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Fire dynamics distinguish grasslands, shrublands and woodlands as alternative attractors in the Central Great Plains of North America

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If you make reference to this version of the manuscript, use the following information:

Ratajczak, Z., Nippert, J. B., Briggs, J. M., & Blair, J. M. (2014). Fire dynamics distinguish grasslands, shrublands and woodlands as alternative attractors in the Central Great Plains of North America. Retrieved from http://krex.ksu.edu

Published Version Information

Citation: Ratajczak, Z., Nippert, J. B., Briggs, J. M., & Blair, J. M. (2014). Fire dynamics distinguish grasslands, shrublands and woodlands as alternative attractors in the Central Great Plains of North America. Journal of Ecology, 102(6), 1374-1385.

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Digital Object Identifier (DOI): doi:10.1111/1365-2745.12311

Publisher's Link: http://onlinelibrary.wiley.com/doi/10.1111/1365-2745.12311/abstract

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- 1 Fire dynamics distinguish grasslands, shrublands and woodlands as alternative attractors in the
- 2 Central Great Plains of North America
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- 9 Running Header: Tri-Stability of Grasslands, Shrublands, and Woodlands

11 Summary

12	1. This review synthesizes evidence that altered fire frequency drives discontinuous ecosystem
13	transitions from mesic grasslands to shrublands or woodlands in the Central Great Plains, U.S.A.
14	2. Long-term fire manipulations reveal that grassland to shrubland transitions are triggered when
15	fire-free intervals increase from 1-3 years to \geq 3-8 years and longer fire returns (~10 years or
16	more) result in transitions to woodlands. Grazing and soil properties alter these fire thresholds.
17	3. Grassland to shrubland transitions are abrupt and exhibit non-linear relationships between
18	driver and state variables. Transitions to shrublands and woodlands exhibit hysteresis, where
19	reintroducing frequent fires does not reverse transitions in management-relevant time-scales
20	(decades).
21	4. Non-linear transitions and hysteresis emerge because grasses generate positive feedbacks with
22	fire that create strong demographic barriers for shrub and tree establishment. Fire-free intervals
23	allow shrubs and trees to reach a size sufficient to survive fire, reproduce, and disrupt the fire
24	feedback loop through competition.
25	5. Synthesis: Mesic grasslands, shrublands, and woodlands constitute self-reinforcing states
26	(alternative attractors) separated by critical fire frequency thresholds. Even without major shifts
27	in climate, altered fire frequency can produce dramatic state-changes, highlighting the
28	importance of fire for predicting future ecosystem states. Local management should focus on
	importance of the for predicting fature coordistent states. Doeur management should focus on

30 Key-words: alternative stable states, bi-stability, bush encroachment, critical transitions, plant

31 population and community dynamics, positive feedbacks, resilience, restoration, stability,

32 tallgrass prairie, tipping points, woody encroachment

33

34 Introduction

35 Woody encroachment—the increasing extent and dominance of woody plants in grass-dominated

36 systems—is occurring across most North American grassland ecosystems (Archer et al. 1988,

37 Briggs et al. 2005, Van Auken and McKinley 2008, Barger et al. 2011, Ratajczak, Nippert &

Collins 2012), and in many other grasslands globally (Eldridge *et al.* 2011). This recent

39 widespread increase in shrub and tree cover in grasslands and savannas can lead to states of co-

40 dominance by shrubs and grasses or complete conversions of grasslands to shrublands or tree-

41 dominated woodlands, often referred to as an ecosystem transition.

42 The ramifications of these ecosystem transitions are multifarious, with impacts on

43 community composition and vegetation structure (Eldridge *et al.* 2011, Ratajczak *et al.* 2012),

44 ecosystem function (Barger et al. 2011), ecohydrology (Huxman et al. 2005, Brunsell, Nippert &

45 Buck 2014) and long-term conservation of biodiversity (Gray & Bond 2012). Woody

46 encroachment into mesic grassland can impact regional economies by reducing forage for large

47 grazers (Hoch, Briggs & Johnson 2002, Briggs et al. 2005, Limb et al. 2010), hindering

48 economically-important livestock production (Limb *et al.* 2011).

Woody encroachment into grasslands has been attributed to a variety of drivers operating
at global (elevated CO₂, climate change; Bond & Midgley 2012, Kulmatiski & Bear 2013),

regional (nitrogen deposition, fragmentation; Kochy & Wilson 2001, Briggs et al. 2005) and

52 local scales (over-grazing, fire; Walker et al. 1981, Roques et al. 2001, Fuhlendorf et al. 2008,

53	Van Auken & McKinley 2008). Within mesic grasslands, including North American tallgrass
54	prairie, changes in the timing, intensity and frequency of fire have been implicated as important
55	proximate drivers of transitions from grasslands to shrubland or woodland (Briggs et al. 2005,
56	Fuhlendorf et al. 2008, Bond 2008, Gibson 2009, Twidwell et al. 2013a).
57	As with many grasslands and savannas globally (Archibald, Staver & Levin 2012), fire
58	frequency in the North American Central Great Plains (CGP) is largely controlled by the number
59	of ignition events, which occur via lightning strikes or by humans (Allen & Palmer 2011,
60	Stambaugh, Guyette & Marschall 2013, Twidwell et al. 2013b). The best estimates of pre-
61	settlement fire regimes in CGP grasslands suggest that fire-free intervals generally ranged from
62	3-5 years (Wright & Bailey 1982, Allen & Palmer 2011, Desantis, Hallgren & Stahle 2010,
63	Strambaugh et al. 2013). Fire frequency now varies across the region (Mohler and Goodin 2012)
64	from annual or biennial in many grasslands managed primarily for cattle production (Smith &
65	Owensby 1978), to 3-4 years in areas managed to balance cattle production and biodiversity
66	(Fuhlendorf et al. 2009, Allred et al. 2011), to long-term fire suppression of 20 years or more
67	associated with a cessation of ranching and sub-urban development (e.g. Hoch et al. 2002,
68	Briggs et al. 2005, Mohler & Goodin 2012). A critical question is if and how this landscape will
69	respond to changes in fire frequency.

