ANALYSIS OF THE EFFECT OF DISTANCE AND WEIGHT AS A DETERMINANT OF POSTURAL CONFIGURATIONS OF A SEATED WORKER

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by

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INTRODUCTION-

The analysis of the effect of distance and weight is a seldom expressed combination when referred to the subject of postural configurations. Such men as Morgan (12), Maynard (10), Caldwell (2) have written books and articles on lifting forces and/or controlling muscle action when moving objects while in a standing position. Hunsicker (8) and Caldwell (2) have contributed much to seating characteristics when the strength of arm extension is involved. The subject of postural configuration implies the disposition of relative parts of the human body. To determine the optimum location of over the counter shelf installation, the relationship of weight and distance must be explored. This may be achieved by measuring the body distortion from a natural seated position while using two handed operations. This would involve different degrees of weight and various shelf heights.

The point of issue in this investigation is to evaluate a prototype mockup model of a corridor designed kitchen and its relation with over the counter shelf heights and objects of different weights. This will involve the human factors and body mechanics principles that apply to the limitation of manual activity of female workers at a seated work station.

Much of the past research is oriented around the experimental situation of finding an average work height to do some particular household function. Roberts, Wilson and Thayer (13) were authors of a bulletin, in 1937, being one of the first groups to conduct studies concerned with work surface heights satisfactory for women in the home. This involved studying kitchen work, ironing, sewing and storage units such as closets and drawers. In 1959, McCracken and Richardson (11) conducted studies to locate the best heights for storage of household goods and compared the energy costs of different designs of

storage. These studies included standing and sitting postures, one and two handed operations, and shelves of various heights and depths.

Anatomical studies on the range of joints by use of living subjects were made by Brown and Slater-Hammel (1), Hugh Jones (7), Dempster (3), Gaughan and Dempster (5) and Whitney (17). These studies are unsatisfactory in their relation to industry and commercial outlets because the data are not readily applicable. Dempster, Gabel, and Felts (4) was one of the first groups to attempt an approach to dynamic anthropometry. Their method of data collection was by use of planimeter measurements of areas obtained by the use of light tracings on photographic negatives. The light tracings represented a series of motions. A light was placed on the subject's hand and motions of the shoulder, elbow and wrist combinations would generate a light tracing. This technique defined some limits for a work space.

The extent of this thesis will encompass the measurement of the seated subject's body configurations while lifting objects to shelves. These sequences involving weight and shelf height, were filmed and then the deviations from the normal seated position were measured by use of a Veeco mechanical arm and a mirror device. A statistical analysis of the data was made to determine weight when related to the experimental corridor kitchen model.

DEVELOPMENT OF EXPERIMENTAL METHOD

During the review of literature which has been published concerning women performing tasks found in the home, it was noted that many of the studies were based on the use of respiratory measuring devices. Some studies involved the use of work simplification and methods improvement principles and were based on comparisons of old and new methods. The technique used in this thesis was similar to that studied by Dempster, Gabel, and Felts (4) which involved dynamic anthropometry.

The term dynamic anthropometry refers to the measurement of the individual body members working together to perform a task. As the body members
perform together, a work area is created relative to the body. This work area
has its outer limits determined by the anotomical structure of the individual
and may be referred to as a space envelope.

There are three major planes of the body denoted X, Y, and Z, each of which is perpendicular to the remaining two planes. The planes of the body are defined as:

- Sagittal plane a vertical plane from front to back, dividing the body in half.
- 2. Frontal plane a vertical plane from side to side, dividing the body in half.
- 3. Horizontal plane a horizontal plane dividing the body into upper and lower halves.

The sagittal, frontal, and horizontal planes each bisect the body, therefore, having a common intersection which may be defined as the center of gravity of that body. The axes of the body are defined as:

1. Vertical axis - that axis which is perpendicular to the ground.

- 2. Frontal axis that axis running horizontally from side to side.
- 3. Sagittal axis that axis running horizontally from front to back.

The variety of ways in which a body may move seems to be countless, but careful consideration of these movements reveal that there are two major classifications of movement. A body may turn about a center of motion or it can move in its entirety from one position to another. The first classification is called angular motion and may be illustrated in terms of levers and wheels. "Angular motion is characterized by movements about an axis with all parts of the object moving in an arc..." (15).

The second classification is translatory because an object is moved as a whole unit from one position to another. Translatory movement is defined in terms of rectilinear and curvilinear motion. "Rectilinear motion, ..., is defined as the linear progression of an object as a whole, with all its parts moving the same, in the same direction, and at a uniform rate of speed."

(15) Curvilinear is all translatory movement that is not classified as rectilinear motion.

Two examples of motion that may be calssified as angular and translatory are walking and riding a cycle. Most of the body joints display axial motion, therefore the related body segments display angular motion. As a result of the angular motion of the forearm and upper arm, the hand is able to have linear motion and when moving an object displays translatory motion.

The space envelope of interest in this study was the range of motion generated by the hands while the subject was in a seated position with the buttocks remaining semi-motionless on the seating surface of an experimental chair.

The envelope is an invisible surface representing the maximum range of motion of the hand while being moved in different directions. This space envelope

may be placed on an X, Y, and Z coordinate system having a size and shape relating to the chair seat and the subject's anatomical structure. The hip mark of the subject was selected as a reference point "O" which is the zero point of the coordinate system. With the hand or wrist mark being referenced directly to the point "O", the movements of the elbow, shoulder and trunk allow a broad range of translational movement. The space envelope generated by these movements is the combination of the range and freedom of the joints involved. The relative dimensions of limb segments in different people have a relationship, but this effect is small considering that they will create a space envelope of a distinctive shape and common to the average person when orientated to the same reference point (4).

Marking the Subject

The reference points which were measured by anthropometry, the science of measuring the human body and its parts, allowed the postural configurations of the subject to be measured from the filmed records through the use of a drafting machine. The subjects wore short shorts and a halter which allowed the markings to be placed directly on the body thus omitting some variation due to fit of clothing.

The age and weight of each subject were recorded because it was desired that each subject comply with an age and weight range so that a homogeneous population might be obtained. Along with the age and weight, various dimensions of body length and width were recorded for each subject involved in the sample population. The landmarks or points of interest were placed on the component parts of the body which generated the space envelope. Most of these landmarks were black adhesive tape but a grease pencil was used to mark the lines where the tape might cause skin irritation. The purpose of

each landmark is to be able to measure the amount of movement of a particular portion of the body while the subject performs a task. The landmarks were connected by a straight line which acted as a visual aid in determining the point at which a subject had completed the act of placing an object on a shelf. These lines were between adjacent landmarks and were of the same material, black adhesive tape or grease pencil, as the landmark in that region. Although, some of the landmarks are not utilized in the collection of data for this experiment; the method of measurement of each is included for possible future reference and/or for continued studies of the film.

The line on the subject which best relates the distortion of the body from the normal seated position is that which connects the shoulder landmark to that of the hip.

Method of Measurement

Each subject was measured and marked by the same person using the procedure set forth below. To facilitate measurement, the following instruments were used; anthropometer - this instrument has a horizontal bar which moves vertically along a fixed calibrated scale; calipers - a scaled bar with one fixed and one sliding jaw; and a steel tape measure. See Plate I.

