

## Research Article

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## A symmetry result for strictly convex domains

**Abstract:** Let  $D \subset \mathbb{R}^2$  be a strictly convex domain with  $C^2$ -smooth boundary. Assume that  $\int_D e^{ix} y^n dx dy = 0$  for all sufficiently large  $n$ . In this paper, we will prove that  $D$  is a disc.

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## 1 Introduction

We assume throughout that  $D \subset \mathbb{R}^2$  is a *strictly convex* domain and its boundary  $S$  is  $C^2$ -smooth. Suppose that

$$\int_D e^{ix} y^n dx dy = 0, \quad n = 0, 1, 2, \dots \quad (1)$$

Our result is stated as Theorem 1.

**Theorem 1.** *If  $D$  is a strictly convex bounded domain in  $\mathbb{R}^2$  and (1) holds, then  $D$  is a disc.*

This result the author obtained while studying the Pompeiu problem, see, for example, [3, Chapter 11]. The result of Theorem 1 can also be established if the following is assumed in place of equation (1):

$$\int_D e^{iy} x^n dx dy = 0, \quad n = 0, 1, 2, \dots$$

This follows from the proof of Theorem 1.

The proof shows that equation (1) is used only for sufficiently large  $n$  because asymptotic formula (3) is used in the proof.

## 2 Proof of Theorem 1

Let  $\ell$  be an arbitrary unit vector,  $L_1$  be the support line to  $D$  (at the point  $s_1 \in S$ ) parallel to  $\ell$ , and  $L_2$  be the support line to  $D$  (at the point  $q_1 \in S$ ) parallel to  $L_1$ , where  $q_1 = q_1(s_1)$ . Since  $D$  is strictly convex, one can introduce the equations  $y = f(x)$  and  $y = g(x)$  of the boundary  $S$  between the support points  $s_1$  and  $q_1$ . For definiteness and without loss of generality let us assume that the orthogonal projection of the point  $s_1$  onto the line  $L_1$  lies not lower than the projection of the point  $q_1$  onto  $L_1$ , and let the  $x$ -axis pass through  $s_1$  and be orthogonal to  $L_1$ . The graph of  $f$  is located above the graph of  $g$ . Since  $S$  is strictly convex the function  $f$  has a unique point of maximum  $x_1$ , where  $x_1 \in (a, b)$ , and  $f(x_1) > f(x)$  for  $x \in [a, b]$ ,  $f(x_1) > 0$  and  $f''(x_1) < 0$ . Here  $a$  and  $b$  are the  $x$ -coordinates of the points  $q_1$  and  $s_1$ ,  $a < b$ . Let us denote by  $s$  the value of the natural parameter (arc length on  $S$ ) corresponding to the maximum point of  $f$ , that is, to the point  $x_1$ . The function  $g$  has a unique point of minimum  $x_2$ ,  $x_2 \in (a, b)$ ,  $g(x) > g(x_2)$ ,  $g(x_2) < 0$  and  $g''(x_2) > 0$ . From the strict convexity of  $S$  it follows that these maximum and minimum are non-degenerate, that is,  $f''(x_1) \neq 0$ , and  $g''(x_2) \neq 0$ . Denote by  $q$  the value of the natural parameter corresponding to the minimum point of  $g$ . Let

us write equation (1) as

$$\int_D e^{ix} y^n dx dy = \int_a^b e^{ix} \frac{f^{n+1}(x) - g^{n+1}(x)}{n+1} dx = 0, \quad n = 0, 1, 2, \dots \quad (2)$$

The factor  $n+1$  in the denominator can be canceled because the integral in (2) equals zero. We want to take  $n \rightarrow \infty$  and use the Laplace method for evaluating the main term of the asymptotic of the integral. Let us recall this known result, the formula for the asymptotic of the integral

$$F(\lambda) := \int_a^b \phi(x) e^{\lambda S(x)} dx = \left( \frac{2\pi}{\lambda |S''(\xi)|} \right)^{\frac{1}{2}} \phi(\xi) e^{\lambda S(\xi)} (1 + o(1)), \quad \lambda \rightarrow \infty,$$

see, for example, [1]. In this formula  $\xi \in (a, b)$  is a unique point of a non-degenerate maximum of a real-valued twice continuously differentiable function  $S(x)$  on  $[a, b]$ ,  $S''(\xi) < 0$ , and  $\phi$  is a continuous function on  $[a, b]$ , possibly complex-valued. We apply this formula with

$$S(x) = \ln |f|, \quad \lambda := 2m := n+1 \rightarrow \infty, \quad \phi = e^{ix},$$

and take  $n = 2m - 1$  to ensure that  $n+1 = 2m$  is an even number, so that  $f^{2m}$  and  $g^{2m}$  are positive, and  $\ln f^{2m}$  and  $\ln g^{2m}$  are well defined. The point  $x_2$  of minimum of  $g$  becomes a point of local maximum of the function  $g^{2m}$ . Note that

$$|(\ln |f|)''| = \frac{|f''(x_1)|}{|f(x_1)|}$$

at the point  $x_1$  where  $f'(x_1) = 0$ ,  $f(x_1) > 0$  and  $f''(x_1) < 0$ .