This review synthesizes and expands upon recent research on fire as a driver of woody encroachment in mesic grasslands (i.e., tallgrass prairies) of the North American CGP. For this review, we define the CGP as the ecoregion bounded to the south by the Cross-Timbers region, to the north by transition from C_4 grass dominance to C_3 grass dominance, to the west by the transition to mixed grass prairie, and to the east by deciduous forest (similar to Barger *et al.* 2011). The focus on temperate mesic grassland transitions is timely, given the need for increased

conservation of this grassland (Hoekstra et al. 2005) and widespread manipulation of fire in
grasslands (Mohler & Goodin 2012, Twidwell et al. 2013b). We review the mechanistic and
experimental evidence for whether fire frequency creates tipping points that separate grasslands,
shrublands and woodlands as alternative attractors. We build on >30 years of extensive research
manipulating fire frequency and grazing in a North American tallgrass prairie at the Konza
Prairie Biological Station (KPBS), as well as data from other tallgrass prairie sites in the region.

83 Conceptual Framework

84 Woody encroachment of grasslands has been described using many different conceptual

85 frameworks, including succession (Archer *et al.* 1988), gradual linear dynamics (Roques *et al.*

2001), state and transition models (Westoby, Walker & Noy-Meir 1989, Briske et al. 2005,

87 Briske, Fuhlendorf, & Smeins 2006), alternative attractors (or alternative stable states) (Walker

et al. 1981, Frehlich *et al.* 1999, Anderies et al. 2002, Folke *et al.* 2004, Bestelmeyer *et al.* 2011),

89 demographic models (Higgins & Schieter 2012), rapid changes in ecosystem drivers

90 (Bestelmeyer *et al.* 2013), physiological thresholds (Hoffman *et al.* 2012, Twidwell *et al.* 2013a)

and others (Scholes & Archer 1997, Bond 2008, Briggs et al. 2005). Here we focus on

92 comparing linear and alternative attractor models, because ecosystems with alternative attractors

are susceptible to rapid and difficult to foresee regime shifts (Holling 2001, Folke *et al.* 2004,

94 Walker & Salt 2006, Scheffer 2009) and knowledge of potential alternative attractors is also key

95 for successful ecosystem restoration (see Briske et al. 2008, Suding & Hobbs 2009).

Different fire frequencies could generate non-linear transitions that are difficult to reverse (i.e. tipping points, critical thresholds). Non-linear responses occur when an ecosystem state is initially resistant to external forcing, but has a point(s) where gradual forcing precipitates non-

linear changes in state (threshold systems) (Fig 1, Nov-Meir 1975, May 1977, Holling 2001, 99 Walker 1981, Folke 2006, Briske et al. 2008, Scheffer 2009, Bestelmeyer et al. 2011). In more 100 extreme cases, threshold transitions also exhibit hysteresis, where eliminating the external 101 102 forcing or returning driving variables to their pre-transition levels is insufficient to reverse the state transition (Nov-Meir 1975, May 1977, Walker et al. 1981). When a system exhibits 103 threshold transitions and hysteresis, we refer to the two potential states as alternative attractors 104 (similar to the concept of alternative stable states and critical transitions), "critical thresholds" 105 refer to non-reversible thresholds, and "regime shifts" refer to transitions from one alternative 106 attractor to another (Scheffer 2009). 107 Determining if systems have alternative attractors requires multiple lines of inference, 108 including but not limited to mechanistic studies and studies relating salient driver variables with 109 ecosystem state (Scheffer & Carpenter 2004, Schroder et al. 2005, Bestelmever et al. 2011, 110 D'Odorico et al. 2012). Mechanistic studies of ecological thresholds typically focus on 111 demography and feedback processes (Archer et al. 1988, Roff & Mumby 2012, Higgins & 112 113 Scheiter 2013), because ecological thresholds occur primarily in systems with demographic barriers and/or strong feedback mechanisms (De Roos and Persson 2002, Walker & Salt 2006, 114 D'Odorico et al. 2012, Boerlijst, Oudman, & Roos 2013, Higgins & Schieter 2013, Huss et al. 115 2013). Demographic bottlenecks are establishment barriers or low population growth rates for a 116 life stage, resulting from evolved life history traits and/or ecological constraints (Grime 1979). 117 Demographic bottlenecks can suppress a potentially dominant functional group through priority 118 effects and other mechanisms (De Roos & Persson 2002, Higgins & Schieter 2012, Huss et al. 119 2013). Distinguishing between feedbacks and demographic bottlenecks can be difficult because 120 121 feedbacks by one group or species can create demographic bottlenecks for other one or more

other species. However, feedbacks generally refer to interactions that amplify (positive 122 feedbacks) or dampen (negative feedbacks) pressures (Walker & Salt 2006, D'Odorico et al. 123 2012). Experimental and observational approaches can identify thresholds by determining 124 125 whether a system exhibits linear or threshold relationships between driver and state (Scheffer & Carpenter 2004, Bestelmeyer et al. 2011). Reversing the change in drivers that precipitated a 126 threshold transition can identify hysteresis (Fig. 1). For transitions from grasslands to shrublands 127 and woodlands, we first review the mechanistic evidence for feedbacks and demographic 128 barriers, followed by evidence for fire frequency thresholds, abrupt ecological shifts and 129 130 hysteresis.