- I. Stature standing
 - A. Instrument anthropometer
 - B. Procedure the crossbar was lowered until it rested on the vertex of the subject's head.
- II. Shoulder height standing
 - A. Instrument anthropometer
 - B. Procedure the crossbar was lowered until it rested on the acromion.

III. Elbow - standing

- A. Instrument anthropometer
- B. Procedure the subject bent her arm so that a right angle was formed by the outside of the arm (upper arm hanging straight). The crossbar was moved to elbow level.

IV. Waist - standing

- A. Instrument anthropometer
- B. Procedure the waist level used lies at the lower edge of the lowest rib and was found by palpating the sides of the body at the midaxillary line. The crossbar was lowered until it rested on this landmark.

V. Hip - standing

- A. Instrument anthropometer
- B. Procedure the measurer's hand palpated the region of the trochanter. A rounded region was thus located, the mid-point of which marked the hip level. The crossbar was lowered to rest on this landmark.

VI. Knee height (tibiale) - standing

- A. Instrument anthropometer
- B. Procedure the tibiale was taken as the highest point on the margin of the glenoid of the tibia when the subject stood erect. The crossbar was brought to rest on this landmark.

VII. Finger tip height - standing

- A. Instrument anthropometer
- B. Procedure the subject was asked to hold the fingers straight but not rigid. The crossbar was lowered until it was at the level of the middle finger tip.

EXPLANATION OF PLATE I

- Figure 1. Shows the subject being measured for the shoulder-elbow dimension by the use of the calipers.
- Figure 2. Shows the subjects shoulder-elbow line being marked with black adhesive tape.





FIGURE 1

FIGURE 2

VIII. Vertex of heat - sitting*

- A. Instrument anthropometer
- B. Procedure the crossbar was lowered to rest on the vertex of the subject's head.

IX. Shoulder - sitting

- A. Instrument anthropometer
- B. Procedure the crossbar was lowered to rest on the acromion process of the scapula.
- X. Elbow sitting
 - A. Instrument anthropometer
 - B. Procedure the subject bent her arm so that a right angle

 was formed by the outside of the arm (upper arm hanging straight).

 The crossbar was moved to the elbow level.

XI. Waist - sitting

- A. Instrument anthropometer
- B. Procedure the crossbar was lowered until it rested on the waist landmark (same as used in standing).

XII. Hip - sitting

- A. Instrument anthropometer
- B. Procedure the crossbar was lowered until it rested on the hip landmark.

XIII. Top of thigh - sitting

- A. Instrument anthropometer
- B. Procedure the crossbar was lowered to the thigh, subject moved forward until the greatest thickness of thigh was found.

^{*}The subject sat erect while sitting measurements were taken.

XIV. Height of top of knee - sitting

- A. Instrument anthropometer
- B. Procedure the crossbar was lowered to top of knee, just where the knee bends.

XV. Widest extension of hips or sitting width

- A. Instrument sliding caliper
- B. Procedure the measurer held the shaft parallel to the floor and placed the fixed bar at the furthest extension of the right hip. The movable bar was moved up to the left hip at the furthest extension.

XVI. Sitting length

- A. Instrument sliding caliper
- B. Procedure the measurer held the shaft of the caliper parallel to the floor and placed the fixed bar at the front of the knee.

 The movable bar was moved up against the buttocks.

XVII. Maximum span at working level - sitting

- A. Instrument steel tape
- B. Procedure subject leaned forward and reached as far along the counter top as possible. The distance measured was between the subject's middle fingertips.

XVIII. Normal span at working level - sitting

- A. Instrument steel tape
- B. Procedure subject placed hands along counter top without straining. The distance measured was between the subject's middle fingertips.

XIX. Sitting height above seat

Seat height of 36 inches was subtracted from vertex of head measurement.

- XX. Sitting eye-level above seat
 - A. Instrument anthropometer
 - B. Procedure the crossbar was lowered to a position so that the subject could see half under the crossbar.
- XXI. Elbow height above seat

Seat height of 36 inches was subtracted from elbow height measurement.

XXII. Shoulder to elbow

- A. Instrument sliding caliper
- B. Procedure the subject stood with normal, erect posture bending her right arm and placing a clenched fist on her hip with the back-side of the hand to the front. The fixed bar of the caliper was placed on the acromion process of the scapula and and the shaft was parallel with the outside of the upper arm.

 The movable bar was moved up against the elbow.

XXIII. Elbow to palm

- A. Instrument sliding caliper
- B. Procedure with the right arm bent at a right angle, the outside of the upper arm was placed against the fixed bar and the subject's forearm rested on the shaft of the caliper. The subject grasped the movable bar as it was moved up against the knuckle of the little finger and palm landmark.

Experimental Task

The primary object was to study postural configurations generated by the translational movements. This type of movement may be up and down, forward and backward, and right and left. This study was restricted to the first two of these, thus involving only movements in a vertical plane.

The primary records taken were micro-motion film showing the subject performing a series of specified tasks. A task consisted of lifting with both hands a covered baking pan (no pan. 0, 5 and 10 pounds) from the counter top and placing it on a designated shelf directly in front of the subject. The pan was placed to the rear of the nine inch deep shelf, released momentarily, regrasped, and returned to its original position on the counter in front of the subject.

The subject was asked to sit in a normal erect position, to start and finish each task with her hands resting on the counter edge and if possible to keep her feet within the rectangle marked on the foot rest. A series of sixteen tasks were composed by placing at random one of the four pan weights or the imaginary pan on one of the four shelves spaced ten inches apart. The subject was told that she could complete each task at her own pace.

An individual task began by having a helper set the desired pan in front of the subject. Directions were then read as to what shelf the pan was to be placed upon. The subject would then grasp the pan and complete the task.

See Plate II. As soon as a task was completed, the helper would replace this pan with the next pan in the sequence indicated by a random numbers table.

Directions concerning this new pan would then be read aloud to the subject.

This procedure continued until the subject completed the series assigned to her by use of random numbers. In order that the subject would understand

the directions as they were read, a preliminary series of tasks were given each subject after which they were given a rest period before testing.

Twenty-three female college students, with an age range of 18 to 21, formed the sample population. Their build was medium with reference to stature and wegith; rotund and thin types were excluded. The subjects selected were between 62 and 65 inches in height and were in the proper weight range as specified by Wessel (15). The most significant mean dimensions are shown below in Table 1.

TABLE 1

MOST SIGNIFICANT MEAN DIMENSIONS

Length (Inches)	Sample Std. Deviation(Inches)	Range (Inches)		
63.223	0.637	62.25 - 64.19		
47.073	2.479	42.25 - 55.19		
12.665	0.345	12.13 - 13.31		
12.565	0.420	11.94 - 13.50		
	(Inches) 63.223 47.073 12.665	(Inches) Deviation(Inches) 63.223 0.637 47.073 2.479 12.665 0.345		

EXPLANATION OF PLATE II

An overall view of the experimental set-up which includes subject, helper, person reading the directions, pan, and the subject's code number (A 8). The experimental set-up has four shelves with the counter top being number one, a shelf at ten inches designated number two, a shelf at twenty inches designated number three, and a shelf at thirty inches designated number four.

