{cases}$$

From equation (2.3.3)

$$(2.3.6) \quad \underline{s}_j = \sum_{i=1}^k m_{ij} \underline{r}_i$$

where m_{ij} is obtained by substituting equation (2.3.4) into equation (2.3.3).

$$\begin{aligned} \underline{s}_j &= \sum_{\ell=1}^k \frac{s_j' c_{j-\ell}}{c_{\ell} c_{j-\ell}} \left(\sum_{i=1}^{\ell} g_{i\ell} \underline{r}_i \right) \\ &= \sum_{i=1}^k \left(\sum_{\ell=i}^k \frac{s_j' c_{j-\ell}}{c_{\ell} c_{j-\ell}} g_{i\ell} \right) \underline{r}_i \end{aligned}$$

$$(2.3.7) \quad m_{ij} = \sum_{\ell=i}^k \frac{s_j' c_{j-\ell}}{c_{\ell} c_{j-\ell}} g_{i\ell} \quad \begin{matrix} i = 1, 2, \dots, k \\ j = 1, 2, \dots, m-k \end{matrix}$$

From equation (2.3.4) and (2.3.1)

$$\underline{Q} = \left(\frac{c_1}{\sqrt{c_1' c_1}}, \frac{c_2}{\sqrt{c_2' c_2}}, \dots, \frac{c_k}{\sqrt{c_k' c_k}} \right) = \underline{\underline{RB}}$$

where $\underline{B}$ is a $k \times k$ matrix whose (i,j) th entry is

$$b_{ij} = \frac{g_{ij}}{\sqrt{c_j' c_j}}.$$

From equation (2.3.6)

$$\underline{S} = \underline{R}\underline{U}$$

where $\underline{U}$ is a $k \times (n-k)$ matrix whose (i,j) th entry is

$$u_{ij} = m_{ik}$$

Step 4: Evaluation of $(\underline{I} + \underline{U}\underline{U}')^{-1}$

By Theorem 2.3.5, $(\underline{I} + \underline{U}\underline{U}')^{-1}$ is achieved by using GSO on $\begin{pmatrix} \underline{U} \\ -\underline{I} \end{pmatrix}$ and then normalizing the result. Hence we have all the necessary matrices to find $\underline{A}^- = \underline{P}(\underline{I}, \underline{U})'(\underline{I} + \underline{U}\underline{U}')^{-1}\underline{BQ}'$.

2.4 Example

This example illustrates the GSO technique of generalized inversion of a matrix $\underline{A}$.

$$\underline{A} = \begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \\ 1 & -1 & 0 \\ 1 & 0 & 1 \end{pmatrix}$$

$$\underline{c} = \begin{pmatrix} 1 \\ 0 \\ 1 \\ 1 \end{pmatrix}, \quad \underline{c}_2 = \begin{pmatrix} 1/3 \\ 1 \\ -2/3 \\ 1/3 \end{pmatrix}, \quad \underline{c}_3 = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

Hence $k = 2$, $\underline{P} = \underline{I}_{3 \times 3}$, and

$$\underline{R} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \\ 1 & -1 \\ 1 & 0 \end{pmatrix}, \quad \underline{S} = \begin{pmatrix} 1 \\ 1 \\ 0 \\ 1 \end{pmatrix}$$

$$\begin{aligned} g_{11} &= 1 & g_{12} &= 1/3 \\ g_{22} &= 1 & g_{21} &= 0 \end{aligned}$$

and

$$m_{11} = 1 \quad m_{21} = 1$$

$$\text{so } b_{11} = \frac{1}{\sqrt{3}} \quad b_{12} = \frac{1/3}{\sqrt{5/3}} = \frac{1}{\sqrt{15}}$$

$$b_{21} = 0 \quad b_{22} = \frac{3}{\sqrt{15}}$$

$$\underline{B} = \begin{pmatrix} 1/\sqrt{3} & 1/\sqrt{15} \\ 0 & 3/\sqrt{15} \end{pmatrix}, \quad \underline{Q} = \begin{pmatrix} 1/\sqrt{3} & 1/\sqrt{15} \\ 0 & 3/\sqrt{15} \\ 1/\sqrt{3} & -2/\sqrt{15} \\ 1/\sqrt{3} & 1/\sqrt{15} \end{pmatrix}$$

$$\begin{pmatrix} \underline{U} \\ \underline{I} \end{pmatrix} = \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix} \xrightarrow{\text{GSO}} \underline{V} = \begin{pmatrix} 1/\sqrt{3} \\ 1/\sqrt{3} \\ 1/\sqrt{3} \end{pmatrix} = \begin{pmatrix} \underline{V}_1 \\ \underline{V}_2 \end{pmatrix}$$

$$\underline{I} - \underline{V}_1 \underline{V}_1' = \begin{pmatrix} 2/3 & -1/3 \\ -1/3 & 2/3 \end{pmatrix} = (\underline{I} + \underline{U}\underline{U}')^{-1}$$

$$(\underline{I} + \underline{U}\underline{U}')^{-1} \underline{B}\underline{Q}' = \frac{1}{15} \begin{pmatrix} 3 & -1 & 4 & 3 \\ 0 & 5 & -5 & 0 \end{pmatrix}$$

$$\begin{pmatrix} \underline{I} \\ \underline{U}' \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \\ 1 & 1 \end{pmatrix}$$

$$\underline{A}^{-} = \begin{pmatrix} \underline{I} \\ \underline{U}' \end{pmatrix} (\underline{I} + \underline{U}\underline{U}')^{-1} \underline{B}\underline{Q}'$$

$$= \frac{1}{15} \begin{pmatrix} 3 & -1 & 4 & 3 \\ 0 & 5 & -5 & 0 \\ 3 & 4 & -1 & 3 \end{pmatrix} .$$

2.5 Linear Model

This section begins our discussion of the linear statistical model represented by $\underline{y} = \underline{X}\underline{\beta} + \underline{e}$ subject to the linear restrictions $\underline{H}\underline{\beta} = \underline{b}$. An equivalent unrestricted linear model, as developed by Milliken [5], will be formulated from the original linear model subject to the restrictions.

The restricted linear model is defined as

$$(2.5.1) \quad \underline{y} = \underline{X}\underline{\beta} + \underline{e}$$

with restrictions $\underline{H}\underline{\beta} = \underline{b}$ where $\underline{X}$ is a $n \times p$ ($p < n$) matrix of known constants (often called the design matrix) of rank q with $q \leq p$, $\underline{y}$ is a $n \times 1$ vector of random observations, $\underline{H}$ is a $k \times p$ ($k \leq p$) matrix of rank h such that $h \leq k$, $\underline{b}$ is a $k \times 1$ vector of constants such that the system of equations $\underline{H}\underline{\beta} = \underline{b}$ are consistent, $\underline{\beta}$ is a $p \times 1$ vector of unknown parameters and $\underline{e}$ is a $n \times 1$ unobservable random vector (random error) with $\underline{e} \sim N(\underline{0}, \sigma^2 \underline{I}_n)$ where σ^2 is an unknown parameter.

Combining the unrestricted linear model with the set of linear restrictions, we develop an equivalent unrestricted linear model.

THEOREM 2.5.1 (Milliken [5]) The restricted linear model $\underline{y} = \underline{X}\underline{\beta} + \underline{e}$ is equivalent to the linear model

$$(2.5.2) \quad \underline{y} - \underline{X}\underline{H}^{-1}\underline{b} = \underline{X}(\underline{I} - \underline{H}^{-1}\underline{H})\underline{\beta} + \underline{e}$$

where $\underline{y}, \underline{X}, \underline{\beta}, \underline{b}$ and $\underline{e}$ are defined in (2.5.1).

The matrix product, $\underline{X}(\underline{I} - \underline{H}^{-1}\underline{H})$ is the new design matrix and is kept as an entity while working with the model.

2.6 Estimation

The linear model of (2.5.2) now is used to obtain a unified definition of estimability for the restricted linear model.

DEFINITION 2.6.1 The linear combinations $\underline{A}\underline{\beta}$ are defined to be estimable for the restricted linear model (2.5.1) if and only if they are estimable for the unrestricted linear model (2.5.2).

The next theorem states the condition for linear functions to be estimable.

THEOREM 2.6.1 (Milliken [6]) The linear combinations $\underline{A}\underline{\beta}$ are estimable for the linear model $\underline{y} = \underline{W}\underline{\beta} + \underline{e}$ if and only if the $\text{rk}[\underline{W}(\underline{I} - \underline{A}\underline{A}')] = \text{rk}(\underline{W}) - \text{rk}(\underline{A})$.

THEOREM 2.6.2 (Milliken [6]) The linear combinations $\underline{A}\underline{\beta}$, where $\underline{A}$ is a $k \times p$ matrix of known constants of rank k , are estimable for model (2.5.1) if and only if (1) or (2) hold:

$$(1) \quad \text{rk}[\underline{X}(\underline{I} - \underline{H}\underline{H}')(\underline{I} - \underline{A}\underline{A}')] = s - k \text{ where}$$

$$\text{rk}[\underline{X}(\underline{I} - \underline{H}\underline{H}')] = s$$

$$(2) \quad \text{tr}\{[\underline{X}(\underline{I} - \underline{H}\underline{H}')(\underline{I} - \underline{A}\underline{A}')] [\underline{X}(\underline{I} - \underline{H}\underline{H}')(\underline{I} - \underline{A}\underline{A}')]'\} = s - k \text{ where}$$

$\text{tr}(\cdot)$ denotes the trace operator.

The form of Theorem 2.6.2 needs to be slightly modified as we will not be using $\underline{X}$ in our computations, but will use $\underline{X}'\underline{X}$ instead. By using Theorem 2.2.2 we can rewrite (1) and (2) of Theorem 2.6.2 as

$$(1) \quad \text{rk}[(\underline{I} - \underline{H}\underline{H}')\underline{X}'\underline{X}(\underline{I} - \underline{H}\underline{H}')(\underline{I} - \underline{A}\underline{A}')] = s - k \text{ where}$$

$$\text{rk}[(\underline{I} - \underline{H}\underline{H}')\underline{X}'\underline{X}(\underline{I} - \underline{H}\underline{H}')] = s$$

$$(2) \quad \text{tr}\{[(\underline{I}-\underline{H}^{-}\underline{H})\underline{X}'\underline{X}(\underline{I}-\underline{H}^{-}\underline{H})(\underline{I}-\underline{A}^{-}\underline{A})][(\underline{I}-\underline{H}^{-}\underline{H})\underline{X}'\underline{X}(\underline{I}-\underline{H}^{-}\underline{H})(\underline{I}-\underline{A}^{-}\underline{A})]^{-}\} = s-k.$$

To help us find the ranks of the above matrices we need the use of the following theorem.

THEOREM 2.6.3 (Graybill [3]) If $\underline{A}$ is an $n \times m$ matrix and $\underline{A}^{-}$ is the generalized inverse of $\underline{A}$ then $\text{tr}(\underline{A}^{-}\underline{A}) = \text{tr}(\underline{A}\underline{A}^{-}) = \text{rk}(\underline{A})$.