131

132 Grassland to shrubland transitions

Mechanistic Background: Historically, much of the CGP was tallgrass prairie, an herbaceous 133 plant community dominated by rhizomatous C₄ (i.e. warm-season) grasses with a diverse 134 subdominant community of C3 grasses, forbs, and legumes (Collins & Adams 1983, Gibson & 135 136 Hulbert 1987, Collins & Calabrese 2012). In this region, the balance of precipitation and evapotranspiration can support woody vegetation (Borchert 1950, Hayden 1998) and yet, woody 137 plant cover was historically low, except along riparian corridors and certain other landscape 138 features (e.g., outcrops, seeps, etc.) (Weaver 1954, Wells 1970, Axelrod 1985, Abrams 1985). 139 The dominant grasses of this region are well-adapted to fire and drought, but poorly adapted to 140 light limitation (Knapp 1993, Scholes and Archer 1997, Bond 2008, Nippert et al. 2011, Schieter 141 & Higgins 2012) and they generate self-reinforcing feedbacks that promote these conditions and 142 demographic barriers that inhibit other plant growth forms by: 1) leaving little open space for 143 144 colonization by other species, even in post-fire windows (Weaver 1954, Briggs & Knapp 2001,

145	Benson & Hartnett 2006); 2) producing large concentrations of fibrous roots in the upper 30 cm
146	(Jackson et al. 1996, Nippert & Knapp 2007, Nippert et al. 2012) that can rapidly utilize water
147	and nutrients at this soil depth (Knapp 1993, Epstein et al. 1997, Knapp et al. 2001,
148	Bredenkamp, Spada, & Kazmierczak 2002, Ocheltree et al. 2013, 2014); and 3) generating large
149	amounts of herbaceous biomass that facilitates frequent and intense fires, resulting in direct
150	mortality of unprotected meristems (Gibson, Hartnett, & Merrell 1990, sensu Van Wilgen et al.
151	2002, Bond 2008, Scheiter & Higgins 2012). As a result, the establishment of shrub seedlings in
152	frequently burned grasslands is rare (Benson & Hartnett 2006, Ratajczak et al. 2011).
153	However, once shrubs establish in grasslands, the competitive dynamics between grasses
154	and shrubs change dramatically. Initially, shrub seedlings recruit as single-stemmed ramets that
155	are highly susceptible to top-kill by fire. Given sufficient time and resource availability
156	encroaching shrub species in CGP tallgrass prairie, such as Cornus drummundii and Rhus
157	glabra, form clonal multi-stem clusters in the grassland matrix ("shrub islands") that increase in
158	both height and radial extent over time (Petranka & McPherson 1979, Collins & Adams 1983,
159	Anderson et al. 2000, Harrell et al. 2001, McCarron & Knapp 2003, Brudvig et al. 2007,
160	Ratajczak, Nippert & Ocheltree in press). Increasing shrub cover leads to light limitation for
161	grasses, along with concomitant decreases in grass cover, grass biomass, and the fine fuels that
162	carry fire (Heisler et al. 2004, Lett & Knapp 2005). While the reductions in grass biomass are
163	greatest at the center of shrub clusters, even the edges have significantly lower fine fuels,
164	allowing new clonal recruits to benefit from shrub-mediated fire suppression (Ratajczak et al.
165	2011). If fire kills the above-ground portion of large shrubs, they typically resprout and reach
166	their former height in as little as one or two years (Heisler et al. 2004, Hajny, Hartnett & Wilson
167	2011). In the even rarer instances where fire kills shrubs completely, the potential for C_4 grasses

to recover their pre-transition productivity in short time frames (2 years or less) has usually
eroded (Lett & Knapp 2005), leaving windows of opportunity for shrub seedlings to establish in
a low-competition environment. Thus, while frequent prescribed fires might inhibit shrub
establishment, they may no longer be a viable filter for prohibiting shrub expansion once shrub
establishment is initiated.

The effects of resource competition and availability also change as shrubs reach larger 173 size-classes. Mature clonal shrubs are deep-rooted and obtain a larger percentage of their water 174 from deeper soils (> 50 cm depth), reducing competition for water with the dominant grasses. 175 which rely primarily on shallow soil water (McCarron & Knapp 2001, Ratajczak et al. 2011). 176 Use of deeper water sources by shrubs mitigates susceptibility to summer drought and climate 177 variability (Nippert et al. 2013). Crucially, deep-rooted parent stems can also transfer water to 178 developing clonal stems in the grassland matrix, allowing them to avoid competition with grasses 179 and increase in size until they can access deep soil moisture, suppress grass growth via shading, 180 and begin developing their own clonal recruits (Ratajczak et al. 2011, Killian 2012). The clonal 181 182 growth form and rooting properties of these shrubs, combined with their effects on fire suppression, creates a positive feedback loop with low fire intensity and alters the demographic 183 bottleneck related to shrub recruitment, both of which facilitate shrub cluster survival and 184 expansion (Petranka & McPherson 1979, Yao et al. 1999, Ratajczak et al. 2011, similar to De 185 Roos & Persson 2002, D'Odorico et al. 2012, Huss et al. 2013), but only if shrubs are allowed to 186 increase in size by fire-free intervals. 187