PLATE II



Apparatus

This experiment was performed in a full-scale mock-up model of an experimental kitchen. This kitchen is of the corridor design and has a chair mounted on a specially designed track which will allow it to move from one end of the counter to the other. For this experiment, the chair was not mobile but remained in one position at the counter. The chair and its relation to the counter and shelves is shown in Plate II.

The seat of this experimental chair was of a solid material, had a slope of approximately three degrees from front to back, and could revolve 360 degrees. The seat was equipped with a Michrohite seat height adjustment mechanism for adjustment of the seat from zero to twelve inches above its minimum height. This adjustment could not be made with the subject in the chair. The seat was positioned vertically so that the front edge of it was twelve inches below the counter top and it remained in this position throughout the experiment.

For the back of this chair, a large contour metal back rest was used which adjusted four ways - up and down, forward and backward. The back rest was adjusted to fit each subject in the small of the back.

A footrest which could be adjusted was mounted on the base portion of the chair. A rectangle, large enough to encircle both feet, was marked in the center of the footrest so that there would be a continuity in support by the legs from subject to subject.

A 16mm Paillard-Bolex, H 16 Reflex movie camera with a variable shutter was mounted on an adjustable tripod and positioned in such a manner that the camera lens was twenty feet from the subject's right shoulder. The camera was manually operated for each task of the series to allow the subject to work at her own pace. Eastman Tri-X. Type 7278, reversal safety film was

used to record the data on 100 foot rolls. The camera position and model kitchen relationship is shown in Plate III.

The film was reviewed and data taken from it by the use of a 16mm Bell & Howell time and motion study projector and a mirror device whose relationship is shown in Plate III. A Veeco mechanical drawing arm was employed to determine the angular movement involved.

The experiment was conducted in the Housing - Equipment Research Laboratory of the Department of Family Economics in Justin Hall, the Home Economics Building.

Experimental Design

In preparing the series of tasks to be randomly assigned to each subject, a random number table was used. Numbers one through sixteen were coded to designate a pan and a shelf, by using two numbers (n and n + 16 as n goes from 1 to 16) to designate the same task the process was shortened. These random numbers then designated the order of a series of tasks and were recorded on a chart such as Form A in the Appendix.

The experiment was analyzed according to a factorial classification for a randomized complete block design, fixed effects model similar to the example discussed in Snedecor (14) pages 338 to 343. This design has shelves and pan as factors, with three and four levels respectively. The subjects were blocks in the design and through the use of several subjects the fluctuations could be averaged out. An analysis of variance was computed with the following sources of variation pooled into error: shelves by individuals; pans by individuals; and shelves by pans by individuals. The model for this design therefore becomes,

$$Y_{ijk} = \mu + I_i + S_j + P_k + SP_{jk} + \varepsilon_{ijk}$$

EXPLANATION OF PLATE III

- Figure 1. A top view of the experimental set-up showing the relationship of the movie camera and the seated subject. A task involved moving Pan A to position Pan A' and then back to its original position.
- Figure 2. A side view of the apparatus used to obtain the data from the film. A mechanical arm (not shown) was used to measure the angle of movement as it was viewed on the object surface.

PLATE III

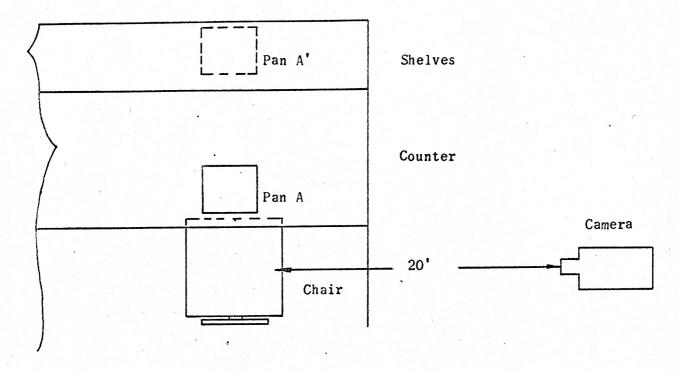


FIGURE 1

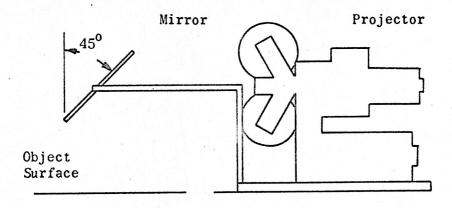


FIGURE 2

where μ = common or average effect, I_j = effect of the i^{th} individual, S_j = effect of the j^{th} shelf, P_k = effect of the k^{th} pan, SP_{jk} = additive effect of the k^{th} pan on the j^{th} shelf, and where ϵ_{ijk} is assumed to be a random variable drawn from a normal population with a mean of zero and a variance of σ^2 . In this model Y_{ijk} , measured in degrees, is an trunk movement observation from the vertical plane made of the i^{th} individual placing the k^{th} pan on the j^{th} shelf. This model assumes each observation to be a linear function of the factorial effect and the experimental error.

Using this design, it was possible to test several hypotheses related to the different pans and shelves utilized in the series of tasks. The first hypothesis to be tested was to evaluate any differences between the pan weights used. The effects of shelf heights used were tested by a second hypothesis. Interaction effects between shelves and pans were also tested. Each hypothesis was checked for significance by the use of an F-test. The hypotheses were as follows:

1. There is no difference in response due to different pan weights:

$$H_{01}$$
: $P_k = 0$ for $k = 1, 2, 3, 4$

 H_{AI} : $P_k \neq 0$ for some k

 $F_1 = \frac{\text{M.S. pans}}{\text{M.S. error}}$ reject if $F_1 \ge F \alpha$, k, error degrees of freedom

2. There is no difference in response due to different shelf heights:

$$H_{02}$$
: $S_j = 0$ for $j = 1, 2, 3, 4$

 $H_{A2} : S_j \neq 0$ for some j

 $F_2 = \frac{\text{M.S. shelves}}{\text{M.S. error}}$ reject if $F_2 \ge F \alpha$, j, error degrees of freedom

3. The effects of shelves is constant for all pans:

$$H_{03}$$
: $SP_{jk} = 0$ for all j and k = 1, 2, 3, 4

 H_{A3} : $SP_{jk} \neq 0$ for some j and k

 $F_3 = \frac{\text{M.S. pxs}}{\text{M.S. error}}$ reject if $F_3 \ge F \alpha$, (j-1) (k-1), error degrees of freedom

RESULTS AND DISCUSSION

The object of this experiment was to evaluate a prototype model of a corridor designed kitchen and its relation with over the counter shelf heights using objects of different weights which may be used from a seated position.

