# A GOAL PROGRAMMING MODEL FOR KOREAN ECONOMIC PLANNING

by

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#### CHAPTER 1

#### INTRODUCTION

Economic planning may be described as the conscious effort of a central organization to influence, direct, and in some cases, even control changes in the principle economic variables (e.g. consumption, investment, saving, etc.) of a certain country or region over the course of time in accordance with a predetermined set of objectives. Economic plans may be either comprehensive or partial. A comprehensive plan sets its targets to cover all major aspects of the national economy. A partial plan covers only a part of the national economy, e.g., industry, agriculture, the public sector, the foreign sector, and so forth [11].

Comprehensive economic planning, which is largely adopted in the developing countries, is based on limited scarce capital and natural resources in relation to competitive targets to be achieved. Thus, in order to utilize efficiently the scarce capital and natural resources, development goals must be established in a hierarchical order of importance [10]. In other words the difficulty in the economic planning analysis is the treatment of conflicting multiple objectives or goals. Hence the conventional single objective programming technique is severely handicapped in this situation.

There are three analytical methods of solution which can handle such multiobjective problems. These are:

Interactive multiobjective programming [2,9]. This technique allows the decision maker to trade off one objective versus another in an interactive manner. A solution is obtained by the decision maker's cyclic involvement in a search process that attempts to locate a satisfactory course rather than a optimum course.

- 2. Multiobjective programming with utility function [6]. Various concepts in utility theory and preference theory can be used to solve such a problem by reducing the multiple objective function to a single objective function.
- 3. Linear goal programming [4,7]. In this technique, all of the decision maker's targets or goals may be incorporated into the achievement function. The objectives of linear goal programming need not be a single dimension. The physical condition of the problem must be satisfied before any goal is considered. The set of feasible solutions which satisfies the physical condition is established. The optimal solution is then selected from the feasible solution which best fulfills the decision maker's stated goals.

The first and second method of solution have some problems concerning an accurate transformation of multiple objectives into a single preference (i.e., surrogate objective function) or utility function. It is worse that interactive multiobjective programming does not have a systematic algorithm employed in the digital computer. Hence the linear goal programming technique is very appropriate tool in solving the multiple objective economic planning problems.

There have been four economic planning models for Korea. The following three models are reviewed in [8].

- an input-output model by Adelman [1]
- a mixed integer programming model by Westphal [1]
- 3. a dynamic nonlinear planning model by Kendrick and Taylor [1] The fourth model, a multisectoral dynamic model by Eckaus and Parikh [3], has been employed by Joe [5].

The purpose of this study is to apply linear goal programming technique to the multisectoral dynamic model for Korean economic planning. Eckaus and Parikh's model is used in this study. The model was employed by Joe for Korean economic planning, but the linear programming technique was utilized. In the present study, the model is reconstructed so as to apply the linear goal programming technique. The models presented herein cover the period of 1977-1981, which corresponds to the period of Korea's Fourth Five-Year Plan.

Linear goal programming has not been widely used yet. Hence an introduction to the linear goal programming problem is presented in Chapter 2. In Chapter 3, the linear programming model of the Five-Year Korean Economic Planning is presented. The solution of this model is also presented in this chapter. In Chapter 4, this linear programming model is reorganized into a linear goal programming model and the linear goal programming solution is obtained. In the final chapter, concluding remarks and proposal for further study are presented.

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#### CHAPTER 2

#### LINEAR GOAL PROGRAMMING

#### 1. Introduction

A tool known as the simplex method for the solution to strictly linear decision models having a single objective, has been developed by Dantzig [2] after World War II. However, it is severely limited in that it cannot solve either non-linear models or models having more than a single objective function. It is common that a system has multiple conflicting objectives to achieve. For example, in studying the feasibility of constructing a new airport, there are many conflicting objectives and interests. The study must consider the cost of construction, the capacity, accessibility of the location, trafficflow planning, noise level for the nearby residents, conservation of natural life in the area, and so on. Obviously, a linear programming model with a single objective (goal) is not generally suitable for such decision analysis.

In the early 1960's Charnes and Cooper [1] presented an approach to the solution of linear decision models having more than a single objective. Later the work of Ijiri [5], Lee [6], and Ignizio [4] has resulted in a systematic methodology known as Goal Programming for solving linear, multiple objective problems wherein preemptive priorities and weightings are associated with the objectives.

In goal programming, instead of trying to maximize or minimize an objective directly as in linear programming, deviations between goals are to be minimized. The deviation variable is represented in two dimensions in the objective function, a positive (overattainment) and a negative (underattainment) deviation from a target value (i.e., a desired level of attainment) of each goal. Then, the achievement function entails the minimization of these deviations, based on the relative importance or priority assigned to them. Hence, goal

programming is to solve problems involving multiple, conflicting goals according to the decision maker's priority structure.

Here Lee's modified simplex algorithm [6] and Ignizio's modified revised simplex algorithm [4] are presented. Both employ the same theory of simplex algorithm, but one of the advantages of Ignizio's method is that it uses the condensed tableau and the revised simplex algorithm in its computations.

#### 2. Model Formulation

2.1 Forming the objective functions. We shall designate the goals or objectives by  $G_i$ . Thus,  $G_2$ , for example, is the second objective function. Each function must be expressed as a function of the decision variables  $(\bar{x})$ , that is,

$$G_i = f_i(\bar{x})$$

Every objective function will, and must, have an associated target value  $(b_i)$ , that is,

$$f_i(\bar{x}) \stackrel{>}{<} b_i$$

This situation allows for the intentional deviations to occur like slack variables in the linear programming. Deviations can be considered either positive, negative or zero from the goals. However, as in linear programming, all deviations in the goal programming must be structured as nonnegative variables. This might pose a problem, but it is easily handled by a simple transformation. For example, if  $D_{\hat{i}} \stackrel{>}{<} 0$  is a deviation from a goal, the deviation may be replaced by the difference between two nonnegative variables, that is,

$$D_i = d_i^- - d_i^+$$

where (a)  $-\infty < D_i < +\infty$ 

(b) 
$$d_{i}^{+} > 0$$

(c) 
$$d_{i} > 0$$

(d) 
$$d_{i}^{-} \cdot d_{i}^{+} = 0$$

The value of  $d_i^-$  reflects the negative deviation from  $b_i(< b_i)$ , while the value  $d_i^+$  reflects positive deviation  $(> b_i)$ . Requirement (d) indicates that  $d_i^-$  and  $d_i^+$  are complementary to each other. If  $d_i^-$  takes nonzero value,  $d_i^+$  will be zero, and vice versa. Consequently, each objective will be of the following final form:

$$f_i(\bar{x}) + d_i^- - d_i^+ = b_i$$
  $i = 1, ..., m$ 

- <u>2.2 Absolute objectives.</u> When setting up the decision model we meet two kinds of objectives. One is the decision maker's goal to attain a desired level, the other is to meet the physical demand or constraint resulting from assumptions or/and conditions of the real situation. The constraints are treated as special kind of objectives and called absolute objectives. The top priority,  $P_1$ , is assigned to these absolute objectives.
- 2.3 Assigning objectives to priority level. Once a set of objectives has been established, we shall rank these objectives (i.e., the nonabsolute objectives) according to preference or importance. All absolute objectives, if they exist, are assigned to the top priority level to insure that they are completely satisfied (if possible). The remaining set of nonabsolute objectives should then be grouped according to their respective priority levels. The assignment of priorities to these objectives is normally decided by the decision maker or the decision maker in conjunction with the analyst. However, the decision maker could assign a ranking that is not directly compatible with the goal programming model. The paired comparison method [7] is an approach that may be used when a single decision maker is asked to rank objectives. The essence of the procedure is to compare objectives, two at a

time, until all possible pairs of objectives have been investigated. The number of such comparisons is given by m<sup>C</sup>2 where m is the total number of objectives. Consider the following typical results of such an approach:

$$G_1 > G_2$$
  $G_2 < G_3$   
 $G_1 > G_3$   $G_2 > G_4$   
 $G_4 < G_1$   $G_3 > G_4$ 

where  $G_1 > G_2$  is read as objective one is preferred to objective two. Rearranging these expressions so that all preference signs points to the right we have:

$$G_1 > G_2$$
  $G_3 > G_2$   
 $G_1 > G_3$   $G_2 > G_4$   
 $G_1 > G_4$   $G_3 > G_4$ 

The most preferred objectives will be preferred to the three other objectives and thus it should appear on the left of our expression three times. This is true for  $G_1$ . The next most preferred goal is  $G_3$ . The final rankings are then:

Rank	Objective	
1	$G_1$	
2	$G_3$	
3	G <sub>2</sub>	
4	G <sub>4</sub>	

Once the objectives had been ranked, we wish to group them into a minimum number of priority levels. It should be noted that only commensurable objectives

may be assigned to the same priority level. Further it must be possible to assign weights to each objective within the same priority level. Weighting values can be judgement values such as: If the profit associated with the product A is four times that associated with product B then we would probably be four times more concerned with minimizing the market underrun of product A than that of product B.

It should be noted that these preemptive priority levels have the following property:

$$P_k >>> P_{k+1}$$
  $k = 1, 2, ..., K-1$ 

Thus, the achievement of those objectives at any priority is immeasurably preferred to the achievement of the objective set at any lower priority. This concept is at the heart of goal programming. As a result, the solution procedure does not find a global optimum satisfying all objectives, rather the goal programming procedure finds a feasible set of optimal solutions to the priority one level, then within this set of solutions it finds another subject of optimal solutions (if possible) to the priority two level, and so forth.

2.4 Forming the achievement function. The final step in model development is the establishment of the achievement function. Let us first consider a typical objective function as shown below:

$$f_{i}(\bar{x}) + d_{i}^{-} - d_{i}^{+} = b_{i}$$

Now we will desire to select  $\bar{x}$  so as to

- (a) equal or exceed the value of  $b_i$
- or (b) equal or less than the value of b<sub>i</sub>
- or (c) exactly equal to the value of  $b_i$ .

These three possibilities may be achieved by minimizing a linear function of the deviation variables as shown in Table 2-1.

Table 2-1 Procedure for Achieving an Objective

	Goal	Pr	rocedure
(a)	Equal or exceed b	Min.	:
(b)	Equal or be less than b	Min.	d <sup>†</sup> i
(c)	Equal b <sub>i</sub>	Min.	$(d_i^- + d_i^+)$
		- E	

Our next step is to associate each objective with the respective preemptive priority. For example,  $P_2(d_1^-)$  means that our second priority is associated with minimizing underattainment of the first objective function (i.e., min.  $d_1^-$ ). The resulting achievement function will be

Min. 
$$\bar{a} = \{P_1[g_1(\bar{d}^-, \bar{d}^+)], P_2[g_2(\bar{d}^-, \bar{d}^+)], \dots, P_K[g_K(\bar{d}^-, \bar{d}^+)]\}$$
  
where  $g_k(\bar{d}^-, \bar{d}^+)$  is a linear function of the deviation variables, and  $P_k$  is

where  $g_k(d, d')$  is a linear function of the deviation variables, and  $P_k$  is the kth priority level associated with  $g_k(\bar{d}^-, \bar{d}^+)$ . We may drop  $P_1, P_2, \ldots$  from the formulation of the achievement function, that is,

Min. 
$$\bar{a} = \{g_1(\bar{d}^-, \bar{d}^+), g_2(\bar{d}^-, \bar{d}^+), \dots, g_K(\bar{d}^-, \bar{d}^+)\}$$

2.5 The general linear goal programming model. After following the preceding steps we shall arrive at the desired model of our multiple objective decision problem. The general linear goal program model takes on the following form:

Find 
$$\bar{x} = (x_1, x_2, ..., x_n)$$
 so as to minimize

$$\bar{a} = \{g_1(\bar{d}^-, \bar{d}^+), g_2(\bar{d}^-, \bar{d}^+), \dots, g_K(\bar{d}^-, \bar{d}^+)\}$$

such that

$$\bar{x}$$
,  $\bar{d}^-$ ,  $\bar{d}^+ \ge 0$ 

#### 3. Graphical Analysis

The technique for solving these models may be understood easily if we first consider a simple graphical approach. Although graphical analysis is only appropriate for a problem having no more than 3 decision variables, it does serve to aid in the understanding of the basic concept and method to be used in large problems.

### Example 2-1

The Hardee toy company makes two kinds of toy dolls. Doll A is a high quality toy and Doll B is of lower quality. The respective profits are \$0.40 and \$0.30 per doll. Each doll of type A requires twice as much time as a doll of type B, and if all dolls were of type B, the company could make 500 per day. The supply of material is sufficient for only 400 dolls per day (both A and B) combined. Assuming that all the dolls for type A and type B the factory can make could be sold, how should the manager schedule production to produce the most profit?

This problem is a typical linear programming problem which is formulated as below:

Max. 
$$Z = 0.4x_1 + 0.3x_2$$

subject to

$$x_1 + x_2 \le 400$$

$$2x_1 + x_2 \le 500$$

$$x_1, x_2 \ge 0$$

where  $x_1$  and  $x_2$  are the number of doll A and that of doll B produced respectively. The optimum solution is,

$$x_1^* = 100 \qquad x_2^* = 300$$

$$Z = $130$$

This profit maximization problem can be formulated as a goal programming problem.

Min. 
$$\bar{a} = \{(d_1^+ + d_2^+), (d_3^-)\}$$

such that

G<sub>1</sub>: 
$$x_1 + x_2 + d_1^- - d_1^+ = 400$$
  
G<sub>2</sub>:  $2x_1 + x_2 + d_2^- - d_2^+ = 500$   
G<sub>3</sub>:  $0.4x_1 + 0.3x_2 + d_3^- - d_3^+ = 240$   
 $\bar{x}, \bar{d}^-, \bar{d}^+ \ge 0$ 

The achievement function consists of two priorities. First priority is given to the minimization of  $(d_1^+ + d_2^+)$  because  $G_1$  and  $G_2$  are absolute objectives (i.e., they come from physical constraints). The second priority factor is assigned to the minimization of  $d_3^-$ , that is, minimize the under attainment of some arbitrarily chosen target value of \$240. This value is set arbitrarily, knowing that we will never be able to achieve a higher profit ( $$0.4 \times 400 = $160 < $240$  and  $$0.3 \times 400 = $120 < $240$ ).

In order to solve this goal programming by the graphical method, all the objective functions must be plotted on graph as shown in Figure 2-1. No feasible region is found to satisfy all three goals, i.e.,  $G_3$  is completely conflicting with  $G_1$  and  $G_2$ . By introducing priority levels in goal programming this difficulty could be handled. The solution space satisfying the objective set of priority level 1  $(P_1)$  is indicated by the cross-hatched area of Figure 2-2. Here both  $d_1^+$  and  $d_2^+$  are set to zero. Next we attempt to satisfy priority level  $2(P_2)$  without degrading the solution of  $P_1$ . In this situation  $d_3^-$  can be minimized until  $d_3^-$  = 110. If  $d_3^-$  becomes smaller than this, it degrades  $P_1$ . Consequently the final solution is point A shown in Figure 2-2 and is,

$$x_1^* = 100$$
  $x_2^* = 300$   $\bar{a}^* = \{0, 110\}$ 

THIS BOOK CONTAINS NUMEROUS PAGES WITH DIAGRAMS THAT ARE CROOKED COMPARED TO THE REST OF THE INFORMATION ON THE PAGE. THIS IS AS RECEIVED FROM CUSTOMER.

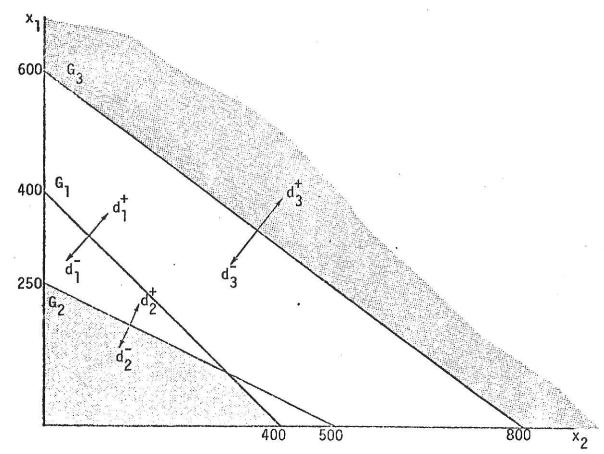


Figure 2-1 No feasible region for satisfying three goals

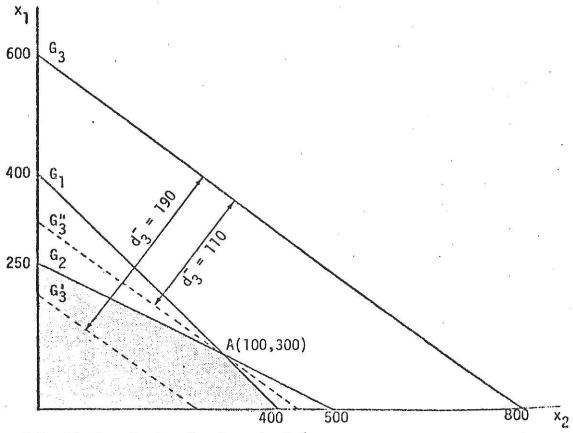


Figure 2-2 Final solution for Example 2-1

#### Example 2-2

Suppose the best customer of the toy company ordered 300 dolls of type A. For various reasons the manager could not decline this order. How should the manager switch the production schedule to meet the sudden demand? Assume that the other conditions are the same as Example 2-1.