188 *Experimental and observational evidence for fire thresholds:*

189 The mechanistic evidence presented thus far indicates that decreasing fire frequency190 should facilitate a transition to shrublands. The presence of feedback mechanisms and

demographic potential associated with clonal life history traits in both grasses and shrubs, 191 suggests that this transition may be non-linear and capable of hysteresis (Walker & Salt 2006). 192 A synthesis of fire frequency studies (Fig 4-5) shows that fire return intervals ≤ 2 years prevent 193 shrub expansion in CGP grasslands (Bragg & Hulbert 1976, Briggs & Gibson 1992, Kettle et al. 194 2001, Bowles & Jones 2013, Ratajczak et al. in press; Fig. 2), 3 year fire returns sometimes 195 maintain grasslands, but can also allow transitions to shrublands, and fire returns >3 years 196 197 consistently result in rapid shrub expansion (Brudvig et al. 2007, Bowles et al. 2013, Ratajczak et al. in press). This non-linear relationship between fire and shrubland formation is consistent 198 with alternative attractor theory. Moreover, the transition from grassland to shrubland has the 199 hallmarks of a threshold transition (e.g. Scheffer & Carpenter 2004, Bestelmeyer *et al.* 2011): 200 abrupt shifts in shrub cover over time, spatiotemporal bi-modality of system state, and non-linear 201 correlations between state and drivers variables (Fig. 2; Ratajczak et al. in press). The transition 202 to shrub-grass co-dominance typically takes 20 years, with gradual increases in shrub cover at 203 first, and rapid rates of clonal expansion later in the process, as illustrated by long-term 204 205 measurements at KPBS (Fig 2B; Collins & Adams 1983, Ratajczak et al. in press). Analysis of 28 years of plant composition at KPBS indicates that abrupt shifts in shrub cover are not related 206 to abrupt shifts in climate or fire (i.e. pulses), but instead are correlated with gradual changes in 207 grass cover (a proxy for fire intensity and the effects of grasses on resource availability; 208 Ratajczak et al. *in press*). This suggests that the abrupt transition from grassland to shrubland 209 represents the crossing of a threshold, rather than a response to abrupt changes in salient driver 210 variables (Bestelmeyer et al. 2011). Demographic rates, in particular the high survival and rapid 211 rate of clonal expansion, might also contribute to the abruptness of grassland to shrubland 212 213 transitions. The importance of demographic bottlenecks (e.g. Huss *et al.* 2013) is further

evidenced by the 8-fold faster expansion rates by clonal shrubs, compared to non-clonal woodplants (Fig 2A-C).

For grasslands and shrublands to be alternative attractors they must also show hysteresis 216 217 with respect to fire frequency and grass dominance (Fig 1C). The clonal shrub Rhus glabra has the capacity to withstand annual fires once established (Hajny et al. 2011) and although exposing 218 clonal oak shrublands to biennial fires initially lowers cover, it returns to previous levels within 2 219 220 years and shrubs that survive increase in size, reducing long-term fire susceptibility (Harrell et al. 2001, Boyd & Bidwell 2002). Data from KPBS also show hysteresis. Directly after a 221 transition to shrubland, ungrazed grasslands were burned twice in 4 years, but failed to return a 222 grassland state (Ratajczak *et al. in press*). We attribute these examples of hysteresis to the ability 223 of shrubs to both suppress grasses and resist fire, and to resprout when top-killed. 224

225 Similar to other alternative attractors (Staver *et al.* 2011, Roff & Mumby 2012), critical thresholds in CGP grasslands appear to be context-specific. Fire intensity and frequency play an 226 interactive role, whereby less frequent but more intense fires can exclude woody plants 227 228 (Fuhlendorf et al. 2008, Twidwell et al. 2013a) and vise versa (Ratajczak et al. in press). Resource availability and other disturbance processes are also important. For instance, most 229 establishment and expansion of shrub species at KPBS and elsewhere occurs in areas with deeper 230 soils, while uplands with thin soils are rarely colonized by shrubs, despite long-term fire 231 suppression (Fig 2D, Bragg & Hulbert 1976, Ratajczak et al. 2011, Bowles & Jones 2013). This 232 is surprising, because upland fires are less intense (Gibson et al. 1990). The inability of shrubs to 233 reach a fire resistant size in uplands is most likely due to greater run-off, coarser soils, and 234 shallower soil depth, which collectively results in lower available soil moisture (Nippert et al. 235

2011) and forces shrubs to compete directly with grasses in upper soil layers (Nippert & Knapp
2007, Ratajczak *et al.* 2011).

Herbivory alters grass-shrub competition in many systems (Holdo et al. 2013). Browsing 238 239 in CGP grasslands does not appear to play a major role in shrubland transitions, considering that the species most preferred by browsers have increased the most in cover (Van Der Hoek et al. 240 2002 vs. Heisler, Briggs & Knapp, 2003, Ratajczak et al. 2011). However, introducing more 241 diverse or larger browsers could potentially have an effect, as seen in similar systems on other 242 continents (Staver et al. 2012). In many grasslands globally, grazing has shifted grassland-243 shrubland thresholds in favor of shrubs by reducing grass dominance (Walker et al. 1981, 244 Scholes & Archer 1997, Fuhlendorf et al. 2008). Recent research in the CGP does not support 245 this paradigm. If anything, grazing appears to suppress dominant shrub establishment (Kettle et 246 247 al. 2000, Brudvig et al. 2007, Ratajczak et al. in press), perhaps because native grazers physically damage woody species (Coppedge & Shaw 1997) and create more bare ground which 248 increases sensible heat and reduces surface soil moisture (Walker et al. 1981, Nippert et al. 249 250 2013). More research is needed on how grazing affects grass-shrub interactions, considering the predominance of grazing in the CGP and mesic grasslands globally. 251

252

253 **Transitions to woodlands**

254 *Mechanistic Background*: The final state of woody plant expansion that we consider is

conversion to woodlands. We focus primarily on Juniperus virginiana (eastern red cedar)

woodlands (subsequently referred to as Juniper woodlands) rather than deciduous woodlands,

because Juniper woodlands exhibit the greatest expansion in the CGP (Twidwell *et al.* 2013b).