The subjects were assigned a series of tasks in random sequence which had been composed by using a random number table. Through the use of 16 mm film, each subject was studied as she performed her particular series of tasks. By a mechanical method the degrees of rotation of the subject's trunk, angle created by the line joining the hip and shoulder landmark moving from the normal seated position, were recorded for each task. This data was subject to two criteria before being recorded; these norms were:

- 1. The subject was not allowed to arise from the chair as an aid in placing a pan on any particular shelf.
- 2. The subject had to maintain some sort of a grip on the pan as it was being positioned.

The possibility of a test concerning shelf number four has been omitted from this experiment because all but one subject failed to comply with the norms above. The use of the experimental design allowed the following information to be compiled:

- Determine whether or not the response of subjects was different due to different pan weights. This response was measured in degrees as the subject performed the task with relation to pan weights.
- 2. Determine whether or not the response of subjects was different due to different shelf heights. The effect was tested as the shelf moved from counter top level to thirty inches at ten inch intervals.

- 3. A test as to whether or not there was interaction between the pans and shelves. This means a check to see if a subject had a shelf preference with a particular pan weight.
- 4. Test the variability between individuals to see if a difference in responce due to individuals was present.

The data was prepared in such a manner that it could be used in an IBM 1620 computer program which was applicable to the design of this experiment. The program and the output which contains the data and the complete analysis of variance are found in Form B of the Appendix.

The analysis of variance fitting this experimental design is shown in Table 2. Five degrees of freedom were lost due to the fact that there were five missing data which had to be estimated. Means were used for these estimations.

TABLE 2

Source	Degrees Freedom	Sum of Squares	Mean Squares	F
Individuals	17	1860.1	109.417	13.908*
Pans	3	139.7	46.567	5.919*
Shelves	2	901.5	450.750	57.296*
Pans X Shelves	6	99.7	16.617	2.112
Error	182	1431.7	7.867	
Total	210	4432.7		

^{*}Significant at .05 level.

The null hypothesis, H_{Ol} , which was tested by the F_1 -test was that there was no difference in response or angle of movement between pans (no pan, 0, 5, and 10 pounds) due to the weights of each pan. The alternate hypothesis, H_{Al} ,

was that there was a difference in response due to pan weight. The F_1 = 5.919 is greater than F (.05, 3, 182) = 2.66 and indicates a significant difference at the .05 level in the means due to pan weight.

The null hypothesis, H_{02} , which was tested by the F_2 -test was that there were no differences in response between shelves (counter top, ten inches, and twenty inches) due to the height of each shelf. The alternate hypothesis, H_{A2} , was that there was some effects due to shelf heights. The F_2 = 57.296 is greater than F (.05, 2, 182) = 3.05 indicates a significant difference at the .05 level in the means due to shelf height.

The null hypothesis, H_{03} , which was tested by the F_3 -test was that there was no interaction between pans and shelves, i.e., the effects of shelves is constant for all pans. The alternate hypothesis, H_{A3} , was that there was interaction between pans and shelves. The F_3 = 2.112 which is less than F (.05, 6, 182) = 2.15 indicates no significant interaction at the .05 level. It was noted however that without a pan as a guide, the subject tended to reach further into shelf one than the remaining shelves even though this effect did not lead to the rejection of H_{03} .

TABLE 3
PANS X SHELVES SUMMARY TABLE OF MEANS

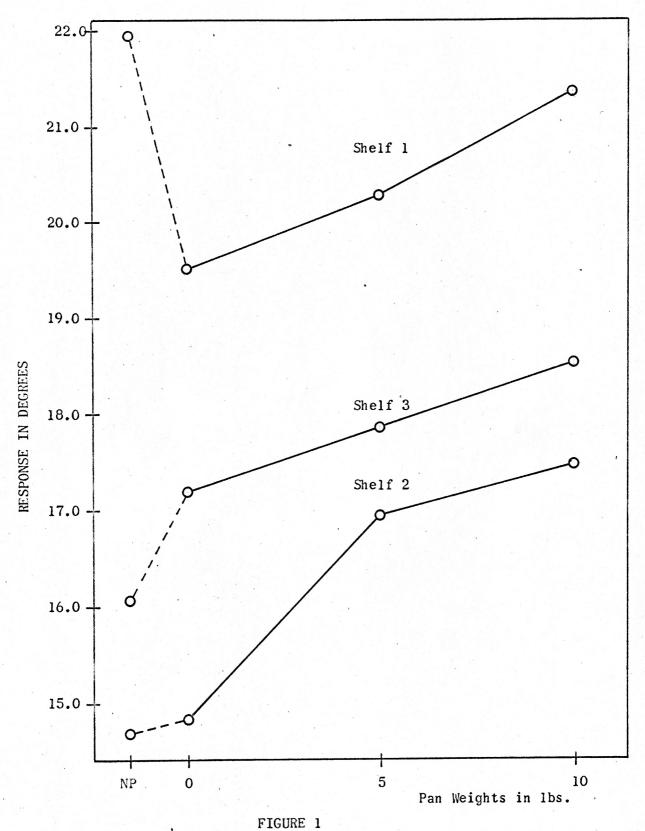
P_1	P_2	P ₃	P ₄	Shelf Mean
21.9674	19.4442	20.3377	21.3886	20.7843
14.6566	14.8007	16.9348	17.4213	15.9533
16.0205	17.1756	17.8330	18.5152	17.3861
17.5481	17.1402	18.3685	19.1083	
				18.0412
	21.9674 14.6566 16.0205	21.9674 19.4442 14.6566 14.8007 16.0205 17.1756	21.9674 19.4442 20.3377 14.6566 14.8007 16.9348 16.0205 17.1756 17.8330	21.9674 19.4442 20.3377 21.3886 14.6566 14.8007 16.9348 17.4213 16.0205 17.1756 17.8330 18.5152

Table 3 gives the mean for each pan-shelf combination used in this experiment. The means for pans averaged over shelves and shelves averaged over pans are also found in this table.

The relation of pan weight and response may be shown by plotting a response curve for each shelf as shown in Figure 1. The response curves are nearly parallel when comparing the individual shelves over pan weights, 0, 5, and 10 pounds. The "no pan" response is plotted and connected to the rest by a dotted line since it does not assume a specific weight and is used only as a visual aid. A study of the "no pan" relationship between shelves indicates that the subjects reach further into the lower shelf, this being number one or the counter top, than shelves number two and three. It would also indicate that there is a relationship between shelves in that the depth of reach is proportional to the height of the shelf.

The fact that shelf number two gave the smallest angle or response over each pan weight tested as seen in Figure 1 is better summarized in Figure 2. The relationship of the shelves shown in Figure 2 was found by plotting the means of the shelves averaged over the pans.