To compute the ranks of $\underline{A}$ and $(\underline{I}-\underline{H}^{-}\underline{H})\underline{X}'\underline{X}(\underline{I}-\underline{H}^{-}\underline{H})$ we will find the following traces:

$$\text{tr}(\underline{A}^{-}\underline{A}) = k$$

$$\text{tr}\{[(\underline{I}-\underline{H}^{-}\underline{H})\underline{X}'\underline{X}(\underline{I}-\underline{H}^{-}\underline{H})(\underline{I}-\underline{A}^{-}\underline{A})][(\underline{I}-\underline{H}^{-}\underline{H})\underline{X}'\underline{X}(\underline{I}-\underline{H}^{-}\underline{H})(\underline{I}-\underline{A}^{-}\underline{A})]^{-}\}.$$

The next theorem provides the Best Linear Unbiased Estimator (BLUE) for estimable functions of the restricted linear model (2.5.1).

THEOREM 2.6.4 (Milliken [5]) The BLUE of $\underline{A}\underline{\beta}$ for the model (2.5.1), where $\underline{A}\underline{\beta}$ are estimable functions, is $\underline{A}\hat{\underline{\beta}}$, where $\hat{\underline{\beta}}$ is any solution to the normal equations:

$$(2.6.1) \quad (\underline{I}-\underline{H}^{-}\underline{H})\underline{X}'\underline{X}(\underline{I}-\underline{H}^{-}\underline{H})\hat{\underline{\beta}} = (\underline{I}-\underline{H}^{-}\underline{H})\underline{X}'(\underline{y}-\underline{X}\underline{H}^{-}\underline{b}).$$

Hence from equation (2.6.1), the solution we will use for computing $\hat{\underline{\beta}}$ is

$$(2.6.2) \quad \hat{\underline{\beta}} = [(\underline{I}-\underline{H}^{-}\underline{H})\underline{X}'\underline{X}(\underline{I}-\underline{H}^{-}\underline{H})]^{-} (\underline{I}-\underline{H}^{-}\underline{H})\underline{X}'\underline{y} - (\underline{I}-\underline{H}^{-}\underline{H})\underline{X}'\underline{X}\underline{H}^{-}\underline{b}.$$

The estimator of $\underline{A}\hat{\underline{\beta}}$ is

$$(2.6.3) \quad \underline{A}\hat{\underline{\beta}} = \underline{A}[\underline{X}(\underline{I}-\underline{H}^{-}\underline{H})]^{-}(\underline{y}-\underline{X}\underline{H}^{-}\underline{b}).$$

Now we will examine the variance-covariance structures of the above estimators.

THEOREM 2.6.5 (Milliken [7]) The covariance matrix of the BLUE of $\underline{\beta}$ and the linear combinations of $\underline{A}\underline{\beta}$ are $\text{Var}(\underline{\beta}) = \sigma^2 [(\underline{I} - \underline{H})\underline{H}]\underline{X}'\underline{X}(\underline{I} - \underline{H})\underline{H}]$ and $\text{Var}(\underline{A}\underline{\beta}) = \sigma^2 \underline{A}' [(\underline{I} - \underline{H})\underline{H}]\underline{X}'\underline{X}(\underline{I} - \underline{H})\underline{H}] \underline{A}$.

The next section considers the problem of hypothesis testing about estimable functions of the unknown parameters.

2.7 Hypothesis Testing

We will use the definition that a hypothesis $\underline{A}\underline{\beta}$ are estimable for the restricted linear model and the vector $\underline{a}$ is such that the system of equations $\underline{A}\underline{\beta} = \underline{a}$ is consistent.

THEOREM 2.7.1 (Milliken [5]) The hypothesis $\underline{A}\underline{\beta} = \underline{a}$ where $\underline{A}$ is a $k \times p$ matrix of known constants of rank k is testable for model (2.5.1) if and only if $\text{rk}[(\underline{I} - \underline{H})\underline{H}]\underline{X}'\underline{X}(\underline{I} - \underline{H})\underline{H}(\underline{I} - \underline{A}'\underline{A})] = s - k$ and $\text{rk}(\underline{A}, \underline{a}) = \text{rk}(\underline{A})$, where $\text{rk}[(\underline{I} - \underline{H})\underline{H}]\underline{X}'\underline{X}(\underline{I} - \underline{H})\underline{H}] = s$.

Next we will defined the principle of conditional error as it is used to obtain the test statistic corresponding to a testable hypothesis.

DEFINITION 2.7.1 The principle of conditional error is defined as: the sum of squares due to a testable hypothesis is the difference between the sum of squares due to error for model (2.5.1) restricted by the conditions of the null hypothesis and the sum of squares due to error for model (2.5.1) i.e.,

$$\text{SSH}_0 = \text{SSE}_0 - \text{SSE}.$$

The sum of squares due to error for model (2.5.1) is

$$\begin{aligned}
 (2.7.1) \quad SSE &= (\underline{y} - \underline{X}\underline{H}^{-}\underline{b})' (\underline{I} - \underline{X}(\underline{I} - \underline{H}^{-}\underline{H}) [\underline{X}(\underline{I} - \underline{H}^{-}\underline{H})]^{-}) (\underline{y} - \underline{X}\underline{H}^{-}\underline{b}) \\
 &= \underline{y}'\underline{y} - \underline{y}'\{\underline{X}(\underline{I} - \underline{H}^{-}\underline{H}) [\underline{X}(\underline{I} - \underline{H}^{-}\underline{H})]^{-}\}\underline{y} \\
 &\quad + \underline{y}'\{\underline{X}(\underline{I} - \underline{H}^{-}\underline{H}) [\underline{X}(\underline{I} - \underline{H}^{-}\underline{H})]^{-}\}\underline{X}\underline{H}^{-}\underline{b} - \underline{y}'\underline{X}\underline{H}^{-}\underline{b} \\
 &\quad - \underline{b}'(\underline{H}^{-})' \underline{X}'\underline{y} + \underline{b}'(\underline{H}^{-})' \underline{X}'\underline{X}(\underline{I} - \underline{H}^{-}\underline{H}) [\underline{X}(\underline{I} - \underline{H}^{-}\underline{H})]^{-}\underline{y} \\
 &\quad + \underline{b}'(\underline{H}^{-})' \underline{X}'\underline{X}\underline{H}^{-}\underline{b} - \underline{b}'(\underline{H}^{-})' \underline{X}'\underline{X}(\underline{I} - \underline{H}^{-}\underline{H})\underline{X}\underline{H}^{-}\underline{b}
 \end{aligned}$$

combining the underlined terms we have

$$\underline{y}'\underline{y} - 2\underline{b}'(\underline{H}^{-})' \underline{X}'\underline{y} + \underline{b}'(\underline{H}^{-})' \underline{X}'\underline{X}\underline{H}^{-}\underline{b}$$

which is the total sum of squares for the restricted linear model (i.e., $(\underline{y} - \underline{X}\underline{H}^{-}\underline{b})'(\underline{y} - \underline{X}\underline{H}^{-}\underline{b})$).

The remaining terms can be further simplified by factoring:

$$\begin{aligned}
 &- \underline{y}'\{\underline{X}(\underline{I} - \underline{H}^{-}\underline{H}) [\underline{X}(\underline{I} - \underline{H}^{-}\underline{H})]^{-}\}\underline{y} + \underline{y}'\{\underline{X}(\underline{I} - \underline{H}^{-}\underline{H}) [\underline{X}(\underline{I} - \underline{H}^{-}\underline{H})]^{-}\}\underline{X}\underline{H}^{-}\underline{b} \\
 &+ \underline{b}'(\underline{H}^{-})' \underline{X}'\underline{X}(\underline{I} - \underline{H}^{-}\underline{H}) [\underline{X}(\underline{I} - \underline{H}^{-}\underline{H})]^{-}\underline{y} + \underline{b}'(\underline{H}^{-})' \underline{X}'\underline{X}(\underline{I} - \underline{H}^{-}\underline{H}) [\underline{X}(\underline{I} - \underline{H}^{-}\underline{H})]^{-}\underline{X}\underline{H}^{-}\underline{b} \\
 &= - \underline{y}'\{\underline{X}(\underline{I} - \underline{H}^{-}\underline{H}) [\underline{X}(\underline{I} - \underline{H}^{-}\underline{H})]^{-}\}(\underline{y} - \underline{X}\underline{H}^{-}\underline{b}) + \underline{b}'(\underline{H}^{-})' \underline{X}'\underline{X}(\underline{I} - \underline{H}^{-}\underline{H}) [\underline{X}(\underline{I} - \underline{H}^{-}\underline{H})]^{-} \\
 &\quad \cdot (\underline{y} - \underline{X}\underline{H}^{-}\underline{b}) \qquad \text{recall } \hat{\underline{\beta}} = [\underline{X}(\underline{I} - \underline{H}^{-}\underline{H})]^{-}(\underline{y} - \underline{X}\underline{H}^{-}\underline{b}) \\
 &= - \underline{y}'[\underline{X}(\underline{I} - \underline{H}^{-}\underline{H})]^{-}\hat{\underline{\beta}} + \underline{b}'(\underline{H}^{-})' \underline{X}'\underline{X}(\underline{I} - \underline{H}^{-}\underline{H})\hat{\underline{\beta}} \\
 &= - \hat{\underline{\beta}}'[(\underline{I} - \underline{H}^{-}\underline{H})\underline{X}'\underline{y} - (\underline{I} - \underline{H}^{-}\underline{H})\underline{X}'\underline{X}\underline{H}^{-}\underline{b}]
 \end{aligned}$$

Hence

$$(2.7.2) \quad \text{SSE} = \underline{y}'\underline{y} - 2\underline{b}'(\underline{H}^-)' \underline{X}'\underline{y} + \underline{b}'(\underline{H}^-)' \underline{X}'\underline{X}\underline{H}^- \underline{b} \\ - \hat{\underline{\beta}}'[(\underline{I}-\underline{H}^-)\underline{H}]\underline{X}'\underline{y} - (\underline{I}-\underline{H}^-)\underline{H}]\underline{X}'\underline{X}\underline{H}^- \underline{b}]$$

The model of (2.5.1) restricted by the null hypothesis can be expressed similar to model (2.5.2) as

$$(2.7.3) \quad \underline{y} - \underline{X}\underline{H}^- \underline{b} - \underline{X}(\underline{I}-\underline{H}^-)\underline{H}]\underline{A}^- \underline{a} = \underline{X}(\underline{I}-\underline{H}^-)\underline{H}]\underline{(I-A^-A)}\underline{\beta}_0 + \underline{e}$$

$$\text{or} \quad \underline{y} = \underline{X}(\underline{I}-\underline{H}^-)\underline{H}]\underline{(I-A^-A)}\underline{\beta}_0 + \underline{e} \quad \text{where}$$

$$\underline{y} = \underline{y} - \underline{X}\underline{H}^- \underline{b} - \underline{X}(\underline{I}-\underline{H}^-)\underline{H}]\underline{A}^- \underline{a}$$

Note the design matrix is $\underline{X}(\underline{I}-\underline{H}^-)\underline{H}]\underline{(I-A^-A)}$, hence the normal equations for (2.7.3) are

$$(2.7.4) \quad \underline{(I-A^-A)}\underline{(I-H^-H)]X}'\underline{y} = \underline{(I-A^-A)}\underline{(I-H^-H)]X}'\underline{X}(\underline{I-H^-H)](I-A^-A)}\underline{\beta}_0 + \underline{e}$$

Hence the estimator for $\underline{\beta}_0$ is

$$\hat{\underline{\beta}}_0 = [\underline{(I-A^-A)}\underline{(I-H^-H)]X}'\underline{X}(\underline{I-H^-H)](I-A^-A)}]^{-1} [\underline{(I-A^-A)}\underline{(I-H^-H)]X}'\underline{y} \\ - \underline{(I-A^-A)}\underline{(I-H^-H)]X}'\underline{X}\underline{H}^- \underline{b} - \underline{(I-A^-A)}\underline{(I-H^-H)]X}'\underline{X}(\underline{I-A^-A)}\underline{A}^- \underline{a}]$$