If we attempt to utilize linear programming to maximize profit, the problem is formulated as below:

Max. 
$$Z = 0.4x_1 + 0.3x_2$$

subject to

$$x_1 + x_2 \le 400$$
 $2x_1 + x_2 \le 500$ 
 $x_1 \ge 300$ 
 $x_1, x_2 \ge 0$ 

The graphical presentation of the model is shown in Fig. 2-3. Obviously, there is no area of feasible solution and consequently the above problem is unsolvable by linear programming. In simple words, the company does not have enough capacity to satisfy the customer's demand.

This difficulty can be handled, if the manager wishes to satisfy his desires as closely as possible rather than absolutely satisfy all goals. Let's assume that his priorities are:

 $P_1$ : Avoid the overtime operation of the plant (500 dolls/day)

P<sub>2</sub>: Meet the best customer's order as closely as possible (i.e. produce at least 300 dolls of type A)

P<sub>3</sub>: Satisfy, as much as possible, the \$240 profit.

Now the linear goal programming model becomes:

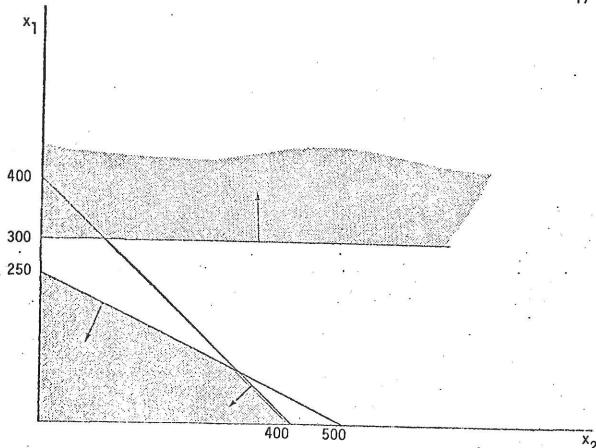


Figure 2-3 Infeasible solution for linear programming model

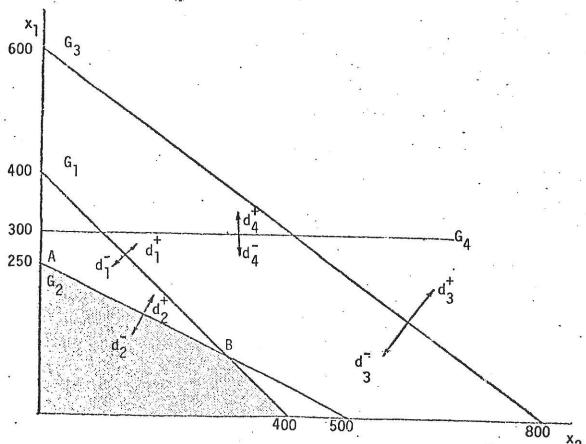


Figure 2-4 Final solution for Example 2-2

Find 
$$\bar{x} = (x_1, x_2)$$
 so as to

Min.  $\bar{a} = \{(d_1^+ + d_2^+), (d_4^-), (d_3^-)\}$ 

such that

 $G_1: x_1 + x_2 + d_1^- - d_1^+ = 400$ 
 $G_2: 2x_1 + x_2 + d_2^- - d_2^+ = 500$ 
 $G_3: 0.4x_1 + 0.3x_2 + d_3^- - d_3^+ = 240$ 
 $G_4: x_1 + d_4^- - d_4^+ = 300$ 
 $\bar{x}, \bar{d}^-, \bar{d}^+ > 0$ 

The above model is shown on the graph in Figure 2-4. Now our first goal is to avoid the overtime operation of the plant by minimizing  $(d_1^+ + d_2^+)$ . That is  $d_1^+ = d_2^+ = 0$ . Hence the feasible solution must be in the cross-hatched area. Our second goal calls for production of 300 type A doll by minimizing  $d_4^-$ . We can proceed until we reach point A (that is  $d_4^- = 50$ ) without degrading the solution to priority level 1. Finally to achieve profit maximization goal of priority level 3, we must minimize  $d_3^-$ . We can proceed from point A to point B, but this movement is against priority level 2. Hence point A has to be the final solution. That is,

$$x_1^* = 250$$
  $x_2^* = 0$   
 $\bar{a}^* = (0, 50, 140)$ 

## Example 2-3

Manhattan China Inc. produces the world's finest china sets. The company's production facility consists of two production lines. Production line 1 is staffed with skilled workers who can produce an average of 5 sets per hour.

Line 2 is capable of producing an average of only 3 sets per hour, as it is staffed with relatively new employees. The regular working hours for the weeks are 40 for each line. The profit from an average set is \$50. It is estimated that the operating cost of the two lines are almost identical. The president of the company has suggested the following multiple goals to be achieved in the coming week in ordinal ranking of importance.

P1: Achieve the production goal of 450 set for the week

P<sub>2</sub>: Limit the overtime operation of line 1 to 10 hours

P<sub>3</sub>: Avoid the underutilization of regular working hours for both lines

 $P_4$ : Limit the sum of overtime operation for both lines.

The following objective functions can be formulated.

Production capacity

$$G_1: 5x_1 + 3x_2 + d_1^- - d_1^+ = 450$$

where

 $x_1$  = number of hours line 1 is in operation

 $x_2$  = number of hours line 2 is in operation

 $d_1^-$  = underattainment of production goal of 450 sets

 $d_1^+$  = production in excess of 450 sets.

Regular working hours.

$$G_2$$
:  $x_1 + d_2^- - d_2^+ = 40$ 

$$G_3$$
:  $x_2 + d_3^- - d_3^+ = 40$ 

where

 $d_2^-$  = underutilization of regular working hours of line 1

 $d_2^+$  = overtime operation in line 1

 $d_3$  = underutilization of regular working hours of line 2

 $d_3^+$  = overtime operation in line 2.

Overtime operation for line 1.

$$G_4$$
:  $x_1 + d_4^- - d_4^+ = 40 + 10 = 50$ 

where

 $d_4^-$  = operation hours of line 1 that total less than 50 hours

 $d_4^+$  = overtime operation of line 1 beyond 10 hours.

The achievement function for this example is then:

Find  $x_1$  and  $x_2$  so as to minimize

$$\bar{a} = \{(d_1^-), (d_4^+), (5d_2^- + 3d_3^-), (3d_2^+ + 5d_3^+)\}$$

That is, our first priority is to achieve the production goal through the minimization of  $d_1^-$ . The second priority is given to limiting overtime operation of line 1 to 10 hours through minimizing of  $d_4^+$ . The third priority is assigned to the minimization of underutilization of regular working hours by minimizing  $d_2^-$  and  $d_3^-$ . Since the productivity of line 1 is 5 units per hour and that of line 2 only 3 units per hour, the president wishes to avoid the underutilization of regular working hours of line 1 more than line 2. The differential weights, then, will be 5 for  $d_2^-$  and 3 for  $d_3^-$ . The fourth and final priority is to minimize the sum of overtime operation for both lines. Again we have to assign differential weights to  $d_2^+$  and  $d_3^+$ . The criterion to be used is the relative cost of overtime. Since ratio of the production rates for the two lines is 5 to 3, the relative cost of overtime for two lines should be 3 to 5. The final decision model is written as:

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THIS IS AS RECEIVED FROM THE CUSTOMER.

Find  $x_1$  and  $x_2$  so as to minimize

$$\bar{a} = \{(d_1^-), (d_4^+), (5d_2^- + 3d_3^-), (3d_2^+ + 5d_3^+)\}$$

such that

G<sub>1</sub>: 
$$5x_1 + 3\bar{x}_2 + d_1^- - d_1^+ = 450$$
  
G<sub>2</sub>:  $x_1 + d_2^- - d_2^+ = 40$   
G<sub>3</sub>:  $x_2 + d_3^- - d_3^+ = 40$   
G<sub>4</sub>:  $x_1 + d_4^- - d_4^+ = 50$   
 $\bar{x}, \bar{d}^-, \bar{d}^+ > 0$ 

The above model is shown on the graph in Figure 2-5. Now our first goal is to achieve the production goal of 450 sets by minimizing  $d_1^-$ . That is  $d_1^-=0$ . Hence the feasible solution must be in the cross-hatched area. Our second goal calls for the limitation of overtime operation for line 2 to 10 hours by minimizing  $d_4^+$  or let  $d_4^+=0$ . This can be plotted as  $x_1 \leq 50$ , as shown in Figure 2-6. The third goal is to avoid underutilization of regular working hours for both lines. Since a greater weight is assigned to the underutilization of line 1, we should examine the working hours of line 1 first. This condition calls for  $x_1 \geq 40$  (minimizing  $5d_2^-$  or let  $d_2^-=0$ ). Plotting this on the graph we obtained the area of feasible solution shown in Figure 2-7. Now, we are also to avoid any underutilization of regular working hours for line 2, that is, to minimize  $3d_3^-$  or let  $d_3^-=0$ . It is evident in Figure 2-7 that the cross-hatched area already satisfies this subgoal. The last goal is to minimize the sum of overtime for both lines. However the limitation for line 2 is given a greater weight. Hence  $d_3^+$ 

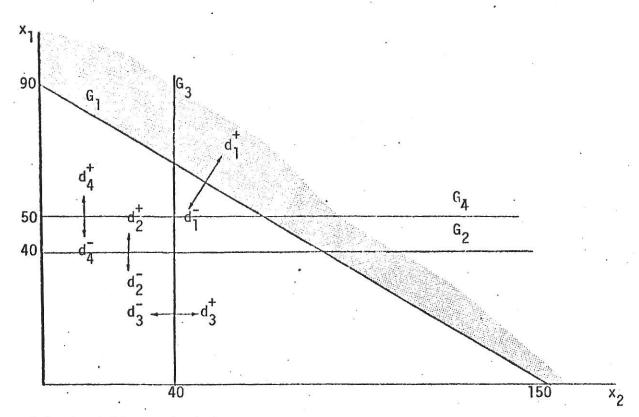


Figure 2-5 P<sub>1</sub> fully satisfied

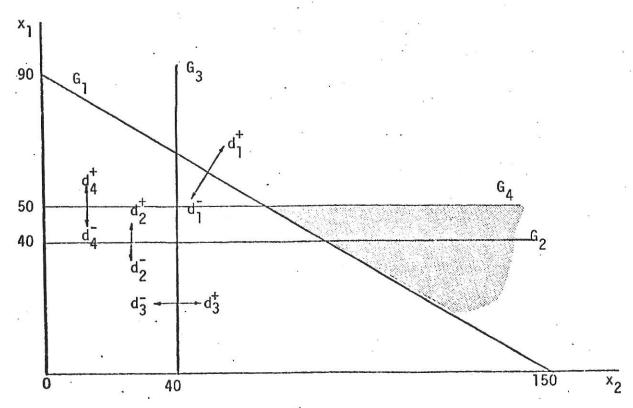


Figure 2-6 P, and P, fully satisfied.

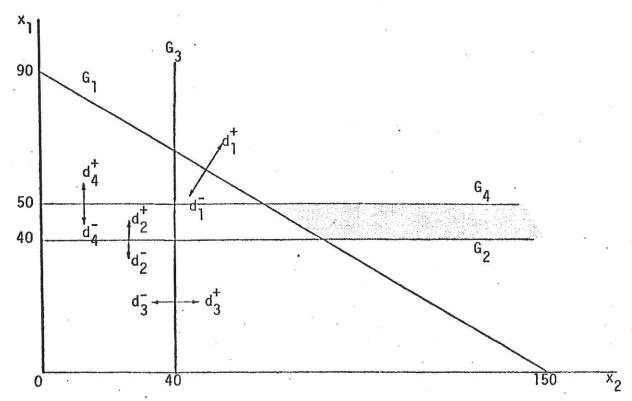
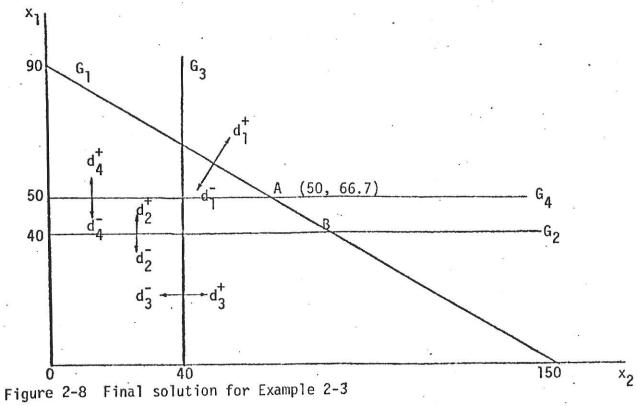


Figure 2-7  $P_1$ ,  $P_2$  and  $P_3$  fully satisfied.



(the overtime operation of line 2) must be minimized to the fullest extent. Obviously, at point A in Figure 2-8,  $d_3^+$  will be minimized while meeting the first three goals. Next we try to minimize  $d_2^+$  (the overtime operation of line 1). We can proceed until it reaches point B, but this movement is against the minimizing of  $d_3^+$ . Since we cannot decrease  $d_2^+$  any further from point A without increasing  $d_3^+$ , point A has to be the optimum point.

That is:

$$x_1^* = 50$$
  $x_2^* = 66.\overline{6}$   
 $\overline{a}^* = (0, 0, 0, 163.3)$ 

with these values  $(x_1 = 50, x_2 = 66.7)$  we could attain our first three goals completely, but could not attain the last goal. The value 163.3 comes from  $g_4 = 3d_2^+ + 5d_3^+ = 3 \times 10 + 5 \times 26.7 = 163.3$ .

## Example 2-4

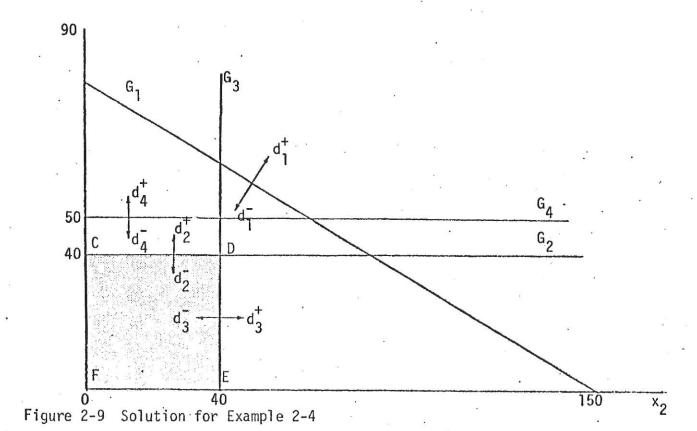
To demonstrate the significance of priority level in goal programming, Example 2-3 is examined again, changing only the ordinal priority of the president's decision.

New priority levels are as follows:

$$P_1 = 01d P_4$$
 $P_2 = 01d P_3$ 
 $P_3 = 01d P_2$ 
 $P_4 = 01d P_1$ 

then the achievement function will be

$$\bar{\mathbf{a}} = \{ (3d_2^+ + 5d_3^+), (5d_2^- + 3d_3^-), (d_4^+), (d_1^-) \}$$



The graphical solution to Example 2-4 is demonstrated in Figure 2-9. Priority level 1 is to minimize  $(3d_2^+ + 5d_3^+)$ , and the feasible region CDEF satisfies this goal. In priority level  $2, d_2^-$  has larger weight, hence  $d_2^-$  is to be minimized first, and line segment CD is the solution. Line DE is the solution to minimize  $d_3^-$ . However, to satisfy the minimization of  $d_2^-$ , point D is the solution. At point D,  $d_4^+$  has already become zero (i.e.,  $P_3$  fully satisfied). Now we attempt to achieve priority level 4 by minimizing  $d_1^-$  or  $d_1^- = 0$ , but this is against all higher priorities, level 1 through level 3. The final solution is point D, that is,

$$x_1^* = 40$$
  $x_2^* = 40$   $\bar{a} = (0, 0, 0, 130)$ .

The above two examples show that there is no feasible solution which satisfies all four goals as long as these goals are conflicting with each other. However, through priority level ranking of the goals, we can reach an optimal solution. Further, it is worth noticing that changes of priority levels give a distinctive optimal solution.

## The Computational Algorithm

Two kinds of algorithms have been presented to solve linear goal programming problems. The generalized inverse technique has been introduced by Ijiri [5], while Lee [6] and Ignizio [4] use the modified simplex method. The modified simplex method is presented here.

