

A Gear Selection Aid  
For Agricultural Tractors

by

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A MASTERS THESIS

submitted in partial fulfillment of the  
requirements for the degree

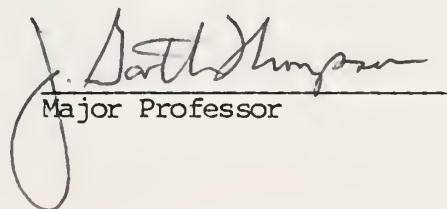
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## PREFACE

This thesis describes the design, construction and testing of a device designed to assist the operators of agricultural tractors to minimize fuel usage during field operations. This project was conceived by Dr. Mark Schrock. His work in promoting gear-up and throttle-down while working for the Agricultural Extension Service provided much of the insight necessary during development of both hardware and software. His assistance and encouragement as both an advisor and friend has made the project much easier.

I would like to give a special thanks to International Harvester for providing the tractor and their technical assistance for this project.

I would also like to acknowledge and thank my major advisor, Dr. J. Garth Thompson for his assistance during this project. He was very helpful with the technical aspect of implementation. His assistance in the implementation of the electronic hardware saved countless hours of delay during equipment development.

I would also like to acknowledge and thank Mike Schwarz and the Agricultural Engineering Department for allowing the use of computer equipment and software Mike had developed for previous projects as well as providing ideas for the software for this project.

And finally, a special thanks to my family. Without their support I would not have been able to finish this project.

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## Chapter 1

### CONCEPT DEVELOPMENT

#### Project Justification

Rising fuel costs have prompted farmers to explore ways of optimizing fuel efficiency in operating their equipment. Diesel fuel prices, for example, increased 588% from 1972 to 1981. This increased cost has made the farmer aware of energy-saving modifications and practices in operating farm equipment.

#### Gear Up and Throttle Down

Many methods of reducing fuel consumption already have been implemented with varying degrees of success. Gear up and throttle down effectively reduces fuel consumption during light field operations with agricultural tractors, Hauck<sup>1</sup> (1979).

The basic concept of gear up and throttle down is to operate the tractor at the most fuel-efficient engine speed and gear ratio while maintaining the desired ground speed. This practice was promoted during the mid to late '70s by Kansas State University Extension Agricultural Engineering Department. Although this practice cannot be implemented in all agricultural field operations, it can be beneficial when the tractor is being operated at less than full load. The savings afforded by gear up and throttle down are due to the reduced engine friction, hydraulic pumping, and fan losses.

#### Estimated Savings

Chancellor<sup>2</sup> (1981) estimated a potential fuel savings of 10% and

an increased rate of work of 17% by operating a tractor at its most efficient torque-speed combination during a field operation. The estimation was based on a hypothetical transmission, selecting from 32 possible gear ranges for light loading during a single field operation. The simulation provided for sampling and changing gears at 10-second intervals. The increased rate of work indicated that the tractor also changed field speed in the optimization.

Stevens<sup>3</sup> (1981) evaluated the fuel savings resulting from operating a John Deere 4640 tractor at 1700 rpm instead of full throttle. The study was based on draft data from 10 relatively low-power requirement field operations. The savings ranged from 13 to 36%, depending on the extent of loading and field variation.

#### Operator Concerns

The main concern in implementing gear up and throttle down is engine damage. Diesel engines and turbochargers can be damaged by prolonged excessive loading at low engine speeds. This overloading at low rpm often is referred to as "lugging." Lugging for short periods will not damage engines, but lugging for extended periods may damage pistons, bearings, and turbochargers.

#### Limitations of Application

Gear up and throttle down also is limited to field operations where implements are not driven by the power take-off (pto). The pto speed is directly proportional to the engine speed, and most pto-driven equipment must be operated at an engine speed of 2100 rpm. Another limitation is the reduction in reserve power, or ability to

recover from short intervals of overloading. At lower engine speeds the torque rise is reduced, thus limiting the ability of the engine to recover during field operations with highly variable loading, such as chiseling or plowing.

The use of gear up and throttle down is believed to be limited. Much of the hesitancy is due to insufficient information provided by the tractor instrumentation and the operator's lack of familiarity with the procedure. Feedback from the tractor to the operator could greatly enhance the use of gear up and throttle down. In most situations, the operator cannot estimate the loading of the engine or the potential fuel savings from using gear up and throttle down. The operator may be reluctant to use the practice because he thinks it may damage the tractor. Depending on the load, this damage may be either real or imaginary, but to the operator, it is a real concern. During most light field operations, the operator can be assured he will not damage the tractor by gear up and throttle down. As the loading is increased, however, the possibility of overloading is increased, and the operator becomes hesitant to implement gear up and throttle down.

#### Operator Interface

If the operator had information indicating the tractor could be operated in a more optimum range without damaging it, the operator's reluctance would be decreased. A gear selection aid could provide this link between the operator and the tractor. If the operator knew the optimum operating range, engine speed, and estimated fuel savings, he would have all the necessary information as well as the incentive to use gear up and throttle down.



## Incentive for Development

Several recent developments have decreased the cost and enhanced the feasibility of developing equipment to implement a gear selection aid for the gear up and throttle down concept. The analysis necessary for evaluating the engine load, ground speed, engine speed, fuel consumption, and potential fuel savings is complex. Although it may have been possible to implement this concept by using TTL or CMOS devices, the microprocessor greatly increased the flexibility of the implementation.

The price, size, and calculating power of microprocessors have changed drastically in recent years. Single board microcomputers with 4000 bytes of RAM and 2000 bytes of ROM can be purchased for less than \$300. The physical dimensions of these units are about the size of a sheet of notebook paper and less than an inch thick. These units can be programmed to do all calculations necessary for the optimization routines.

Electronic sensors capable of direct connection to the micro-computer also have enhanced the implementation. Automotive and agricultural equipment now use digital electronics that are less expensive, more accurate, more reliable, and more rugged than the older analog technology.

The reserve torque capacity of tractor engines also has increased with the newer engine designs. Many of the early turbocharged diesel tractor engines had a relatively sharp torque drop with reduced engine speed. When the engine was loaded and the rpm decreased, the torque

also decreased rapidly, thus causing the engine to lug or stall. This made operating the engine at speeds less than 1800 rpm possible only during light loading. The more recent tractor engines have relatively high torque rises, which helps to minimize the possibility of overloading or lugging the engines.

The drawbar pull, or draft, for most field operations increases with ground speed. Thus, if the ground speed is decreased, the draft decreases. If the engine torque remains constant or increases, the tractor can maintain short periods of overload without having to shift down. After the field conditions have changed and the draft has decreased, the tractor will be able to resume its previous ground speed. If the draft is increased for an extended period of time, the operator should select a lower gear ratio.

#### Implementation Criteria

Equipment to encourage the use of gear up and throttle down must meet several criteria. The device must be accurate enough to achieve the desired results, reliable within the constraints of the design criteria, and easily understood by the operator. Because the device is transferring information rather than providing direct implementation, the device also must have credibility with the operator.

In this project all the tractor's original instrumentation was left operational. This allowed the operator to use the instrumentation to set engine rpm and check such items as ground speed and exhaust gas temperature. The operator was advised to monitor all safety indicators, such as the exhaust gas temperature warning indicator, and to stop operations if any sign of engine overloading or

damage occurred. Because the device recommended operations within the constraints of the tractor safety indicators, the operator was provided with the confidence to implement the suggestions. If the operator had any concern about the tractor's ability to operate at the recommended ranges, the operator was able to check the instrumentation to verify the tractor's performance.