Since the shelf heights and pan weights were evenly spaced, a more detailed analysis was conducted to partition the pans, shelves, and pans by shelves interaction sums of squares into orthogonal comparisons. The linear and quadratic components for pans, shelves, and the interactions of the components for pans and shelves are given in Table 4. The coefficients are also given along with the sum of squares for each component. Pan 1 is compared to pans 2, 3, and 4 in line 1 of the table and the linear and quadratic comparisons of pan 1 are found in lines 10 and 11. Pan 1 was compared to the remaining pans and analyzed separately with respect to linear and quadratic



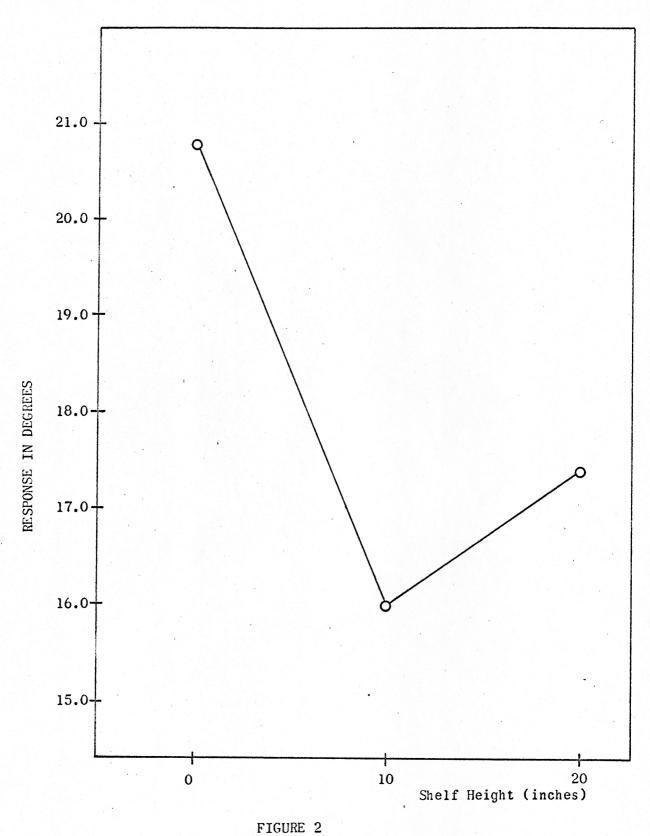
This is a graph of response vs. pan weights.

components for shelf height because its weight could not be given as a numerical measurement on the scale of pan weights. Each component may be tested for significance by computing $F = ((\Sigma c_i \bar{x}_i)^2 n/\Sigma c_i^2)/M$. S. error with 1 and error degrees of freedom. The orthogonal comparisons that are significant have been starred in the table.

In order that the results found in this experiment may be illustrated better, a response surface has been determined as shown in Figure 3. The equation for the response surface can be computed from the treatments, lines 2 through 9 in Table 4, but due to the fact that only the comparisons 2, 4, and 5 were significant, they were the only terms used in this equation. These three comparisons were responsible for 97.15 percent of the variability of the means over the nine experimental treatments. The equation for the response surface is,

$$Y = 16.386 + .984z - 1.274x + 2.730x^2$$

where z = (pan weight - 5)/5 and x = (shelf height - 10)/10. The method of orthogonal polynomials presented in Kendall and Stuart (9) on page 356 was used for the determination of the equation. Assuming that the response surface presented in Figure 3 approximates the true relationship between the response and treatments, it may be used to determine an optimum set of experimental conditions.

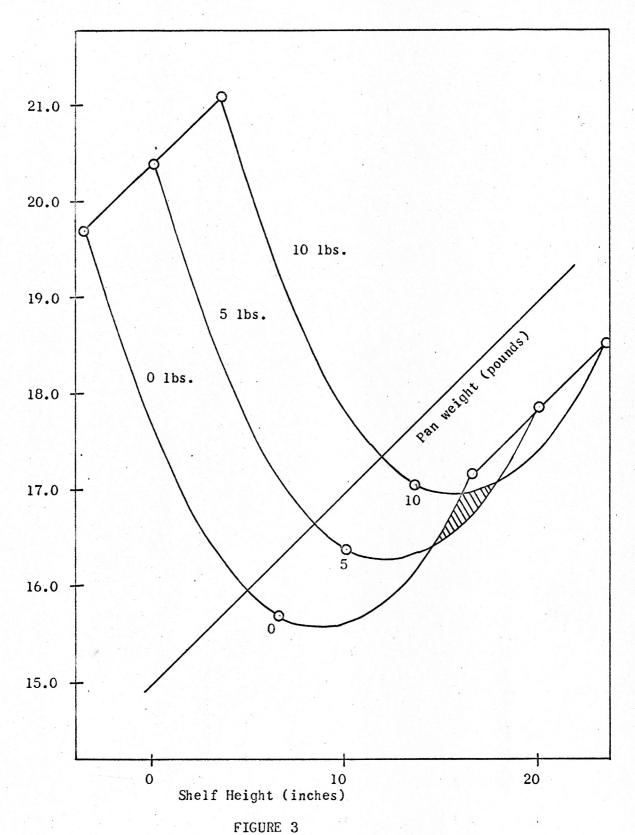


This is a graph of response vs. shelf means.

TABLE 4
ORTHOGONAL COMPARISONS

Line	Comparisons	P ₁ S ₁	P_1S_2	P ₁ S ₃	P ₂ S ₁	P_2S_1	P ₂ S ₃	P ₃ S ₁	P_3S_2	P ₃ S ₃	P ₄ S ₁	P_4S_2	P ₄ S ₃	$\sum c_i^2$	$\sum_{\mathbf{c_i}} \mathbf{\bar{x}_i}$	$\frac{\left(\sum c_{i}\bar{x}_{i}\right)^{2}n}{\sum c_{i}^{2}} -$	F
											,					T Z'i	
1	P ₁ to (P ₂ ,P ₃ ,P ₄)	-3	-3	-3	1	1	1	1	1	1	1	1	1	36	5.9176	17.5089	
2	Linear Pans	0	0	0	-1	-1	-1	0	0	0	1	1	1	6	5.9049	104.6034	*
3	Quadratic Pans	0	0	0	1	1	1	- 2	-2	- 2	1	1	1	18	-1.4654	2.1474	
4	Linear Shelves	0	0	0	-1	0	1	-1	0	1	-1	0	1	6	-7.6467	175.4160	*
5	Quadratic Shelves	0	0	. 0	1	-2	1	1	-2	-1	1	-2	1	18	16.3807	268.3273	*
6	Lin. Pans X Lin. Shelves	0	0	0	1	0	-1	0	0	0	- 1	0	1	4	6048	1,6461	
7	Lin. Pans X Quad. Shelves	0	0	0	-1	2	<u>-1</u>	0	0	0	1	-2	1	12	-1.9472	5.7459	
8	Quad. Pans X Lin. Shelves	0	0	0	-1	0	ì	2	0	-2	-1	0	1 .	12	1326	.0264	
9	Quad. Pans X Quad. Shelves	0	0	0	1	-2	1	-2	4	-2	1	-2	1	36	3.4774	6.0461	
10	Lin. for Pan 1	-1	0	1	0	0	0	Ô	0	0	0	0	0	2	-5.9469	318.2904	
11	Quad. for Pan 1	1	-2	1	0	0	0	0	0	0	0	0	0	6	8.6741	225.7200	N N
	Total															1125.4779	

^{*}Significance at the .05 level.



ridune o

This is a graph of the response curve with the shelf heights shown related to a pan weight of 5 lbs.