The sum of squares due to error for the model of (2.7.3) is

$$(2.7.5) \quad \text{SSE}_0 = \underline{z}'\underline{(I-X(I-H^-H)](I-A^-A)}[\underline{X(I-H^-H)](I-A^-A)}]^{-1}\underline{z} \\ = \underline{z}'\underline{z} - \hat{\underline{\beta}}_0' \underline{(I-A^-A)}\underline{(I-H^-H)]X}'\underline{y}$$

where $\underline{z}'\underline{z}$ the total sum of squares for (2.7.3) is

$$\begin{aligned}
(2.7.6) \quad \underline{z}'\underline{z} &= \underline{y}'\underline{y} - 2\underline{y}'\underline{X}\underline{H}^{-}\underline{b} - 2\underline{y}'\underline{X}(\underline{I}-\underline{H}^{-}\underline{H})\underline{A}^{-}\underline{a} \\
&+ 2\underline{b}'(\underline{H}^{-})'\underline{X}'\underline{X}(\underline{I}-\underline{H}^{-}\underline{H})\underline{A}^{-}\underline{a} + \underline{b}'(\underline{H}^{-})'\underline{X}'\underline{X}\underline{H}^{-}\underline{b} \\
&+ \underline{a}'(\underline{A}^{-})'(\underline{I}-\underline{H}^{-}\underline{H})\underline{X}'\underline{X}(\underline{I}-\underline{H}^{-}\underline{H})\underline{A}^{-}\underline{a}
\end{aligned}$$

and

$$\begin{aligned}
(2.7.7) \quad \hat{\beta}'_0(\underline{I}-\underline{A}^{-}\underline{A})(\underline{I}-\underline{H}^{-}\underline{H})\underline{X}'\underline{z} &= \hat{\beta}'_0[(\underline{I}-\underline{A}^{-}\underline{A})(\underline{I}-\underline{H}^{-}\underline{H})\underline{X}'\underline{y} \\
&- (\underline{I}-\underline{A}^{-}\underline{A})(\underline{I}-\underline{H}^{-}\underline{H})\underline{X}'\underline{X}\underline{H}^{-}\underline{b} - (\underline{I}-\underline{A}^{-}\underline{A})(\underline{I}-\underline{H}^{-}\underline{H})\underline{X}'\underline{X}(\underline{I}-\underline{H}^{-}\underline{H})\underline{A}^{-}\underline{a}]
\end{aligned}$$

We will use the last two forms (2.7.6) and (2.7.7) to compute SSE_0 .

Now we can find the sum of squares due to the hypothesis as

$$(2.7.8) \quad SSH_0 = SSE_0 - SSE.$$

The following theorem can now be established.

THEOREM 2.7.2 (Milliken [5]) The sums of squares in (2.7.2), (2.7.5) and (2.7.8) have these distributional properties:

$$(i) \quad \frac{SSH_0}{\sigma^2} \sim \chi^2(k, \lambda)$$

$$(ii) \quad \frac{SSE}{\sigma^2} \sim \chi^2(n-s)$$

(iii) SSH_0 and SSE are independently distributed; and

$$(iv) \quad F = \frac{SSH_0}{SSE} \frac{n-s}{k} \sim F(k, n-s, \lambda)$$

where

$$\lambda = \frac{1}{\sigma^2} (\underline{A}\underline{\beta} - \underline{a})' \underline{A}'^{-1} (\underline{I} - \underline{H}^{-1} \underline{H}) \underline{X}' [\underline{I} - \underline{X}(\underline{I} - \underline{H}^{-1} \underline{H}) (\underline{I} - \underline{A}^{-1} \underline{A}) \\ \cdot [\underline{X}(\underline{I} - \underline{H}^{-1} \underline{H}) (\underline{I} - \underline{A}^{-1} \underline{A})]^{-1}] \underline{X}(\underline{I} - \underline{H}^{-1} \underline{H}) \underline{A}^{-1} (\underline{A}\underline{\beta} - \underline{a})$$

We are ready to begin the computing $\hat{\underline{\beta}}$, $\hat{\underline{\beta}}_0$, SSE, SSE_0 , and SSH_0 and testing the desired hypothesis, making sure it is testable first, by examining the ranks of the matrices involved.

Chapter 3

EXAMPLES ILLUSTRATING THE TECHNIQUES

This chapter provides two examples which are carried out in detail to illustrate the internal computations of the program as well as the final output. The remaining examples illustrate the flexibility features of the restrictions used and the hypothesis that are tested.

Example 3.1 Consider the model $y = \alpha + X_1\beta_1 + X_2\beta_2 + \varepsilon$ where no restrictions are imposed upon the model. The hypothesis of interest is:

$$H_0: \beta_1 = \beta_2 = 1 \quad \text{vs} \quad H_a: \text{not } H_0.$$

The data vector y and the independent variable matrix X are:

$$\underline{X} = \begin{pmatrix} 1 & 10 & 4 \\ 1 & 6 & 6 \\ 1 & 9 & 10 \\ 1 & 7 & 3 \\ 1 & 10 & 6 \\ 1 & 2 & 3 \\ 1 & 9 & 2 \\ 1 & 2 & 7 \\ 1 & 7 & 7 \\ 1 & 9 & 7 \\ 1 & 4 & 9 \\ 1 & 7 & 2 \end{pmatrix}, \quad \underline{y} = \begin{pmatrix} 14.3 \\ 13.2 \\ 21.3 \\ 10.7 \\ 17.0 \\ 5.6 \\ 10.7 \\ 13.4 \\ 15.7 \\ 17.1 \\ 14.9 \\ 9.2 \end{pmatrix}$$

The input cards necessary for the analysis are:

TITLE, TESTS THE H0 THAT THE SLOPES OF Y=X1B1+X2B2+A EQUAL 1
PARAMETERS,4,12,0,0,1,1.
(F1.0,2F2.0,F3.1)
111014143
:
1 7 2 92
(4F2.0)
HYPOTHESIS, 2,1.
0 1 0 1
0 0 1 0

Both the title and parameter cards are mandatory. The values of the parameter card indicate there are 4 variables in the model (includes y), 12 rows of the $\underline{X}$ matrix or observations, 0 rows of $\underline{H}$, the restriction matrix, 0 subscript cards, 1 hypothesis to be tested and the last 1 indicates the variance covariance matrix of the parameters is to be printed.

The matrices $\underline{X}'\underline{X}$, $\underline{X}'\underline{y}$, and $\underline{y}'\underline{y}$ are stored in XPX(I,J). These are calculated as the data cards are read.

$$\text{XPX(I,J)} = \left(\begin{array}{ccc|c}
 & \underline{X}'\underline{X} & & \\
 12 & 82 & 68 & 163.1 \\
 82 & 650 & 451 & 1180.9 \\
 68 & 451 & 474 & 1024.4 \\
 \hline
 163.1 & 1180.9 & 1024.4 & 2406.67
 \end{array} \right) \left. \begin{array}{l} \\ \\ \\ \end{array} \right\} \begin{array}{l} \\ \underline{X}'\underline{y} \\ \\ \end{array}$$

$\underline{y}'\underline{y}$

Since there are no restrictions

$$HGH(I,J) = \underline{I} - \underline{H} \underline{H}' \underline{H} = \underline{I}_3$$

and

$$\underline{b} = \underline{0}$$

hence

$$C(I,J) = (\underline{I} - \underline{H} \underline{H}' \underline{H}) \underline{X}' \underline{X} (\underline{I} - \underline{H} \underline{H}' \underline{H}) = \underline{X}' \underline{X}$$

and

$$CG(I,J) = [(\underline{I} - \underline{H} \underline{H}' \underline{H}) \underline{X}' \underline{X} (\underline{I} - \underline{H} \underline{H}' \underline{H})]^{-1} = (\underline{X}' \underline{X})^{-1} = \begin{pmatrix} 1.1238 & -0.0880 & -0.0774 \\ -0.0880 & -0.0114 & 0.0017 \\ -0.0774 & -0.0017 & 0.0115 \end{pmatrix}.$$

$$HHXY(I) = (\underline{I} - \underline{H} \underline{H}' \underline{H}) \underline{X}' \underline{y} = \underline{X}' \underline{y} = \begin{pmatrix} 163.1 \\ 1180.9 \\ 1024.4 \end{pmatrix}.$$

We have all the necessary matrices to estimate the parameters as follows:

$$BETA(I) = CG(I,J) * HHXY(I) = \hat{\underline{\beta}} = (\underline{X}' \underline{X})^{-1} \underline{X}' \underline{y} = \begin{pmatrix} -0.0117 \\ 0.9345 \\ 1.2737 \end{pmatrix}.$$

Next the total sum of squares, regression sum of squares and error sum of squares are calculated yielding

$$\text{TOTSS} = \underline{y}'\underline{y} = 2406.87$$

$$\text{BH} = \text{BETA}(\text{I}) * \text{HHXY}(\text{I}) = \hat{\underline{\beta}}'(\underline{X}'\underline{y}) = 2406.42$$

$$\text{ESS} = \text{TOTSS} - \text{BH} = \underline{y}'\underline{y} - \hat{\underline{\beta}}'(\underline{X}'\underline{y}) = .4499$$

To help determine if the hypothesis is testable the $\text{tr}[(\underline{X}'\underline{X})^{-1}(\underline{X}'\underline{X})]$ is computed.

$$\text{CGC}(\text{I},\text{J}) = \text{CG}(\text{I},\text{J}) * \text{C}(\text{I},\text{J}) = (\underline{X}'\underline{X})^{-1}(\underline{X}'\underline{X})$$

$$= \begin{pmatrix} 1.00 \times 10^{-0} & 2.44 \times 10^{-11} & 1.70 \times 10^{-11} \\ 1.22 \times 10^{-13} & 1.00 \times 10^{-0} & 4.17 \times 10^{-14} \\ -1.77 \times 10^{-14} & -1.79 \times 10^{-14} & 1.00 \times 10^{-0} \end{pmatrix}$$

Thus

$\text{RANKX} = 3$, the rank of the independent variable or design matrix.