### Project Objective

The objective of this project was to build and evaluate a gear selection aid to assist the operator in minimizing fuel consumption during field operations. To evaluate the performance of the gear selection aid, the tractor and operator's performance were monitored both before and after the device was made operational. Engine speed, ground speed, and rack position were recorded and stored so the operator's performance as well as the performance of the gear selection aid could be evaluated. The number of times the gear selection aid recommended gear changes and how often the operator responded to those recommendations was also recorded. Thus, the success of implementation could be determined. The data also provided information to optimize the different variables used in the optimization routines.

### Thesis Objective

The objective of this thesis is to explain how a gear selection aid with data collection was designed, constructed, installed, and tested on an International Harvester 3588 agricultural tractor. Because the data analysis will be the topic of another thesis, there will be only minimal discussion of the data collected during testing.

## Chapter 2

### METHODOLOGY

#### Fuel Optimization Alternatives

Several methods of implementing fuel optimization routines for agricultural tractors are possible. The choices range from simply educating the operators about the economic advantages of gear up and throttle down to a device having complete control of the tractor. Attempts at educating operators have met with limited success. Complete control of tractor engine speed and gear selection would be quite expensive and may not be accepted by the tractor owners.

The exact savings of the different methods are almost impossible to calculate. If the operator is given sufficient information, presented in an understandable format; a large portion of the potential savings may be realized. This project was based on the idea of providing the necessary information to the operator and leaving the implementation to the operator's discretion. Because the key to implementing the optimization routine was the interfacing between the tractor and the optimization device, it was important to find a tractor that could be modified and instrumented with the appropriate sensors, data manipulation equipment, and a display.

#### Equipment for Implementation

The International Harvester Company loaned the Agricultural Engineering Department at Kansas State University a Model 3588, 4-wheel drive tractor to use on this project, (Fig. 2a). This tractor has two important features which simplified the implementation of the instru-

mentation for this project. The tractor has electronic instrumentation and an American Bosch fuel-injection system.

The tractor's electronic instrumentation incorporated magnetic pick-ups for engine speed and wheel speed. By sensing the outputs of these pick-ups rather than developing new engine and wheel speed sensors, the development time of the project was reduced. The American Bosch fuel injection system was also an important factor in simplifying the instrumentation for this project. Rather than using a mechanical load transducer and a fuel meter to measure load and fuel consumption, the engine speed and rack position were used to estimate the fuel consumption and engine load using mathematical models.

#### Optimization Procedure

To determine the recommended gear ratio/engine speed, the engine speed and position of the fuel metering rod (rack) were used to calculate an estimate of the present load and fuel consumption. Assuming the same ground speed and engine load, the program then computed the fuel consumption for successively higher gear ratios and correspondingly reduced engine speeds until the program estimated an engine overload or an engine underspeed condition. The estimated fuel consumption at each gear ratio was compared with the present fuel consumption estimations to determine potential fuel savings.

If the estimated minimum fuel usage resulted in a predicted savings of greater than .5 gallons per hour (gph), the display was enabled. The estimated present fuel flow, predicted fuel savings, recommended gear ratio, and recommended engine speed were displayed to



the operator. Specific details of the development and use of the model are given in Chapters 4, 5, and 6. After developing, testing, and verifying the optimization models, it was important to develop a method of presenting the information to the operator in a manner that would be acceptable and meet the design constraints.

### Design Criteria

The main design criteria were that the device be reliable, accurate, easy to understand, and above all, be credible with the operators. The reliability and accuracy of the device were verified during several stages of testing. This included several hundred hours of testing during the performance mapping and other laboratory tests and approximately 100 hours of field operations by the research staff. After the unit was built, it was tested in the lab using a signal generator to simulate ground speed and a dynamometer to simulate field loading. By using the simulated loading, the range limits could be tested, and the accuracy of the calculations could be verified. The next step was to determine if the display presented the information to the operator in a way that made it easy to implement the recommendations.

Because the operator often is doing several tasks during tractor operations, the device also must be easy to understand. To accomplish this, a light on the display panel alerted the driver when new information was displayed. The present fuel consumption, recommended gear ratio and engine speed, and the potential fuel savings were displayed to the operator. The operator then had the information necessary to make the gear change, but the actual implementation was still at the

operator's discretion.

### Field Operation

Because the device was designed to assist the operator only during field operations, it was important that the device be activated only during the field operations. If the display were allowed to operate during activities other than field work, the display would give erroneous recommendations, and the operator would soon learn to ignore the display. Ground speed and time were used as an indication of when the tractor was operating in field conditions.

Most field operations require a ground speed of from four to nine miles per hour and are operated within this range for extended periods of time. Other operating modes such as moving the tractor to and from the field and connecting to implements are either outside this range of speed or are for short periods of time. The program required the tractor to be operating between four and nine m.p.h. for at least one minute before the display could be activated. Because the tractor was to be operated under lightly loaded conditions where wheel slippage is minimal, the wheel speed and ground speed are approximately the same. Wheel speed is easier to detect so it was used as an indicator of when the tractor was operating in field conditions.

It was also important to monitor the peak field loading conditions to eliminate possible overloading. If the engine was operated for more than eight consecutive seconds with an average rack position of greater than 90% of full rack, the calculations for savings were not performed for that minute. This minimized the possibility of

selecting a gear range that could cause overloading of the engine. This overloading would result in the operator having to shift down from the previously recommended gear range and could reduce the credibility of the device.

### Operator Interface

When the operating parameters are within the program limits and an output is displayed, the operator can choose to implement or ignore the recommendations. The display will stay on for one minute regardless of whether the recommended changes are made. The display is then disabled for the next minute. This one minute delay occurs any time the display has been on. At the end of the minute, the calculations are performed to determine if a recommendation should be made. If the operator did not make any changes and the field conditions have not changed, the calculations should result in the same recommendations to the operator.

If the operator makes the recommended changes, the display will still remain on for the entire minute. This gives the operator enough time to check that the new gear range and engine speed are correct. The display then will be disabled for the next minute. After the recommended change has been made, the optimization routines will occur every minute but the display will stay off unless the field conditions change. The reason the display stays off is that the routine has been optimized for that specific field loading pattern.