## 4.1 The modified simplex method.

## Establishing the Initial Tableau

The extended tableau for this method is shown in Table 2-2. After a brief explanation of the tableau, some examples will be used to demonstrate the procedure. The elements within this tableau may be defined as follows:

Table 2-2 The Extended Tableau for the Modified Simplex Method

	1	-								
- - -	Δ.	۳ <sub>×</sub>	w K,1	:	WK,n WK,n+1	:	WK,n+m WK,n+m+l	:	WK,n+2m	
Stub				•••		•••				Stub
	<u></u>		W,1		L+u, L <sup>W</sup> n, L <sup>W</sup>	:	W1,n+m W1,n+m+1	:	W1,n+2m	
P <sub>K</sub> P <sub>1</sub>	۸		r <sub>x</sub>	:	x <sub>n</sub> d <sub>1</sub>	:	d <u>"</u> d+	:	+ <sub>p</sub> =	ıΔ
л, к · · · и	լր   լ, լս	<u></u>	e <sub>1,1</sub>		el,n el,n+l	:	el,n+m el,n+m+l	:	el,n+2m	b,
• • •								•••		• • •
μ, κ υ <sub>m, 1</sub>		J-E	e <sub>m,1</sub>	:	e m,n em,n+1	i	em,n+m em,n+m+l	÷	em,n+2m	ď
; ;	<u> </u>	P <sub>1</sub>	1,1	:	I,n Il,n+l	÷	I,n+m I,n+m+l	:	I,n+2m	ď
Rows				•••		• • •		•••		
*	<u>D.</u>	~	I,1	•	IK,n IK,n+1	:	IK,n+m IK,n+m+l	:	IK,n+2m	a <sub>K</sub>

#### Headings:

 $P_k$  = the kth priority level, k = 1, ..., K

V = decision and deviational variables. The variables below  $V(d_i)$  are the initial set of basic variables.

 $\bar{b}$  = the elements below  $\bar{b}$  are the  $b_i$ s, i.e., the right-hand-side values of each objective.

### Elements:

j = 1, ..., n; i = 1, ..., m; s = 1, ..., S; k = 1, ..., K.

 $e_{i,s}$  = coefficient of the sth variable in the ith objective.

 $w_{i,s}$  = weighting factor of priority k ( $P_k$ ) associated with the sth variable.

 $u_{i,k}$  = weighting factor of priority k ( $P_k$ ) associated with ith basic variable.

 $I_{k,s}$  = index number for priority k under the sth variable.

 $a_{k}$  = level of achievement of priority k.

All elements except  $I_{k,s}$  and  $a_k$  are from the initial mathematical decision model. However,  $I_{k,s}$  and  $a_k$  must be computed as follows:

$$I_{k,s} = \sum_{i=1}^{m} (e_{i,s} \cdot u_{i,k}) - w_{k,s}$$

$$a_k = \sum_{i=1}^{m} (b_i \cdot u_{i,k})$$

Referring again to the extended tableau of Table 2-2, it should be noted that if we remove the rows and columns associated with the "Top Stub", "Left Stub" and "Index Rows", the remaining matrix is simply the matrix of objective

function coefficients, and the right hand side values of each objective. In the initial tableau the basic variables will always be the set of negative deviation variables  $(d_i)$ . That is, with m objectives, only m variables may be basic and all others are set to a value of zero and denoted as nonbasic. The iterations of the simplex algorithm consist of exchanging a present nonbasic variable for a present basic variable if such an exchange improves the present solution. If only a single priority level had been established, this tableau would be similar to the traditional "single objective" simplex tableau of linear programming. The solution to the linear goal programming model, at any stage, is given by  $a_1, a_2, \ldots, a_K$ , where  $a_k$  represent the level of achievement for priority k. Since the achievement function in linear goal programming model is always of the minimization form, the lower the value of  $\mathbf{a}_{\mathbf{k}}$ , the better the level of achievement. A zero value means that this particular priority level has been completely achieved. The set of index rows  $(I_{k,s})$  in the tableau serve to indicate whether or not the present solution is optimal and, if not, the proper exchange between a basic and nonbasic variable for a better solution.

### The Algorithm

The steps of the modified simplex algorithm are:

- Step 1: Initialization. Establish the initial tableau and the index row.
  Set k = 1 and proceed to Step 2.
- Step 2: Check for Optimality. Examine  $a_k$ . If  $a_k$  is zero go to Step 6. Otherwise, examine each positive valued index number  $(I_{k,s})$  in the kth index row. Select the largest, positive  $I_{k,s}$  for which there are no negative valued index numbers at a higher priority in the same column. Designate this column as optimum column (s'). Ties

in the selection of  $I_{k,s}$  may be broken arbitrarily. If no such  $I_{k,s}$  may be found, go to Step 6. Otherwise, go to Step 3.

- Step 3: <u>Determining the New Entering Variable</u>. The nonbasic variable in the optimum column (s') is the new entering variable.
- Step 4: <u>Determining the Departing Variable</u>. Determine the row associated with the minimum nonnegative value of:

$$b_{i} / e_{i,s'}$$
  $i = 1,2, ..., m$ 

In the event of ties, select that row having the basic variable with the higher priority level. Designate this row as key row (i'). The basic variable associated with key row (i') is the departing variable.

## Step 5: Establishment of the New Tableau.

- (a) Set up a new tableau with all e<sub>i,s</sub>, b<sub>i</sub>, I<sub>k,s</sub> and a<sub>k</sub> elements empty. Replace the position of the basic variable heading in optimum row with the nonbasic variable heading in the key column.
- (b) Make each objective have one basic variable with a coefficient of +1, and make sure that this basic variable does not appear in any other objective (by the Gaussian elimination method). This can be done [3] by performing the elementary row operations (c) and (d).
- (c) Multiplying an objective by a nonzero constant.
- (d) Adding a multiple of one objective to another objective.
- (e) Establish the new values for  $I_{k,s}$  and  $a_k$ .
- (f) Return to Step 2.
- Step 6: Evaluate Next Lower Priority Level. Set k = k+1. If k exceeds K (the total number of priority levels), then stop as the solution is optimal. If  $k \le K$  go to Step 2.

#### Example 2-5

Example 2-1 illustrated by graphical solution is again considered. Find  $\bar{x} = (x_1, x_2)$  so as to

Min. 
$$\bar{a} = \{(d_1^+ + d_2^+), (d_3^-)\}$$

such that

$$x_1 + x_2 + d_1^- - d_1^+ = 400$$
 $2x_1 + x_2 + d_2^- - d_2^+ = 500$ 
 $0.4x_1 + 0.3x_2 + d_3^- - d_3^+ = 240$ 
 $\bar{x}, \bar{d}^-, \bar{d}^+ \ge 0$ 

Step 1: The initial tableau for this example is given in Table 2-3. For clarity, the zero elements of the tableau have been omitted. The basic solution of this tableau is,

$$d_1^- = 400$$
 $d_2^- = 500$ 
 $d_3^- = 240$ .

All other variables (those nonbasic) are zero.  $P_1$  is completely satisfied since  $a_1 = 0$ .  $P_2$  is not completely satisfied since  $a_2 = 240$ .

Step 2: Since  $a_1 = 0$ , go to Step 6.

Step 6: k = k+1 = 2  $k \le K$  since k = 2, K = 2 go to Step 2.

Step 2:  $a_2 = 240$ . Hence, examine all positive valued indicators in index row 2 ( $I_{2,s}$ ).  $I_{2,1}$  is the largest value (+0.4) and there are no negative valued index numbers above  $I_{2,1}$  ( $I_{1,1} = 0$ ). Thus s' = 1 go to Step 3.

Step 3:  $x_1$  is the new entering variable.

Table 2-3 The Initial Tableau for Example 2-1

	9	P <sub>2</sub>				Tall Territorius Innovadurativa Vincen	1				
		P <sub>1</sub>						1	1		
P <sub>2</sub>	P <sub>1</sub>	٧	×ı	× <sub>2</sub>	d <sub>1</sub>	d <sub>2</sub>	d <sub>3</sub>	d†	d <sub>2</sub> <sup>+</sup>	d <sup>+</sup> <sub>3</sub>	Б
		d <sub>1</sub>	1	1	1			-1			400
		d <sub>2</sub>	2	1		. 1			-1		500
1		d <sub>3</sub>	.4	.3			1			-1	240
		P <sub>1</sub>						-1	-1		0
		P <sub>2</sub>	.4	.3						-1	240

Table 2-4 Second Tableau for Example 2-1

		P <sub>2</sub>					1		-		
		P <sub>1</sub>						1	1		
P <sub>2</sub>	P <sub>1</sub>	٧	× <sub>1</sub>	× <sub>2</sub>	d <sub>1</sub>	d <sub>2</sub>	d <sub>3</sub>	d†	d <sup>+</sup> <sub>2</sub>	$d_3^+$	Б
		d <sub>1</sub>		(5)	1	5		-1	.5		150
		×1	1	. 5		.5			5		250
1		d <sub>3</sub>		.1		2	1		.2	-1	140
		P <sub>1</sub>						-1	-1		0
		P <sub>2</sub>		[.]		2			.2	-1	140

Table 2-5 Third Tableau for Example 2-1

			P <sub>2</sub>					1	rapagy v kirkilat data kuju v agranging v	vivial sees on relative to the party		
			P <sub>1</sub>						1	1		
-	P <sub>2</sub>	P <sub>1</sub>	٧	x <sub>1</sub>	× <sub>2</sub>	d <sub>1</sub>	d <sub>2</sub>	d <sub>3</sub>	d <sup>+</sup>	d <sub>2</sub> <sup>+</sup>	$d_3^+$	Б
			x <sub>2</sub>		1	2	-1		-2	1	•	300
			×ı	1		-1	1		1	-1		100
	1		d <sub>3</sub>			2	1	1	.2	.1	-1	110
•	<del>TO FOLY - S P FOR T</del>		P <sub>1</sub>						-1	-1		0
			P <sub>2</sub>	Security and the second		2	1		.2	.1	-1	110

Step 4: Computing nonnegative entering b<sub>i</sub>/e<sub>i,s'</sub>.

We obtain

$$b_1/e_{1,1} = 400/1 = 400$$
  
 $b_2/e_{2,1} = 500/2 = 250$  (minimum value)  
 $b_3/e_{3,1} = 240/0.4 = 600$ .

Hence i' = 2 and departing variable is  $d_2$ .

Step 5: Replace basic variable of  $d_2$  with  $x_1$ .

New  $e_{i,s'}$  values can be calculated by the following way,

New 
$$e_{2,s} = 01d e_{2,s}/2$$
 (since  $e_{i',s'} = 2$ )  
New  $e_{1,s} = 01d e_{1,s} - New e_{2,s}$   
New  $e_{3,s} = 01d e_{3,s} - 0.4 New e_{2,s}$ 

New tableau is set up in Table 2-4.

Go to Step 2.

- Step 2:  $a_2 = 140$ , so priority level 2 is not satisfied. Hence examine all non-negative indicator elements in row 2 and find that  $i_{2,7} = 0.2$  is the largest. However, since there is a negative index number above this element  $(I_{1,7} = -1)$ , an exchange cannot be made here without degrading the achievement of priority level 1. Hence, go to  $I_{2,2} = 0.1$ , thus s' = 2. Go to Step 3.
- Step 3:  $x_2$  is the new entering variable.
- Step 4: Computing nonnegative  $b_i/e_{i,s}$ , the following is obtained:

$$b_1/e_{1,2} = 150/0.5 = 300 \text{ (minimum value)}$$
  
 $b_2/e_{2,2} = 250/0.5 = 500$   
 $b_3/e_{3,2} = 140/0.1 = 1400$ 

Thus i' = 1 and departing variable is  $d_1^-$ .

Step 5: Third tableau is shown in Table 2-5.

Go to Step 2.

Step 2:  $a_2 = 110$ , so priority 2 is not completely satisfied. However, positive  $I_{2,6}$  and  $I_{2,7}$  values have negative elements above them at a higher priority  $(P_1)$ , Hence, go to Step 6.

Step 6: k = 2+1 = 3, and k > K, thus the solution is optimal.

The solution to this example is then:

$$x_1^* = 100$$
  $x_2^* = 300$   $\bar{a}^* = \{0, 110\}$ 

### Example 2-6

In this example we shall solve the model of Example 2-3 again. Only the tableaus will be shown since by now the reader should be able to follow the steps resulting in each tableau with little difficulty. Tables 2-6 through 2-11 illustrate the progress of the algorithm.

The optimal solution is read from the last tableau and is:

$$x_1^* = 50$$
  $x_2^* = 200/3$   $\bar{a}^* = (0, 0, 0, 490/3)$ 

# Example 2-7

By the same token, Table 2-12 through 2-14 illustrate the progress of the algorithm applying to solve Example 2-4.

The optimal solution is read from the final tableau and is:

$$x_1^* = 40$$
  $x_2^* = 40$   $\bar{a}^* = (0, 0, 0, 130)$ 

- Table 2-6 Initial Tableau for Example 2-3

			·····			w= ==++++						
	P <sub>4</sub>				5	3			3	5		
	P <sub>3</sub>				•	J					1	
-	P		-	1	ee was		-	F-14 to 100 miles				
P <sub>4</sub> P <sub>3</sub> F <sub>2</sub> P	1 1	x <sub>1</sub>	x2	d,	d <sub>2</sub>	$d_3$	d <sub>4</sub>	d†	d <sub>2</sub> +	d <sup>+</sup> 3	d <sup>+</sup> <sub>4</sub>	Б
1	di	5	3	1				-1				450
5	45	1			1				-1			40
3	d <sub>3</sub>		1			1				-1		4û
	ď <sub>4</sub>	1					1				-1	50
	1	[5]	3					-1		**********		450
	P <sub>2</sub>	5	3						E	2	-1	0
	14		J	P-100 1 100 1 100 1			943		-5 -3	-3 -5		320 0

Table 2-7 Second Tableau for Example 2-3

		or s		P <sub>4</sub> P <sub>3</sub> P <sub>2</sub>				,5	3	•••••	· · · · · · · · · · · · · · · · · · ·	3	5	1	
P <sub>4</sub>	P <sub>3</sub>	F <sub>2</sub>	Р,	P <sub>1</sub>	×ı	×. <sub>2</sub>	1 d;	d <sub>2</sub>	d <sub>3</sub>	d <sub>4</sub>	d <sup>†</sup>	q <sup>5</sup>	d <sup>+</sup> <sub>3</sub>	ď4	Б
	·		1	٦ <u>.</u>		3	1	-5	<u></u> 5	4_	-1	5	- 3		250
	3			x <sub>1</sub>	1	,		1				-1			40
	J	•		d <sub>4</sub>		1		-1	1	3		(I)	-1	,	40
	and the transport was			7		3		-5			-1	[5]		<u>-1</u>	10 250
				P <sub>2</sub>		3		-5			12.		-3	-1	0 120
	24			P <sub>4</sub>	wepperane	***********						-3	-5		0

- Table 2-8 Third Tableau for Example 2-3

98	15			P <sub>4</sub> P <sub>3</sub>			b- 10-10 20-1-	5	3			3	5		1
58				P <sub>2</sub>			1	J	,					1	
P <sub>4</sub>	P <sub>3</sub>	P <sub>2</sub>	P <sub>1</sub>	٧	×1	×2	d <sub>1</sub>	d <sub>2</sub>	$d_3^{\overline{z}}$	d <sub>4</sub>	d†	d <sub>2</sub> +	d <sub>3</sub> <sup>+</sup>	d <sub>4</sub> <sup>+</sup>	Б
			1	d <sub>1</sub>		3	1			-5	-1			(5)	200
				×1	1					1				-1	50
	3	,		d <sub>3</sub>		1			1				-1		40
3		-	***	d <sub>2</sub> <sup>+</sup>				-1		1		1		-1	10
				P) -		3		0.000.00.00.00 <del>.0</del> 0.00.00 <del>.00</del>		-5	-1			5	200
				P <sub>2</sub>		2		-					_	-1	0
				P <sub>3</sub>		3	ĵ.	-5					-3		120
				P <sub>4</sub>		·		-3		3			-5	-3	30

Table 2-9 Fourth Tableau for Example 2-3

	P <sub>4</sub>								3	5		]
	P <sub>3</sub> P <sub>2</sub>	٠		•	5	3				9.	1	
P <sub>4</sub> P <sub>3</sub> P <sub>2</sub> P <sub>1</sub>	Р <sub>1</sub> V	ХJ	x <sub>2</sub>	ر ا ا	d <sub>2</sub>	d <sub>2</sub>	d <sub>4</sub>	d <sup>+</sup>	d <sup>+</sup> <sub>2</sub>	d <sup>+</sup> <sub>3</sub>	d <sup>+</sup>	Б
1 '	d <sub>4</sub> <sup>+</sup>		3/5	1/5			-1	-1/5	-	***************************************	1	40
	x <sub>1</sub>	1	3/5	1/5				-1/5				90
3 ,	d <sub>3</sub>	(	1)			1				-1		40
3	d <sup>+</sup>		3/5	1/5	-1			-1/5	1			50
	P <sub>2</sub>	- Long	3/5	-1 1/5			-1	-1/5	b			0 40
. ·	P <sub>3</sub> P <sub>4</sub>		3 9/5	3/5	-5 -3			-3/5		-3 -5	8	120 150

\_ Table 2-10 Fifth Tableau for Example 2-3

	5		51	P <sub>4</sub> P <sub>3</sub> P <sub>2</sub>		kirangirini garamanga gara		5	3	and the global and		3	5	]	
				P			1	:							
P <sub>4</sub>	P <sub>3</sub>	P <sub>2</sub>	Pı	γ	×ı	x2	d <sub>1</sub>	d <sub>2</sub>	d <sub>3</sub>	d_4	ď	$d_2^{+}$	d <sup>+</sup> 3	d <sup>†</sup> ₄	Б
		1		d <sub>4</sub>			1/5		-3/5	-1	-1/5		3/5	1	16
				×1	1		1/5		-3/5		-1/5		3/5		66
			,	x <sub>2</sub>	,	1			'n				-1		40
3			•	x <sub>2</sub> d <sub>2</sub> <sup>+</sup>			1/5	-1	-3/5		-1/5	1	3/5		26
				Pi			-1	-			-				0
				P <sub>2</sub>			1/5	-5	-3/5 -3	-1	-1/5		3/5		16 0
				P <sub>4</sub>	-	**************************************	3/5	-3	-9/5		-3/5		-16/5		78