258	As with shrubs, the pyrogenic traits of C_4 grasslands impose limits on Juniper trees. In
259	fact, Juniper woodland expansion should be acutely constrained by fire because unlike grasses
260	and shrubs, J. virginiana does not resprout when top-killed and J. virginiana develops bark
261	slowly, leaving it poorly insulated against fires until older ages (Vanderweide & Hartnett 2011).
262	As a result, smaller J. virginiana (<2 m tall) suffer high mortality rates during fires (Hoch, et al.
263	2002, Fuhlendorf et al. 2008, Vanderweide & Hartnett 2011). For these reasons, greater fire
264	suppression should be needed for Juniper woodland formation, compared to shrublands.
265	Once J. virginiana reaches a larger size its response to fire may exhibit hysteresis. J.
266	virginiana suppresses grass growth with dense canopies that intercept the majority of sunlight
267	(Hoch et al. 2002, McKinley et al. 2008, Myster 2009, Limb et al. 2010, Van Els et al. 2010).
268	With time, this disruption of fuel continuity decreases fire transmission (Abades et al. this issue),
269	creating a positive feedback between J. virginiana and fire suppression. With long-term fire
270	suppression J. virginiana can also over-top and replace shrubs, as shown in long-term vegetation
271	surveys and the inability of shrubs seedlings to regenerate under older J. virginiana canopies
272	(Myster 2009, Van Els et al. 2010). Thus, while the fires typical of grasslands and shrublands
273	might prohibit tree establishment, exposing mature woodland trees to fires should have little
274	effect.

Unlike transitions to shrubland, low water availability and thin soils are less important constraints for *J. virginiana* expansion (Volder *et al.* 2010, 2013). Evergreen trees are at least, if not more, drought resistant than grasses under most drought scenarios (Awada *et al.* 2012). As a result, *J. virginiana* seedlings in fire-free locations have high survivorship in both high-diversity and grass-dominated patches (Ganguli *et al.* 2008), shallow soils, and through droughts (Yao *et*

al. 1999, Eggemeyer *et al.* 2006, Engle *et al.* 2006, Volder *et al.* 2010, 2013)—conditions that
typically exclude trees and most invasive species (Bond 2008, Seabloom *et al.* 2013).

282

283 Theoretical Description & Empirical Support

Statistical indications of regime shifts (e.g. abrupt shifts, state bi-modality) require experiments 284 and observational data-sets with frequent sampling events and replicates that are scaled with the 285 life span and spatial footprint of organisms involved (van Nes & Scheffer 2005, Bestelmeyer et 286 al. 2011). Given the long generation time of J. virginiana, observing a threshold transition to 287 woodland would require an experiment that increases fire returns slowly, allowing tree species to 288 equilibrate with their changing carrying capacity until a potential threshold is crossed. Instead, 289 most observations of woodland transitions have large gaps between samples (~a decade, Fig. 4, 290 291 5- references therein), which are not suitable for tests of abrupt shifts between states. Moreover, most examples of woodland transitions take place when fire frequency is altered from frequent 292 fires (1-3 yrs) to complete fire suppression. This effectively pushes the driver variable (fire) far 293 294 past any potential thresholds. The ecological response to this change in driver variables should be loss of grasses and a pattern of logistic growth by trees and shrubs as they reach their new 295 carrying capacity (May 1977, Hughes et al. 2012); this result is evident over 30 to 50 year 296 observations in areas with fire suppression (Fig. 2, 3) (Anderson et al. 2000, Hoch et al. 2002, 297 Peterson, Reich & Wrage 2007, Limb et al. 2010, Van Els et al. 2010, Twidwell et al. 2013, 298 299 Ratajczak et al. in press).

While we lack the data to identify "abrupt shifts" during woodland transitions we can identify management thresholds by asking: is there a fire frequency threshold that prohibits transitions from shrubland to woodland? And if so, does increasing fire frequency in woodlands

303	reverse the transition or does the ecosystem show hysteresis? Detailed mapping of tree
304	establishment and analyses of shrub cover at KPBS shows that 30 years of prescribed fire at 3-4
305	year frequencies allows establishment of shrubs, but not trees (Fig. 2). The lack of tree
306	establishment over a 30-year period with 3-4 year fire intervals and the prevalence of clonal
307	shrublands throughout the region (Petranka & McPherson 1979, Collins & Adams 1983,
308	Anderson et al. 2000, Harrell et al. 2001, Brudvig et al. 2007, Ratajczak et al. 2011), suggests
309	that shrublands are a separate alternative attractor from woodlands and that longer fire-free
310	intervals are needed to precipitate a transition to woodland. Less frequent burning (~ 20 year fire
311	returns) or complete fire suppression allows tree establishment (Fig 3) and eventual formation of
312	closed-canopy woodland (Bragg & Hulbert 1976, Kettle et al. 2000, Norris et al. 2001, Hoch et
313	al. 2002, Engle et al. 2006, Twidwell et al. 2013a).