This display format was designed to help operators that are leery of the recommended changes. If the operator thinks the gear ratio displayed is too high and engine speed too low, he can choose a gear

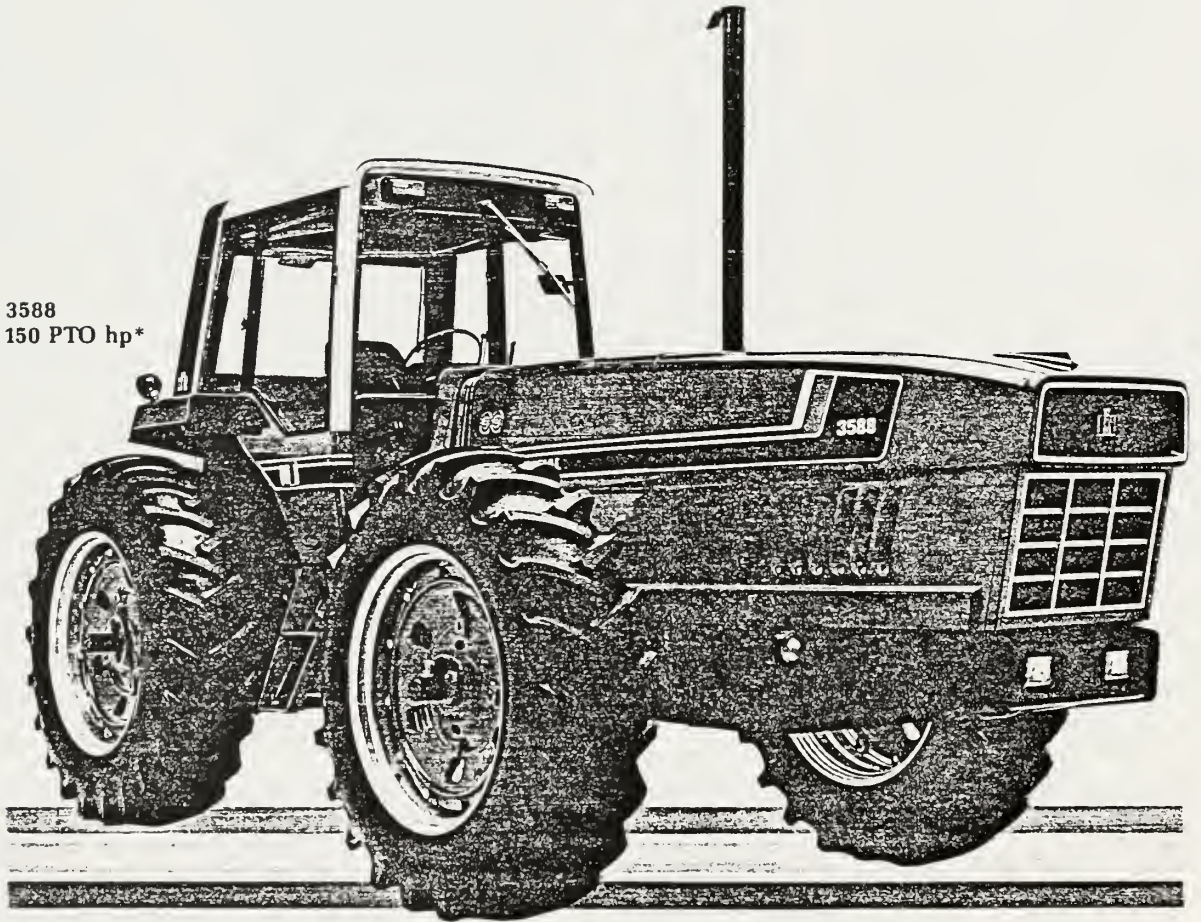


ratio between the present gear and the displayed gear. If the selected gear ratio and engine speed do not result in performance within optimum gear ratio and engine speed after a one minute interval. If the field conditions have not changed, this recommendation will be the same as the previous one.

#### Data Collection

To determine how often the display was enabled and if the operators implemented the recommended changes, a data collection system was added. The data recorded were time, average rack value, pulse counts from the engine and transmission pick-ups, and the recommended gear ratio and engine speed. The previous 30 minutes of data were stored on cassette tapes at 15-minute intervals for later analysis. By storing 30 minutes of data each 15 minutes, the data were duplicated to provide a backup in case of tape reading problems. The analysis was performed using the DEC PDP11/34 computer in the Agricultural Engineering Department.

3588  
150 PTO hp\*



International Harvester Model 3588 Tractor  
Fig. 2a

## Chapter 3

### HARDWARE DEVELOPMENT

#### Selecting the Computer

Several types of computers could have been used for on-board computing and data collection for this project. The inexpensive single-board, eight-bit microcomputers, such as the SYM-1, and the medium cost eight-bit micros with disc drives, such as the Apple II, were considered in detail.

The Apple II had been used by the Agricultural Engineering Department for machine language program development, but had not been tested in the field environment. The main advantage of the Apple II was the availability of floppy disc drives. The disc drives would allow for more data storage but were unproven for unattended operation in a harsh environment. Because the speed and quantity of storage necessary could be met with cassette tapes and because cassette tapes are more rugged, it was determined that cassette tape storage should be used for this project.

The SYM-1 had been used in environments with large temperature swings, but had not been used in environments with the vibration encountered in the field operation. To minimize vibration and temperature swings, the computer and associated peripherals were mounted in the cab of the tractor. The operator cab of the tractor is mounted on isolation dampers and is air conditioned and heated for the operator's comfort. By mounting most of the equipment inside the cab, the equipment was in a relatively stable environment during the operation. The

cab reached temperatures higher than 100°F when not being used, but during the field operations the cab was air conditioned.

After evaluating previously developed data collection software and hardware, it was decided to minimize the hardware costs and size and to reduce programming time by using a SYM-1 microcomputer with cassette tape storage (Fig. 3a). The SYM-1, built by the Synertec Corporation, is an inexpensive single-board computer that has been used successfully for data logging and control applications within the agricultural and mechanical engineering departments. Some of the in-house software, such as data collection and real time clock subroutines, could be used with minimal changes, thus reducing the development time.

#### Real Time Clock

The previously developed real time clock with its own back-up battery and hardware that provided the day of the year, and time of day in hours, minutes, and seconds was important to the project. A MSM5832RS clock chip and associated circuitry had been developed and tested on the SYM-1 microcomputer, Schwarz<sup>4</sup> (1984). The clock was interfaced to the SYM-1 using external port A. The clock provided the timing needed for determining when to collect data, calculate potential savings, and store data on tape. Interfacing the computer to the magnetic pickups for engine and wheel speed was accomplished by using operational amplifiers.

#### Interfacing Tractor Instrumentation

To avoid disabling or loading of the tractor's existing instru-



mentation, capacitor coupling to the magnetic pickups was used, (Figure 3b). For each pickup a capacitor was connected to each lead. The other end of the capacitors was connected to the inputs of the appropriate operational amplifier. Balancing resistors were used as shown to keep the inputs of the operational amplifier at approximately six volts. The outputs of the amplifiers were connected to pulse-counting inputs of port PB6 on the SYM-1.

### Sensing Rack Position

Sensing of rack position was not available on the tractor's standard instrumentation, therefore a method of sensing the fuel metering rod, commonly referred to as the "rack", was developed. The rack position was determined by sensing the rotational position of a shaft. The shaft was accessible by removing a cover from the fuel pump. Because the shaft did not extend outside the fuel injector housing, it was necessary to extend the fuel metering shaft to allow attachment of a position sensor.

Several methods of measuring the rotation of the shaft were considered. The first consideration was the use of a potentiometer and a regulated power supply to provide an analog signal. Limitations associated with potentiometers are their non-linearity and drift when subject to temperature variations. The analog signals are also more susceptible to noise problems than digital signals and the analog signal would have to be converted to a digital signal before interfacing to the SYM-1. To eliminate the analog signals and minimize electrical interference problems a digital rotary position encoder was used for this project.