Table 2-11 Final Tableau for Example 2-3

					P <sub>4</sub> P <sub>3</sub> P <sub>2</sub> P <sub>1</sub>			1	5	3			3	5	1	
P	1	P <sub>3</sub>	P <sub>2</sub>	P <sub>1</sub>	γ	×ı	<sup>x</sup> 2	d <sub>1</sub>	d <sub>2</sub>	d <sub>3</sub>	d <sub>4</sub>	d <sub>1</sub> <sup>+</sup>	d <sub>2</sub> <sup>+</sup>	d <sup>†</sup> <sub>3</sub>	d+	Б
5					d <sub>4</sub>			1/3		-1	-5/3	-1/3		1	5/3	80/3
	i.				×1	1					1				-1	50
			ş		x <sub>2</sub>		1	1/3			-5/3	-1/3			5/3	200/3
3				•	d <sup>+</sup> <sub>2</sub>				-1		1		1	12	-1	10
					P			-1			*****					0
					P <sub>2</sub> P <sub>3</sub>				-5	-3					-1	0
		¥	(F		P <sub>4</sub>			5/3	-3		-16/3	3 -5/3	<u></u>		16/3	490/3

-- Table 2-12 Initial Tableau for Example 2-4

			8	P <sub>4</sub>		· · · · · · · · · · · · · · · · · · ·	1					***************************************			1
				P <sub>3</sub>				5	3					1	
	· <del></del>	-		Pı								3	5		
P <sub>4</sub>	P <sub>3</sub>	P <sub>2</sub>	P <sub>1</sub>	γ	×1	x <sub>2</sub>	ď,	d2	$d_3$	d <sub>4</sub>	d†	$d_2^+$	$d_3^+$	d <sup>+</sup> 4	Б
1				d <sub>1</sub>	5	3	1				-1				450
		5		d_2	1			1				-1			40
		3		d <sub>3</sub>		1			1				-1		40
				d <sub>4</sub>	1					1				-1	50
				ار ا								-3	-5		0
			ĺ	P <sub>2</sub>	5	3						-5	-3		320
				P <sub>3</sub>	5	3				·	-1		e#.	-1	0 450

Table 2-13 Second Tableau for Example 2-4

				P <sub>4</sub>			1		•					······································	1
				P <sub>3</sub>				5	3					1	
				P1								3	5		
P <sub>4</sub>	P <sub>3</sub>	P <sub>2</sub>	P <sub>1</sub>	٧	×η	xS	d <sub>1</sub>	d <sub>2</sub>	d <sub>3</sub>	d <sub>4</sub>	d†	$d_2^{\dagger}$	<b>d</b> <sup>+</sup> <sub>3</sub>	d <sup>+</sup> <sub>4</sub>	ũ
1				q.		3	1	-5			-1	5			250
				×1	1			1				-1			40
		3		d <sub>3</sub>		1			1	8	8		-1		40
				d <sub>4</sub>				-1		1		1		-1	10
				Pl		[2]		-				-3	-5		0
				P <sub>2</sub> P <sub>3</sub>		3		-5			36		-3		120
				P <sub>4</sub>		3		-5			-1	5		-1	0 250
			•		and the second				n						

Table 2-14 Final Tableau for Example 2-4

- × · · ·	1											ľ
	P <sub>4</sub>			1	¥.						,	
<u>.</u>	P <sub>3</sub>				5	3					1	
	P <sub>2</sub>				5	3			3	5		
P <sub>4</sub> P <sub>3</sub> P <sub>2</sub> P <sub>1</sub>	٧	×ı	x <sub>2</sub>	d <sub>1</sub>	d <sub>2</sub>	d <sub>3</sub>	d <sub>4</sub>	d†	d <sub>2</sub> <sup>+</sup>	d <sub>3</sub> <sup>+</sup>	d <sup>+</sup> 4	Б
1	ďį			1	-5	-3		-1	5	3		130
	×1	1			1				-1			40
	x <sub>2</sub>		1			1				-1		40
,	d <sub>4</sub>				-1		1		1		-1	10
	را						ales againment anailtagi	4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4	-3	-5		0
	P <sub>2</sub>				-5	-3						0
	P <sub>3</sub>				-5	-3		-1	5	3	-1	0 130

4.2 The modified revised simplex method. A condensed tableau is introduced by Ignizio [4]. Table 2-2 is condensed to Table 2-15. This new tableau eliminates  $d_{\overline{i}}$  from the heading. The columns of  $d_{\overline{i}}$  in the heading simply reflect the set of basic variables associated with the identity matrix of the tableau. Now, it is unnecessary to include the columns associated with  $d_{\overline{i}}$ , since, if these variables are basic, there will always be an identity matrix associated with their columns. Removal of these columns of the extended tableau results in a condensed tableau shown in Table 2-15. Explanation of headings and elements are identical with the extended tableau.

Another savings in computation may be achieved by computing only those index rows necessary for the iteration under consideration. That is, if we are presently interested in achieving priority level k then only the index rows associated with  $P_1, \ldots, P_k$  need to be computed (i.e.,  $P_{k+1}, \ldots, P_K$  is not needed).

#### The Algorithm.

Throughout 6 steps of the algorithm, only Step 5 is changed.

# Step 5: Establishment of the New Tableau.

- (a) Set up a new tableau with all  $e_{i,s}$ ,  $b_i$ ,  $I_{k,s}$  and  $a_k$  elements empty. Exchange the positions of the basic variable heading in optimum row (i') with the nonbasic variable heading in key column (s'). Calculations of the  $e_{i,s}$  and  $b_i$  elements is given in (b), (c) and (d) below.
- (b) Row i' of the new tableau (except for  $e_{i',s'}$ ) is obtained by dividing row i' of the previous tableau by  $e_{i',s'}$ .
- (c) Column s' of the new tableau (except for  $e_{i',s'}$ ) is obtained by dividing column s' of the previous tableau by  $(-e_{i',s'})$ .

Table 2-15 The Condensed Tableau for the Modified Revised Simplex Method

	PK	₩ <sub>K,1</sub>		W <sub>K</sub> ,n	W <sub>K</sub> ,n+1		₩ <sub>K,n+m</sub>	)
l oft	:		:	N		:		Top Stub
Left Stub	P <sub>1</sub>	w <sub>1,1</sub>	•••	₩ <sub>l,n</sub>	W <sub>1,n+1</sub>	• • •	₩ <sub>l,n+m</sub>	) Stub
P <sub>K</sub> P <sub>1</sub>	٧	x <sub>1</sub>		x <sub>n</sub>	$d_1^{\dagger}$		d <sup>+</sup> m	Б
u <sub>1,K</sub> u <sub>1,1</sub>	d- 1	e <sub>1,1</sub>		e <sub>l,n</sub>	e <sub>l,n+l</sub>	• • •	e <sub>l,n+m</sub>	b <sub>1</sub>
:	:		:			:		:
и <sub>т,К</sub> и <sub>т,1</sub>	d <sub>m</sub>	e <sub>m,1</sub>	• • •	e <sub>m,n</sub>	e <sub>m,n+l</sub>		e <sub>m,n+m</sub>	ь <sub>ш</sub>
	Pı	I <sub>1,1</sub>		I <sub>l,n</sub>	I <sub>l,n+l</sub>		I <sub>l,n+m</sub>	a <sub>1</sub>
Index Rows	:		•			:		:
	PK	<sup>I</sup> K,1		I <sub>K,n</sub>	I <sub>K,n+1</sub>	• • •	Ι <sub>Κ</sub> ,n+m	a <sub>K</sub>

(d) The new element at position  $e_{i',s'}$  is the reciprocal of  $e_{i',s'}$ . The remaining elements are computed as follows.

Let  $\hat{b}_i$  and  $\hat{e}_{i,s}$  represent the new set of elements to be computed and  $b_i$  and  $e_{i,s}$  represent the previous value for these elements (from the previous tableau). Then for those elements not in row i' or column s':

$$\hat{e}_{i,s} = e_{i,s} - \frac{(e_{i's})(e_{i,s'})}{e_{i',s'}}$$

$$b_{i} = b_{i} - \frac{(b_{i})(e_{i,s'})}{e_{i',s'}}$$

- (e) Establish the new values for  $I_{k,s}$  and  $a_k$
- (f) Return to Step 2.

To illustrate the procedure of the modified revised simplex method, we shall use the same Examples of 2-1, 2-3, and 2-4. The reader will realize that both methods give exactly the same tableau and solutions except for the simpler heading.

### Example 2-8

Tables 2-16 through 2-18 illustrate the progress of applying the algorithm to Example 2-1. The optimal solution is read from the last tableau and is:

$$x_1^* = 100 \qquad x_2^* = 300$$

$$\bar{a}^* = (0, 110)$$

# Example 2-9

Tables 2-19 through 2-24 illustrate the progress of applying the algorithm to Example 2-3. Until the third tableau we don't have to calculate index row

of k>l because we are presently interested in achieving priority level l. Index rows in the fourth and fifth tableau are calculated up to the 2nd row and all index row calculations are performed in the final tableau. The optimal solution is:

$$x_1^* = 50$$
  $x_2^* = 200/3$ 

$$\bar{a}^* = (0, 0, 0, 490/3)$$

### Example 2-10

Table 2-25 through 2-27 illustrate the progress of applying the algorithm to Example 2-4. The optimal solution is

$$x_1^* = 40$$
  $x_2^* = 40$ 

$$\bar{a}^* = (0, 0, 0, 130)$$

## 5. Complications and Their Resolutions

- 5.1 Right-hand side value. In an objective such as maximizing profit or minimizing cost, there is no target value specified. This causes no problem as long as a reasonable value (an aspiration level) is given. Alternatively, one could use a right-hand side value that determines either an upper bound in maximization or a lower bound in minimization. Nevertheless, it is still important that such upper or lower bound values be reasonable. Unreasonable levels can serve to degrade any resulting solution. For example, if we set the profit of an objective to some unreasonably high value, the achievement of this value can result in less likelihood of the achievement of lower priority objectives.
  - 5.2 Negative right-hand side. Consider the objective below:

$$G_1 = -2x_1 - 3x_2 + d_1 - d_1^+ = -30$$

Table 2-16 Initial Condensed Tableau for Example 2-1.

		P <sub>2</sub>	1		1	1		
P <sub>2</sub>	Pı	V 1	Х1	× <sub>2</sub>	d <sub>1</sub> +	d <sup>+</sup> <sub>2</sub>	d <sup>+</sup> 3	Б
	1	d_ 1	1	1	<del>'</del> -		<u> </u>	400
		d <sub>2</sub>	2	1		-1		500
1		d <sub>3</sub>	0.4	0.3	ū	le .	-1	240
		P <sub>1</sub>			-1	-1		0
		P <sub>2</sub>	0.4	0.3			-1	240

Table 2-17 Second Condensed Tableau for Example 2-1.

	P <sub>2</sub>			1	1		
P <sub>2</sub> P <sub>1</sub>	٧	d <sub>2</sub>	× <sub>2</sub>	d†	d <sub>2</sub> +	d <sup>+</sup> 3	Б
	d <sub>1</sub>	-1/2	1/2	-1	1/2	8	150
	×1	1/2	1/2		-1/2		250
1	d <sub>3</sub>	-0.2	0.1		0.2	-1	140
	P <sub>1</sub>			-1	-1		0
	P <sub>2</sub>	-0.2	0.1		0.2	-1	140

Table 2-18 Final Condensed Tableau for Example 2-1.

	P <sub>2</sub>				<del></del>		
	P <sub>1</sub>		3	1	1		
P <sub>2</sub> P <sub>1</sub>	٧	d <sub>2</sub>	d <sub>1</sub>	d†	d <sup>+</sup> 2	$d_3^+$	Б
	x <sub>2</sub>	-1	2	-2	1		300
	×1	1	-1	1	-1		100
1	d <sub>3</sub>	-0.1	-0.2	0.2	0.1	-1	110
•	P <sub>1</sub>			-1	-1		0
	P <sub>2</sub>	-0.1	-0.2	0.2	0.1	-1	110

Table 2-19 Initial Condensed Tableau for Example 2-3.

				P <sub>4</sub>				3	5		
				P <sub>3</sub>							
				P <sub>2</sub>						1	i e
page and the second		salak anadi di dalah Persak		P <sub>1</sub>	hamma di Mingdiji haya haka haka ku ya da ƙasar di S		SCHOOLSHIP TO THE USE OF				
. P <sub>4</sub>	P <sub>3</sub>	P <sub>2</sub>	P <sub>1</sub>	У	× <sub>1</sub>	x <sub>2</sub>	d†	d <sub>2</sub> <sup>+</sup>	d <sup>+</sup> 3	d <sub>4</sub> <sup>+</sup>	Б
			-1	d <sub>1</sub>	5	3	-1				450
	5			d <sub>2</sub>	1			-1			40
	3			d <sub>3</sub>		1			-1		40
				d <sub>4</sub>	1					-1	50
				P <sub>1</sub>	5	3	-1				450

Table 2-20 Second Condensed Tableau for Example 2-3.

					P <sub>4</sub>				3	5		
					P <sub>3</sub>	5						
					P <sub>2</sub>						1	
					P <sub>1</sub>							
	P <sub>4</sub>	Р3	P <sub>2</sub>	P <sub>1</sub>	٧	d <sub>2</sub>	x <sub>2</sub>	d†	d <sup>+</sup> 2	d <sup>+</sup> 3	d <sub>4</sub> +	Б
				1	ď	-5	3	-1	5			250
					× <sub>1</sub>	1			-1			40
		3			d <sub>3</sub>		1			-1 .		40
					d <sub>4</sub>	-1			1		-1	10
•					P <sub>1</sub>	-5	3	-1	5			250

Table 2-21 Third Condensed Tableau for Example 2-3.

					150					The second second second second	
				P <sub>4</sub>				¥(	5		
				Р3	5						
		ži.		P <sub>2</sub>	0					1	
				P <sub>1</sub>			ppagasa ka aad pasa pasah i 145 maa				
P <sub>4</sub>	Р3	P <sub>2</sub>	P <sub>1</sub>	٧	d <sub>2</sub>	<sup>x</sup> 2	$d_1^+$	$d_4^-$	$d_3^+$	d <sub>4</sub> +	Б
			1	d <sub>1</sub>		3	-1	-5		5	200.
				×ı				1		-1	50
	3			d <sub>3</sub>	e	1			-1		40
3				d <sub>2</sub> +	1			1		-1	10
AND DESCRIPTION OF THE PARTY OF		ALL PROPERTY OF THE PERSON NAMED IN		P <sub>1</sub>		3	-1	-5		5	200

Table 2-22 Fourth Condensed Tableau for Example 2-3.

				P <sub>4</sub>			***********	The way and the second section of the second	5		
				P <sub>3</sub>	5		12	3			
				P <sub>2</sub>							
				P <sub>1</sub>						.1	
P <sub>4</sub>	Р3	P <sub>2</sub>	P <sub>1</sub>	٧	d <sub>2</sub>	×2	d†	d <sub>4</sub>	d <sup>+</sup> 3	d <sub>1</sub>	Б
		1		d <sup>+</sup> 4		3/5	-1/5	-1		1/5	40
				×ı		3/5	-1/5			1/5	90
	3			d <sub>3</sub>		1			-1		40
3				d <sub>2</sub> +	-1	3/5	-1/5			1/5	50
				P <sub>1</sub>						-1	0
				P <sub>2</sub>		3/5	-1/5	-1		1/5	40

Table 2-23 Fifth Condensed Tableau for Example 2-3.

					D	<del>                                      </del>				5	the spinished property.	
				8	P <sub>4</sub>		12			IJ		
					P <sub>3</sub>	5	3				is .	
		8			P <sub>2</sub>							
			*	180	P <sub>1</sub>						8	
	P <sub>4</sub>	Р <sub>3</sub>	P <sub>2</sub>	P <sub>1</sub>	V	d <sub>2</sub>	d <sub>3</sub>	d <sup>+</sup> 1	d <sub>4</sub>	d <sup>+</sup> 3	d <sub>1</sub>	Б
			1		d <sup>+</sup> <sub>4</sub>		-3/5	-1/5	-1	3/5	1/5	16
				3	x <sub>1</sub>		-3/5	-1/5		3/5	1/5	66
					x <sub>2</sub>		1			-1		40
-		Sec. 1			d <sub>2</sub> +	1	-3/5	-1/5	Division Statement Statement	3/5	1/5	26
	and the second second		tin anus-s, Jünstil üssi		Pı						-1	0
					E.	2 <b>*</b> 5	_3/5	_1/5	_1	2/5	1/5	16

Table 2-24 Final Condensed Tableau for Example 2-3.