This means there are 3 d.f. associated with estimation

The error degrees of freedom and mean square error are

$$\text{DFE} = \text{NR} - \text{RANKX} = 9$$

$$\text{ERRMS} = \text{ESS}/\text{DFE} = .04999.$$

The covariance matrix for $\hat{\underline{\beta}}$ is

$$\text{D}(\text{I},\text{J}) = \text{ERRMS} * \text{C}(\text{I},\text{J}) = \hat{\underline{\sigma}}^2(\underline{X}'\underline{X})^{-1} = \begin{pmatrix} 0.5999 & & \\ 4.0995 & 32.4961 & \\ 3.3996 & 22.5473 & 23.6971 \end{pmatrix}$$

The hypothesis matrix is read as

$$A(I,J) = (\underline{A}, \underline{a}) = \begin{pmatrix} 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 1 \\ A & & & Q \end{pmatrix}$$

and the generalized inverse of $\underline{A}$ is

$$AGINV(I,J) = \underline{A}^- = \begin{pmatrix} 0 & 0 \\ 1 & 0 \\ 0 & 1 \end{pmatrix}.$$

The $\text{tr}[\underline{A}^- \underline{A}]$ is needed, hence

$$AGA(I,J) = AGINV(I,J) * A(I,J) = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

providing

$$\text{RANKA} = 2$$

and

$$AGA(I,J) = (\underline{I} - \underline{A}^- \underline{A}) = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}.$$

To compute the $\text{tr}\{[(\underline{I} - \underline{H}^- \underline{H}) \underline{X}' \underline{X} (\underline{I} - \underline{H}^- \underline{H}) (\underline{I} - \underline{A}^- \underline{A})]^- [\underline{I} - \underline{H}^- \underline{H}) \underline{X}' \underline{X} (\underline{I} - \underline{H}^- \underline{H}) (\underline{I} - \underline{A}^- \underline{A})]^- \}$,

the series of matrix multiplication are performed as follows:

$$CA(I,J) = C(I,J) * AGA(I,J) = \underline{X}' \underline{X} (\underline{I} - \underline{A}^- \underline{A}) = \begin{pmatrix} 12 & 0 & 0 \\ 82 & 0 & 0 \\ 68 & 0 & 0 \end{pmatrix}$$

$$CAG(I,J) = [(\underline{X}' \underline{X}) (\underline{I} - \underline{A}^- \underline{A})]^- = \begin{pmatrix} .0010 & .0071 & .0059 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

thus

$$D(I,J) = CA(I,J) * CAG(I,J) = \begin{pmatrix} .0125 & & \\ .0856 & .5852 & \\ .0710 & .4852 & .4023 \end{pmatrix}$$

yielding

$$RANKQ = 1.$$

To determine if the hypothesis is testable, we must have $RANKQ = RANKX - RANKA$, which is satisfied for these matrices i.e. $1 = (3-2)$, hence the hypothesis is testable.

Now, the conditional error and $\underline{\beta}_0$ can be estimated by computing

$$D(I,J) = AGA(I,J) * CA(I,J) = (\underline{I} - \underline{A}^{-} \underline{A}) \underline{X}' \underline{X} (\underline{I} - \underline{A}^{-} \underline{A}) = \begin{pmatrix} 12 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

$$CG(I,J) = [(\underline{I} - \underline{A}^{-} \underline{A}) \underline{X}' \underline{X} (\underline{I} - \underline{A}^{-} \underline{A})]^{-} = \begin{pmatrix} .08333 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

and

$$AHXY(I) = AGA(I,J) * HHXY(I) = (\underline{I} - \underline{A}^{-} \underline{A}) \underline{X}' \underline{y} = \begin{pmatrix} 163.1 \\ 0 \\ 0 \end{pmatrix}$$

$$AGQ(I) = AGINV(I,J) * Q(I) = \underline{A}^{-} \underline{a} = \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix}.$$

To complete the computation of conditional error we must calculate:

$$HGB(I) = C(I,J) * AGQ(I,J) = \underline{X}' \underline{X} \underline{A}^{-} \underline{a} = \begin{pmatrix} 150 \\ 1101 \\ 925 \end{pmatrix}$$

hence

$$AXA = AGQ(I) * HGB(I) = \underline{a}' (\underline{A}^{-})' \underline{X}' \underline{X} \underline{A}^{-} \underline{a} = 2026$$

and

$$AXY = AGQ(I) * HHXY(I) = \underline{y}' \underline{X} (\underline{I} - \underline{H} \underline{H}^{-} \underline{H}) \underline{A}^{-} \underline{a} = 2205.3$$

$$2*AXY = 4410.6$$

the total sum of squares under the null hypothesis is

$$ZZ = TOTSS - AXY + BA + AXA = \underline{y}' \underline{y} + 2 \underline{y}' \underline{X} \underline{A}^{-} \underline{a} + 0 + \underline{a}' (\underline{A}')^{-} \underline{X}' \underline{X} \underline{A}^{-} \underline{a} = 22.27$$

and

$$CAPAGQ(I) = CA(J,I) * AGQ(I) = (\underline{I} - \underline{A}^{-} \underline{A}) (\underline{X}' \underline{X}) \underline{A}^{-} \underline{a} = \begin{pmatrix} 150 \\ 0 \\ 0 \end{pmatrix}$$

thus

$$AHXY(I) = AHXY(I) - CAPAGQ(I,J) = (\underline{I} - \underline{A}^{-} \underline{A}) \underline{X}' \underline{y} - (\underline{I} - \underline{A}^{-} \underline{A}) \underline{X}' \underline{X} \underline{A}^{-} \underline{a}$$

$$= \begin{pmatrix} 13.1 \\ 0 \\ 0 \end{pmatrix}.$$

The parameters under the null hypothesis $\hat{\beta}_0$ are estimated as

$$\text{BETA}(I) = \text{CG}(I,J) * \text{AHXY}(I) = \begin{bmatrix} 1.0917 \\ 0 \\ 0 \end{bmatrix}$$

and

$$\text{BAHXY} = \text{BETA}(I) * \text{AHXY}(I) = \hat{\beta}_0 [(\underline{I} - \underline{A} \underline{A}^{-1} \underline{A}) \underline{X}' \underline{y} - (\underline{I} - \underline{A} \underline{A}^{-1} \underline{A}) \underline{X}' \underline{X} \underline{A}^{-1} \underline{a}] = 14.3008$$

The conditional error is

$$\text{ESSO} = \text{ZZ} - \text{BAHXY} = 7.9691$$

and the sum of squares due to the hypothesis is

$$\text{SSHO} = \text{ESSO} - \text{ESS} = 7.5191$$

To complete the Analysis of Variance Table the remainder sum of squares, the hypothesis mean square and the F ratio are calculated as

$$\text{REM} = \text{BH} - \text{SSHO} = 2398.9$$

$$\text{HYMS} = \text{SSHO}/\text{RANKA} = 3.75956$$

$$F = \text{HYPMS}/\text{ERRMS} = 75.20026$$

This completes the programs calculations for this data and the model.

The output is given on the following page.

TITLE, TESTS THE H_0 THAT THE SLOPES OF $Y = B_1X_1 + B_2X_2 + A$ EQUAL 1.

PARAMETERS, 4, 12, 0, 0, 1, 1.

(F1, 0, 2, F2, 0, F3, 1)

BETA = -0.0117 0.9345 1.2737

TITLE, TESTS THE HO THAT THE SLOPES OF $Y = B_1X_1 + B_2X_2 + A$ EQUAL 1.

COVARIANCE MATRIX FOR BETA

0.6002	4.1013	3.4011
4.1013	32.5104	22.5572
3.4011	22.5572	23.7076
(	4F2.0)	

TITLE, TESTS THE H_0 THAT THE SLOPES OF $Y = \beta_1 X_1 + \beta_2 X_2 + A$ EQUAL 1.

THE HYPOTHESIS MATRIX

0.1.0.1.

0.0.1.1.

ANALYSIS OF VARIANCE FOR HYPOTHESIS 1

SOURCE	D.F.	SUM OF SQUARES	MEAN SQUARES	F	PROB
TOTAL	12	2406.86899			
REGRESSION	3	2406.41884			
DUE TO H_0	2	7.51908	3.75954	75.16675	0.00000
REMAINDER	1	2398.89966			
ERROR	9	0.45014	0.05002		

Example 3.2 Now we will examine the computations involved when a restriction other than zero, is imposed upon the model. Suppose one has a set of observations which seem to lie on the exponential curve. The model is derived from $e^{ax} = 1 + ax + \frac{a^2 x^2}{2!} + \frac{a^3 x^3}{3!} + \dots$ and is approximated by $y = \alpha + \beta_1 X + \beta_2 X^2 + \beta_3 X^3$.

The observations y and the X matrix are

$$\underline{X} = \begin{pmatrix} 1 & .1 & .01 & .001 \\ 1 & .2 & .14 & .008 \\ 1 & .3 & .09 & .027 \\ 1 & .4 & .16 & .064 \\ 1 & .5 & .25 & .125 \\ 1 & .6 & .36 & .216 \\ 1 & .7 & .49 & .343 \\ 1 & .8 & .64 & .512 \\ 1 & .9 & .81 & .729 \\ 1 & 1.0 & 1.00 & 1.000 \\ 1 & 1.1 & 1.21 & 1.331 \\ 1 & 1.2 & 1.44 & 1.728 \\ 1 & 1.3 & 1.69 & 2.197 \\ 1 & 1.4 & 1.96 & 2.744 \\ 1 & 1.5 & 2.25 & 3.375 \end{pmatrix}, \quad \underline{y} = \begin{pmatrix} 1.1 \\ 1.2 \\ 1.3 \\ 1.4 \\ 1.6 \\ 1.8 \\ 2.0 \\ 2.2 \\ 2.4 \\ 2.7 \\ 3.0 \\ 3.3 \\ 3.6 \\ 4.1 \\ 4.5 \end{pmatrix}$$

The restriction imposed upon the model is $\alpha = 1$ and the hypothesis of interest are

$$H_0: \begin{pmatrix} \beta_1 = 1 \\ \beta_2 = \frac{1^2}{2!} = .5 \\ \beta_3 = \frac{1^3}{3!} = .167 \end{pmatrix} \quad \text{vs} \quad H_a: \text{not } H_0$$

and then each β_i is tested separately.

The $\underline{X}'\underline{X}$ matrix is computed as

$$\begin{array}{c}
 \underline{X}'\underline{X} \\
 \text{XPX(I,J)} = \left\{ \begin{array}{ccccc} 15.0 & 12.0 & 12.4 & 14.4 & | & 36.2 \\ 12.0 & 12.4 & 14.4 & 17.8 & | & 35.6 \\ 12.4 & 14.4 & 17.8 & 22.9 & | & 41.1 \\ 14.4 & 17.8 & 22.9 & 30.4 & | & 51.0 \\ \hline 36.2 & 35.6 & 41.1 & 51.0 & | & 103.9 \end{array} \right\} \begin{array}{c} \underline{X}'\underline{Y} \\ \\ \\ \\ \underline{Y}'\underline{Y} \end{array}
 \end{array}$$

The restriction matrix, $\underline{H}$ is read as

$$\underline{H}(\underline{I}, \underline{J}) = (\underline{H}, \underline{b}) = \begin{bmatrix} 1 & 0 & 0 & 0 & | & 1 \\ \hline & & & & & b \end{bmatrix}$$

and

$$\underline{HGINV}(\underline{I}, \underline{J}) = \underline{H}^- = \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

thus

$$\underline{HGH}(\underline{I}, \underline{J}) = \underline{H}^- \underline{H} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

and

$$\underline{HGH}(\underline{I}, \underline{J}) = \underline{I} - \underline{H}^- \underline{H} = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

To complete the calculations of the design matrix under the restriction, we must find the following matrices

$$D(I,J) = HGH(I,J) * XPX(I,J) = (\underline{I} - \underline{H} \underline{H}^{-} \underline{H}) \underline{X}' \underline{X} = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 12.0 & 12.4 & 14.4 & 17.8 \\ 12.4 & 14.4 & 17.8 & 22.9 \\ 14.4 & 17.8 & 22.9 & 30.4 \end{pmatrix}$$

and the new restricted design is

$$C(I,J) = D(I,J) * HGH(I,J) = (\underline{I} - \underline{H} \underline{H}^{-} \underline{H}) \underline{X}' \underline{X} (\underline{I} - \underline{H} \underline{H}^{-} \underline{H}) = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 12.4 & 14.4 & 17.8 \\ 0 & 14.4 & 17.8 & 22.9 \\ 0 & 17.8 & 22.9 & 30.4 \end{pmatrix}$$

where

$$CG(I,J) = [(\underline{I} - \underline{H} \underline{H}^{-} \underline{H}) \underline{X}' \underline{X} (\underline{I} - \underline{H} \underline{H}^{-} \underline{H})]^{-} = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 8.16 & -15.87 & 7.19 \\ 0 & -15.87 & 32.88 & -15.51 \\ 0 & 7.19 & -15.51 & 7.52 \end{pmatrix}$$