314 A process-based approach suggests that woodland transitions may be possible at lower 315 fire frequencies than the 20-year fire experiment presented here (Fig 4). To resist typical grassland fires, J. virginiana must reach a height of ~2.5 m and diameter of 17.5 cm at breast 316 317 height (1.4 m) (Owensby, Eaton, & Russ 1973, Hoch et al. 2002, Vanderweide & Hartnett 2012). Connecting these thresholds to reported J. virginiana growth rates (Owensby et al. 1973, Engle 318 & Kulbeth 1992, Schmidt & Wardle 2002), we estimate that fire free intervals of 15-20 years 319 320 would allow consistent tree establishment, although this interval may be as short as 6-10 years for locations with abundant tree seed sources and heavy grazing (Owensby et al. 1973, Hoch et 321 al. 2002, Fuhlendorf et al. 2008). These estimates closely match modeling by Fuhlendorf and 322 colleagues (2008), as well as historical observations that J. virginiana is more common in 323 pyrrhic woodlands with a fire frequency >5 years (Batek et al. 1999, Stambaugh et al. 2013). 324 325 Similarly, a fire following 15 years of fire suppression at KPBS killed $\sim 3/4$ of Juniper trees, but

did not stop the transition to woodland when it was followed by further fire suppression (Fig
2C). This indicates that transitions to Juniper woodland are possible at 15 year fire return
intervals. However, the rate of transition will be significantly suppressed with more frequent
fires (Fig 2C).

Expansion of J. virginiana can decrease fire intensity, which could create hysteresis in 330 response to fire. In mixed deciduous/Juniper woodlands, re-introduction of 3-year fire returns 331 and aerial chemical controls allows J. virginiana to maintain ~20% cover (Engle et al. 2006). In 332 both the southern and northern CGP, reintroducing fire returns of ~2-3 years for a duration of 20 333 to 30 years had only marginal effects on tree cover and increased grass cover to only 10-20% 334 (Peterson et al. 2007, Burton, Hallgren & Palmer 2010, Burton et al. 2011). In historical records 335 (dendrochronology) Juniper woodlands persisted in areas with fire returns ranging from 2 to 6 336 years (Batek et al. 1999, Desantais et al. 2010, Strambaugh et al. 2013). However, studies by 337 Burton et al. (2010, 2011) and Peterson et al. (2007) were performed in primarily deciduous 338 woodlands, and results may not apply to Juniper woodlands. 339 340 A more rapid reversion of woodlands to grasslands typically requires physical or

A more rapid reversion of woodiands to grassiands typically requires physical of
chemical removal of *J. virginiana* trees, combined with frequent burning to foster grass
dominance and fire promoting feedbacks (Engle *et al.* 2006, Pierce & Reich 2010, Alford *et al.*2012). To achieve this, tree removal and reintroduction of fire should coincide, or the legacy
effects of woodland dominance can facilitate a rapid return to the woodland state (Kettle *et al.*2000). It also may be possible to achieve faster reversals to grasslands using novel burning
techniques that stimulate high-intensity (Twidwell *et al.* 2013a).

Woodland fire thresholds are context specific in ways that differ from thresholdsdifferentiating grasslands and shrublands. A unique attribute of woodland trees, relative to

shrubs, is their ability to establish in more xeric and thin soils with sufficient fire suppression 349 (Fig 4B: Engle et al. 2006, Eggemeyer et al. 2006, Knapp et al. 2008, McKinley et al. 2008). 350 Conventional cattle grazing generally favors greater tree establishment by reducing fuel loads, 351 352 and thereby, fire intensity (Hoch et al. 2002, Fuhlendorf et al. 2008, Twidwell et al. 2013a). Grazing can also create microsite conditions that facilitate woodland seedling establishment 353 (Owensby *et al.* 1973). In contrast, native grazers such as bison (*Bos bison*) can significantly 354 restrict woodland development. At moderate densities at KPBS, bison physically damage J. 355 virginiana trees (personal observations) and these behavioral traits have been observed in Bos 356 bison from other North American grasslands (Bork et al. 2013, but see Coppedge & Shaw 1997). 357 At KPBS, this effect is so strong that J. virginiana is asbent from Bos bison grazed areas, and 358 instead other trees are more prevalent, such as the thorned tree Gleditsia triacanthos 359 360 (Unpublished data, Z. Ratajczak). These observations indicate the importance of considering grazer impacts as a whole in grassland to woodland transitions, and not just their indirect effects 361 on trees via grass abundance and soil characteristics. 362

363

364 Synthesis and Opportunities

Based on the data presented here and our synthesis of results from other fire frequency studies (Fig 4), we propose a conceptual framework of tri-stability for the CGP that treats grasslands, shrublands and woodlands as alternative attractors moderated by critical fire frequency thresholds. Based on experimental and observational studies of fire and ecosystem state we have constructed complementary catastrophe fold (Fig 4) and state and transition models that illustrate the positions of critical thresholds and the system's capacity for hysteresis (Fig. 5). In areas with lower water holding capacity or thin soils that restrict access to deep soil moisture, shrubs cannot

establish and grasslands and woodlands are the only viable alternative attractors. Starting with
grasslands as the baseline state, fire return intervals of 3-8 years result in transitions to
shrublands, and fire frequencies of 8-10 years lead to transitions to woodlands (Fig 5). Once a
shrubland or woodland state is established, self-reinforcing feedback mechanisms and altered
demographic sensitivity to fire result in hysteresis, such that decreasing the fire return interval to
pre-transition levels does not readily return the ecosystem to a grassland state.