				P <sub>1</sub> P <sub>2</sub> P <sub>3</sub> P <sub>4</sub>	5	3	alle de la company de la compa		1	1	
P <sub>4</sub>	Р3	P <sub>2</sub>	P <sub>1</sub>	٧	d <sub>2</sub>	d <sub>3</sub>	d <sup>+</sup>	d <sub>4</sub>	d <sub>4</sub> +	d <sub>1</sub>	Б
5				d <sup>+</sup> 3		-1	-1/3	-5/3	5/3	1/3	80/3
				× <sub>1</sub>				1	-1		50
				x <sub>2</sub>			-1/3	-5/3	5/3	1/3	200/3
3		٠		d <sup>+</sup> <sub>2</sub>	-1			1	-1		10
				P <sub>1</sub>						-1	0
				P <sub>2</sub>					-1		0
				P <sub>3</sub>	-5	-3			22		0
				P <sub>4</sub>	-3	-5	-5/3	-16/3	16/3	5/3	490/3

Table 2-25 Initial Condensed Tableau for Example 2-4.

					-						
				P <sub>4</sub>				·			
				P <sub>3</sub>				60	•	1	
				P <sub>2</sub>							4
4				Pl				3	5		
P <sub>4</sub>	$P_3$	P <sub>2</sub>	Pı	٧	x <sub>1</sub>	x <sub>2</sub>	$d_1^+$	$d_2^+$	$d_3^+$	d <sub>4</sub> +	Б
1				d <sub>1</sub>	5	3	-1		·		450
		5		d <sub>2</sub>	1			-1			40
		3		d <sub>3</sub>		1			-1		40
				d <sub>4</sub>	1					-1	50
	£.		1655 (15 to 16	P <sub>1</sub>				-3	-5		0
				P <sub>2</sub>	5	3		-5	-3		320

Table 2-26 Second Condensed Tableau for Example 2-4.

	P <sub>4</sub>						1	
	P <sub>2</sub>	5				F		
	P <sub>1</sub>		210	d <sub>1</sub> <sup>+</sup>	3 .+	5 .+		-
P <sub>4</sub> P <sub>3</sub> P <sub>2</sub> F	1 7	d <sub>2</sub>	<sup>x</sup> 2	d <sub>1</sub>	d <sub>2</sub> +	d <sub>3</sub> +	d <sub>4</sub>	Б
	d <sub>1</sub>	-5	. 3	-1	5			250
	×1	1			-1			40
3	d <sub>3</sub>		1			-]-		40
	$d_{4}^{-}$	-1			1		-1	10
	P <sub>1</sub>				-3	-5		0
	P <sub>2</sub>	-5	3			-3		120

Table 2-27 Final Condensed Tableau for Example 2-4.

	P <sub>4</sub>			er e e e e e e e e e e e e e e e e e e			1	
3	P <sub>2</sub>	5	3		3	5	·	
$P_4$ $P_3$ $P_2$ $P_1$	P <sub>1</sub>	d <sub>2</sub>	d <sub>3</sub>	d†	d <sup>+</sup> <sub>2</sub>	d <sup>+</sup> <sub>3</sub>	d <sup>+</sup> <sub>4</sub>	Б
1	d <sub>1</sub>	-5	-3	-1	5	3		130
·	×1	1			-1			40
	x <sub>2</sub>		1			-1		40
	d <sub>4</sub>	-1			1		-1	10.
Belleville Colores and Selection recognises and Selection (Selection Production Selection and Advances of Selection	P <sub>1</sub>	programming programmer in			-3	-5		0
	P2	-5	-3					0
	P <sub>3</sub>						-1	0
	P <sub>4</sub>	-5	-3	-1	5	3		130

There is basically nothing wrong with this objective from a mathematical or physical point of view. However, the modified simplex algorithm requires that all right-hand side values be nonnegative. This requirement is easily satisfied by simply multiplying  $G_1$  by (-1). The new objective becomes:

$$-G_1 = 2x_1 + 3x_2 - d_1^- + d_1^+ = 30$$

If we desire to achieve exactly -30 in  $G_1$ , this is accomplished by minimizing both  $d_1^-$  and  $d_1^+$  at the same priority level. However, if we wish to make  $G_1$  equal to or greater than -30, then  $d_1^-$  must be minimized in - $G_1$  Similarly, to satisfy the desire to have  $G_1$  equal to or less than -30,  $d_1^+$  must be minimized in - $G_1$ .

- 5.3 Tie for entering variable. It may occur, during the progress of the modified simplex algorithm, that a tie occurs in the selection of the new entering variable, i.e., two or more columns with the same  $I_{k,s}$  value at the highest unattained priority level. If the tie cannot be broken, selection between the contending variables may be made arbitrarily. The other variable will generally be introduced into the solution base in the subsequent iterations.
- 5.4 Tie for the departing variable. The departing variable is selected through the choice of the smallest, nonnegative  $b_i/e_{i,s'}$ . It may happen that two or more rows have the same  $b_i/e_{i,s'}$  value. The tie may be broken by selecting the row that has the basic variable with the higher priority level. In some cases the basic variables will not have an associated priority level and ties must be broken arbitrarily.

5.5 Alternative optimal solutions. It is possible that two or more points provide optimal solutions that attain exactly the same level of goals. Such a situation never occurs as long as there is a single deviation variable at each priority level and differential weights are assigned in the same priority level when there is more than a single goal at each priority level. To illustrate the point, let us examine Example 2-3. Suppose the president of the company altered the  $P_4$  level and made each weight same value. The achievement function is then:

$$\bar{a} = \{(d_1^-), (d_4^+), (5d_2^- + 3d_3^-), (d_2^+ + d_3^+)\}$$

Optimal solution is at any point on the line segment AB in Figure 2-8.

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#### CHAPTER 3

#### LINEAR PROGRAMMING MODEL

#### 1. Introduction

Throughout the less developed nations of the world the quest for rapid economic progress has been predicated largely upon the formulation and implementation of comprehensive development plans, which cover all major aspects of the national economy [12]. Thus, after World War II, many developing countries started their economic planning in order to establish new patterns of welfare statism. Korea is one of the first nations to recognize this urgent need. Soon after the military coup in 1961, the Korean government made clear its intention to manage the national economy in accordance with a fully articulated, comprehensive plan. The First Five-Year Development plan was drawn up in 1961. The second development plan lasted from 1967 to 1971, and the third development plan began in 1972 and ended in 1976. The model presented herein covers the period 1977-1981, which corresponds to the period of Korea's Fourth Five-Year Development plan.

Korea's development planning methodology involved a three-pronged approach, the plan consisting of an aggregate model, a sectoral model, and an investment program. The aggregate model was to be used to select a growth rate consistent with the supply of foreign and domestic savings and foreign exchange. Given the growth rate, the sectoral annual input-output model was to be employed to assure the balance of demand and supply in each sector and to set minimal levels of investment. The sectoral model was to rely on some macroeconomically derived parameters, such as private consumption and imports, for the exogenous estimates of final demand. Thus, the Korean sectoral model

# Symbols Used in the Model

Variabl	es and Parameters*	Dimensions for n sectors, k activities T periods
A(t)	net foreign capital inflow in period t	Т
a(t)	matrix of interindustry current flow coefficients appropriate to period t	s nxk
b(t)	diagonal matrix of capital-output ratio	kxk
c(t)	<pre>column vector, each term of which indicates the proportion of the sector's output in total consumption</pre>	n
C(t)	aggregate consumption in each period	Т
D(t)	<pre>vector of the amount of fixed capital (components in each sector that is completely depreciated in period t</pre>	s) k
d	diagonal matrix of depreciation rate to capital stock	kxk
E(t)	column vector of exports by each sector	n
F(t)	column vector of deliveries by each sector for private consumption purposes	<u>n</u>
G(t)	column vector of deliveries by each sector for government consumption	n
H(t)	column vector of deliveries by each sector for inventory accumulation	n
I	identity matrix	nxn or kxk
I(t)	column vector of investment by each sector	n
J(t)	column vector of deliveries of intermediate inputs by each sector	n
K(t)	column vector of fixed-capital capacity in each sector	k
M(t)	column vector of total imports	n
M'(t)	column vector of noncompetitive imports	k
m'(t)	diagonal matrix of import coefficients relating noncompetitive imports to sectoral output	t kxk

Variabl	es and Parameters*	Dimensions for n sectors, k activities T periods		
M"(t)	column vector of competitive imports	k		
m"(t)	column vector of coefficients indicating in each sector the maximum use of the foreign exchange available after noncompetitive imports requirements have been satisfied	n		
p(t)	capital composition matrix in period t	nxk		
r	social discount rate	1		
S <sup>D</sup> (t)	sum of domestic savings in period t	т		
S <sup>F</sup> (t)	savings by foreign sectors in period t	T		
s(t)	matrix of inventory coefficient in period t	nxk		
u	unit row vector	nxn		
W	social welfare indicator	1		
X(t)	column vector of gross domestic outputs	k		
Z(t)	column vector of new additions to fixed-capital capacity in each sector	k		
βo	savings constant	1		
β	marginal propensity to save	1		
p(t)	minimum rate of growth of aggregate consumption $C(t)$ over $C(t-1)$	1		
δ	marginal contribution of capital stock to the aggregate consumption	1		

<sup>\*</sup>Variables in capital letters; parameters in small letters.

was designed to test the consistency of a development program based on targets derived from the macro-model and to indicate total investment requirements and the appropriate sectoral allocation of investment [1].

This linear programming model was adopted from Eckaus and Parikh's multi-sectoral dynamic model [4]. Joe [7] embodied the terminal condition of capital stock into the objective function, thus deleting terminal conditions of capital from the set of constraints. Lack of reliable labor coefficients impedes the addition of labor supply constraints to this model.

The primary purpose of this chapter is to suggest the up-to-date linear economic model of Korea as a first step in the development of the linear goal programming model, hence the postoptimal sensitivity analysis is not considered.

#### 2. Model Formulation

- 2.1 Industry classification. The 1970 input-out tables, recently published by the Bank of Korea, are in the form of a 56x56 matrix. But, for the purpose of this study they are further aggregated into 16 sectors so that the program becomes manageable. The sixteen sectors are:
- 1. Agriculture, forestry, and fisheries
- 2. Mining
- Processed foods
- 4. Textiles
- 5. Lumber, plywood, wood product, and furniture
- 6. Chemicals
- 7. Petroleum products and coal products (fuel)
- 8. Non-metallic mineral products
- 9. Metallurgical products
- 10. Machinery

- 11. Other manufacturing
- 12. Construction
- · 13. Electricity and water
  - 14. Transportation and communication
- 15. Banking, insurance, and real estate
- 16. Commerce, services, and others
- 2.2 Objective function. Ideally, the objective function should be a social welfare function. Since this function is unknown and aggregate private consumption is the most important determinant of welfare, Eckaus and Parikh [4] has used this exclusively as the objective function. To this definition of the objective function Joe [7] has embodied the terminal condition of capital stock into the objective function, and calls it social welfare indicator (W). Hence,

$$W = f(C,K) \tag{3.1}$$

The derivative of eq. (3.1) is

$$dW = \frac{\partial f}{\partial C} dC + \frac{\partial f}{\partial K} dK$$
 (3.2)

It is assumed that W is proportional to C at a given value of K, because K employs only in the final planning year. The mathematical expression of this will be  $\frac{\partial f}{\partial C} = 1$ . Equation (3.2) is divided by  $\frac{\partial f}{\partial C}$ , it becomes

$$dW = dC + \frac{\partial C}{\partial K} dK \tag{3.3}$$

Integrating both sides yields

$$\int dW = \int dC + \frac{\partial C}{\partial K} \int dK$$
 (3.4)

or 
$$W = C + \frac{\partial C}{\partial K} \cdot K$$
 (3.4)

A one-year investment lag makes the investment in year t matured into capital stock in the following year. Assuming that the capital stock at the end of (t+1) year continues to produce the aggregate consumption at the constant marginal productivity of  $\delta = \frac{\partial C}{\partial K}$  and that the social discount rate is constant after (t+1) years, the sum of a geometric progression gives  $(\frac{1+r}{r})\delta$ . First, starting with a single year planning horizon and measuring the variables in total amounts;

$$W = C(t) + \left(\frac{1+r}{r}\right) \delta K(t+1)$$
 (3.5)

A multi-year planning horizon requires discounting as follows;

$$W = \sum_{t=1}^{T} \frac{c(t)}{(1+r)^{t}} + \frac{\left(\frac{1+r}{r}\right) \delta K(T+1)}{(1+r)^{T+1}}$$
(3.6)

where T is the terminal year. A simplification of eq. (3.6) leads to;

$$W = \sum_{t=1}^{T} \frac{C(t)}{(1+r)^{t}} + \frac{\delta K(T+1)}{(1+r)^{T} \cdot r}$$
 (3.6)'

If the depreciation of the capital stock is considered, the final form of the objective function becomes

$$W = \sum_{t=1}^{T} \frac{C(t)}{(1+r)^{t}} + \frac{\delta^{*}}{(1+r)^{T} \cdot r} K(T+1)$$
 (3.7)

where  $\delta^* = \delta(1-d/b)$ 

- 2.3 Constraints. Four types of constraints are involved in the model, namely, physical balance, capacity, foreign exchange, and savings constraints.
  Brief explanations of these follow:
- 1) Consumption growth constraints (CG)

$$C(t+1) \ge [1 + \rho(t)]C(t)$$
  $t = 0, ..., T-1$  (3.8)  
 $C(0) = \overline{C(0)}$ 

where  $\overline{C(0)}$  = the aggregate private consumption in the pre-plan period. From now on "bar" indicates preassigned value.

These constraints represent the monotonic growth of aggregate consumption between successive periods.

2) Capacity constraints (CC)

This insures that output in each sector in each period can not exceed the amount producible with the fixed capital in that sector available at the beginning of that period.

Capital accounting relationships (CAR)

$$K(t+1) = K(t) + I(t) - D(t)$$
  $t = 1, ..., T$  (3.10)  
 $K(1) = \overline{K(1)}$ 

This states that the capital available at the beginning of period (t+1) is equal to the capital available at the beginning of the previous period (t)

plus the new completed additions to capacity less the depreciated capacity.

Investment and depreciation variables have the following relationships.

3-1) Investment requirement

$$I(t) = p(t)Z(t+1)$$
  $t = 1, ..., T$  (3.11)

3-2) Depreciation of capital

$$D(t) = dX(t)$$
  $t = 1, ..., T$  (3.12)

With these subrelationship, eq (3.10) becomes

$$K(t+1) - K(t) - p(t)Z(t+1) + dX(t) = 0$$
  $t = 1, ..., T$  (3.10)

4) Balance of payment constraints (BOP)

$$uM(t) \leq \overline{A(t)} + u\overline{E(t)}$$
  $t = 1, ..., T$  (3.13)

The total amount of imports in each period is limited by the available foreign exchange. Imports are divided into non-competitive imports and competitive imports. Import subrelationships follow:

$$M(t) = M'(t) + M''(t)$$
  $t = 1, ..., T$  (3.14)

$$M'(t) = m'(t) X(t)$$
  $t = 1, ..., T$  (3.15)

with the subrelationships above, eq (3.13) becomes

$$um'(t) X(t) + uM''(t) \le \overline{A(t)} + u\overline{E(t)}$$
  $t = 1, ..., T$  (3.13)'

5) Competitive import ceilings (CIC)

$$uM''(t) \le m''(t) [\overline{A(t)} + u\overline{E(t)} - uM'(t)] t = 1, ..., T$$
 (3.16)

This indicates that competitive imports make use of whatever foreign exchange is left after non-competitive imports are satisfied. With import subrelations of eq. (3.14) and (3.15), eq. (3.16) becomes

$$[m''(t)]^{-1} M''(t) + um'(t) X(t) \le \overline{A(t)} + u\overline{E(t)}$$
  $t = 1, ..., T$  (3.16)

6) Distributional relationships (DR)

$$J(t) + H(t) + I(t) + F(t) + G(t) + E(t) \le M(t) + X(t)$$

$$t = 1, ..., T$$
(3.17)

The first six terms represent uses of the output of each sector, and two terms in RHS are the sources of availability of the outputs. Hence, total demand for each sector in each year can not exceed availability in that year. Left-hand-side terms of eq. (3.17) have the following subrelationships with the key decision variables.

6-1) Intermediate product

$$J(t) = a(t) X(t)$$
  $t = 1, ..., T$  (3.18)

6-2) Inventory accumulation

$$H(t) = s(t) [X(t) - X(t-1)] \qquad \chi(0) = \overline{\chi(0)} \qquad t = 1, ..., T \quad (3.19)$$

6-3) Private consumption

$$F(t) = c(t)C(t)$$
  $t = 1, ..., T$  (3.20)

6-4) Government Consumption

$$G(t) = \overline{G(t)}$$
  $t = 1, ..., T$  (3.21)

6-5) Export

$$E(t) = \overline{E(t)}$$
  $t = 1, ..., T$  (3.22)

By substituting eq. (3.11), (3.14), (3.15), (3.18), (3.19), (3.20), (3.21) and (3.22) into eq. (3.17), the following equation is obtained.