CONCLUSIONS

This experiment was conducted to evaluate a prototype model of a corridor designed kitchen and its relation with the over the counter shelf heights and objects of different weights. The data collected from the filmed sequences of designated tasks allowed several conclusions to be drawn from the experimental model through the use of a analysis of variance and an orthogonal polynomial.

The analysis of variance allowed the following conclusions to be drawn:

- 1. There was a significant difference in the angle of response due to the difference in object weight.
- 2. There was a significant difference in the angle of response due to the difference in shelf heights.
- 3. There was no significant interaction between pans and shelves.
- 4. There was a significant difference in response due to variability of individuals.

The above conclusions were based on F-tests at the .05 level.

The relationship of the shelves, found by plotting the means of the shelves averaged over the pans, implies that shelf number two (10 inches above the counter top) is the shelf height which requires the least body movement. Therefore, shelf number two was the optimum shelf height tested while doing seated tasks. Using the mean of all pans tested, shelf number two required 30.3 percent less trunk movement than shelf number one and 8.9 percent less trunk movement than shelf number three. The approximate response to a particular object weight and shelf height may be determined by using the response surface, Figure 3, or its equation. Taking the first derivative of the response surface equation with respect to X, setting it equal to zero and solving

for X, the optimum shelf height for the experimental kitchen being tested was found to be 12.33 inches above the counter top when doing seated tasks.

The relationship of the "no pan" and shelf height indicated that the depth of reach is proportional to the height of the shelf with the subject reaching further into the shelf as the shelf height approached the counter top.

Shelf number four was deleted from the experiment after it was found to be outside of the space envelope for the subjects when test procedures were followed.

The results of this experiment allows the positioning of utensils on different shelf heights according to object weight when considering minimum trunk movement which may be considered to be the least demanding in terms of effort. These results pertain only to two-handed, seated operations being performed by females with an age range of 18 to 21 and a specified height and weight range.

ACKNOWLEDGMENTS

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APPENDIX

FORM A

Name		Code
The following sequences was use	ed by this subject:	
Take pan	Place on shelf	
Take pan	place on shelf	
Take pan	place on shelf	
Take pan	place on shelf	· · · · · · · · · · · · · · · · · · ·
Take pan	place on shelf	
Take pan	place on shelf	
Take pan	place on shelf	
Take pan	place on shelf	- Communication of the Communi
Take pan	place on shelf	
Take pan	place on shelf	
Take pan	place on shelf	
Take pan	place on shelf	
Take pan	place on shelf	Language and the same of the s
Take pan	place on shelf	
Take pan	place on shelf	
Take pan	place on shelf	
Date	time	na pravincia protecta de la composició d

FORM B

IBM program print-out

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FORTRAM LISTING

3-WAY ANALYSIS OF VARIANCE, UP TO IEN LEVELS OF EACH FACTOR
COMPUTES ORTHOGONAL POLYNOMIALS OF FIRST THREE DEGREE FOR TWO FACT
UMIT POLYNOMIALS BY READING BLANK CARDS
USE FORMAT FOR DATA AND COEFFICIENT PUNCH INSTRUCTIONS
NN IS NO OF UBS PER CELL, DATA IS IN XIJH NOTATION AND
NN IS NO OF UBS PER CELL, DATA IN I, J,K ORDER, WITH THE
AND H=1 TO N LEVELS OF T PACK DATA IN I,J,K ORDER, WITH THE
NN CELL OBS PUNCHED ON A SINGLE CANDL MAX OF SEVEN)
PROGRAM USES ONE CONTROL CARD
PACK, CONTROL CARD, DATA, POLYNOMIAL MULTIPLIER(OR6BLANK), REPEAT
PACK, CONTROL CARD, DATA, POLYNOMIAL MULTIPLIER(OR6BLANK), REPEAT
FOR SEVERAL PROBLEM, LAST CARD IS A BLANK TO STOP ROUTINE
FOR SEVERAL PROBLEM, LAST CARD IS A BLANK TO STOP ROUTINE
J. TBAR(4), TI(42), TIRAR(4), TR(42,4), TRBAR(42,4), TT(42,4), TTBAR(4), TSBAR(4,4), TSBAR(4,4), RT(4), RTBAR(4), TE(4
DIMENSIONTLA(1,1), RLA(1,1)
DIMENSION TLA(10,10), RLA(10,10)
FORMAT(515)
PROBMAT(515)
PROBMAT(515)
PROBMAT(515)
PROBMAT(515)
                                                                                                                                                                                                                                                                                                   0
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                                                                                                                                                                                                                                                                                                     0
   04000 FORMAT(17X, 9HCOMPONENT, 17, 6HSS=---, E14.8)
09000 FORMAT(15F4.0)
07001 FORMAT(E20.10)
    00870 FORMAT(F20.10)
                                                                                                                                                                                                                                                                                                     0
     00003 FORMAT(F10.5)
    00004 FORMAT(1X,F1.0)
00005 FORMAT(2X,F1.0)
00006 FORMAT(3X,F1.0)
     00007 FORMAT (4X, F1.0)
     00008 FORMAT(5X, F1.0)
     00009 FORMAT(6X,F1.0)
00010 FORMAT(7X,F1.0)
     00011 FORMAT(8X, F1.0)
                     IFOR=0
     01000 READ(1,2)ID,L,M,N,NN
IFOR=IFOR+1
                     IF(L.EQ.O)STOP
                    CTSQ=0.0
                    WRITE(3,199) ID
                    ANN=NN
                    AL=L
                    \Delta N = N
                     \Delta M = M
                     TOTN=L*N*M*NN
                     TOT=0.0
                     TOTSQ=0.0
                     WRITE(3,831) NN
                     D050I=1,M
                     DU50J=1,L
                     D050K=1,N
                     CT(1,J,K)=0.0
GOTO(800,801,802,803,804,805,806,807,808),IFOR
      00800 DG502II=1,NN
      00502 READ(1,3)X(II)
                      GOTO12
       00801 D0503II=1,NA
      00503 READ(1,4)X(II)
GOTO12
       00802 D0504[[=1,NN
```

```
00504 READ(1,5)X(11)
GOTO12 .

00803 DO505[I=1,NN

00505 READ(1,6)X(II)
          GUTU12
00804 D0506II=1,NN
00506 READ(1,7)X(II)
GUT012
00805 00507[[=1,NN
00507 READ(1,8)X([I])
GOT012
00806 D0508[[=1,NN
00508 READ(1,9)X([[])
00807 DC509II=1,NN
00509 READ(1,10)X(II)
GOTU12
00808 DU510II=1,NN
00808 DU510II=1,NN

00510 READ(1,11)X(II)

00012 DU56II=1,NN

CT(I,J,K)=CT(I,J,K)+X(II)

TOT=TOT+X(II)