The tri-stability framework presented here is novel on two fronts. First, evidence for 378 alternative attractors with descriptive mechanisms and non-linear transitions and hysteresis in 379 response to changes in driver variables are rare in terrestrial ecosystems (Schroder et al. 2005). 380 Identifying ecosystem thresholds, hysteresis, and the mechanisms behind these processes are 381 major challenges in adaptive management and governance (Walker & Salt 2006) and ecosystem 382 383 and community ecology (Sutherland et al. 2013). Second, in a single region (CGP) and climate zone, we provide evidence for three distinct ecosystem states depending on human management 384 of fire, soil type, and to some extent, grazer identity and abundance. In light of the growing 385 386 control of fire by humans, we argue that predictions of future vegetation shifts cannot rely solely on climate, and should incorporate fire frequency and social factors that determine fire 387 388 management plans.

Our conceptual framework provides testable hypotheses that can be applied to other sites and in experimental settings. Spatial analyses of tree cover would provide evidence for whether transitions to woodland constitute a regime shift (using methods described in Hirota *et al.* 2011, Staver *et al.* 2011). Other avenues for future research include testing competition models (Chesson 2000), theoretically derived "generic leading indicators" of impending thresholds (Scheffer et al. 2012), and demographic models that have advanced prediction in several ecological systems (De Roos & Perssons 2002, Huss *et al.* 2013). Such research might also help
identify opportunities for reversing transitions (Fig. 5; Holmgren & Scheffer 2001, Twidwell et
al. 2013b).

In the CGP and similar systems the tri-stability framework may serve as a valuable 398 management tool, allowing landowners to employ fire frequency to avoid unwanted state 399 changes. Given the economic and conservation priorities in the CGP (Hoekstra et al. 2005), the 400 tri-stability framework suggests that preventing transitions to shrublands and woodlands is more 401 cost effective than post-encroachment restoration, because returning fire will not necessarily 402 facilitate the transition back to a grassland state on management-relevant time scales. Therefore, 403 reversing unwanted transitions will likely require costly inputs, such as physical and chemical 404 removal. 405

Combining theoretical predications and application, we agree with others who have 406 cautioned that critical thresholds can vary over time (Bestelemeyer & Briske 2012). Conditions 407 that facilitate grass growth, greater fire intensity, or reduce tree/shrub growth will favor the 408 409 grassland state, requiring longer fire-free intervals to facilitate a transition to a shrubland or woodland (Fig. 4C, sensu Staver et al. 2011, Bond & Midgley 2012, Hoffmann et al. 2012, Roff 410 & Mumby 2012). Initial evidence suggests that fire thresholds have already changed in the CGP; 411 prior to European arrival, the estimated fire return interval for the CGP was ~4 years (Wright & 412 Bailey 1982, Allen & Palmer 2011) and that much of the region was devoid of shrublands and 413 woodlands (Weaver 1954, Wells 1970, Axelrod 1985, Abrams 1986). Now, 3 to 4 year fire 414 frequencies are often insufficient to prevent the transition to shrublands (Fig 2). These 415 observations suggest that fire thresholds have responded to global and/or regional pressures, such 416 417 as elevated CO₂ (Bond & Midgley 2012), loss of larger browsers and native grazers, and exurban

418	expansions that have increased woody plant cover and enhanced woody plant seed sources
419	(Briggs et al. 2005). Given this potential flexibility, continued monitoring of grasslands and
420	adaptive management are critical (for examples, see Fuhlendorf et al. 2008, Bestelmeyer &
421	Briske 2012, Twidwell et al. 2013b).
422	The CGP grasslands share many drivers, feedbacks, and demographic traits for woody
423	encroachment with other grasslands and savannas (Scholes & Archer 1997, Wu & Archer 2005,
424	Bond 2008, Staver et al. 2011, D'Odorico et al. 2012, Higgins & Schieter 2013, Holdo et al.
425	2013), contributing fertile ground for cross-site syntheses and development of more sustainable
426	grassland management. One major research opportunity is elucidating the role of grazers and
427	browsers on woody encroachment in the CGP. Identifying system-specific roles of grazers and
428	browsers on ecosystems transitions will improve our ability to identify patterns and generalize
429	across ecosystems, resulting in better a priori detection of ecosystem thresholds and enhanced
430	opportunities to avoid critical thresholds.
431	Acknowledgements

We thank the site management and personnel of the Konza Prairie Biological Station who have
maintained the large-scale fire and grazing experiments for over 30 years. Support from the
NSF-LTER program to Konza LTER since 1981 has supported collection of these data. We
greatly appreciate the efforts of many different researchers that made our synthetic framework
(Fig 4 and 5) possible. NSF Grant DEB-1242747 and SARAS made participation in this special
issue possible. ZR was supported by a U.S. D.O.E. GAANN fellowship.