Taking the above into consideration, one obtains from (2) the following asymptotic formula:

$$\int_D e^{ix} y^n dx dy = \left[ e^{ix_1 + 2m \ln |f(x_1)|} \left( \frac{\pi |f(x_1)|}{m |f''(x_1)|} \right)^{\frac{1}{2}} - e^{ix_2 + 2m \ln |g(x_2)|} \left( \frac{\pi |g(x_2)|}{m |g''(x_2)|} \right)^{\frac{1}{2}} \right] (1 + o(1)) = 0, \quad n \rightarrow \infty, \quad (3)$$

where  $2m = n+1$ ,  $x_1 \in (a, b)$  and  $x_2 \in (a, b)$ . It follows from the above formula that the expression in the brackets, that is, the main term of the asymptotic, must vanish for all sufficiently large  $m$ . This implies that  $f(x_1) = |f(x_1)| = |g(x_2)|$  and  $|f''(x_1)| = |g''(x_2)| = |g''(x_2)|$ , because  $f(x_1) > 0$ ,  $g(x_2) < 0$ ,  $f''(x_1) < 0$  and  $g''(x_2) > 0$ . It also follows from formula (3) that  $e^{ix_1} = e^{ix_2}$ . This implies  $x_1 = x_2 + 2\pi p$ , where  $p$  is an integer. The integer  $p$  does not depend on  $s$  because  $p$  is locally continuous and cannot have jumps. Thus,

$$x_1 - x_2 := 2\pi p; \quad |f(x_1)| = |g(x_2)|; \quad |f''(x_1)| = |g''(x_2)|. \quad (4)$$

We prove in Lemma 2 (see below) that  $p = 0$ . Another proof of this is given in Remark 3 below the proof of Lemma 2.

Consider the support lines  $L_3$  at the point  $s$  and  $L_4$  at the point  $q$ , where  $L_3$  and  $L_4$  are orthogonal to  $\ell$ . Denote by  $L = L(s)$  the distance between  $L_3$  and  $L_4$ , that is, the width of  $D$  in the direction parallel to  $\ell$ . Note that  $L = f(x_1) - g(x_2) > 0$ , and

$$L = (r(s) - r(q), \ell),$$

where  $r = r(s)$  is the radius vector (position vector) corresponding to the point on  $S$  which is defined by the parameter  $s$ . This point will be called point  $s$ . The same letter  $s$  is used for the point  $s \in S$  and for the corresponding natural parameter. Let  $R = R(s)$  denote the radius of curvature of the curve  $S$  at the point  $s$  and let  $\kappa = \kappa(s)$  denote the curvature of  $S$  at this point. Then one has

$$R^{-1} = \kappa = |f''(x_1)|,$$

because  $\kappa = |f''(x_1)| [1 + |f'(x_1)|^2]^{-\frac{3}{2}}$  and  $f'(x_1) = 0$  since  $x_1$  is a point of maximum of  $f$ .

From (4) we will derive that

$$L(s) = 2R(s) \quad \text{for all } s \in S. \quad (5)$$

It will be proved in Lemma 2 that equation (5) implies that  $D$  is a disc. Thus, the conclusion of Theorem 1 will be established.

We denote by  $r = r(s)$  the equation of  $S$ , where  $s$  is the natural parameter on  $S$  and  $r$  is the radius vector of the point on  $S$ , corresponding to  $s$ . One has  $r'(s) = t$ , where  $t = t(s)$  is a unit vector tangential to  $S$  at the point  $s$ . We have chosen  $s$  so that  $t(s)$  is orthogonal to  $\ell$ . Since  $\ell$  is arbitrary, the point  $s \in S$  is arbitrary. The point  $q \in S$ ,  $q = q(s)$ , is uniquely determined by the requirement that  $t(q) = -t(s)$ , because  $S$  is strictly convex. One has  $(r(s) - r(q), \ell) = L$ , where  $L = L(s)$  is the width of  $D$  in the direction parallel to  $\ell$ . Since  $r'(s) = t(s)$ , the first formula in (4) implies

$$(r(q) - r(s), r'(s)) = 2\pi p, \quad (r(q) - r(s), r'(q)) = -2\pi p \quad \text{for all } s \in S. \quad (6)$$

Differentiate the first equation in (6) with respect to  $s$  and get

$$\left(r'(q) \frac{dq}{ds} - r'(s), r'(s)\right) + (r(q) - r(s), r''(s)) = 0 \quad \text{for all } s \in S. \quad (7)$$

Note that  $r'(s) = t(s) = -t(q) = -r'(q)$  and  $r''(s) = \kappa(s)v(s)$ , where  $v(s)$  is the unit normal to  $S$  (at the point corresponding to  $s$ ) directed into  $D$ , and  $(r(s) - r(q), \ell) = L(s) = (r(q) - r(s), v(s))$ , because  $v(s)$  is directed along  $-\ell$ . Consequently, it follows from (7) that

$$-\frac{dq}{ds} - 1 + \kappa(s)L(s) = 0 \quad \text{for all } s \in S. \quad (8)$$

One has  $L(s) = L(q)$ , and it follows from formulas (4) that  $\kappa(s) = \kappa(q)$ .