In order to compute $\hat{\beta}$, a series of vectors are computed as

$$HHXY(I) = HGH(I,J) * XPX(I,NIV) = (\underline{I} - \underline{H} \underline{H}^{-} \underline{H}) \underline{X}' \underline{Y} = \begin{pmatrix} 0 \\ 35.6 \\ 41.1 \\ 51.0 \end{pmatrix}$$

and

$$HGB(I) = \underline{H} \underline{H}^{-} \underline{b} = \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

thus

$$XHB(I) = XPX(I,J) * HGB(I) = \underline{X}' \underline{X} \underline{H} \underline{H}^{-} \underline{b} = \begin{pmatrix} 15.0 \\ 12.0 \\ 12.4 \\ 14.4 \end{pmatrix}$$

and

$$HXHB(I) = HGH(I,J) * XHB(I) = (\underline{I} - \underline{H} \underline{H}^{-} \underline{H}) \underline{X}' \underline{X} \underline{H}^{-} \underline{b} = \begin{pmatrix} 0 \\ 12.0 \\ 12.4 \\ 14.4 \end{pmatrix}$$

hence

$$HXY(I) = HHXY(I) - HXHB(I) = (\underline{I} - \underline{H} \underline{H}^{-} \underline{H}) \underline{X}' \underline{y} - (\underline{I} - \underline{H} \underline{H}^{-} \underline{H}) \underline{X}' \underline{X} \underline{H}^{-} \underline{b} = \begin{pmatrix} 0 \\ 23.6 \\ 28.7 \\ 36.6 \end{pmatrix}$$

so $\hat{\underline{\beta}}$ is

$$BETA(I) = CG(I,J) * HXY(I) = \begin{pmatrix} 0 \\ .8690 \\ .5178 \\ .3027 \end{pmatrix}.$$

The rest of the calculations for the remaining analysis is similar to that of Example 3.1.

The output is as follows.

TITLE, TESTS THE FIT OF THE EXPONENTIAL CURVE $Y=A+B_1X+B_2X^2+B_3X^3+E$.

PARAMETERS, 5, 15, 1, 0, 4, 1.

(F1.0, F2.1, F3.2, F4.3, 1X, F2.1)

(SF1.0)

R ² T ² =	0.0	0.8690	0.5178	0.3027
---------------------------------	-----	--------	--------	--------

TITLE, TESTS THE FIT OF THE EXPONENTIAL CURVE $Y=A+B_1X_1+B_2X_2+B_3X_3+E$.

COVARIANCE MATRIX FOR BETA

0.0	0.0	0.0	0.0
0.0	0.0128	0.0148	0.0184
0.0	0.0148	0.0184	0.0237
0.0	0.0184	0.0237	0.0314

(4F2.0,1 X,F6.4)

TITLE, TESTS THE FIT OF THE EXPONENTIAL CURVE $Y=A+81X1+B2X2+B3X3+E$.

THE HYPOTHESIS MATRIX

0.1.0.0. 1.0000

0.0.1.0. 0.5000

0.0.0.1. 0.1670

ANALYSIS OF VARIANCE FOR HYPOTHESIS 1

SOURCE	D.F.	SUM OF SQUARES	MEAN SQUARES	F	PROB
TOTAL	15	46.49996			
REGRESSION	3	46.48761			
DUE TO H_0	3	0.18986	0.06329	61.45992	0.00000
REMAINDER	0	46.29773			
ERROR	12	0.01236	0.00103		

TITLE, TESTS THE FIT OF THE EXPONENTIAL CURVE $Y=A+B_1X_1+B_2X_2+B_3X_3+E$.

THE HYPOTHESIS MATRIX

0.1.0.0. 1.0000

ANALYSIS OF VARIANCE FOR HYPOTHESIS 2

SOURCE	D.F.	SUM OF SQUARES	MEAN SQUARES	F	PROB
TOTAL	15	46.49996			
REGRESSION	3	46.48761			
DUE TO HO	1	0.00210	0.00210	2.03919	0.17879
REMAINDER	2	46.48550			
ERROR	12	0.01236	0.00103		

TITLE, TESTS THE FIT OF THE EXPONENTIAL CURVE $Y=A+B_1X_1+B_2X_2+B_3X_3+E$.

THE HYPOTHESIS MATRIX

0.0.1.0. 0.5000

ANALYSIS OF VARIANCE FOR HYPOTHESIS 3

SOURCE	D.F.	SUM OF SQUARES	MEAN SQUARES	F	PROB
TOTAL	15	46.49996			
REGRESSION	3	46.48761			
DUE TO HO	1	0.00000	0.00000	0.00349	1.00000
REMAINDER	2	46.48761			
ERROR	12	0.01236	0.00103		

TITLE, TESTS THE FIT OF THE EXPONENTIAL CURVE $Y=A+B_1X_1+B_2X_2+B_3X_3+E$.

THE HYPOTHESIS MATRIX

0.0.0.1. 0.1670

ANALYSIS OF VARIANCE FOR HYPOTHESIS 4

SOURCE	D.F.	SUM OF SQUARES	MEAN SQUARES	F	PROB
TOTAL	15	46.49996			
REGRESSION	3	46.48761			
DUE TO HO	1	0.00244	0.00244	2.37432	0.14929
REMAINDER	2	46.48515			
ERROR	12	0.01236	0.00103		

Example 3.3 In regression analysis one is often interested in finding out whether sets of coefficients in two linear regressions are equal. The example from Gujarati [4] studies the linear relationship between savings (y) and income (X) for a set of n_1 observations. Suppose that on additional n_2 observations were obtained on the same variables but under different conditions.

Assuming savings and income are linearly related, the model is:

$$\underline{y} = \alpha + \delta_1 + \delta_2 + \beta X + \gamma_1 X_1 + \gamma_2 X_2 + e$$

where $\alpha = \frac{1}{2} (\delta_1 + \delta_2)$, the average intercept; $\beta = \frac{1}{2} (\gamma_1 + \gamma_2)$, the average slope; γ_1, γ_2 are the slopes and δ_1, δ_2 are the intercepts of the regression lines.

The data vector, y , and the design matrix are

$$\underline{X} = \begin{pmatrix} 1 & 1 & 0 & 8.8 & 8.8 & 0 \\ 1 & 1 & 0 & 9.4 & 9.4 & 0 \\ 1 & 1 & 0 & 10.0 & 10.0 & 0 \\ 1 & 1 & 0 & 10.6 & 10.6 & 0 \\ 1 & 1 & 0 & 11.0 & 11.0 & 0 \\ 1 & 1 & 0 & 11.9 & 11.9 & 0 \\ 1 & 1 & 0 & 12.7 & 12.7 & 0 \\ 1 & 1 & 0 & 13.5 & 13.5 & 0 \\ 1 & 1 & 0 & 14.3 & 14.3 & 0 \\ 1 & 0 & 1 & 15.5 & 0 & 15.5 \\ 1 & 0 & 1 & 16.7 & 0 & 16.7 \\ 1 & 0 & 1 & 17.7 & 0 & 17.7 \\ 1 & 0 & 1 & 18.6 & 0 & 18.6 \\ 1 & 0 & 1 & 19.7 & 0 & 19.7 \\ 1 & 0 & 1 & 21.1 & 0 & 21.1 \\ 1 & 0 & 1 & 22.8 & 0 & 22.8 \\ 1 & 0 & 1 & 23.9 & 0 & 23.9 \\ 1 & 0 & 1 & 25.2 & 0 & 25.2 \end{pmatrix}, \quad \underline{y} = \begin{pmatrix} .36 \\ .21 \\ .08 \\ .20 \\ .10 \\ .12 \\ .41 \\ .50 \\ .43 \\ .59 \\ .90 \\ .95 \\ .82 \\ 1.04 \\ 1.53 \\ 1.94 \\ 1.75 \\ 1.99 \end{pmatrix}$$

The set of restrictions to be imposed are $\delta_2 = 0$ and $\gamma_2 = 0$ which results in columns 3 and 5 of the design matrix being set to zeros. This results

in a model which is identical to Gujarati's dummy variable model.

The hypothesis of interest is to test equality of the slopes and equality of the intercepts. Since γ_2 and δ_2 were equated to zero the hypothesis to be tested becomes

$$\begin{array}{l} \delta_1 = 0 \\ \text{Ho: } \gamma_1 = 0 \end{array}$$

The resulting Analysis of Variance Table is as follows:

TEST FOR EQUALITY BETWEEN SETS OF COEFFICIENTS IN TWO LINEAR REGRESSIONS.

PARAMETERS,7,18,2,0,1,0.

(3F1.0,3(1X,F3.1),1X,F3.2)

(7(F1.0))

BETA =	-1.7502	1.4839	0.0	0.1505	-0.1034	0.0
	(	7(F2.0)	)			

TEST FOR EQUALITY BETWEEN SETS OF COEFFICIENTS IN TWO LINEAR REGRESSIONS.

THE HYPOTHESIS MATRIX

0.1.0.0.0.0.0.

0.0.0.0.1.0.0.

ANALYSIS OF VARIANCE FOR HYPOTHESIS 1

SOURCE	D.F.	SUM OF SQUARES	MEAN SQUARES	F	PROR
TOTAL	18	17.78919			
REGRESSION	4	17.45643			
DUE TO MD	2	0.23945	0.11973	5.03713	0.02249
REMAINDER	2	17.21696			
ERROR	14	0.33276	0.02377		

This is the type of approach used by the standard programs except the restrictions, usually are $\gamma_1 + \gamma_2 = 0$ and $\delta_1 + \delta_2 = 0$. Another approach perhaps a more meaningful one would be to use

$$\underline{X} = \begin{pmatrix} 1 & 0 & 8.8 & 0 \\ 1 & 0 & 9.4 & 0 \\ 1 & 0 & 10.0 & 0 \\ 1 & 0 & 10.6 & 0 \\ 1 & 0 & 11.0 & 0 \\ 1 & 0 & 11.9 & 0 \\ 1 & 0 & 12.7 & 0 \\ 1 & 0 & 13.5 & 0 \\ 1 & 0 & 14.3 & 0 \\ 0 & 1 & 0 & 15.5 \\ 0 & 1 & 0 & 16.7 \\ 0 & 1 & 0 & 17.7 \\ 0 & 1 & 0 & 18.6 \\ 0 & 1 & 0 & 19.7 \\ 0 & 1 & 0 & 21.1 \\ 0 & 1 & 0 & 22.8 \\ 0 & 1 & 0 & 23.9 \\ 0 & 1 & 0 & 25.2 \end{pmatrix}$$

as the design matrix and place no restrictions on this model. The two hypothesis are $H_{01}: \gamma_1 - \gamma_2 = 0$ vs $H_{a1}: \gamma_1 - \gamma_2 \neq 0$ and $H_{02}: \delta_1 - \delta_2 = 0$ vs $H_{a2}: \delta_1 - \delta_2 \neq 0$. We could also test these simultaneous if we wish ie

$$H_0: \begin{pmatrix} \delta_1 - \delta_2 \\ \gamma_1 - \gamma_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \text{ vs } H_a: \text{not } H_0$$

This results in answering which parameters are different - the intercepts or the slopes. The Analysis of Variance Table is given as

TEST FOR EQUALITY BETWEEN SETS OF COEFFICIENTS IN TWO LINEAR REGRESSIONS.