To determine the required resolution of the encoder, it was necessary to determine the amount of rotation of the fuel metering shaft. To accomplish this, the position of the shaft was marked with the throttle set to the minimum position. The tractor was loaded to maximum horsepower using a dynamometer, and maximum shaft rotation was marked. The difference between the minimum and maximum position was approximately  $60^{\circ}$ . Encoders were available in either eight or 10-bit resolution for  $360^{\circ}$  of rotation. Eight-bit units have an accuracy of approximately 1.41 degrees of rotation per bit. The 10-bit unit has an accuracy of .35 degrees per bit. To achieve the accuracy required by the mathematical model the 10 bit unit was selected.

After reviewing specifications of several encoders, it was determined that the Litton Model 76-NB10-2-S-1, 10 bit, absolute rotary encoder (Appendix A) would have suitable resolution and would withstand the vibration and temperature environments. The encoder was ordered with gray code conversion to natural binary. The gray code eliminates the possibility of getting incorrect readings during state changes of the encoder.

#### Installing Encoder

Mounting the encoder required modification of the fuel pump cover. A machined aluminum plate was used to attach the encoder to the fuel injector pump housing. The shaft of the metering rod was extended and a zero-backlash flexible coupling was used to connect the encoder to the shaft. Because the encoder was located on the engine, it was exposed to high vibration levels and large temperature vari-

ations. After attaching the encoder to the fuel injector pump, it was determined that the heat transfer to the encoder was causing the encoder temperature to exceed the specifications given for the encoder. To accomplish some thermal isolation, an asbestos gasket was installed between the adapter plate and the encoder. With this modification, the encoder case temperature was limited to a maximum of 160°F during full load dynamometer testing. This temperature was within the specifications of the encoder. The electrical interface connection to the SYM-1 was port PA0, bits 0 through 7. The power supply for the encoder was provided by the SYM-1.

#### Power Supplies

The power for the instrumentation package was provided by the tractor battery through voltage convertors and regulators. The SYM-1, the digital encoder, and the display unit, required five volts dc. This was provided by a Lambda Model LAS1405 dc-to-dc converter. The six volts dc required by the recorder was provided by a Radio Shack 12 volt dc to 6 volt dc converter.

#### Display Unit

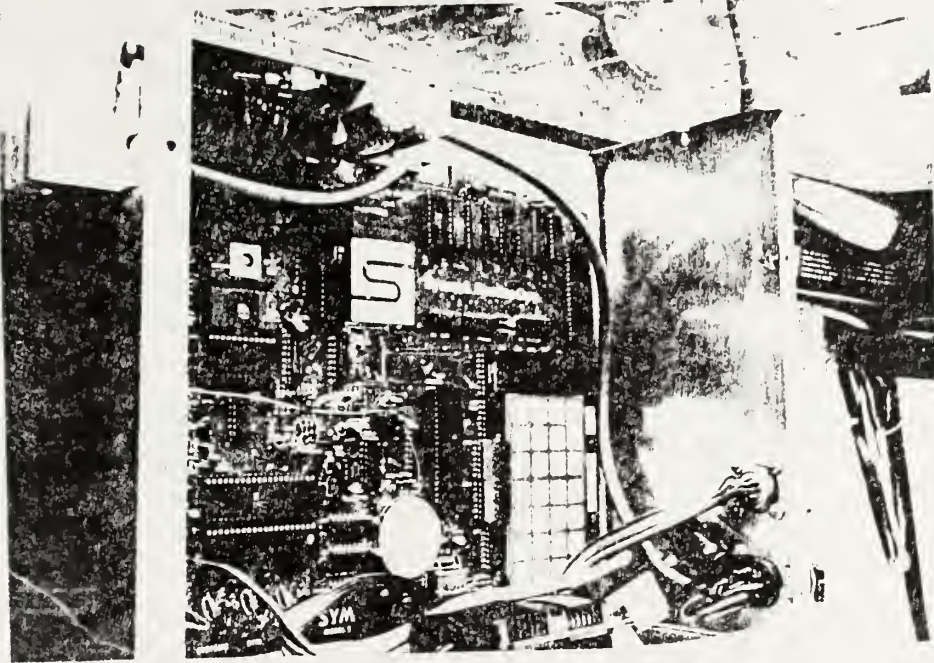
The display unit was designed to provide the operator with the recommended gear selection and engine speed. The tractor had a dual range differential, a four-range manual transmission, and a hydraulically activated dual range torque amplifier. This provided 16 possible gear ratios. The original concept was to display the gear number, one through 16. This would have been quite confusing unless the operator was familiar with the gear ratios for this particular

tractor and would have required the operator to determine mentally the three control settings required to obtain the recommended gear ratio.

To simplify the display and provide more concise instructions to the operator, the gear selection display was designed using a combination of light-emitting diodes (LEDs) (Fig. 3c). The recommended gear ratio was displayed by lighting one of two LEDs for the T/A, one of four LEDs for the transmission gear, and one of two LEDs for the range of the differential. Because the engine speed will vary by a few hundred rpm in typical field operations, the recommended engine speed was rounded to the nearest hundred and displayed using two seven-segment displays to indicate hundreds and thousands of rpm.

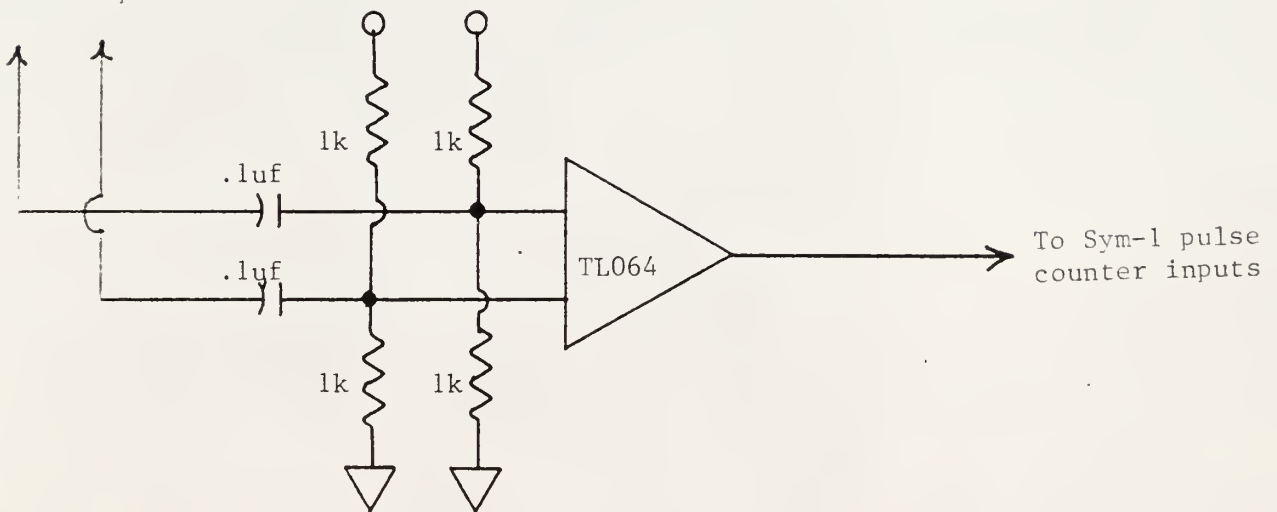
Estimated fuel consumption and estimated fuel savings were calculated to the nearest tenth of a gallon per hour (gph). The maximum anticipated fuel consumption was less than 10 gph, so the estimated fuel consumption and estimated fuel savings were displayed using two seven-segment displays for each value.