Differentiate the second equation in (6) with respect to  $q$  and get

$$\left(t(q) - t(s) \frac{ds}{dq}, t(q)\right) + (r(q) - r(s), r''(q)) = 0. \quad (9)$$

Note that  $t(q) = -t(s)$  and  $r''(q) = \kappa(q)v(q)$ , where  $v(q) = -v(s)$  because  $L_3$  is parallel to  $L_4$ . Consequently, equation (9) implies

$$\frac{ds}{dq} + 1 - \kappa(s)L(s) = 0 \quad \text{for all } s \in S. \quad (10)$$

Compare (8) and (10) and get  $\frac{ds}{dq} = \frac{dq}{ds}$ . Thus,  $\left(\frac{dq}{ds}\right)^2 = 1$ . Since  $\frac{dq}{ds} > 0$ , it follows that

$$\frac{ds}{dq} = \frac{dq}{ds} = 1 \quad \text{for all } s \in S. \quad (11)$$

Therefore, equation (8) implies

$$\kappa(s)L(s) = 2 \quad \text{for all } s \in S. \quad (12)$$

Let us derive from (12) that  $D$  is a disc.

Recall that  $s$  is the natural parameter on  $S$ ,  $L(s)$  is the width of  $D$  at the point  $s$  (that is the distance between two parallel supporting lines to  $S$  one of which passes through the point  $s$ ) and  $\kappa(s)$  is the curvature of  $S$  at the point  $s$ .

**Lemma 2.** Assume that  $D$  is a strictly convex domain with a smooth boundary  $S$ . If equation (12) holds, then  $D$  is a disc.

*Proof.* Denote by  $K$  the maximal disc inscribed in the strictly convex domain  $D$ , and by  $r$  the radius of  $K$ . If there are no points of  $S$  outside  $K$ , then  $D$  is a disc and we are done. If  $S$  contains points outside  $K$ , let  $x \in S$ ,  $x \notin K$ . Let  $\tilde{L}$  be the line passing through the center of  $K$  and through the point  $x \in S$ ,  $x \notin K$ . Let  $L'$  be the support line to  $S$  orthogonal to the line  $\tilde{L}$  and tangent to  $S$  at a point  $x'$ ,  $x' \notin K$ . Denote the radius of curvature of  $S$  at the point  $x'$  by  $\rho$ . One has  $\rho \leq r$ , because  $K$  is the maximal disc inscribed in  $D$ . The width  $L$  of  $D$  at the point  $x'$  in the direction of the line  $\tilde{L}$  is greater than  $2r$  because  $x' \notin K$ . One has  $L > 2r$  and  $L = 2\rho \leq 2r$ . This is a contradiction. It proves that  $D = K$ . Thus,  $D$  is a disc, and, consequently, the parameter  $p$  in formula (4) is equal to zero. Lemma 2 is proved.  $\square$

Thus, Theorem 1 is proved.

**Remark 3.** Let us give another proof that  $p = 0$ , where  $p$  is defined in formula (4). One has

$$L(s) = (r(q) - r(s), v(s)).$$

Differentiate this equation with respect to  $s$  and get

$$L'(s) = -(r(q) - r(s), \kappa(s)t(s)) + \left(r'(q) \frac{dq}{ds} - r'(s), v(s)\right), \quad (13)$$

where  $t(s)$  is the unit vector tangential to  $S$  at the point  $s$ . Here the known formula  $v(s)' = -\kappa(s)t(s)$  was used. The second term in equation (13) vanishes since  $r'(s)$  and  $r'(q)$  are orthogonal to  $v$ . Thus,  $L'(s) = -2\pi p\kappa(s)$ . Since  $D$  is strictly convex, one has the inequality  $\min_{s \in S} \kappa(s) \geq \kappa_0 > 0$ , where  $\kappa_0 > 0$  is a constant. The function  $L(s)$  must be periodic, with the period equal to the arc length of  $S$ . The differential equation  $L'(s) = -2\pi p\kappa(s)$  does not have periodic solutions unless  $p = 0$ . Therefore,  $p = 0$ .

The author considered other symmetry problems in [2, 4, 5].

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