PARAMETERS, 7, 18, 0, 1, 2, 0.

SUBSCRIPTS, 2, 3, 5, 6, 7.

(3F1.0, 3(1X, F3.1), 1X, F3.2)

BETA = -0.2662 -1.7502 0.0470 0.1505

(4F3.0, F 2.0)

TEST FOR EQUALITY BETWEEN SETS OF COEFFICIENTS IN TWO LINEAR REGRESSIONS.

THE HYPOTHESIS MATRIX

1.-1. 0. 0.0.

ANALYSIS OF VARIANCE FOR HYPOTHESIS 1

SOURCE	D.F.	SUM OF SQUARES	MEAN SQUARES	F	PROR
TOTAL	18	17.78919			
REGRESSION	4	17.45643			
DUE TO HO	1	0.23658	0.23658	9.95324	0.00702
REMAINDER	3	17.21985			
ERROR	14	0.33276	0.02377		

TEST FOR EQUALITY BETWEEN SETS OF COEFFICIENTS IN TWO LINEAR REGRESSIONS.

THE HYPOTHESIS MATRIX

0. 0. 1.-1.0.

ANALYSIS OF VARIANCE FOR HYPOTHESIS 2

SOURCE	D.F.	SUM OF SQUARES	MEAN SQUARES	F	PROB
TOTAL	18	17.78919			
REGRESSION	4	17.45643			
DUE TO HO	1	0.22982	0.22982	9.66890	0.00769
REMAINDER	3	17.22661			
ERROR	14	0.33276	0.02377		

Example 3.4 The final example involves a two way analysis of variance (without interaction) with missing observations. The rows are five pollinators, columns are five female lines and the observations, y are the yield in pounds of sugar beets for the resulting crosses. The model used to analyze the crossing system is

$$y_{ijk} = \mu + \beta_i + \tau_j + e_{ijk}$$

where μ is the general mean, β_i is the general combining ability of the i th female line and τ_j is the general combining ability of the j th pollinator. The design matrix $\underline{X}$ and the observation vector $\underline{y}$ are:

$$\underline{X} = \begin{pmatrix} 1 & 1 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ 1 & 1 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\ 1 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \\ 1 & 0 & 1 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 1 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\ 1 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 1 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 1 & 0 & 0 & 1 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 1 & 0 & 1 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 1 \end{pmatrix}, \underline{y} = \begin{pmatrix} 124.2 \\ 128.0 \\ 108.0 \\ 112.9 \\ 115.6 \\ 107.9 \\ 112.6 \\ 129.2 \\ 93.1 \\ 122.6 \\ 133.6 \\ 142.6 \\ 118.4 \\ 121.6 \\ 133.9 \\ 107.5 \end{pmatrix}$$

No restrictions are imposed on the design and the hypothesis to be tested are

$$H_{01}: F_1 = F_2 = F_3 = F_4 = F_5 \quad \text{vs} \quad H_{a1}: \text{not } H_{01}$$

and

$$H_{02}: P_1 = P_2 = P_3 = P_4 = P_5 \text{ vs } H_{a2}: \text{not } H_{02}.$$

The hypothesis matrices $\underline{A}_1$ and $\underline{A}_2$ are

$$\underline{A}_1 = \begin{pmatrix} 0 & 1 & -1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & | & 0 \\ 0 & 1 & 1 & -2 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & | & 0 \\ 0 & 1 & 1 & 1 & -3 & 0 & 0 & 0 & 0 & 0 & 0 & | & 0 \\ 0 & 1 & 1 & 1 & 1 & -4 & 0 & 0 & 0 & 0 & 0 & | & 0 \end{pmatrix}$$

$\underline{a}$

and

$$\underline{A}_2 = \begin{pmatrix} 0 & 0 & 0 & 0 & 0 & 0 & 1 & -1 & 0 & 0 & 0 & | & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 1 & -2 & 0 & 0 & | & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 1 & 1 & -3 & 0 & | & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 1 & 1 & 1 & -4 & | & 0 \end{pmatrix}$$

$\underline{a}$

One should note the program can be used to analyze any model of a diallel crossing system, with the usual AOV programs cannot do.

The resulting AOV tables are

ESTIMATING GENERAL COMBINING ABILITY FROM AN INCOMPLETE CROSSING SYSTEM

PARAMETERS, 12, 16, 0, 0, 2, 1.

(11F1.0, F4.1)

BETA =	83.3517	20.1159	12.1826	11.0574	24.1628	15.8330	18.1179	23.2747
	34.8639	-1.3091	8.4044					

ESTIMATING GENERAL COMBINING ABILITY FROM AN INCOMPLETE CROSSING SYSTEM

COVARIANCE MATRIX FOR BETA

157.8573	29.5982	29.5982	29.5982	29.5982	39.4643	49.3304	39.4643
29.5982	9.8661	29.5982	29.5982				
29.5982	0.0	0.0	0.0	0.0	0.0	9.8661	9.8661
0.0	0.0	9.8661					
29.5982	0.0	29.5982	0.0	0.0	0.0	9.8661	9.8661
0.0	0.0	9.8661					
29.5982	0.0	0.0	29.5982	0.0	0.0	9.8661	0.0
9.8661	9.8661	0.0					
29.5982	0.0	0.0	0.0	29.5982	0.0	9.8661	9.8661
9.8661	0.0	0.0					
39.4643	0.0	0.0	0.0	0.0	39.4643	9.8661	9.8661
9.8661	0.0	9.8661					
49.3304	9.8661	9.8661	9.8661	9.8661	9.8661	49.3304	0.0
0.0	0.0	0.0					
39.4643	9.8661	9.8661	0.0	9.8661	9.8661	0.0	39.4643
0.0	0.0	0.0					
29.5982	0.0	0.0	9.8661	9.8661	9.8661	0.0	0.0
29.5982	0.0	0.0					
9.8661	0.0	0.0	9.8661	0.0	0.0	0.0	0.0
0.0	9.8661						
29.5982	9.8661	9.8661	0.0	0.0	9.8661	0.0	0.0
0.0	0.0	29.5982					

(2F2.0,4 F3.0,F2.0,4F3.0,F2.0)

ESTIMATING GENERAL COMBINING ABILITY FROM AN INCOMPLETE CROSSING SYSTEM

THE HYPOTHESIS MATRIX

0.1.-1. 0. 0. 0.0. 0. 0. 0. 0.0.

0.1. 1.-2. 0. 0.0. 0. 0. 0. 0.0.

0.1. 1. 1.-3. 0.0. 0. 0. 0. 0.0.

0.1. 1. 1. 1.-4.0. 0. 0. 0. 0.0.

ANALYSIS OF VARIANCE FOR HYPOTHESIS 1

SOURCE	D.F.	SUM OF SQUARES	MEAN SQUARES	F	PROB
TOTAL	16	230769.83594			
REGRESSION	9	230700.77339			
DUE TO HO	4	320.82137	80.20540	8.12941	0.00908
REMAINDER	5	230379.93750			
ERROR	7	69.06255	9.86608		

ESTIMATING GENERAL COMBINING ABILITY FROM AN INCOMPLETE CROSSING SYSTEM

THE HYPOTHESIS MATRIX

0.0. 0. 0. 0.1.-1. 0. 0. 0.0.

0.0. 0. 0. 0.1. 1.-2. 0. 0.0.

0.0. 0. 0. 0.1. 1. 1.-3. 0.0.

0.0. 0. 0. 0.1. 1. 1. 1.-4.0.

ANALYSIS OF VARIANCE FOR HYPOTHESIS 2

SOURCE	D.F.	SUM OF SQUARES	MEAN SQUARES	F	PROB
TOTAL	16	230769.83594			
REGRESSION	9	230700.77339			
DUE TO HO	4	1394.79935	348.69995	35.34331	0.00010
REMAINDER	5	229305.93750			
ERROR	7	69.06255	9.86608		

APPENDIX

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MAIN

FORTAN IV G LEVEL 21

C THIS PROGRAM WILL ESTIMATE UP TO 15 PARAMETERS (BETA VECTOR) BY USE
C OF GENERALIZED INVERSES AND TEST HYPOTHESIS ABOUT THE PARAMETERS.

C INPUT CARDS

C 1. TITLE

C 2. PARAMETERS, NOV, NR, NRH, NS, NH, COV.

C THE PARAMETER CARD MUST HAVE THESE 6 VALUES EACH IMMEDIATELY

C FOLLOWED BY A COMMA, EXCEPT THE LAST VALUE WHICH MUST BE

C IMMEDIATELY FOLLOWED BY A PERIOD.

C 3. SUBSCRIPTS,

C (OPTIONAL)

C 4. XFORMAT

C DATA FOR X MATRIX

C IF THERE ARE NO CHANGES IN SUBSCRIPTS THE LAST VARIABLE READ IN

C EACH ROW OF X MUST BE Y, THE OBSERVATION OR DEPENDENT VARIABLE.

C 5. HFORMAT

C DATA FOR H

C THE LAST VALUE OF H IS TO BE AN ELEMENT OF THE B VECTOR, WHERE

C B=H*BETA.

C 6. AFORMAT

C THE SAME A FORMAT IS USED FOR ALL THE HYPOTHESIS MATRICES

C 7. HYPOTHESIS, NRA, NPRINT.

C NRA IS THE NUMBER OF ROWS OF THE A MATRIX IT MUST BE IN CARD

C COLUMN 13 OR 12 AND 13 BOTH.

C NPRINT CAN BE 0 OR 1 IF IT IS 1 THE HYPOTHESIS MATRIX, A WILL

C BE PRINTED

C DATA FOR A

C THE LAST VALUE OF A MUST BE AN ELEMENT OF THE Q VECTOR, WHERE

C Q=A*BETA.

C NOV IS THE TOTAL NUMBER OF VARIABLES READ FROM THE X MATRIX

C THIS INCLUDES THE Y OBSERVATION.

C NR IS THE NUMBER OF ROWS IN X, ONE ROW MAY BE ON ONE OR MORE CARDS,

C BUT THERE IS NOT TO BE MORE THAN ONE ROW PER CARD.

C THE A AND H MATRIX MUST ALSO FOLLOW THE ABOVE STIPULATION.

C NRH IS THE NUMBER OF ROWS OF THE H RESTRICTION MATRIX, IF THIS IS

C 0 NO RESTRICTIONS ARE IMPOSED ON THE X MATRIX, HENCE NO HFORMAT CARD

C NOR H DATA MATRIX.

C NS ARE THE NUMBER OF SUBSCRIPT CARDS. THIS ENABLES ONE TO CHANGE THE

C ORDER THE VARIABLES ARE READ IN OR TO IGNORE SOME OF THE VARIABLES

C IN THE ANALYSIS. ALL THE INDEPENDENT VARIABLES MUST BE FIRST

C AND IMMEDIATELY FOLLOWED BY A COMMA WHILE THE DEPENDENT VARIABLE

C Y IS TO BE LAST SUBSCRIPT AND FOLLOWED IMMEDIATELY BY A PERIOD.

C NH IS THE NUMBER OF HYPOTHESIS TO BE TESTED, IT MUST BE AT LEAST 1

C COV IS EITHER 0 OR 1 .A 1 INDICATES THE COVARIANCE MATRIX OF BETA

C IS TO BE PRINTED.