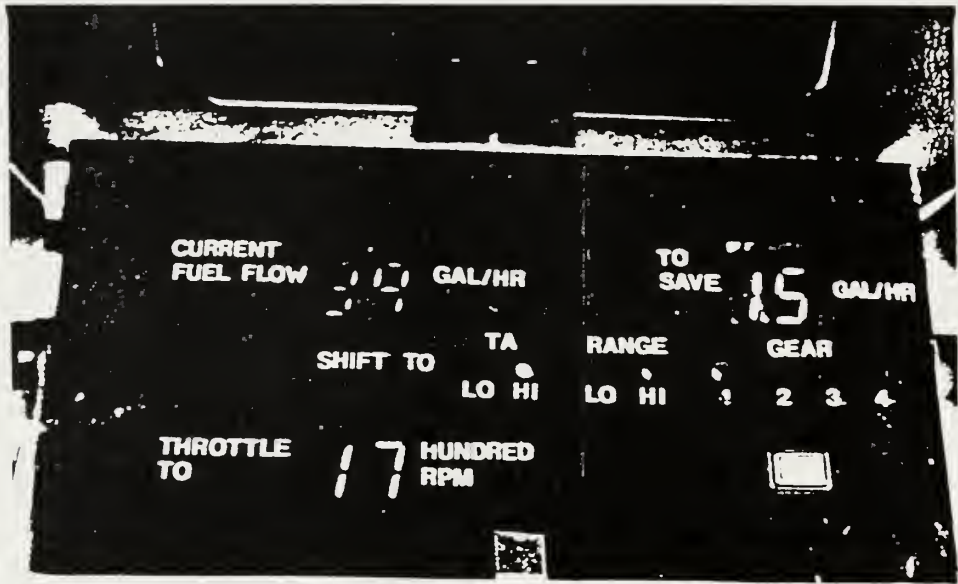


SYM-1 Computer by Synertec Corporation  
Fig. 3a

From Magnetic  
Pickups



Magnetic Pick-up Interface  
Fig. 3b



Display Unit for Optimization Device  
Fig 3c

## Chapter 4

### ENGINE PERFORMANCE MAPPING

#### Performance Map Criteria

Mapping the engine performance was critical for developing the models used during this project. The tractor used for this project was furnished by International Harvester Corporation. The International Harvester Company provided recommended limits for operating of the engine safely: a minimum engine speed of 1200 rpm for full load and a maximum exhaust gas temperature (EGT) of 1400 °F for any loading. During the mapping, the engine was operated at speeds as low as 1500 rpm with wide open throttle, and the EGT remained below the 1400° F limit.

A performance map for the engine was provided with the tractor; however, this performance map was not sufficient for this project because it did not include fan, hydraulic, and other drive train losses. The modeling also required a value for the rack position corresponding to each point of the engine performance map. This position was not provided with the original engine map. Other measurements necessary for the engine mapping were engine speed, engine load, and fuel flow. The engine speed and rack position measurement were implemented as described in chapter 3. Measuring the fuel flow was necessary for mapping the engine, but a mathematical model was used during the field testing.

#### Fuel Measurement

The fuel flow was calculated by measuring fuel weight at the

beginning and end of each test and dividing by time. The diesel fuel from the diesel injection pump is not completely consumed by the tractor engine. Some of the fuel is passed through the injector and returned to the fuel tank. This "return" fuel is necessary to prevent the injector from overheating. The quantity of return is highly variable and dependent on engine speed and load. To measure only the consumed fuel, two three-way valves were added to the fuel lines (Fig. 4a). One valve selected the supply, either tractor tank or weigh scale, and the other valve selected the return path, either tractor tank or weigh scale.

During warm-up and between tests, both the supply and return were set to position A. During each test, the supply and return were set to position B. Because the return was going back to the weigh scale, the change in quantity of fuel in the weigh scale represented the actual fuel consumed by the engine. The weigh scale was filled by pumping fuel from the tractor tank to the weigh scale. This was accomplished by setting the supply valve to position A, opening the fill valve, and turning on the auxiliary fill pump. During most of the testing, this allowed the weigh scale to be filled while the engine temperature was stabilizing between tests. After filling the weigh scale, the fill pump was turned off and the fill valve was closed.

#### Fuel Temperature

Before the performance mapping could begin, it was necessary to investigate the effect of fuel temperature on engine performance. <sup>5</sup>Wu

and McAulay indicate an inverse relationship between fuel temperature and horsepower output for a diesel powered engine. To determine if the supply fuel temperature effected the engine performance, the temperature of the fuel supply was subject to temperature variations much larger than could be experienced during actual field operations.

The fuel supply line was disconnected from the inlet of the fuel filter. A finned tube heat exchanger was connected between the fuel line and the fuel filter. Thermocouples were placed on the surface of the fuel line at five locations; the supply tank, before the heat exchanger, after the heat exchanger, at the inlet to the injector pump, and the outlet of the injector pump.

The tractor engine was operated at various speeds and loads while the temperatures, engine speed, fuel flow, and horsepower output were recorded. The heat exchanger then was submerged in an ice bath to cool the fuel supply. The engine speeds and loading were repeated, and the temperatures, engine speed, fuel flow, and horsepower output were recorded.

The temperatures recorded at the inlet of the injector pump and the outlet of the injector pump were approximately the same regardless of supply fuel temperature, engine speed, or engine loading. This stable fuel temperature was attributed to the large heat transfer surfaces provided by the fuel filters, fuel lines, the injector pump, and the relatively slow flow rates.

Further analysis of fuel consumption for the entire range of engine loads and fuel supply temperatures indicated no significant change in engine performance due to changes in fuel supply tempera-



tures. Therefore, the fuel supply temperature was disregarded in the performance testing and modeling. The heat exchanger then was removed from the fuel supply line before the final engine mapping was performed.

#### Data Collection

During the performance mapping, engine speed, fuel weight, rack position, dynamometer torque, and time of day were recorded. Engine speed, rack position, and time were recorded and stored on cassette tape by the SYM-1. The fuel weight was measured by suspending a two-gallon tank from an Ametek model BA-25-LB strain gage transducer (Appendix B). The strain gage was powered and sensed by a Calnex model 166 voltage to frequency converter (Appendix C). The output, which was proportional to weight, was connected to port PB6 pin A of the SYM-1.

A program was written for the SYM-1 to count the pulse inputs from the engine speed and fuel weight during each two-second interval, and to store these values in memory. At the end of each two-minute test, these stored values and the time were recorded automatically on cassette tape.

Dynamometer torque and exhaust gas temperature were recorded manually at 15-second intervals during each test. The torque was read from the digital display on the Model NEB 400 A&W dynamometer. The exhaust gas temperature was read from the tractor instrumentation.

#### Testing Range

The engine loading was for the range of 50% to full load for

engine speeds of 1500 rpm to wide open throttle. The tractor was operated at wide open throttle, and the load was increased until an engine speed of 1500 rpm was maintained. Data then were recorded for this condition. The load was decreased until an engine speed of 1700 was maintained at wide open throttle. This process was repeated at 200 rpm steps until approximately 50% of the full load, 75 horsepower, was reached.

During the next series of test points, the engine load was reduced approximately 10 horsepower for each of the engine speeds previously determined until a minimum of 75 horsepower was recorded. This was accomplished by having the tractor operator set the engine rpm while the dynamometer was set to the appropriate load. After this set of data was collected, the loads were reduced another 10 horsepower for each of the engine speeds until 75 horsepower was recorded.