7) Savings constraints (SC)

$$uI(t) + uH(t) \le S^{D}(t) + S^{F}(t)$$
  $t = 1, ..., T$  (3.23)

This states that investment and increase in inventory should be limited by the amount of available investment, which is the sum of domestic savings and savings in the foreign sectors. Two kinds of savings have the following subrelationships.

$$S^{D}(t) = \beta_{0} + \beta_{1}\{[I - a(t)] X(t)\}$$
  $t = 1, ..., T$  (3.24)

$$S^{F}(t) = \overline{A(t)} + u[E(t) - M(t)]$$
  $t = 1, ..., T$  (3.25)

By substituting eqs. (3.11), (3.19), (3.24) and (3.25) into eq. (3.23), it becomes

2.4 The basic model. The model has the following final form of the linear programming problem.

maximize W = 
$$\sum_{t=1}^{T} \frac{C(t)}{(1+r)^t} + \frac{\delta(1-d/b)}{(1+r)^T \cdot r} K(T+1)$$
 (3.7)

subject to

$$[1+\rho(t)]C(t) - C(t+1) \le 0$$
  $t = 0, ..., T-1$  (3.8)

$$-K(t) + b(t) X(t) \le 0$$
  $t = 1, ..., T$  (3.9)

$$-K(t) + K(t+1) + dX(t) - p(t) Z(t+1) = 0$$
  $t = 1, ..., T$  (3.10)

$$uM''(t) + um'(t) X(t) \le \overline{A(t)} + \overline{uE(t)}$$
  $t = 1, ..., T$  (3.13)

$$[m''(t)]^{-1}M''(t) + um'(t) X(t) \le \overline{A(t)} + u\overline{E(t)}$$
  $t = 1, ..., T$  (3.16)

$$c(t)C(t) - M''(t) - s(t) X(t-1) + [a(t) - I - m'(t) + s(t)] X(t)$$

$$+ p(t) Z(t+1) < - \overline{E(t)} - \overline{G(t)} \qquad t = 1, ..., T \qquad (3.17)'$$

$$uM''(t) - us(t) X(t-1) + u\{s(t) + m'(t) - \beta_{1}[I-a(t)]\} X(t) + up(t) Z(t+1)$$

$$\leq \beta_{0} + \overline{A(t)} + \overline{uE(t)}$$

$$t = 1, ..., T$$
 (3.23)

$$C(t)$$
,  $K(t)$ ,  $M''(t)$ ,  $X(t)$ ,  $Z(t) \ge 0$ 

where  $C(o) = \overline{C(o)}$ 

 $K(1) = \overline{K(1)}$ 

 $\chi(o) = \overline{\chi(o)}$ 

#### 3. Estimation of Data

#### 3.1 Estimation of parameters

- 1) Intermediate Input-Output Coefficients (a<sub>ij</sub>): This model assumes that input coefficients are constant over the planning horizon, due to the difficulty of adjusting those coefficients to future changes in industrial structure and in order to narrow the scope of this study to the programming technique itself. Thus, the 1970 Input-Output Tables, the latest version available, published by the Bank of Korea [2], are used to estimate the input coefficients. The 16 sectors' input coefficients for this model are calculated simply by a further aggregation of the 52 sectors' transaction tables, as shown in Table 3-1.
- 2) Capital coefficients  $(b_{ij})$ : The Bank of Korea's estimation shows that the aggregate capital coefficients by industries are not in a matrix form of  $(b_{ij})$ , hence Song's [11]estimation by 16 sectors is used. The 16 sectors' capital coefficients are shown in Table 3-2.

Table 3-1 Input Coefficient Matrix for 1970 by 16 Sectors  $(a_{ij})$  [2].

Sections	-1	71	mi	<b>≠</b> 1	so)	-01	7	æ)	<b>6</b> 1	의	=1	21	디	듸	<b>:1</b>	91
1. Agriculture, for- estry, & fisheries	.111347	.021698	410849	.087655	.498706	.002544	.000062	.001314	. 000271	.000453	.081144	.018195	9 90000	.000043	.000179	.020892
2. Mining	.000671	.001675	.002820	.000280	.000325	.021355	.471228	.137231	.043070	.00200.	.001002	.020177	.035385	.000063		,001025
3. Processed foods	.046015		.115709	.000952	.004238	.025450		9,0000.	.000142	960000	.034298	.000021	.000092			,007038
4. Textiles	.006303	.002163	.004646	.369410	.001833	.004656	.001429	.001113	.001623	.003345	.016990	.000724	.000902	.003989	.000766	.008041
S. Lurber, plywood, wood products & furniture	.002424	.001057	.002245	. 000360	.054554	.002299	.000217	.003379	.002036	.010588	.005720	.066080	.000795	018000	.000138	.001811
6. Chesteals	.041653	801400.	.019419	117818	.037561	.283103	.012105	.035882	869510	.026316	.070010	.017759	.005669	. 002925	.000288	.016139
7. Petroleum prod- ucts, & coal products	,006444	.013403	167500.	.007003	.008321	.038862	.013565	189990	.016559	.010668	.007862	.014463	.124183	.095453	.002851	.011433
8. Non-metallic mineral products	.000437	.001122	251200'	691000	.004303	.008785	.000318	.052686	.011846	.010790	.013469	.120352	.001406	.001223	.000075	.002190
9. Metallurgical products	.003022	.020153	190900.	.002555	.006917	.009756	.005560	.027616	.548427	174378	.015694	.136981	.001604	,002826	\$10000	. 002150
10. Machinery	.003156	.018559	192100	.005116	.006475	.004697	.007664	.008046	460900.	.257628	.005303	-064434	.024830	.077597	.702568	.006762
II. Other Manu- facturing	.003164	.010133	.015845	.011268	1005500.	.032661	.002547	.039392	.004642	.025543	.169585	.007620	.004324	.026930	.012571	.048102
12. Construction	.000766	.002781	.000503	.000476	. 00032	.000790	.000738	.000572	.000342	.000554	.000758	.001050	.015555	.003280	.088422	192600
13. Electricity & water	.000113	996510.	.016216	.014071	.008503	.038844	.005257	.061047	.037823	.009933	.010782	.001035	.023027	.002842	.00200	.005852
15. Transportation & communication	.006816	.011321	.018190	.009504	.021894	.033837	.064921	.088229	.026041	.017027	.020999	.040299	.025869	.033649	272210.	.024630
15. Senting, insur- sore, 6 resi	.006286	.021112	.007287	.014368	.017032	.021466	.008495	.014927	.014452	.016718	.012311	.008300	.035847	.010058	.012180	,008537
i6. Comerce, ser- '	.035680	.055546	.102843	.092206	.083248	.119416	.074612	.077158	.076465	.110184	.094255	.102349	.043900	.100595	.031512	.108954
Total intermediate	.274297	.250793	.734276	.733882	.759800	.648521	.669718	. 595120	.805331	.677593	.560209	.619839	.343407	,361982	.167096	.282801
Consumption of fixed capital	.011428	.084496	.011059	.016024	.022906	.059973	.035552	961990	420000	.023625	.013251	.010473	114908	,116908	.068516	368500.
d 1-a }	.725703	.749207	.265724	.266118	.240200	.351479	.331282	.404380	194669	.322407	.439791	.380161	.656593	,638018	.832994	.717199

Table 3-2 Capital Coefficients Matrix (b<sub>ij</sub>) and Capital Composition Matrix (p<sub>ij</sub>) [8].

91								ĕ		(.243)		.706820					.986400
2										.258640		5.899500					6.158140
77										2.520690							
2							*/			.506700		3.021840 2.096790 (.856) (.454)					3,528540 4.617480
77					223							.206600					.206607
11					.007700				.004730	.129200	.000920	.093950					.236500
의					.007160				.011990	.149120	.002160	.144580				**	.315010
প					.002800				.008050	.254900	.001110	.122570					.389430
ωj					.004490				.012190	,572090	.006690	.274560					.870020
7	826				.010660				.006130	,354560 (,659)	.000240	.166080					537670
৩					.007930				.014440	.303280	.005970	.143990					475610
v)					.005930				.007360	.141180	.000120	.070070					735660
কা					.003090	•			.003500	.285330	.000940	137060					670074
ଳା			,		.003260				.004270	.145420	.000500	.107460			*	ă.	240910
<b>~</b> 4			ŧ		.004560				.008650	.275990	.000590	.211900					007108
-1	.124620				.003410				.012410	.101369	.001480	.242983					Vicion.
Sectors	-	2	9	7	so.	. 9	7	æ	6	10	=	12	13	14	15	91	š

The capital composition matrix  $(P_{ij})$  is shown in parenthesis in the same Table 3-2.

- 3) Composition of Private Consumption coefficients ( $c_i(t)$ ): Estimation of private consumption by sectors is obtained from Song's [11] table. Table 3-3 shows the proportions of each sector based on Song's estimation of private consumption by 16 sectors through 1981.
- 4) Import coefficients (m', m"): Non-competitive import coefficients (m') are calculated directly from the inter-industry complementary import transaction table for 1970, 1970 I-O Tables, and Framework of the 1970 Input-Output Tables. To estimate ratio of competitive imports to uncommitted foreign exchange (m"), competitive imports by sectors are first calculated by subtracting non-competitive imports from corresponding total imports. Uncommitted foreign exchange is defined as the sum of exports of commodities and services and net foreign capital inflow less noncompetitive imports. The values of m' and m" are estimated as shown in Table 3-4.
- 5) Inventory-Output Coefficients ( $s_{ij}$ ): The Korea Development Institute estimated the inventory coefficients matrix by using Han's [6] aggregate inventory-output coefficient by sectors for 1968. The inventory-output coefficient matrix for 52 sectors is further aggregated into 16 sectors for this model, as shown in Table 3-5.
- 6) Marginal Contribution of Capital to Aggregate Consumption ( $\delta = \partial C/\partial K$ ): The estimation of marginal contribution of capital by way of  $\Delta C(t+1)/\Delta K(t)$  is to reflect the assumed one-year investment lag. Here 10 years average of 0.356 is used to represent the value of  $\partial C/\partial K$ , as shown in Table 3-6.

Table 3-3 Composition of Private Consumption by Sectors [8].

Sectors	M(i)	1977	1978	1979	1980	1981
1	.506595	.2099	.2021	.1950	.1885	.1826
2	.870212	.0010	.0010	.0010	.0010	.0010
3	1.856269	.1492	.1521	.1547	.1571	.1593
4	<b>.724</b> 539	.0596	.0589	.0583	.0577	.0572
5	.883089	.0030	.0030	.0030	.0030	.0030
6	1.878018	.0030	.0306	.0311	.0316	.0320
7	1.564144	.0241	.0244	.0247	.0250	.0253
8	.78888	.0016	.0016	.0016	.0016	.0016
9	.972799	.0027	.0027	.0027	.0027	.0027
10	<b>3.111</b> 818	.0382	.0394	.0405	.0415	.0424
11	1.588226	.1094	.1111	.1126	.1139	.1152
12						
13	1.930684	.0118	.0120	.0123	.0125	.0126
14	1.853652	.0890	.0907	.0923	.0937	.0950
15	.760211	.0425	.0421	.0417	.0414	.0410
16	1.039909	.2280	.2283	.2285	.2288	.2291

Table 3-4 Imports Coefficients m', m" and  $(m'')^{-1}$  [2].

Sectors	<u>m * </u>	m''	$(m'')^{-1}$
1	.001051	.036457	.304165
2	.002685	.003216	.026831
3	.033822	.130452	1.088379
4	.067614	.175680	1.465723
5	.465055	.012705	.105999
6	<b>.2</b> 09636	.040104	<b>.334</b> 593
7	.336877	.002073	.017295
8	.007835	.012367	.103180
9	<b>.0</b> 85699	.124716	1.040523
10	.087107	,110523	.922109
11	.031087	.119768	.999242
12	.007320	.152592	1.273096
13	.007752	.001806	<b>.0</b> 15068
14	.016420	.022546	.188104
15	.000181	.002103	.017587
16	.003213	.052888	.441252

Note that  $(m'')^{-1}$  is obtained by using a generalized inverse method; that is,  $A^- = \frac{A^+}{A^+ \cdot A}$ 

Table 3-5 Inventory-output Coefficient Matrix (s<sub>ij</sub>) [9].

9]	.0194	1100.	.0125	1010.	7710.	2072	.0211	6000	.0021	6800.	.0818				• 5		.2124
15				•				2	3 <b>4</b>								
14				.0001			.0052	1000		1700.	.0011						.0112
13		.0018		.0001		*000*	.0073			10000	.0002						.0105
17	.0010	6000.			.0020	,0004	.0013	.0052	.0054	.0047							.0209
긔	.0452	.0002	.0187	.0084	.0257	.0358	.0034	9200.	.0078	.0021	.0319	z			4		.1868
0]	.0001	.0003		.0007	.0058	* 0008	.0025	.0027	1250.	5090	.0030						.1295
<b>6</b>	.0002	7600.		.0003	0100.	.0048	.0068	,0056	.1545	.0024	,000			,	٠		.1854
00 j	.000	.0810		5	0160.	.0185	.0339	.0253	.0131	.0031	\$100.						.2079
7		1881.		2000		-0044	.0054		.0015	.0027							.1728
91	.0007	1600.	.0084	.0012	.0109	.0503	.0222	.0026	.0026	.0013	.0013						.1112
νi	.1231	.0002	6000.	.0005	.0222	6600	.0022	.0012	.0030	6000	.0003						.1644
41	.0306		.0002	.0849	.001	.0452	.0023		.0005	9100.	.0007						.1671
ml	.0590		.0170	.0010	.0010	.0040	.0010		.0010		.0010			٠			.0850
7	1510	.0018		.0021	6000.	.0356	6010.	0100.	.0182	1710.	1200						.1098
<b>-</b> 1	.0318		.0131	7000	1000	.0121	- 0004		6000	0001	6000						.0598
Sectors	.1	2		4	5	9	,	60	σ	10	=	12	13	14	15	16	Total

Table 3-6 Marginal Contribution of Capital  $(\frac{\Delta c}{\Delta K})$  [3].

Year	Consumption (C)	A.C.	<u>∧</u> K	AC(1+1)/AK(+)
1962	1,017.73		133,38	.283
1963	1,055.51	37.78	167.79	.443
1964	1,124.20	68.69	155.12	.496
1965	1,201.12	76.92	195.40	.416
1966	1,282.37	81.25	294.28	.389
1967	1,396.87	114.50	358.63	.415
1968	1,545.55	148.68	498.30	.321
1969	1,705.63	160.08	639.23	.279
1970	1,884.25	178.62	650.20	.301
1971	2,080.12	195.87	680.14	.214
	(1000 1071)			25.0
Average	(1962-1971)			• 356

7) The other parameters  $(\rho,d,r,\beta_1)$ : From the historical data we assumed that the minimum growth rate of private consumption  $(\rho)$  is 10%, the social discount rate is 10%, the depreciation rate is 10%, and marginal propensity data  $(\beta_1)$  is 0.2629.

# 3.2 Estimation of exogenous variables.

1) Exports and Net Capital Inflow: The Korean Government has set up an export plan (1971-1980), as shown in Table 3-7, aiming to reach 10 billion U.S. dollars in 1980 in current U.S. dollars. Exports for the target year are estimated by using an average growth rate of export during 1977-1980. Since the export plan is in current U.S. dollars, it is deflated to 1970 constant prices.

Projections of the other source of foreign exchange earnings are obtained from "Long-term projections of the Korean economy" as shown in Table 3-8.

- 2) Government Consumption (G(t)): Lack of fundamental data in the U.S.A. makes it necessary to use Song's estimation of government consumption by 16 sectors, his projections are based on 1968 constant prices and are converted to 1970 constant prices, as shown in Table 3-9.
- 3) Initial Capital Stocks and Inventories: The estimation of initial capital stock by sectors is made simply by exogenously estimating X(1) directly and then multiplying the estimated X(1) by the aggregated capital output ratio, b(t). A simple estimation of X(1) exogenously is to interpolate the past trends of outputs by sectors. The estimation of initial capital stock and inventory levels using Song's [11] output estimation by sectors is shown in Table 3-10.

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Table 3-7 Export Projections (At 1970 Prices) [10]. (Unit: \$ in Million US Dollars, W in Million Won)\*

1981	=	164,960	12,737	13,048	570,993	67,103	93,509	38,211	27,959	269,032	1,278,077	228,646						2,765,184
	64	531	41	43	1,838	216	301	123	06	998	4,116	736						8,901
1980	*	151,291	12,737	13,048	526,879	65,549	77,354	32,309	25,474	214,977	983,550	208,764						2,310,689
•	₩.	487	41	42	1,696	112	249	104	82	692	3,166	672						7,438
1979	× \$	139,176	12,737	12,737	488,047	966, 89	63,385	26,095	23,300	172,727	764,534	197,269						1,964,303
	₩	448	41	41	1,571	206	205	84	75	556	2,461	635						6,323
1978	М	128,924	12,737	12,116	451,078	62,753	52,502	22,057	21,746	139,797	588,079	175,523						1,667,312
								-	22									5,367
1977	3	115,566	12,737	12,116	414,110	59,957	43,803	19,572	19,572	109,974,	447,972	158,747						1,413,813
	₩	372	41	39	1,333	193	141	63	63	354	1,442	511						4,551
	sectors	_	2	က	4	rs.	9	7	ස	თ	0	<u>_</u>	12	13	14	15	16	Total

\* The 1970-averaged foreign exchange rate, 310.66, is applied to calculate won equivalents from U.S. dollars.

Table 3-8 Availability of Foreign Exchanges on Current Account (In Million Dollars) [5].