C DIMENSION ID(20), X(100), IPARM(80)

C REAL*8 TITLE(10), FMT(10), XPX(16,16), D(15,15), HXY(15),

C 1 AGINV(15,15), CG(15,15), CAG(15,15), AGA(15,15), Q, SSQ, ESSD, BAHXY,

C 2 C(15,15), AHXY(15), HGR(15), XHR(15), XHX(15), XHXD(15), RXR, BHXY, TOTSS, ESS

C REAL*8 HGINV(15,15), BETA(15), AXA, HGH(15,15), A(16,16),

C 1 H(16,16), B, AGQ(15), CAPAGQ(15), HA, AXY, CAG(15,15), HXHB(15),

C 2 AHXR(15), RH, HHXY(15), FMTH(15), ERRMS, FT(17,35),

C INTEGER W(6), R(5), COMMA(17), PERIOD(17), OFE, DFR, COV

C INTEGER NUMS(10)/0,1,2,3,4,5,6,7,8,9/

C EQUIVALENCE (HGH(1,1), AGA(1,1))

C EQUIVALENCE (H(1,1), CAG(1,1), A(1,1)), (HGINV(1,1), AGINV(1,1))

C 169 READR(50, END=600) TITLE

C 50 FORMAT(10A8)

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FORTRAN IV G LEVEL 21

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0010 WRITE(W,51) TITLE
0011 51 FORMAT('1',///,25X,10A8)
0012 54 FORMAT('0',25X,10A8)
0013 L=-1
0014 GO TO 66
0015 166 NOV=1D(1)
0016 NR=1D(2)
0017 NRH=1D(3)
0018 NS=1D(4)
0019 NH=1D(5)
0020 COV=1D(6)
0021 NIV=NOV
0022 IF(NS.EQ.0) GO TO 62

C
C DECODES THE PARAMETER AND SUBSCRIPT CARDS.
C
0023 66 READ(R,53) IPARM
0024 53 FORMAT(80A1)
0025 WRITE(W,55) IPARM
0026 55 FORMAT('0',25X,80A1)
0027 L=L+1
0028 J=1
0029 IF(L.GT.1) GO TO 63
0030 IEND=0
0031 NIV=0
0032 J=12
0033 NUM=0
0034 65 DO 59 I=1,10
0035 IF(IPARM(J).NE.NUMS(I)) GO TO 59
0036 NUM=NUM+10*(I-1)
0037 GO TO 60
0038 59 CONTINUE
0039 60 J=J+1
0040 IF(J.EQ.81) GO TO 66
0041 IF(IPARM(J).EQ.COMMA) GO TO 61
0042 IF(IPARM(J).EQ.PERIOD) GO TO 64
0043 GO TO 65
0044 IEND=1
0045 61 NIV=NIV+1
0046 IF(NIV.GT.61) GO TO 500
0047 J=J+1
0048 IF(J.EQ.81) GO TO 66
0049 ID(NIV)=NUM
0050 IF(L.EQ.0.AND.NIV.EQ.6) GO TO 166
0051 IF(IEND.NE.0) GO TO 68
0052 GO TO 63
0053 62 DO 67 I=1,NOV
0054 67 ID(I)=I

C
C READ FORMAT FOR DESIGN MATRIX X & OBSERVATIONS Y, WHERE Y=X0+E.
C
0055 68 READ (R,50) FMT
0056 WRITE(W,54) FMT
0057 DO 5 I=1,NIV
0058 DO 5 J=1,NIV
0059 5 XPX(I,J)=0.000
0060 READS X AND Y.
0061 DO 1 K=1,NR

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FORTRAN IV G LEVEL 21 MAIN

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0061 READ(R,FMT)(X(I),I=1,NOV)
C
C COMPUTES X'X,X'Y AND Y'Y.
C
DO 3 I=1,NIV
  II=IO(I)
DO 3 J=1,NIV
  JJ=JO(J)
  3 XPX(I,J)=X(II)*X(JJ)+XPX(I,J)
  1 CONTINUE
  8=0.000
C NC IS THE NUMBER OF COLUMNS OF H
  NC=NIV-1
  IF(NRH.EQ.0) GO TO 118
C READ FORMAT FOR (H,B) MATRIX
  READ(R,50) FMT
  WRITE(W,54) FMT
C
C RFADS (H,B) , THE RESTRICTION MATRIX.
C
C
DO 11 I=1,NRH
  11 READ(R,FMT) (H(I,J),J=1,NIV)
DO 117 I=1,NRH
  117 B=H(I,NIV)*H(I,NIV)*8
DO 7 I=1,NRH
DO 7 J=1,NC
  7 HGINV(I,J)=H(I,J)
  CALL GINV(HGINV,NC,NRH)
  CALL MULT(HGINV,NC,NRH,H,NC,HGH,16)
C
C COMPUTES I-H_H
C
C
DO 8 I=1,NC
DO 8 J=1,NC
  IF(I.EQ.J) HGH(I,J)=-(1.000-HGH(I,J))
  8 HGH(I,J)=-HGH(I,J)
  GO TO 121
  118 DO 120 I=1,NC
DO 119 J=1,NC
  119 HGH(I,J)=0.000
  120 HGH(I,J)=1.000
  121 CALL MULT(HGH,NC,NC,XPX,NC,D,16)
  CALL MULT(D,NC,NC,HGH,NC,C,15)
DO 85 I=1,NC
DO 85 J=1,NC
  85 CG(I,J)=C(I,J)
  CALL GINV(CG,NC,NC)
  ESS=0.000
  BXR=0.000
  RHXY=0.000
DO 20 I=1,NC
DO 20 J=1,NC
  HXY(I)=0.000
DO 20 J=1,NC
  HXY(I)=HXY(I)+HGH(I,J)*XPX(J,NIV)
  20 HXY(I)=HXY(I)
  20 IF(B.EQ.0.000) GO TO 21
DO 22 I=1,NC
  HGB(I)=0.000

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FORTRAN IV G LEVEL 21

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0109      DO 22 J=1,NRH
0109      22 HGB(I)=HGB(I)+HGINV(I,J)*H(J,NIV)
0110      DO 23 I=1,NC
0110      XHB(I)=0.000
0111      DO 23 J=1,NC
0111      23 XHB(I)=XHB(I)+XPX(I,J)*HGB(J)
0114      DO 24 I=1,NC
0114      HXHB(I)=0.000
0115      DO 24 J=1,NC
0115      24 HXHB(I)=HXHB(I)+HGH(I,J)*XHB(J)
0116      DO 25 I=1,NC
0116      25 HXY(I)=HXY(I)-HXHB(I)
0117      DO 26 I=1,NC
0117      26 BXR=BXR+HGB(I)*XHB(I)
0118      DO 27 I=1,NC
0118      27 BXY=BXY+HGB(I)*XPX(I,NIV)
0119      BXY=2.0*BXY
0120      BETAI=0.000
0121      DO 19 J=1,NC
0121      BETAI(BETAI)+CG(I,J)*HXY(J)
0122      WRITE(W,155) (BETAI(I),I=1,NC)
0123      155 FORMAT('0.5X','BETA = ',8F14.4,7(/.13X,8F14.4))
0124      TOTSS=XPX(NIV,NIV)-BXY*BXR
0125      C
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0153 C
0154 127 NHYP=0
0155 150 FORMAT(A1,A7,9A8)
0156 READ (R,150) FMT
0157 WRITE(W,54) FMT
0158 FMTH(1)=FT
0159 DO 190 I=2,10
0160 190 FMTH(I)=FMT(I)
0161 C IF NPRINT = 1 THE HYPOTHESIS MATRIX WILL BE PRINTED
0162 160 READ(R,130)NRA,NPRINT
0163 130 FORMAT(11X,12,1X,11)
0164 NHYP=NHYP+1
0165 C
0166 READS (A,Q) THE HYPOTHESIS MATRIX
0167 C
0168 DO 30 I=1,NRA
0169 30 READ(R,FMT) (A(I,J),J=1,NIV)
0170 IF (NPRINT.NE.1) GO TO 135
0171 WRITE(W,191)TITLE
0172 191 FORMAT('1',///,25X,10A8,///,35X,'THE HYPOTHESIS MATRIX')
0173 DO 192 I=1,NRA
0174 192 WRITE(W,FMT) (A(I,J),J=1,NIV)
0175 135 Q=0.000
0176 DO 131 I=1,NRA
0177 131 Q=Q+A(I,NIV)*A(I,NIV)
0178 DO 31 I=1,NRA
0179 31 AGINV(I,1)=A(I,J)
0180 CALL GINV(AGINV,NC,NRA)
0181 CALL MULT(AGINV,NC,NRA,A,NC,AGA,16)
0182 C
0183 COMPUTES THE RANK OF A
0184 C
0185 RANKA=0
0186 DO 36 I=1,NC
0187 36 RANKA=RANKA+AGA(I,1)
0188 C
0189 COMPUTES I-A_A
0190 C
0191 DO 34 I=1,NC
0192 34 J=1,NC
0193 IF (I.EQ.J) AGA(I,J)=-(1.000-AGA(I,J))
0194 34 AGA(I,J)=-AGA(I,J)
0195 C
0196 COMPUTES THE RANK OF :
0197 ((I-H_H)*X(I-H_H)(I-A_A))_((I-H_H)*X(I-H_H)(I-A_A) OR D
0198 C
0199 CHECKS THE ESTIMABILITY AND TESTABILITY OF THE HYPOTHESIS.
0200 C
0201 CALL MULT(C,NC,NC,AGA,NC,CA,15)
0202 DO 37 I=1,NC
0203 37 J=1,NC
0204 CAG(J,I)=CA(I,J)
0205 CALL GINV(CAG,NC,NC)
0206 CALL MULT(CAG,NC,NC,CAG,NC,D,15)
0207 RANKQ=0
0208 DO 38 I=1,NC

```

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0193      38 RANKQ=RANKQ+D(I,I)
0194      1A=RANKA+.005
0195      IQ=RANKQ+.005
0196      IF(IQ.NE.(IX-IA)) GO TO 503
C
C
C      ESTAMITING BETA AND CONDITIONAL ERROR UNDER THE HYPOTHESIS A.
0197      DO 40 I=1,NC
0198      AHXY(I)=0.000
0199      DO 40 J=1,NC
0200      40 AHXY(I)=AHXY(I)+AGA(I,J)*HHXY(J)
0201      ZZ=TOTSS
0202      IF(I8.EQ.0.000) GO TO 71
0203      DO 41 I=1,NC
0204      AHXHB(I)=0.000
0205      DO 41 J=1,NC
0206      41 AHXHB(I)=AHXHB(I)+AGA(I,J)*HXHB(J)
0207      71 IF(I8.EQ.0.000) GO TO 48
0208      DO 42 I=1,NC
0209      AGQ(I)=0.000
0210      DO 42 J=1,NRA
0211      42 AGQ(I)=AGQ(I)+AGINV(I,J)*A(J,NIV)
C
C
C      COMPUTES Z*Z THE TOTAL SUM OF SQUARES UNDER THE HYPOTHESIS
0212      DO 83 I=1,NC
0213      HGR(I)=0.000
0214      DO 83 J=1,NC
0215      83 HGR(I)=HGR(I)+C(I,J)*AGQ(J)
0216      AXA=0.000
0217      DO 84 I=1,NC
0218      AXA=AXA+AGQ(I)*HGR(I)
0219      RA=0.000
0220      IF(I8.EQ.0.000) GO TO 87
0221      DO 89 I=1,NC
0222      89 RA=RA+HXHB(I)*AGQ(I)
0223      RA=2.0*RA
0224      87 AXI=0.000
0225      DO 86 I=1,NC
0226      AXI=AXI+AGQ(I)*HHXY(I)
0227      AXI=2.0*AXI
0228      ZZ=TOTSS-AXI+RA+AXA
0229      DO 43 I=1,NC
0230      CAPAGQ(I)=0.000
0231      DO 43 J=1,NC
0232      43 CAPAGQ(I)=CAPAGQ(I)+CA(J,I)*AGQ(J)
0233      IF(IQ.NE.0.000) GO TO 47
0234      GO TO 48
0235      47 IF(I8.EQ.0.000) GO TO 72
0236      DO 74 I=1,NC
0237      74 AHXY(I)=AHXY(I)-AHXHB(I)-CAPAGQ(I)
0238      GO TO 81
0239      72 DO 73 I=1,NC
0240      73 AHXY(I)=AHXY(I)-CAPAGQ(I)
0241      GO TO 81
0242      48 IF(I8.NE.0.000) GO TO 75
0243      GO TO 81
0244      75 DO 76 I=1,NC