00056 TOTSQ=FOTSQ+X(II)*X(II)

CTSQ=CTSQ+CT(I,J,K)*CT(I,J,K)/ANN

CTBAR=CT(I,J,K)/ANN

00050 WRITE(3,7001)CTBAR

C CT ARE CELL TOTALS, HAVE SUM AND SUM OF SQUARES COMPUTED

BRANCH ARGUND MODIFICATION

GOTO6005
          G0T06005
00851 READ(1,9000)(TLA(1,K),K=1,1)
DO852[=1,1
00852 READ(1,9000)(RLA(I,J),J=1,1)
06005 DO471=1,M
          DO47J=1,L
00047 \text{ TR}(I,J)=0.0
          TRSQ=0.0
DU511=1,M
          D051J=1,L
          D053K=1,N
00051 TRBAR(I,J)=TR(I,J)/(AN*ANN)
          D0591=1,M
          D059K=1,N
00059 TI(I,K)=0.0
          TTS0=0.0
D060I=1.M
          D060K=1,N
          0063J = 1, L
D079J=1,L
          D079K=1,N
        TS(J,K)=0.0
TSSQ=0.0
CO70J=1,L
         DOTOK=1,N
00071 I= 1,M
00071 TS(J,K)=TS(J,K)+CT(I,J,K)
TSSQ=TSSO+TS(J,K)*TS(J,K)/(AM*ANN)
00070 TSBAR(J,K) = TS(J,K)/(AM*ANN)
          CFAC=TOT*TOT/TOTN
CTOTSQ=TOTSQ-CFAC
DO83J=1,L
00083 RT(J)=0.0
          RTSQ=0.0
          DC81J=1,L
00080 RT(J)=RT(J)+TS(J,K)
RTBAR(J)=RT(J)/(AM*AN*ANN)
00081 RTSQ=RTSQ+RT(J)*RT(J)/(AM*AN*ANN)
          D094K=1,N
00094 TE(K)=0.0
```

```
TESO=0.0
0091K=1.N
00090 J=1,L

00090 TE(K)=TE(K)+TS(J,K)

TBAR(K)=TE(K)/(AL*AM*ANN)

00091 TESO=TESO+TE(K)*TE(K)/(AM*AL*ANN)
                  D01001=1,M
                TI(I)=0.0
 00100
                 TISO=0.0
D0105I=1,M
                  D0106K=1,N
 00106 TI(I)=TI(I)+TT(I,K)
TIBAR(I)=TI(I)/(AN*AL*ANN)
                TISQ=TISQ+TI(I)*TI(I)/(AN*AL*ANN)
                  DFR=AL-1.0
                  DFS=4M-1.0
                 DFT=AN-1.0
DFRS=DFR*DFS
DFRT=DFR*DFT
                 DEST=DES*DET
DESRT=DEST*DER
               DFSRT=DFST*DFR

DFE=IOTN-1.0-DFR-DFS-DFT-DFRS-DFRT-DFSRT

CRSS=RTSQ-CFAC

CSSS=IISQ-CFAC

CTSS=TESQ-CFAC

CTSS=TESQ-CTSS-CSS-CFAC

CRSSS=ITSQ-CTSS-CSSS-CFAC

CRSSS=ITSQ-CTSS-CRSS-CFAC

CRSSS=ITSQ-CTSS-CRSS-CFAC

CRSSS=TSSQ-CFAC-CRSS-CSS-CTSS-CRSS-CTSS-CRTSS

ESS=CTOTSQ-CFAC-CRSS-CSS-CTSS-CRSS-CTSS-CRTSS

ESS=CTOTSQ-CFAC-CRSS-CSS-CTSS-CRSSS-CTSS-CRTSS

ESS=CTOTSQ-CFAC

RMS=CRSS/DFR

SMS=CRSS/DFR

TMS=CRSSS/DFT

RSMS=CRSSS/DFRI

RSTMS=CRSSS/DFRI

RSTMS=CRSSS/DFE

WRITE(3,205)N

WRITE(3,205)N

WRITE(3,205)((TRBAR(I,J),J=1,L),I=1,M) — 18 × 0
                WRITE(3,870) ((TRBAR(I,J),J=1,L),I=1,M)
WRITE(3,204)L
WRITE(3,870) ((TTBAR(I,K),K=1,N),I=1,M)
WRITE(3,203)M
WRITE(3,870) ((TSBAR(J,K),K=1,N),J=1,L)
                                                                                                                                           18×4
                                                                                                                                              3 X4
                                                                                                                                           3 X18
                 LM=L*M
                WRITE(3,202)LM
WRITE(3,870)(TBAR(K),K=1,N)
                 LN=L*N
                WRITE(3,201)LN
WRITE(3,870)(TIBAR(I),I=1,M)
                MN=M*N
WRITE(3,200)MN
WRITE(3,870)(RTBAR(J),J=1,L)
WRITE(3,206)
WRITE(3,208)DFS,CSSS,SMS
WRITE(3,209)DFT,CTSS,TMS
BRANCH AROUND MODIFICATION
C
                 G0T06001
                 DC30011=1,3
                 TSUL = 0.0
                 TLAM=0.0
DC3000K=1, N

IF(TLA(I,1).EG.0.0)GOTG60G1

TLAM=TLAM+TLA(I,K)*TLA(I,K)

O3000 TSUL=TSUL+TLA(I,K)*TE(K)

TCUSG=TSUL*TSUL/(TLAM*AL*AM*ANN)
03001 WRITE(3,4000)1,TCUSQ
06001 WRITE(3,210)DFR,CRSS,RMS
                    BRANCH AROUND MODIFICATION
                 GOT06000
                 D020011=1,3
                RSUL=0.0
                 RLAM=0.0
                 D02000J=1,L
```

```
IF(RLA(I,1).EQ.O.O)GOTO6000
RLAM=RLAM+RLA(I,J)*RLA(I,J)

02000 RSUL=RSUL+RLA(I,J)*RT(J)
RSUSQ=RSUL*RSUL/(RLAM*AM*AN*ANN)

02001 WRITE(3,4000)I,RSUSQ
06000 WRITE(3,211)DFST,CTSSS,TSMS
WRITE(3,212)DFRT,CRTSS,RTMS
WRITE(3,213)DFRS,CRSSS,RSMS
WRITE(3,214)DFSRT,CRSTSS,RSMS
WRITE(3,214)DFSRT,CRSTSS,RSMS
WRITE(3,215)DFE,ESS,EMS
DFTO=TOTN-1.0
WRITE(3,216)DFTO,CTOTSQ
WRITE(3,207)
GOTO1000
END
                 END
                                                                                            LOCATION
00780
00806
    LOCATION 00775
                                 FORTRAN NAME
            00801
                                 IFOR
                                                                                                    00826
            00841
                                                                                                   00846
            00861
                                                                                                    00866
            07621
                                 TRBAR
                                                                                                    08965
                                                                                                    11909
                                 TSBAR
            11781
           12005
12717
12749
                                                                                                   12037
12725
12757
                                 TBAR
                                 RLA
                                 AN
            12781
                                 TUTSQ
                                                                                                    12789
                                                                                                   12821
12853
12885
12917
            12813
12845
                                 TSSQ
TESQ
            12877
                                 DET
            12909
                                 DESRI
                                                                                                   12949
12981
13013
13045
                                 CTSS
CRSTSS
TMS
            12941
12973
            13005
            13037
                                 RSTMS
                                 TCUSQ
DFTO
            13069
                                                                                                    13077
            13101
                                                                                                    13109
                                 00800
            13139
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DEF. DEF.