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Fig. 1: A depiction of potential internal ecosystem dynamics in response to fire. For all panels, 789 solid lines denote stable equilibria, and in C) dotted lines delineate unstable repellors. A) shows 790 the null hypothesis where fire does not result in ecosystems transitions (grey line) and a scenario 791 792 where CGP ecosystems respond gradually to fire (black). B) shows a threshold system where 793 small changes in fire can lead to disproportionate, but reversible change in system state. In systems with alternative attractors (C), shifts between states show threshold behavior as in (B). 794 795 However, returning drivers to their pre-transition values does not reverse the transition. This figure is based on works by Noy-Meir (1975), Walker et al. (1981), Holling (2001), Folke et al. 796 (2004), Scheffer (2009), and Bestelmeyer et al. (2011). 797



Fig 2. Measurements of shrub and tree dynamics in treatments of Konza Prairie exposed to 800 different prescribed frequencies starting in the late 1970's. "Clonal shrubs" refer to Cornus 801 drummondii, Rhus glabra, and Prunus americana cover and "non-clonal shrubs" include all 802 803 other shrub species with a canopy that exists above the grass layer. (A) and (B) depict changes in shrub cover within lowland topographies for non-clonal (A) and clonal (B) functional groups. 804 Fire free intervals vary from 1 year (black fill), 4 years (white fill) and 20 years (grey fill). (C) 805 depicts the factorial cross of fire frequency and topography (uplands and lowlands) with respect 806 to shrub cover, for non-clonal (white) and clonal shrubs (black) after 30 years of fire frequency 807 manipulation (i.e. the level of shrub cover circa 2012). All shrub cover estimates are averaged 808 across grazed and ungrazed treatments (n = 40, 10 m² plots per combination of fire and 809 topography, derived equally from grazed and ungrazed areas). (D) Shows changes in J. 810 811 virginiana tree density for ungrazed areas with a fire free interval of 4 years (white fill) and 20 years (grey fill). These data come from detailed mapping of catchment basins (see figure 3). The 812 arrow in (D) indicates the timing of a wildfire that affected the 20-year fire treatment. 813



Fig. 3: Changes in woody species occurrence on an ungrazed catchment basin at Konza Prairie in 816 A) 1981 and B) 2012, with only one fire since 1983. In both 1981 and 2012, coordinates of all 817 tree stems and shrubs above the grass canopy were recorded. Trees were mapped as points and 818 819 shrubs as polygons (see Briggs et al. 2002 for more details). For symbols, *Juniperus virginiana* = red dots, *Gleditsia triacanthos* = blue dots, *Ulmus americana* = yellow dots, all other tree species 820 = black dots, and shrub cover = green polygon. Note that the watershed boundaries changed 821 822 between 1981 and 2012, therefore, the original mapping boundaries are delimited with a black 823 line.



Fig. 4: The CGP tri-stability framework for alternative attractors of grasslands, shrublands, and 827 woodlands in (A) deep and (B) thin soils. Horizontal black lines denote alternative attractors and 828 dotted lines denote unstable states. Circles with roman numerals represent contrasting ecosystem 829 830 states identified by experimental or observational studies showing CGP ecosystem has existed at the respective state and fire frequencies indicated on the x- and y-axes. Following thresholds 831 from Ratajczak *et al. in press*, grasslands were those ecosystems with <10% shrub cover and C₄ 832 grasses present, shrublands were 10-60% shrub cover, with minimal trees present, and 833 woodlands were those ecosystems with many trees above the 2.6 m tall, 17 cm diameter at breast 834 height fire-mortality thresholds (Owensby 1973, Hoch et al. 2002, Vanderweide & Hartnett 835 2011). C) depicts how thresholds may change (grey lines) relative to current thresholds (black 836 lines), if shrub growth rate is increased more than grass growth rate (e.g. more grazing, elevated 837 CO_2). Factors that favor grass dominance would move the curve in the opposite direction. Note 838 that shifts from grassland to shrubland were discrete (occurring in 2-5 years), whereas transitions 839 are more gradual between grassland and woodland, and shrubland and woodland. Supporting 840 citations: Bowles and Jones 2013: A) i, ii, iii, v, B) i, ii, iii, iv, v; Boyd and Bidwell 2002: A) iv; 841 Bragg and Hulbert 1976: A) ii, ix; Briggs and Gibson 1992, Briggs et al. 2002, Fig 2 & 3 (this 842 review): A) i, ii, v, xi; B) i, iii, viii; Fuhlendorf et al. 2008: A) viii; Fuhlendorf et al. 2009: A) iii; 843 Harrell et al 2001: A) ii; Kettle et al. 2000: A) ii, xi; Hoch et al. 2002: A) ix B) viii; Owensby et 844 al. 1973: A) i, ii; Peterson et al 2007: A) vii, viii, ix; Process-based estimates (described in text): 845 A) viii; Ratajczak et al. 2011, Ratajczak et al. in press, Fig 3: A) i, iv, v, vi; B) i, iv, viii; Engle et 846 al 2006: B) vii, viii; Burton et al. 2010, 2011: B) vi, viii. 847



851 Fig 5. State and transition model of grassland, shrubland, and woodland states. Following Westoby et al (1989) and Briske et al. (2005), squares represent states and arrows represent processes that may or may 852 not elicit a transition to another state. Dashed arrows represent state trajectories that are only possible in 853 854 lowland and mesic soils. Hysteresis is accounted for by the "selfing" arrows for shrubland and woodland states, where conditions that used to maintain grasslands do not reverse shrubland and woodland 855 transitions once they have occurred. There are few opportunities to reverse transitions to shrublands and 856 857 woodlands with fire alone, but we have left an arrow labeled "unknown opportunities" in anticipation that 858 new techniques and adaptive management schemes will emerge to return CGP ecosystems to grasslands 859 (e.g. Twidwell et al. 2013). Photo Credits: (Grassland: Eva Horne, Shrubland: Zak Ratajczak, Woodland: John Blair). 860