1981	8,901	-591	9/	8,386 (2,605,195)
1980	7.438	-534	. 91	6,980 (2,168,407)
1979	6,323	-476	83	5,930 (1,842,214)
1978	5,367	-430	82	5,022 (1,560,135)
1977	4,551	-380	109	4,280 (1,329,625)
00	Exports	Invisible Trade Balance	Transfer (net)	Total Availability

\* Figures in parenthesis are won equivalents in millions of 1970 won.

Table 3-9 Projection of Government Consumption (1977-1981) [8] (At 1970 Prices).

Sectors	1977	1978	1979	1980	1981
1	2,488.9	2.693.0	2,914.1	3,152.8	3,452.9
2	27.4	30.6	34.3	38.4	43.2
3	246.2	275.4	274.2	307.6	345.3
4	328.2	336.6	377.1	384.5	431.6
5	1,039.3	1,101.6	1,199.9	1,307.2	1,424.3
6	3,309.5	3,580.4	3,874.0	4,191.0	4,575.2
7	2,488.9	2,662.4	2,879.8	3,114.4	3,409.8
8	519.7	612.1	685.7	769.0	863.3
9	27.4	. 30.6	34.1	38.4	43.2
10	8,287.5	9,464.2	10,593.6	11,957.8	13,509.8
11	83,365.0	95,875.7	109,809.3	125,191.0	142,565.4
12	49,724.4	57,133.7	65,515.3	74,783.9	85,245.8
13	3,883.9	4,192.5	4,559.7	4,960.0	5,438.5
14	10,119.9	11,016.7	11,999.2	13,111.3	14,373.1
15	1,996.7	1,224.1	342.9	346.0	345.3
16	105,493.4	115,889.3	127,739.5	140,801.4	155,600.5
Total	273,346.3	306,118.9	342,832.7	384,454.7	431,667.2

(Unit: in million won)

Table 3-10 Estimation of Initial Capital Stocks and Inventory Levels [8] (Unit: Million Won).

Sectors	Initial Capital Stocks	Initial Inventory Levels
1	776,475	199,221
2	80,872	63,602
3	182,230	69,750
4	342,001	86,781
5	40,439	67,140
6	138,403	169,016
7	140,601	. 65,898.
8	179,485	27,018
9	162,665	100,749
10	237,549	66,361
11	250,737	153,751
12	182,015	
13	576,211	
14	2,668,903	и
15	1,308,605	
16	1,549,832	
Total	8,817,023	1,069,287

# 4. Analysis of Solution

After all the possible substitutions have been made, there remain five key variables which are the gross domestic output X(t), the level of aggregate consumption C(t), competitive imports M''(t), capital stocks K(t), and new capital Z(t). Hence the linear programming model has five key variables and seven key constraints covering the five year planning period. These key variables can be divided into 16 industrial sectors except for C(t). And these distribution relationship (DR), capital constraint (CC) and capital accounting relationship (CAR) have 16 rows each through (16x16) matrix coefficient multiplication. From the computational point of view, this linear model has 325, i.e.,  $(4 \times 16 \times 5 + 1 \times 1 \times 5)$  technological variables and 260, i.e.,  $(3 \times 16 \times 5 + 4 \times 1 \times 5)$  rows.

This linear programming problem required 3 minutes 15 seconds solved by the MPS/360 computer programming using an IBM 370-158 computer. Row and column notations used in computer printout are shown in Table 3-11. For example row 211 indicates the first industrial sector in the third year's distributional relationship (DR) constraints. The computer printout of the optimal solution is presented in Table 3-12.

From the optimal solution the following two important characteristics can be shown. First, total domestic output grows at an annual rate of around 0.24% =  $3 \frac{9011}{8946}$ , but declined a small amount in the final year, as shown in Table 3-13. It shows rapid growth of manufacturing sector, especially in the heavy and chemical industry where the growth rate is 11.9% =  $3 \frac{2500}{1782}$ , while some sectors like mining and social overhead capital achieved negative growth. Secondly, turning to the national income accounts the gross national product

Table 3-11 Notations for Computer Output

# Row (Constraints)

Year	(t) 1	2	3	4	5
Object CG(t) DR(t) CC(t) CAR(t) BOP(t) CIC(t) SC(t)	101 102 103-118 119-134 136-151 152 153 154	156 157-172 173-188 190-205 206 207 208	210 211-226 227-242 244-259 260 261 262	264 265-280 281-296 298-313 314 315 316	318 319-334 335-350 352-367 368 369 370

# Column (technological variables)

Year (t)	239		120	2	
Modelle volkel	1	2	3	4	. 5
Col.					
X(t) C(t)	101-116	166-181	231-246	296-311	361-376
C(t)	117	182	247	312	377
M(t)	118-133	183-198	248-263	313-328	378-393
Z(t+1)	134-149	199-214	264-279	329-344	394-409
K(t+1)	150-165	215-230	280-295	345-360	410-425

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NOTE	KUNZ 75 LL 535.C3000 PORZ 74 CC000 PORZ 75 LL 74.CC000 PORZ 75 LL 13.CCC00 PORZ 75 LL 13.CCC00 PORZ 75 LL 140.C0000 PORZ 75 LL 140.C0000 PORZ 75 PORZ	13.0	NOON NOON BE BUILDING NOON BE BUILDING NOON BE BUILDING NOON BUILDING NO	6.81588 6.81588 6.81580 6.81580 9.01613-
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ROW 23 /L         S. 25686 -         5.25686         NCVE           ROW 23 /L         NCNE         NCNE         NCNE           ROW 23 /L         34.21515 -         34.21515 NONE         NONE           ROW 23 /L         35.21515 -         25.03012 -         25.03012 NONE           ROW 23 /L         UL         NONE         NONE           ROW 24 /L         UL         NONE         NONE           ROW 25 /L         UL         NONE         NONE	ROWZ82 UL 84.21515- 34.215	989		.9.01613- 15.68326-
RCM294         UL         NONE         NONE           RCM284         UL         34.21515         NONE         NONE           RCM284         UL         26.03012-         26.03512         NONE           RCM285         UL         NONE         NONE           RCM287         UL         NONE         NONE           RCM293         UL         NONE         NONE           RCM294         UL         NONE         NONE           RCM295         UL         NONE         NONE           RCM293         UL         NONE         NONE           RCM294         UL         NONE         NONE           RCM295         UL         NONE         NONE           RCM296         UL         NONE         NONE           RCM295         UL         NONE         NONE           RCM296         UL         NONE         NONE           RCM309         EQ         RCM309         EQ           RCM309         EQ         RCM309         EQ           RCM306         EQ         RCM306         EQ           RCM307         EQ         RCM308         EQ           RCM308         EQ	RCW283 UL RCW283 UL RCW284 95 RCW284 95 RCW285 UL RCW287 UL RCW287 UL RCW288 UL RCW289 UL			.0161
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RCM 2887         UL         NONE           RCM 288         BS         77.39850         77.39850           RCM 288         BS         77.39850         77.39850           RCM 290         UL         NONE           RCM 291         UL         NONE           RCM 293         UL         NONE           RCM 294         UL         NONE           RCM 295         UL         NONE           RCM 296         UL         NONE           RCM 296         UL         NONE           RCM 296         EQ         NONE           RCM 301         EQ         NONE           RCM 302         EQ         RCM 303           RCM 303         EQ         RCM 304           RCM 305         EQ         RCM 305           RCM 306         EQ         RCM 307           RCM 305         EQ         RCM 305           RCM 306         EQ         RCM 307           RCM 306         EQ         RCM 307           RCM 306         EQ         RCM 307           RCM 307         EQ         RCM 307           RCM 308         EQ         RCM 307           RCM 307         EQ <td>RCH281 UL 77.29850- 77.88FL289 UL 8FL290 UL</td> <td></td> <td>•</td> <td>.05901</td>	RCH281 UL 77.29850- 77.88FL289 UL 8FL290 UL		•	.05901
ROLARS         BS         77.29850         NONE           ROLARS         UL         NONE         NONE           ROLARS         UL         NONE         NONE           ROLARS         UL         NONE         NONE           ROLARS         UL         NONE         NONE           ROLARS         EQ         NONE         NONE <tr< td=""><td>R0h289 UL 77.29850- 77.886h289 UL 86h289 UL</td><td>NO.</td><td>*</td><td>8</td></tr<>	R0h289 UL 77.29850- 77.886h289 UL 86h289 UL	NO.	*	8
ROH239         UL         NCNE           RCH290         UL         NONE           RCH291         UL         NONE           RCH293         UL         NONE           RCH294         UL         NONE           RCH295         UL         NONE           RCH296         UL         NONE           RCH297         UL         NONE           RCH296         UL         NONE           RCH297         EQ         RCH298           RCH306         EQ         RCH307           RCH307         EQ         RCH307           RCH308         EQ         RCH307           RCH309         EQ         RCH307           RCH309         EQ         RCH307           RCH309         EQ           RCH309         EQ           RCH309         EQ           RCH309         EQ           RCH309         EQ           RCH309         EQ	ROH239	50	٠	
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Table 3-13 Output Level by Industry.

(Unit: Billions of 1970 Won)

		BONDAN ST		HAND IN A COURT HAND IN THE STREET	
Industry	1977	1978	1979	1980	1981
Agriculture, Forestry & Fishery	1599	1463	1610	1618	1594
Mining	155	134	111	93	77
Manufacturing	4256	4705	4701	4750	4525
Heavy & Chemical Industry	1782	2197	2267	2500	2308
Other Manu.	2474	2508	2434	2250	2217
Social Overhead Capital (SOC)	1151	969	852	802	<b>7</b> 93
Trade, Services to Others. (TOS)	1785	1772	1759	1748	1736
Total	8946	9043	9033	9011	8725

Source: Table 3-12

Note: Sectors 6 to 10 are classified to heavy and chemical industry; sectors 3,4,5, and 11 to other manufacturing; SOC covers sectors 12, 13, and 14; and trade, services, and other sectors 15 and 16.

as calculated from the expenditure side is the sum of private consumption (C), government consumption (G), business investment (I+H), and the sale of goods and services abroad minus purchases from abroad (E-M). GNP, calculated this way, grows at the annual growth rate of 4.1%  $\left\{=\frac{4\sqrt{5274}}{4486}\right\}$  from 4,486 billion Won to 5,274 billion Won as shown in Table 3-14.

Table 3-14 National Income Accounts.

(Unit: Billions of 1970 Won)

Classification	<u>1977</u>	<u>1978</u>	<u>1979</u>	1980	1981
Consumption	3579	3943	4343	4784	5272
Private	3306	3637	4000	4400	4840
Government	273	306	343	384	432
Investment	907	480	207	0	2
Fixed Inv.	870	433	95	0	2
Inventory Inc.	37	47	112	0	0
Foreign Exchange	0	0	0	0	0
Receipts	1330	1560	1842	2168	2605
Payments	1330	1560	1842	2168	2605
GNP	4486	4423	4550	4784	5274

Source: Table 3-12

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# Chapter 4

### LINEAR GOAL PROGRAMMING MODEL

### 1. Introduction

Economic planning, especially in developing countries, is the selection of the optimum allocation of resources among many competing development goals. To employ this comprehensive economic planning effectively, economic development goals are desired to be established in a hierarchical order of importance. Since economic planning problems involve multiple goals, it has long been desired to have efficient analytical techniques to handle this problem. Goal programming is very appropriate for solving the economic planning problem because it can handle multiple economic goals in such a way that goal satisfaction is based on a hierarchial structure of priorities [2].

The linear model solved by the linear programming technique in Chapter 3 is again considered from the viewpoint of the linear goal programming technique. The decision of priority level in the linear goal programming model is very hard to make at this time, hence the author's option here is to present two kinds of priority structure. The results obtained by the linear goal programming model are then compared with the results obtained by the linear programming model.

### 2. Model Formulation

There are two kinds of objective functions in goal programming model, and these are the absolute and nonabsolute objective functions. Among seven types of constraints in the linear programming model, the private consumption

# Additional Symbols Used in this Chapter

Variables and P	arameters	Dimensions for n secto k activities T periods P priorities	
a* i	goal achievement in the ith	priority level	Р
D <sub>i</sub> (t)	column vector of underachie objective function group in $[D_{1}^{-}(t)]^{T} = [d_{1}^{-}(t) d_{2}^{-}(t) \dots]^{T}$	period t, i.e.,	k
D; (t)	column vector of overachieve objective function group in		k
$d_{k}^{-}(t)$	underachievement of the kth function in period t	objective	I
$d_k^{\dagger}(t)$	overachievement of the kth o	objective function	Т
d <sup>*</sup>	<pre>underachievement of the ith in computer printout</pre>	objective function	1
d**	overachievement of the ith of in computer printout	objective function	1
GNP(t)	specified GNP goal in period government consumption and available		Т
a(t)	specified rate of growth of	GNP(t)	1
γ(t)	<pre>specified rate of growth of stock K(t+1) over K(t)</pre>	aggregate capital	1

constraint and the balance of payment constraint are selected as candidates to be nonabsolute objectives, because they are assumed to be more flexible constraints and be more meaningful objectives in the linear goal programming. Gross national product (GNP) growth and capital stock growth are introduced as nonabsolute objectives. Hence this model is composed of five kinds of absolute objectives and four kinds of nonabsolute objectives.

#### 2.1 Forming the absolute objective functions.

Distributional relationships (DR: Ref. eq. (3.17)')

$$c(t)C(t) - M''(t) - s(t)X(t-1) + [a(t) - I - m'(t) + s(t)] X(t)$$

$$+ p(t) Z(t+1) + D_1^-(t) - D_1^+(t) = -\overline{E(t)} - \overline{G(t)}$$

$$t = 1, ..., T$$
(4.1)

2) Capacity relationships (CC: Ref. eq. (3.9))

$$-K(t) + b(t) X(t) + D_2^{-}(t) - D_2^{+}(t) = 0$$

$$t = 1, ..., T$$
(4.2)

3) Capital accounting relationships (CAR: Ref. eq. (3.10'))

$$-K(t) + K(t+1) + dX(t) - p(t) Z(t+1) + D_3^-(t) - D_3^-(t) = 0$$

$$t = 1, ..., T$$
(4.3)

4) Competitive import ceilings (CIC: Ref. eq. (3.16)')

$$[m''(t)]^{-1} M''(t) + um'(t) X(t) + d_{3k+1}^{-}(t) - d_{3k+1}^{+}(t) = \overline{A(t)} + u \overline{E(t)}$$

$$t = 1, ..., T$$
(4.4)

5) Savings relationships (SC: Ref. eq. (3.23)')

$$uM''(t) - us(t) X(t-1) + u(s(t) + m'(t) - \beta_1[I-a(t)]) X(t)$$

$$+ up(t) Z(t+1) + d_{3k+2}^{-}(t) - d_{3k+2}^{+}(t)$$

$$= \beta_0 + \overline{A(t)} + u \overline{E(t)}$$

$$t = 1, ..., T (4.5)$$

#### 2.2 Forming the nonabsolute objective functions.

Consumption growth (CG: Ref. eq. (3.8))

$$-[1 + \rho(t)] C(t) + C(t+1) + d_{3k+3}^{-}(t) - d_{3k+3}^{+}(t) = 0$$

$$t = 0, ..., T-1 (4.6)$$

where  $d_{3k+3}^{-}(t)$  = underachievement on grass private consumption growth goal in period t

 $d_{3k+3}^{+}(t)$  = overachievement on gross private consumption growth goal in period t.

Capital stock growth (CSG)

$$-u[1+\gamma(t)] K(t) + uK(t+1) + d_{3k+4}^{-}(t) - d_{3k+4}^{+}(t) = 0$$

$$t = 1, ..., T \quad (4.7)$$

where  $d_{3k+4}^{-}(t)$  = underachievement on gross capital stock growth goal in period t

 $d_{3k+4}^{+}(t)$  = overachievement on gross capital stock growth goal in period t.

3) Balance of payment (BOP: Ref. eq. (3.13)')

$$uM''(t) + um'(t) X(t) + d_{3k+5}^{-}(t) - d_{3k+5}^{+}(t) = \overline{A(t)} + u\overline{E(t)}$$
  
 $t = 1, ..., T$  (4.8)

where  $d_{3k+5}^-(t)$  = amount of foreign exchange surplus in period t  $d_{3k+5}^+(t)$  = amount of foreign exchange deficit in period t.

4) Gross national product (GNP)

The GNP can be expressed by an expenditure concept as follows;

GNP = Consumption + Business investment + Net export

where Consumption = Private consumption + Government consumption

Business investment = New investment + Inventory increase

Net export = Foreign exchange available - Imports.

Government consumption and foreign exchange available can be excluded from the GNP formulation due to their exogenous characteristics of this model (i.e., preassigned values). Hence GNP objective function becomes,

C(t) + up(t) Z(t+1) + us(t) [X(t) - X(t-1)] - um'(t) X(t) 
$$- uM''(t) + d_{3k+6}^{-}(t) - d_{3k+6}^{+}(t) = \overline{GNP(t)} \qquad t = 1, ..., T \quad (4.9)$$

where  $d_{3k+6}^-(t)$  = underachievement on GNP goal in period t  $d_{3k+6}^+(t)$  = overachievement on GNP goal in period t.