#### Testing Procedure

The test procedure for collecting each data point on the performance mapping follows.

1. The tractor is started and idled with the pto off and the fuel selectors in position A.
2. The fuel fill valve is opened, and the fill pump is turned on until the weigh scale is full. The fill pump is turned off, and the fill valve is closed.
3. When the engine water and oil temperatures indicate the engine is warm, the pto is engaged with no load on the dynamometer. Then the dynamometer load and engine speed were set.

4. The engine exhaust temperature is monitored until it stabilizes.

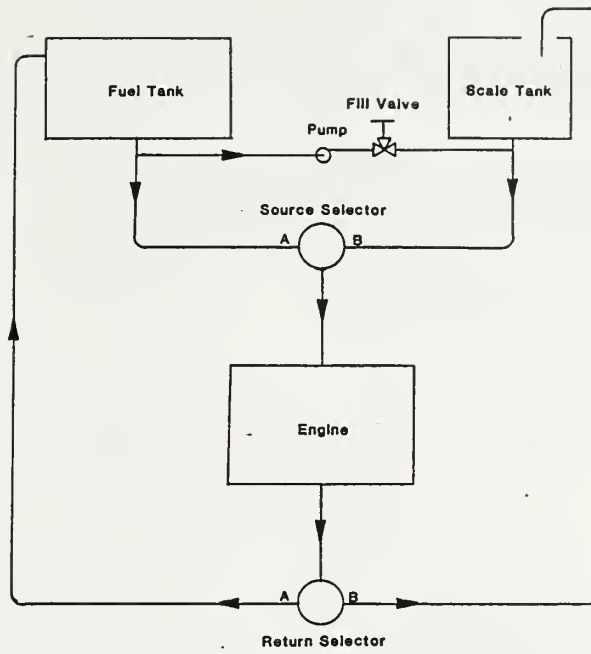
5. The fuel selectors are switched to position B.

6. The SYM-1 data collection is started, and the operator records the exhaust gas temperatures and pto torque and horsepower every 15 seconds.

7. At the end of the two minutes, the dynamometer load is reduced while reducing the engine speed. The pto is disengaged, and the engine is set to idle.

8. Steps two through six are repeated for each of the test points.





Fuel Flow Switching Valves  
Fig. 4a

## Chapter 5

### DEVELOPMENT OF THE MATHEMATICAL MODELS

After collecting data for the performance map, different models were evaluated by the statistics department at KSU. It was determined that a linear regression model did not fit the parameters with the desired accuracy. The regression procedure in the Statistical Analysis System (Helwig, 1979) was tested. This procedure provided models with accuracy well within the project guidelines, so it was used to develop the mathematical models for engine loading, fuel consumption, and rack position.

To simplify the model, the average rpm and encoder readings were subtracted from the data values before entering the value into the equation. For the original data these values were 1921.51 and 128.054, respectively.

Horsepower Calculation:

Average horsepower is predicted by using the rack position and the engine rpm in the following equation.

Equation 1

$$\text{hphat} = 2.070851 + (.023899 * \text{rpm}) + (1.681623 * \text{rack}) \\ - (.00003113075 * \text{rpm} * \text{rpm}) + (.001008684 * \text{rpm} * \text{rack})$$

where:

$$\text{hphat} = \text{ptohp predicted from the model} \\ \text{rpm} = (\text{engine rpm}) - 1921.51 \\ \text{rack} = (\text{encoder reading}) - 128.054$$

The "F" statistic of this model is 2804.53 and the "R squared" value is 0.9968 for the range of engine speeds and loads used during the dynamometer tests. Both the "F" statistic and the "R squared"

values indicate a good fit to the original dynamometer data.

#### Fuel Flow Calculation:

Average fuel flow is predicted by using the rack position and the engine rpm in the following equation:

#### Equation 2

$$\begin{aligned} \text{ffhat} = & 45.331760 + (.016695 * \text{rpm}) + (.539934 * \text{rack}) \\ & - (.0000055161 * \text{rpm} * \text{rpm}) + (.00199687 * \text{rack} * \text{rpm}) \\ & + (.0002517891 * \text{rpm} * \text{rack}) \end{aligned}$$

where:

$$\begin{aligned} \text{ffhat} &= \text{predicted fuel flow in lbs/hr} \\ \text{rpm} &= (\text{engine rpm}) - 1921.51 \\ \text{rack} &= (\text{encoder reading}) - 128.054 \end{aligned}$$

The "F" statistic of this model is 2637.99 and the "R squared" value is 0.9973 for the range of engine speeds and loads used during the dynamometer tests. Both the "F" statistic and the "R squared" values indicate a good fit to the original dynamometer data.

#### Rack Position Calculation:

Average rack position is predicted by using the engine rpm and the predicted horsepower from the first equation as follows:

#### Equation 3

$$\begin{aligned} \text{rackhat} = & -1.310154 - (.015853 * \text{rpm}) + (.615521 * \text{hp}) \\ & + (.00002779667 * \text{rpm} * \text{rpm}) - (.000372483 * \text{rpm} * \text{hp}) \end{aligned}$$

where:

$$\begin{aligned} \text{rackhat} &= \text{predicted encoder reading} - 128.054 \\ \text{rpm} &= (\text{engine rpm}) - 1921.51 \\ \text{hp} &= (\text{engine hp}) - 104.53 \end{aligned}$$

The "F" statistic of this model is 2129.37 and the "R squared" value is 0.9958 for the range of engine speeds and loads used during the dynamometer tests. The "F" statistic and the "R squared" values both indicate a good fit to the original dynamometer data.

The rpm and the rack data were "normalized" as discussed before,

128.054 must be added to the rackhat to obtain a predicted encoder reading.

## Chapter 6

### COMPUTER PROGRAM

#### Machine Language Assembler

The computer programs used for the SYM-1 computer were developed on an Apple II computer using a machine language assembler. The programs were transferred to an EPROM which was used on the SYM-1. The SYM-1 computer has the capacity for two EPROM chips, one of which can be used to boot the system. Because the SYM-1 must be initialized each time the tractor is started, the circuit board was modified to boot from the EPROM program when the power is turned on or the computer is reset. Reset was provided by either manual reset or by an external automatic reset circuit.

#### Automatic Reset

The automatic reset was implemented to initiate a reset if the computer program gets lost. To accomplish the reset an external 4047 multivibrator circuit was added. The 4047 was operated in the astable mode and a time constant per cycle of 30 seconds was implemented. When operated in this mode, retriggering causes the time period to start over. Every second the SYM-1 main program retriggers the 4047, which prevents the output from changing states. The output was connected to a logic gate on the hardware reset. The only time the one second interruption would not occur was when the program saves data to cassette tape. Saving data to tape required approximately 10 seconds, therefore the time constant on the 4047 was set to 30 seconds to allow saves to tape without resetting the program.

## Data Storage

Data read from the instruments was in fixed point binary form. To perform the calculations and store and display the results, several other forms were required.