DEF. 21215 DEF. 21737 PROGRAM ENTRY IS 13115

13820

13848 13975

14114

14354

14594

14834

15343

15716

16453 17228

17848

18415

21136 21658

PROGRAM SIZE IS 22104

00804

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13806

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LOCATION 00785 00811 00831 00851 00901 10309 11941 12373 12765 12797 12829 12861 12893 12925 12925 12925 12989 13053 13085	FORTRAN 00000+9 L 1 M CTTBAR RTIBAR TIBAR TIBAR TOTNO TROTS CDFR T CCTSS S CTSS S TSUA RLAM		LOCATION 00793 00816 00836 00836 06277 11653 11973 12741 12773 12837 12837 12837 12993 12997 13061 13093
13806 13834 13862 13994 14474 14714 15073 16128 16816 17539 18161 20741 21263	00802 00806 00502 13813 13827 13845 000343 00071 000071 000000 03000 02000	FOR. FOR. DEF. DEF. DEF. DEF.	13813 13841 13874 14102 14342 14582 14822 15197 15626 17003 17723 18286 20954 21476

FORM B

Data and AOV print-out

17.666600CC00 13.833300CC00 11.250000CC0 13.833300CCCCOO
11.2500000CCCCOO
12.666600CCCCOO
18.7500000CCCCOO
18.500000CCCCOO
14.916600CCCCOO
14.500000CCCCOO
20.833300CCCCCOO
27.500000CCCCOO
27.6666600CCCCOO
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27.6666600CCCOO 17.666600CC00
15.666600CC00
19.166600CC00
20.00000CC00
17.250000CC00
22.166600CC00
16.3333000CC0
16.50000CC00
19.50000CC00

1

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17.833300C000
17.666600CC00
21.3333300CC00
21.1666000CC00
14.50C0000CC00
31.C0C000CC00
21.8333300CC00
21.8333300CC00
21.8333300CC00
21.8333300CC00
21.8333300CC00
21.8333300CC00
17.416600CC00
22.666600CC00
11.515600CC00
11.5333300CC00
11.586600CC00
11.5833300CC00
18.8333000000

11.6666000000

19.00000000000

15.50000000000

14.8333000000

15.6666000000

17.6666000000

17.3333000000

17.33333000000

17.3333000000

18.416600000000

18.4166000000000

18.250000000000

16.000000000000

15.00000000000
                                                                                                   RS
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15.972200C000
17.916600CC00
20.972200C00
16.888800C00
                 15
17
20
                             6888000000
65833000000
64166000000
63333000000
75555000000
                 15.19.27.
                27.555000000
26.6944000000
17.5883300000
15.611000000
17.472200600
17.472200600
17.2499000000
12.5833000000
12.5833000000
                17.41660000000
18.2500000000
22.5833000000
20.00000000000
20.8610000000
20.8888000000
               20.88888C0CCCO

16.3055000CCO

17.1944C0CCCO

17.111000CCCO

17.111000CCO

17.6388C0CCCO

18.249900CCCO

13.8333000CCO

12.24990CCCO

14.805500CCCO

14.805500CCCO

14.805500CCCO

14.805500CCCO

14.805500CCCO

14.805500CCCO
```

ST

1

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體

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18
 RT
         72
 T
         12
繼
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14.5346000000

14.2186000000

R MEANS BELOW, K=

17.5481000000

17.1402000000

18.3685000000

19.1083000000

SOURCE

ST.

T.

R.

3.

TS.
                                                                                                                                                                                                                                                                                                                                                  51
                                                                                                                                               54
      SOURCE DF SS MS

S 17. . .18601000E 04 .100

T 2. .90150000E 03 .450

R 3. .13970000E 03 .460

TS 34. .30230000E 03 .880

TR 6. .99700000E 02 .160

RS 51. .57850000E 03 .111

TRS 102. .55090000E 03 .540

ERR . .00000000E-99 .000

FIXED, MIXED, OR RANDOM , NO F TESTS DONE
                                                                                                                                                                                                                                                                             .10941700E 03
.45075000E 03
.46566600E 02
.88911700E 01
.16616600E 02
.11343100E 02
.54009800E 01
.000000000E-99
```

FORM C

ANTHROPOMETRIC MEASUREMENTS

Name Address Age

Weight

Body Build Index $\frac{\text{wt}}{\text{ht}}$ =

Standing

Sitting

Stature

Vertex of head

Shoulder

Shoulder

Elbow

Elbow

Waist

Waist

Hip

Hip

Knee

Height top of thigh

Fingertip

Height top of knee

Standing

Greatest width at shoulders

Greatest width at arms bent

Greatest width below 36"

Height of stage 101/2"

Widest extension of hips

Sitting length

Maximum span at working level

Normal span at working level

Depth

Sitting eye level above seat

Bust

Elbow height above seat

Abdominal

Seat length

Bust

Seat width

Hip

back Seat height front

Arm Length

Shoulder to elbow

Elbow to palm

Classification of Stature

Classification of Weight

Short 1 Medium 2 Tall 3

Underweight 1 Medium 2 Overweight 3

ANALYSIS OF THE EFFECT OF DISTANCE AND WEIGHT AS A DETERMINANT OF POSTURAL CONFIGURATIONS OF A SEATED WORKER

by ·

JERRY W. WHITT

B. S., Kansas State University, 1963

AN ABSTRACT OF A MASTER'S THESIS

submitted in partial fulfillment of the

requirements for the degree

MASTER OF SCIENCE

Department of Industrial Engineering

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The prime purpose of this experiment was to evaluate a prototype mock-up model of a corridor designed kitchen and its relation with over the counter shelf heights using objects of different weights which may be used from a seated position.

A literature review revealed that many books and articles had been written on lifting forces and/or controlling muscle action when moving objects while in a standing position. It was also noted that contributions have been made to seating characteristics when the strength of arm extension is involved. Adequate information concerning seated tasks which involved both object weight and shelf height was not available. In order to evaluate this model kitchen in terms of the optimum location of over the counter shelf installations, the relationship of weight and distance was explored. This was achieved by measuring the body distortion from a normal seated position while using two-handed operations. A task consisting of lifting an object (no pan, 0, 5, and 10 pounds) from the counter top and placing it on a designated shelf directly in front of the subject was tested. Each sequence, composed of a series of tasks, was filmed and then the deviations from the normal seated position were measured by the use of a mechanical drawing arm and a mirror device.

Twenty-three female college students, with an age range of 18 to 21, formed the sample population. Their build was medium with reference to stature and weight. The subjects selected were between 62 and 65 inches in height and were within a specified weight range according to age and height.

The effect of object weight, of shelf height, and the interaction between the objects were analyzed statistically using an analysis of variance.

The results of the analysis show that both object weight and shelf height are significant; therefore, there is a difference in response due to these two sources of variation. It was also noted that there was a significant variability from individual to individual although they were similar in stature and weight. A study of the graphical results indicates that shelf number 2 (10 inches above the counter top) required the minimal response on the part of the subject using anyone of the object weights tested; therefore, it may be assumed to be the optimal shelf height tested.