 $\overline{\mathsf{GNP}(\mathsf{t})} = \mathsf{projected} \ \mathsf{GNP} \ \mathsf{goals} \ (\mathsf{set} \ \mathsf{at} \ \mathsf{10\%} \ \mathsf{annual} \ \mathsf{growth} \ \mathsf{rate}$   $(\alpha(\mathsf{t}) = 0.1) \ \mathsf{are} \ \mathsf{shown} \ \mathsf{in} \ \mathsf{Table} \ \mathsf{4-1.})$ 

2.3 Forming the achievement functions. Since at the beginning of the simulation the decision maker's priority structure of his goals would not be fixed, it might be desirable to simulate the model for different priority structures. In this study two priority structures will be used.

Table 4-1 GNP Target (Unit: billion Won)

	1977	<u>1978</u>	1979	1980	<u>1981</u>
G(t)	273	306	343	384	432
$\overline{A(t)} + u\overline{E(t)}$	1330	1560	1842	2168	2605
GNP(t)*	<b>34</b> 43	3684	3920	4164	4350
GNP**	5045	5550	6105	6715	7387

<sup>\*</sup>Right hand side value of eq. (4.9)

<sup>\*\* 10%</sup> annual growth rate of GNP target

#### Priority Structure 1

P<sub>1</sub>: Satisfy all absolute objectives

 $P_2$ : Achieve  $\rho(t)$  x 100% annual growth of gross private consumption

 $P_3$ : Achieve  $\gamma(t) \times 100\%$  annual growth of gross capital stock

 $P_{\Delta}$ : Achieve balance of payment in foreign trade

 $P_5$ : Achieve  $\alpha(t)$  x 100% annual growth of GNP

then the achievement function is;

Min. 
$$\bar{a} = \left\{ \sum_{t=1}^{T} \left[ uD_{1}^{+}(t) + uD_{2}^{+}(t) + uD_{3}^{+}(t) + uD_{3}^{-}(t) + d_{3k+1}^{+}(t) + d_{3k+2}^{+}(t) \right], \right.$$

$$\left[ \sum_{t=1}^{T} d_{3k+3}^{-}(t) \right], \left[ \sum_{t=1}^{T} d_{3k+4}^{-}(t) \right], \left[ \sum_{t=1}^{T} d_{3k+5}^{+}(t) \right], \left[ \sum_{t=1}^{T} d_{3k+6}^{-}(t) \right] \right\}$$

$$\left. (4.10)$$

#### Priority Structure 2

 $P_{j}$ : Satisfy all absolute objectives

 $P_2$ : Achieve  $\alpha(t)$  x 100% annual growth of GNP

 $P_3$ : Achieve balance of payment in foreign trade

 $P_4$ : Achieve  $\gamma(t)$  x 100% annual growth of gross capital stock

 $P_5$ : Achieve  $\rho(t)$  x 100% annual growth of gross private consumption the achievement function of this structure is;

Min. 
$$\bar{a} = \left\{ \sum_{t=1}^{T} \left[ uD_{1}^{+}(t) + uD_{2}^{+}(t) + uD_{3}^{+}(t) + uD_{3}^{-}(t) + d_{3k+1}^{+}(t) + d_{3k+2}^{+}(t) \right], \right\}$$

$$\left[ \sum_{t=1}^{T} d_{3k+6}^{-}(t) \right], \left[ \sum_{t=1}^{T} d_{3k+5}^{+}(t) \right], \left[ \sum_{t=1}^{T} d_{3k+4}^{-}(t) \right], \left[ \sum_{t=1}^{T} d_{3k+3}^{-}(t) \right] \right\}$$

$$(4.11)$$

In the above two achievement functions each year's weight is assumed to be the same within each priority level, but it is optional. A heavier weight could be assigned to the latter years if the last year's success was considered to be of higher merit.

#### Analysis of Solutions

The planning span is 5 years actually and the model formulation is also planned for the entire 5 year period, but its computer solution is made up to the 2nd year due to its excessive computer execution time required. The simplified model consists of 130, i.e., (4x16x2 + 1x1x2) technological variables; 108, i.e., (3x16x2 + 6x1x2) positive  $(d_i^{+*})$  and negative  $(d_i^{-\star})$  deviational variables and 5 priorities. The computer linear goal programming code used herein was constructed by Bershader [1]. This model is solved on an IBM 370/158 computer using FORTRAN G level with 256K region size required. The solution is obtained after approximately 11 minutes of execution time. (For one-year planning, it took about 1.5 minutes; for three-years planning it required more than 40 minutes.) Here the results of 2 year economic planning with 2 kinds of priority structure with 10% annual growth rate of private consumption, capital stock and GNP respectively (i.e.,  $\alpha(t) = \gamma(t) = \rho(t) = 0.1$ ) are presented. Notations used in the computer printout are shown in Table 4-2. Notice that, for the column identification, ZBAR is  $a_k^\star$ , XSTAR is technological variable, PSTAR is  $d_i^{+*}$ , and NSTAR is  $d_i^{-*}$ . For example, GNP objective function has deviational variable of  $(d_1^{-*}$  and  $d_1^{+*})$  for the first year, and of  $(d_{55}^{-*} \text{ and } d_{55}^{+*})$  for the second year. For technological variable, optimal amount of C(1) is found in the 17th row, and C(2) in the 82th row in column name of XSTAR.

3.1 Run-1. The result, based on the priority structure 1 with twice the weight for the first year than that of the second year (i.e.,  $a_k = 2d_i(1) + d_i(2)$ ) within the same priority level, are shown in Table 4-3. Its goal achievements are as follows;

Table 4-2 Notations for Computer Output

## 1. Deviational variables $(d_i^{-*} \text{ and } d_i^{+*})$

Year (t)		
<u>Object</u>	1	2
GNP(t) CG(t)	1 2	55 56
DR(t)	3 - 18	57 - 72
CC(t) CSG(t)	19 - 34 35	73 - 88 89
CAR(t)	36 - 51	90 - 105
BOP(t) CIC(t)	52 53	106 107
SC(t)	54	108

### 2. Technological variables

Year (t)	1	2
Var.		
X(t) C(t)	. 1 - 16 17	66 - 81 82
M(t) Z(t+1)	18 - 33 34 - 49	83 - 98 99 - 114
K(t+1)	50 - 65	115 - 130

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-	0.0	1556.6531	0.0	432,3337	,
2	0.0	162.3253	0.0	0.0	
M 4	146,4320	686.7476	0.0	0,0	
1	1734.4224	66.2006	0.0	5.0	
ψí		289,9158	0.0	0.0	
- @		205-1468	0-0	9.7011	
Ç		419,0229	0	112,3786	
0.4		755.557	0.0	61.4366	The state of the s
		1001.1235	0.0	0.0	
1.6		126.2431	145.9685		
1:		533.027i	0.0	0.0	
л ч ~		1573 1121	0.0	0.0	
1		33.05.9541	0.0	0.0	
3 7		66.2261	0.0	0.0	
61		45.8578	0.0	0.0	
25		6.3	0.0	0.0	
22		6.3	0.0	0.0	
23		189.9557	0.0	20.9395	
7 2		0.0	0.0	0.0	
25		200.0142	0.0	0.0	
- ac		292,0486	0.0	0.0	
52		0.0	0.0	0.0	
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6.7		0.0	0.0	0.0	•
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35		397.7512	0.0	0.0	

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- $P_1$  is achieved ( $a_1^* = 0$ ). All of the economic constraints are satisfied.
- P<sub>2</sub> is satisfied (a<sup>\*</sup><sub>2</sub> = 0). 10% annual growth of gross private consumption is exactly achieved.
- $P_3$  is partially achieved ( $a_3^* = 2d_{35}^{-*} + d_{89}^{-*} = 0 + 146.4 = 146.4$ ). The first year's growth of capital stock is 10% and second year's is 8.49% which comes from (9699 x 1.1 146.4)/9699 = 1.0849.
- $P_4$  is not achieved ( $a_4^* = 2d_{52}^{+*} + d_{106}^{+*} = 2 \times 139.9 + 309.7 = 589.5$ ). The first year's import is exceed by 10.53% (139.9/1330) and the second year's by 19.87% (309.7/1560) than that allocated.
- $P_5$  is not achieved ( $a_5^* = 2d_1^{-*} + d_{55}^{-*} = 2 \times 432.3 + 869.8 = 1734.4$ ). The first year's GNP is 4164 billion Won (5046-432) and the second is 4680 billion Won (5550-870). These are 0.58% and 1.44% of the annual growth rate respectively.
- 3.2 Run-2. The result, based on the priority structure 2 with the same weight for both planning years, are shown in Table 4-4. Its goal achievements are as follows;
  - $P_1$  is achieved ( $a_1^* = 0$ ). All of the economic constraints are satisfied.
  - P<sub>2</sub> is not achieved ( $a_2^* = d_1^{-*} + d_{55}^{-*} = 119.4 + 389.0 = 508.4$ ). The first year's GNP is 4927 billion Won (5046-119) and the second is 5161 billion Won (5550-389), which are 7.41% and 4.76% of the growth rate respectively.
  - $P_3$  is partially achieved ( $a_3^* = d_{52}^{+*} + d_{106}^{+*} = 134.0 + 0 = 134.0$ ). The first year inport volume is exceed by 10.08% (134/1330) but the second year import volume is only 83.91% (1-251/1560) of the allocated fund because of  $d_{106}^{-*} = 251$ .

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		289.9158	0.0	0.0		
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		755,1559	0.0	0		
-		931.1431	0.0	0.0		
12		866.4338	0.0	0.0		
-		171.3263	0.0	0.0		
		5671.034	o (	C. C.		
. 9		1571-1228	0.0			
11		3555.1909	0.0	0.0		
87.		36.3338	0.0	0.0		
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. 21		135.9182	00.0	2000		
2.2		0.0	0.0	0.0		
53		204.1054	0.0	28.9179		
		0.0	0.0	31.8470		
26		174.6114	0.0	64.6263		1
		264.5459	° °	0.0		
1		0.0	6.0	22,1183		1
30		0.0	0.0	0.0		
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105.4259	0.0	388.9426	1294.6646	0.0	6.0	0.0	C.O	0°0	0.0	0.0	6.0	0.0	0.0	0.0	0.0	0.0	0.0	0.00	6.0	17.0195	0.0	18:7831	0.0	38.0635		6.0	48.1176	142.4508	485.6982	0.0	0.0		0.00	0.0	0.0	0.0	0.0	0.0	0.0	T 0	0.0	0.0	0.0	0 in 10	251,1645	433.3484	2 C • O	0.0	
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329.2644	41.8342	120-6751	178,2258	172.8000	169.7333	413.7112	240.3178	9798-066	575,4485	26.07.0864	4426-1151 1011-0121	48171841 0000 XE 40	174-8845	612.5229	769.1279	127.6394	201.3345	1611-222	440.1558	1307.8391	877.4779	1126.3923	116.8235	446.4678	1577.2055	2618.5974	6.0	0.0	113.6833	0.0	341.0784		372,3289	0.0		0.0	0.0	0.0	0.0	0.0	0.0	د <b>٠</b> ٥	0.0	7.0	0.0	c	0.0	558.1323	c
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- $P_4$  is achieved (a\* = 0). Due to d\*\* = 38, d\*\* = 318, the first year's growth rate of gross capital stock is 10.43% ((9699 + 38)/8817) and the second is 12.83% ((9699 x 1.1 + 318)/(9699+38)).
- P<sub>5</sub> is not achieved ( $a_5^* = d_2^{-*} + d_{56}^{-*} = 0 + 1294.7 = 1294.7$ ). Due to  $d_2^{+*} = 249.2$ , the first year's gross private consumption growth rate is 18.3% ((3306 + 249)/3005) and the second is -34.43% ((3636-1295)/(3306+249)).
- 3.3 Comparison with linear programming model. Aggregate values of five key variables from two runs in linear goal programming and the linear programming model of two year planning are shown in Table 4-5. Domestic output does not vary much, but total volume from run-2 increased due to its top priority goal of GNP. Private consumption from linear programming model and from run-1 has the same value because maximization of private consumption is one part of the objective function in the linear programming model and also private consumption growth is top priority goal in run-1. In competitive import side, the volume in run-2 is sharply decreased to boost the GNP achievement as top priority level. In run-2 private consumption reduced much, hence this amount is left for increasing new additions to fixed capital capacity. Fixed capital stock is relatively consistent because its priority level among goals does not change much.

A real contribution of the linear goal programming is found in GNP achievement. In the linear programming model GNP grows at the average rate of 4.1%, whereas it grows 0.58% and 1.44% during the first and the second year respectively by run-1, and 7.4% and 4.8% respectively by run-2 in the linear goal programming model.

Table 4-5 Aggregate Values of Endogenous Variables (Unit: Billion Won)

Var.	Method	1st year	2nd year	Total
16 \( \sum_{i=1}^{\text{X}} \) \( \text{X}_{i} \)	LP G/P RUN-1 RUN-2	9,404 9,517 9,389	9,635 9,450 10,129	19,039 18,967 19,518
С	LP G/P RUN-1 RUN-2	3,306 3,306 3,555	3,637 3,634 2,618	6,934 6,940 6,173
16 ∑ M" i=1	LP G/P RUN-1 RUN-2	922 1,021 1,061	1,120 1,477 844	2,042 2,498 1,905
16 ∑ Z <sub>i</sub>	LP G/P RUN-1 RUN-2	1,026 1,063 1,107	729 1,058 1,527	1,755 2,121 2,634
16	LP G/P RUN-1 RUN-2	9,610 9,700 9,749	10,098 10,589 10,910	19,708 20,289 20,659

Source: Table 4-3 and 4-4.

#### REFERENCES

- Bershader, Paula S., <u>Linear Goal Programming Package</u>, University Park,
   Pa.: The Pennsylvania State University, 1975.
- 2. Tantasuth, V., Goal Programming and Long Range Planning in Underdeveloped Countries, Ph.D. Dissertation: Texas Tech University, 1975.

#### CHAPTER 5

#### CONCLUDING REMARKS AND PROPOSAL FOR FURTHER STUDY

The results obtained in this study show that linear goal programming is a successful analytical method for solving a multiobjective economic planning problem. To make the linear goal programming technique a more reliable planning tool for Korea, the following suggestions are made.

#### 1. Extended Computer Run for 5 Year Planning

The planning span for Korea economic planning is 5 years and the model is also formulated for the entire 5 year period, but its computer solution is made up to the 2nd year only due to the excessive computer execution time required. It is expected that around 3 hours (1.5 min.  $\times 5^3$ ) computer execution time (using IBM 370/158 computer) is needed to solve the 5 year planning by linear goal programming.

This amount of computer execution time is probably acceptable as a national project. It is, however, too much for this project, so therefore an alternative approach must be considered. One way is to reduce the number of variables in the model. This linear goal programming model has 5 key variables which are composed of 16 industrial sectors with a 5 year planning span, hence the model has 325 (i.e.,  $4 \times 16 \times 5 + 1 \times 1 \times 5$ ) technological variables and 270 (i.e.,  $3 \times 16 \times 5 + 6 \times 1 \times 5$ ) positive and negative deviational variables. If we aggregate 16 industrial sectors into 8 sectors, this model will have 165 (i.e.,  $4 \times 8 \times 5 + 1 \times 1 \times 5$ ) technological variables and 150 (i.e.,  $3 \times 8 \times 5 + 6 \times 1 \times 5$ ) positive and negative variables, and it may be solved within 25 minutes (1.5 min  $\times 5^3/2^3$ ). But if the number of

variables used in the model is too small, the model will not reflect a sharp image of the real economic situation.

Another way considered is to use what is called here "Sequential Linear Programming" technique. This is the maximization/minimization of priority one nonabsolute objective first within the feasible solution set formed by all the other objectives. Then maximize/minimize priority two nonabsolute objective within the feasible solution set formed by low/upper bound of the attained priority one nonabsolute objective as well as the other objectives, and so on. As long as goals are conflicting, it may not form any feasible region which is the necessary condition in the linear programming. Hence this rationale can not be utilized. The solution of this model run by the linear programming technique using this algorithm turns out to be infeasible. It indicates that the selected goals in the linear goal programming model are conflicting in one way or the other.

#### Modification of Priority Level

After initial solutions with the different priority structure have been made, the linear goal programming technique gives the planner a chance to review hierarchical structure of priority among goals. Regrouping or change of priority level can be considered. The best attainable solution of this economic model can be obtained with this modification procedure.

# A GOAL PROGRAMMING MODEL FOR KOREAN ECONOMIC PLANNING

by

#### KWANGSUN YOON

B.S. (C.E.), Seoul National University, Korea, 1971

AN ABSTRACT OF A MASTER'S THESIS

submitted in partial fulfillment of the requirements for the degree

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Manhattan, Kansas

Many economic planning problems are composed of multiple objectives or goals which the planner wishes to achieve. Furthermore, the degree of importance of these goals are not equal. Because of these characteristics of planning problems, analytical techniques which can efficiently solve this type of problem are desired. Linear goal proprogramming, which is a relatively new analytical technique, is introduced to handle multiple objective planning problems.

Eckaus and Parikh's multisectoral dynamic model is reorganized for the Fourth Five-Year Plan of Korea so as to apply the linear goal programming technique. Chosen economic goals in the model are GNP growth, private consumption growth, capital stock growth and balance of payment in foreign trade. Two kinds of priority structures are tried. The solutions from both linear programming model and linear goal programming model are compared.

While certain improvements are needed to make it a reliable planning tool for Korea, linear goal programming is shown to be a suitable technique for the economic planning problems.