The data saved on tape and the values used in the model equations are average values of several data samples. The calculations to obtain the averages and the calculations of the model equations were performed in floating point form to insure adequate precision in the results. A set of floating point subroutines were used which had been developed and tested on the SYM1 by Mike Schwarz of the Agricultural Engineering Department. Data was converted from binary form to floating point form for the calculations and converted back to binary form for storage on the cassette tape. Values to be displayed including fuel flow, fuel savings and engine rpm were converted to BCD for use by the display output routines.

The data was recorded on cassette tape using a Radio Shack Model TRS81 audio tape recorder controlled by the microcomputer. When the tractor key switch was on, data was saved on the tape every 15 minutes. The computer copied the data for the previous 30 minutes during each save to tape. This provides duplicate copies of each set of data.

There are no means of sustaining the power to the recorder after the key switch is off, thus if the key is turned off at 10 minutes after the data was saved on tape, the last ten minutes data would not be saved. The maximum amount of data that could be lost is 15 minutes. If the tractor is operating properly, it should be allowed to

idle for several minutes after heavy field operations. Therefore, in the last five to 10 minutes, the tractor should not be used in field operations.

#### Determining Field Operations

The optimization routines were designed for operating in actual field conditions, therefore the specific times of operation, types of field operation, etc. were unknown. To determine when the tractor was operating in field conditions and to account for the variability of the load, the optimization routine used a combination of 1-second, 4-second, and 1-minute averages. The 1-second and 4-second values of rack, engine speed, and transmission speed were used to determine load peaking and to count operation changes that could give false averages. These peak loads and changes were counted by "flags".

#### Out-of-Range Indication

Each flag uses one byte of memory. Bit seven is used to indicate the event is happening and bits 0 to 6 were used to count the number of times the event occurred during each minute. For example, if the operator stopped for 30 seconds during one minute, the averages for engine speed, ground speed, and rack used in the calculations, would not be a good indication of the actual working conditions. To detect this change in operation, the program monitors the ratio of engine speed and ground speed. When this ratio changes, bit seven of the gear change flag is set. The bit stays set until the ratio of engine speed to ground speed is not zero and is the same for at least two seconds. Then bit seven is cleared, and one is added to the value of



the gear change flag and bit zero of the mflag is set. The mflag is the minute flag. When any flag is incremented the minute flag is set to indicate that there was a change or out-of-range measurement during that minute. After the mflag is tested at the end of each minute, the mflag is shifted to the left. This allows the program to determine if the flags were set during any of the previous eight minutes.

### Memory Storage

The computer RAM serves as a temporary storage location for calculations and for storing information to be recorded on tape. The main storage area for saving data on tape is arranged in sets of 10 bytes starting with the most current data at address 200 hex. Each time data is added, it is moved up ten bytes in memory. This stacking arrangement of the data in memory occupies memory from 200 hex to the end of the 4K of RAM (Table 6a).

The data was either 4-second or 1-minute data depending when it was saved into memory (Table 6b). The 4-second data is stored in memory every 4 seconds, whenever the clock minute value ends in a 5 or 0. The first seven bytes are averages of the four previous 1-second samples. As a means of checking the output routines, each 4-second save used the last three bytes to store the number of flags for gear change, transmission change, and overload. There were 15 data sets for each minute of 4-second saves.

The 1-minute data is stored for each minute that the 4-second data is not stored. The values stored are the sums of the 4-second averages for that minute. The program saves data on tape during one of the minute saves four times per hour. The save takes approximately



10 seconds, and data collection is terminated during the save on tape so the number of 4-second samples are counted and recorded to prevent errors in the minute averages.

### Keyboard Display

The main program also is used to update and scan the keyboard display on the SYM-1 computer. This display is located on the computer and is not accessible to the operator, but it is necessary in monitoring the parameters or memory values when trouble shooting. The real time clock and the other monitored values are displayed in a sequential repeating format on the SYM-1 keyboard display (Table 6c).

### Main Program Initialization

The main program consists of a combination of monitoring, calculating, and recording routines. As the program resets, it assigns the interrupt vectors and copies the initialization values from ROM to the appropriate RAM locations. The program then sets the input and output ports. The memory used to store data is then set at zero. The program then jumps to the main program.

### One Second Calculations

The program monitors the seconds of the external clock. Whenever the second's value changes, the program jumps to the interrupt routine. This interrupt stops the keyboard display routine, then reads the engine and transmission parameters into the RAM one-second locations. The counters for engine and transmission speed are then set at zero, and the counters restarted. The value for seconds is

then compared to the seconds value during the last interrupt to check if more than one second has elapsed since the last interrupt occurred.

If it has been longer than one second since the last interrupt, the program will return from interrupt to the display program until the next interrupt. If it has been one second since the last interrupt count1, the number of 1-second averages since the last 4-second calculation, is incremented, and the 1-second values are added to the 4-second sums. The second's value is then checked to see if it is time to do the 4-second calculations. If it is not time, the program returns from interrupt to the display routine.

#### Four Second Calculations

If the second's value is divisible by four, count1 is tested to see if there are four 1-second values in the 4-second sums. If there are not, the 4-second sums are set to zero and the program jumps past the 4-second calculations and checks if it is time to do minute averaging.

If count1 is 4, count1 is set to zero and count2, which is the number of four-second averages since the last minute calculations, is incremented. The ratio of transmission and engine pulses are compared to a gear ratio table to determine the present operating gear. This gear ratio is compared to the last 4-second gear ratio to determine if the operator has changed gear ratios. If the gear ratio has changed or the ground speed is zero, the gear change flag bit seven of SFLG2 is set. If the gear ratio has not changed, the gear change flag is tested. If bit seven is set and the gear ratio is the same as the previous 4-second average, the SFLG2 is incremented, bit 7 is cleared

and bit zero of MFLG is set. The 4-second values are divided by four to get the 4-second averages.

Next, the tractor ground speed and engine load are checked. If the ground speed is not between three and 10 mph then SFLG3, the ground speed out-of-range indicator, is set and bit zero of MFLG is set. If the engine rpm is less than 1500 and the rack is greater than 95 percent, the program checks bit seven of SFLG4, the overload indicator flag. If it is not set, the program sets bit seven. If it is set SFLG4 is incremented, bit seven of SFLG4 is cleared; and bit zero of MFLG is set. The 4-second averages then are added to the minute sums, the 4-second averages and count2 are set to zero, and count3, which is the number of 4-second averages added to the minute averages, is incremented.

If the clock's minute value ends in either 5 or 0, the 4-second averages are copied to the data area of RAM for storing on tape at a later time. The program checks to see if the seconds value is 56. If it is not, the program returns from interrupt to the display routine. Otherwise the program checks the status of the display. If it has been on during the last minute, the display is turned off and bit zero of mflag is set to prevent the display from coming on for the next minute.

#### 1-Minute Calculations

First, bit zero of mflag is checked to determine if operation is within operating parameters. If mflag is not zero, the program shifts the mflag left and jumps to see if it is time to record on tape, then

returns from interrupt to the display routine. If mflag is zero, the minute sums are divided by count3 and mflag is shifted left. These values are used as the average rack position, engine speed, and ground speed for the last minute. The minute averages are used to calculate the average horsepower (equation 1, Chapter 5), fuel flow (equation 3, Chapter 5), ground speed, and the gear ratio for the last minute. The memory locations reserved for these calculated values are set to zero. Values for fuel flow, engine speed, and rack are estimated for the higher gear ratios.