```

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```

0245 76 AHXY(I)=AHXY(I)-AHXHB(I)
0246 81 CALL MULTTGA,NC,NC,CA,NC,D,15)
0247 DO 39 I=1,NC
0248 DO 39 J=1,NC
0249 39 CG(J,I)=D(I,J)
0250 CALL GINV(CG,NC,NC)
0251 DO 82 I=1,NC
0252 BETA(I)=0.000
0253 DO 82 J=1,NC
0254 82 BETA(I)=BETA(I)+CG(I,J)*AHXY(J)
0255 BAHXY=0.000
0256 DO 88 I=1,NC
0257 88 BAHXY=BAHXY+BETA(I)*AHXY(I)
0258 ESSO=ZZ-BAHXY

```

```

C
C
C COMPUTES THE ANALYSIS OF VARIANCE TABLE.

```

```

0259 SSHO=ESSO-ESS
0260 IF(NPRINT.NE.1) WRITE(W,51)TITLE
0261 WRITE(W,400) NHYP
0262 400 FORMAT('0',////,35X,'ANALYSIS OF VARIANCE FOR HYPOTHESIS ',I2,///)
0263 WRITE(W,401)
0264 401 FORMAT('0',10X,'SOURCE',11X,'D.F.',10X,'SUM OF SQUARES',8X,'MEAN
      1 SQUARES',10X,'F',14X,'PROB')
0265 WRITE(W,402) NR,TOTSS
0266 402 FORMAT('0',10X,'TOTAL',10X,15,F22.5)
0267 WRITE(W,403) IX,RH
0268 403 FORMAT('0',10X,'REGRESSION',8X,12,F22.5)
0269 HYPMS=SSHO/RANKA
0270 F=HYPMS/ERRMS
0271 PROR=F/PROB(RANKA, FLOAT(DFE),F)
0272 WRITE(W,404) IA,SSHO,HYPMS,F,PROB
0273 404 FORMAT('0',13X,'DUE TO HO',8X,12,2(F22.5),2(F15.5))
0274 REM=RH-SSHO
0275 DFR=IX-1A
0276 WRITE(W,405)DFR,REM
0277 405 FORMAT('0',13X,'REMAINDER',8X,12,F22.5)
0278 WRITE(W,406) DFE,ESS,ERRMS
0279 406 FORMAT('0',10X,'ERROR',10X,15,2F22.5)
0280 IF(NH.NE.NHYP) GO TO 160
0281 GO TO 169
0282 503 WRITE(W,502)IA,IX,IQ
0283 502 FORMAT('0',10X,'THE HYPOTHESIS IS NOT TESTABLE',/,10X,'RANK A = ',
      113,3X,'RANK X = ',13,3X,'RANK Q = ',13)
0284 IF(NH.NE.NHYP) GO TO 160
0285 GO TO 169
0286 500 WRITE(W,501)
0287 501 FORMAT('0', 'THE NUMBER OF VARIABLES EXCEEDS THE MAXIMUM OF 60, HEN
      1CE THE PROGRAM IS TERMINATED.')
0288 600 STOP
0289 END

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MULT

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```

0001 SURROUTINE MULT(F,N,M,S,K,R,IS)
0002 REAL*8 F(15,15),S(IS,IS),R(15,15)
0003 DO 1 I=1,N
0004   DO 1 L=1,K
0005     R(I,L)=0.000
0006   DO 1 J=1,M
0007     1 R(I,L)=R(I,L)+F(I,J)*S(J,L)
0008   RETURN
0009 END

```


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GINV

```

0001 SUBROUTINE GINV(A,NR,NC)
0002 REAL*8 A(15,15),U(15,15),AFLAG(15),ATEMP(15)
0003 REAL*8 FAC,DOT1,DOT2,TOL,DSORT,DOT,SMALL,DABS,DOTA,DOTU
0004 SMALL=1.0D-16
0005 DO 150 I=1,NR
0006 DO 150 J=1,NC
0007 IF(DABS(A(I,J)).LT.SMALL) A(I,J)=0.000
0008 DO 10 I=1,NC
0009 DO 5 J=1,NC
0010 U(I,J)=0.000
0011 U(I,I)=1.000
0012 DOTA=0.000
0013 DO 101 J1=1,NR
0014 DOTA=DOTA+A(J1,I)*A(J1,I)
0015 FAC=DOTA
0016 IF(FAC) 11,12,11
0017 11 FAC=1.000/DSORT(FAC)
0018 IF(NG,EQ.1) FAC=1.000/DOTA
0019 DO 15 I=1,NR
0020 A(I,I)=A(I,I)*FAC
0021 IF(NG,EQ.1) GO TO 1400
0022 DO 20 I=1,NC
0023 U(I,I)=U(I,I)*FAC
0024 AFLAG(I)=1.000
0025 N=32
0026 TOL=(10.*0.5**N)**2
0027 DO 100 J=2,NC
0028 DOTA=0.000
0029 DO 250 J1=1,NR
0030 DOTA=DOTA+A(J1,J)*A(J1,J)
0031 DOT1=DOTA
0032 J1=J-1
0033 DO 50 L=1,2
0034 DO 30 K=1,J1
0035 DOTA=0.000
0036 DO 299 J1=1,NR
0037 DOTA=DOTA+A(J1,J)*A(J1,K)
0038 ATEMP(K)=DOTA
0039 30 CONTINUE
0040 DO 45 K=1,J1
0041 DO 35 I=1,NR
0042 A(I,J)=A(I,J)-ATEMP(K)*A(I,K)*AFLAG(K)
0043 DO 40 I=1,NC
0044 U(I,J)=U(I,J)-ATEMP(K)*U(I,K)
0045 45 CONTINUE
0046 50 CONTINUE
0047 DOTA=0.000
0048 DO 545 J1=1,NR
0049 DOTA=DOTA+A(J1,J)*A(J1,J)
0050 DOT2=DOTA
0051 IF(DOT2-(DOT1*TOL)) 55,55,70
0052 55 DO 60 I=1,J1
0053 ATEMP(I)=0.000
0054 DO 60 K=1,I
0055 ATEMP(I)=ATEMP(I)+U(K,I)*U(K,J)
0056 DO 65 I=1,NR
0057 A(I,J)=0.000

```

C DEPENDENT COL TOLERANCE FOR N BIT FLOATING POINT FRACTION

```

0058      DO 65 K=1,JM1
0059      65 A(I,J)=A(I,J)-A(I,K)*ATEMP(K)*AFLAG(K)
0060      AFLAG(J)=0.000
0061      DOTU=0.000
0062      DO 601 J1=1,NC
0063      601 DOTU=DOTU+U(J1,J)*U(J1,J)
0064      FAC=DOTU
0065      IF(FAC) 66,75,66
0066      66 FAC=1.000/DSQRT(FAC)
0067      GO TO 75
0068      70 AFLAG(J)=1.000
0069      FAC=1.000/DSQRT(DOT2)
0070      DO 80 I=1,NR
0071      80 A(I,J)=A(I,J)*FAC
0072      DO 85 I=1,NC
0073      85 U(I,J)=U(I,J)*FAC
0074      100 CONTINUE
0075      DO 130 J=1,NC
0076      DO 130 I=1,NR
0077      FAC=0.000
0078      DO 120 K=J,NC
0079      120 FAC=FAC+A(I,K)*U(J,K)
0080      130 A(I,J)=FAC
0081      1400 RETURN
0082      END

```

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FPROB

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0001 FUNCTION FPROB(U,V,F)
 CFPROC F-PROBABILITY VIA CONVERGENT SERIES OF POSITIVE TERMS
 C

```

0002 A=.5*U
0003 B=.5*V
0004 TEMP=R+A*F
0005 X=A*F/TEMP
0006 FPROB=1.0
0007 IF (F.LE.0.0.OR.X.LE.0.0)RETURN
0008 XC=B/TEMP
0009 AB=A+B
0010 CON=0.
0011 SGN=+1.
0012 IF (F.GE.1.0)GO TO 120
0013 TEMP=A
0014 A=R
0015 B=TEMP
0016 TEMP=XC
0017 XC=X
0018 X=TEMP
0019 CON=1.
0020 SGN=-1.
    C 120 CONVERGENT SERIES EXPANSION - SEE AMS-55 PG. 944
      TOP=AB
      BOT=B+1.
      SUM=1.
      TERM=1.
    130 TEMP=SUM
      TERM=TERM*(TOP/BOT)*XC
      SUM=SUM+TERM
      TOP=TOP+1.
      BOT=BOT+1.
      IF (SUM.GT. TEMP)GO TO 130
      FPROB=CON+SGN*EXP(A*ALOG(X)+B*ALOG(XC)+ALGAMA(AB)-ALGAMA(A)
      1 -ALGAMA(B))*SUM/B
      RETURN
    END
0032
0033
```

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```

0001      CALGAMA      LOG GAMMA FUNCTION
0002      FUNCTION ALGAMA(A)
0003      W=A
0004      TEMP=0.
0005      IF(W.GT.13.)GO TO 120
0006      N=14.-W
0007      TEMP=1.
0008      DO 110 I=1,N
0009      TEMP=TEMP*W
0010      110 W=W+1.
0011      TEMP=ALOG(TEMP)
0012      120 W2=W*W
0013      ALGAMA=(-.833333333D-01-(-.27777777D-02--.793650793D-03/W2)/W
0014      1+.918938533D-04*(W-.5)*ALOG(W))-TEMP
          RETURN
          END

```

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COMPUTATIONAL TECHNIQUES FOR THE ANALYSIS OF
THE GENERAL LINEAR MODEL

by

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AN ABSTRACT OF A MASTER'S REPORT

submitted in partial fulfillment of the
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Computational procedures and computer programs for estimation of the parameters of standard statistical linear models, and testing of the usual hypothesis about the parameters of these models have been available for some time. However, there are experimental situations where the corresponding linear models are different from the standard statistical linear model. Hence, one is unable to properly analyze the model or test the desired hypothesis with these standard programs.

This study involves translating theoretical techniques of analyzing a linear model with various types of restrictions into computational procedures suitable for programming. The first part of the study is concerned with the computational techniques of parameter estimation and hypothesis testing. These techniques are used to analyze the most general linear statistical model with an uncorrelated error structure, provide flexibility in the restrictions imposed upon the model (if a researcher wishes to do so) and test any desired testable hypothesis.

The second portion of this study is composed of some illustrative examples to exhibit the versatility of the developed techniques in the statistical analysis. These computational procedures were implemented in a computer program which is provided in the appendix.