The estimated values assume the same average horsepower because the ground speed is assumed constant. By knowing the present gear ratio and the ground speed, the next higher gear ratio is used to calculate the new engine rpm. If this calculated engine speed is greater than 1500 rpm, the program calculates the new rack value. (equation 3, Chapter 5). If the calculated rack is less than 95 percent of the maximum rack, the fuel flow is calculated using the values for engine speed and rack value (equation 1, Chapter 5). The program repeats the tests and calculations for the next higher gear. These calculated values are stored in memory according to the gear ratio used for each calculation (Table 6d). The calculations continue until the engine rpm is less than 1500 or the calculated rack is greater than 95 percent of maximum.

After the calculations for all gear ratios within the specified range of engine speed and rack are complete, the program determines the minimum computed fuel flow. This fuel flow is compared to the previous minute's fuel flow. If the savings is .5 gal/hr or greater

the program sets display output flag. A second check is performed to determine if the gear ratio corresponding to the minimum fuel flow provides a savings of .2 gallons/hour more than the next lower gear ratio. If the optimum gear does not provide a savings of at least .2 gal/hr more than the next lower gear, that lower gear was recommended to the operator.

The fuel flow, engine rpm, and fuel savings were converted to and stored in decimal format so they can be sent out the port to the latches and decoder drivers in the display. The gear ratio was decoded for the display by a look-up table in ROM (Table 6e). This table was used to indicate the positions of the three shift levers. The selected gear ratio, engine rpm, fuel flow, fuel savings, and time were also stored in RAM for recording on tape. The program checks the output flag to determine if the optimization results should be displayed to the operator. If the output flag is set, the recommended values for T/A, range, gear, and engine speed are displayed with the present fuel flow and estimated savings.

#### Saving Data on Tape

The program sets the minute averages to zero and checks to determine if it is time to record the data on tape. If the minute value was 56, the header data which contains the time and flags, has moved to the stack, the interrupts are disabled, and the data for the last 30 minutes is recorded on tape. The program then enables the interrupts and returns to the display routine and the main program starts over.



Location	Contents
First 6 bytes	Year, Month, Day, hour, Minute, Seconds (Header)
Next 10 bytes	Minute data from minute 15
Next 10 bytes	15th 4-second data from minute 15
Next 10 bytes	14th 4-second data from minute 15
Next 10 bytes	13th 4-second data from minute 15
Next 10 bytes	12th 4-second data from minute 15
Next 10 bytes	11th 4-second data from minute 15
Next 10 bytes	10th 4-second data from minute 15
Next 10 bytes	9th 4-second data from minute 15
Next 10 bytes	8th 4-second data from minute 15
Next 10 bytes	7th 4-second data from minute 15
Next 10 bytes	6th 4-second data from minute 15
Next 10 bytes	5th 4-second data from minute 15
Next 10 bytes	4th 4-second data from minute 15
Next 10 bytes	3rd 4-second data from minute 15
Next 10 bytes	2nd 4-second data from minute 15
Next 10 bytes	1st 4-second data from minute 15
Next 10 bytes	Minute data from minute 14
Next 10 bytes	Minute data from minute 13
Next 10 bytes	Minute data from minute 12
Next 10 bytes	Minute data from minute 11
Next 10 bytes	15th 4-second data from minute 10
Next 10 bytes	14th 4-second data from minute 10
Next 10 bytes	13th 4-second data from minute 10
Next 10 bytes	12th 4-second data from minute 10
Next 10 bytes	11th 4-second data from minute 10
Next 10 bytes	10th 4-second data from minute 10
Next 10 bytes	9th 4-second data from minute 10
Next 10 bytes	8th 4-second data from minute 10
Next 10 bytes	7th 4-second data from minute 10
Next 10 bytes	6th 4-second data from minute 10
Next 10 bytes	5th 4-second data from minute 10
Next 10 bytes	4th 4-second data from minute 10
Next 10 bytes	3rd 4-second data from minute 10
Next 10 bytes	2nd 4-second data from minute 10
Next 10 bytes	1st 4-second data from minute 10
Next 10 bytes	Minute data from minute 9
Next 10 bytes	Minute data from minute 8
Next 10 bytes	Minute data from minute 7
Next 10 bytes	Minute data from minute 6
Next 10 bytes	15th 4-second data from minute 5
Next 10 bytes	14th 4-second data from minute 5
Next 10 bytes	13th 4-second data from minute 5
Next 10 bytes	12th 4-second data from minute 5
Next 10 bytes	11th 4-second data from minute 5
Next 10 bytes	10th 4-second data from minute 5
Next 10 bytes	9th 4-second data from minute 5
Next 10 bytes	8th 4-second data from minute 5
Next 10 bytes	7th 4-second data from minute 5
Next 10 bytes	6th 4-second data from minute 5
Next 10 bytes	5th 4-second data from minute 5
Next 10 bytes	4th 4-second data from minute 5
Next 10 bytes	3rd 4-second data from minute 5
Next 10 bytes	2nd 4-second data from minute 5
Next 10 bytes	1st 4-second data from minute 5
Next 10 bytes	Minute data from minute 4
Next 10 bytes	Minute data from minute 3
Next 10 bytes	Minute data from minute 2
Next 10 bytes	Minute data from minute 1

FORMAT FOR DATA SAVE ON CASSETTE TAPE

Table 6a



Contents of 4-Second Data

Byte	
00-01	4-second average of transmission speed pulses
02-03	4-second average of engine speed pulses
04-05	4-second average of rack pulses
06	Number of 1-second samples in the 4-second averages
07	4-second sum of Flag 2
08	4-second sum of Flag 3
09	4-second sum of Flag 4

Contents of 1-Minute Data

00-02	1-minute sum of transmission speed pulses
03-05	1-minute sum of engine speed pulses
06-08	1-minute sum of rack positions
09	Number of 1-minute samples in the 1-minute sums

DATA STORAGE TYPES  
Table 6b

Sequence Number*	Contents
01	Year Month Day
02	Hour Minutes Seconds
03	Transmission Speed
04	Engine Speed
05	Rack Position

\* Sequence numbers may be selected manually to observe a specific display, otherwise the sequence is repeated with each sequence displayed for two seconds.

SYM-1 KEYBOARD DISPLAY  
Table 6c

MEMORY STORAGE FOR CALCULATED VALUES DURING OPTIMIZATION

Memory Location	Content
0142	Fuel Flow for gear ratio 1
0143	Fuel Flow for gear ratio 2
0144	Fuel Flow for gear ratio 3
0145	Fuel Flow for gear ratio 4
0146	Fuel Flow for gear ratio 5
0147	Fuel Flow for gear ratio 6
0148	Fuel Flow for gear ratio 7
0149	Fuel Flow for gear ratio 8
014A	Fuel Flow for gear ratio 9
014B	Fuel Flow for gear ratio 10
014C	Fuel Flow for gear ratio 11
014D	Fuel Flow for gear ratio 12
014E	Fuel Flow for gear ratio 13
014F	Fuel Flow for gear ratio 14
0150	Fuel Flow for gear ratio 15
0151	Fuel Flow for gear ratio 16
0152	Engine Speed for gear ratio 1
0153	Engine Speed for gear ratio 2
0154	Engine Speed for gear ratio 3
0155	Engine Speed for gear ratio 4
0156	Engine Speed for gear ratio 5
0157	Engine Speed for gear ratio 6
0158	Engine Speed for gear ratio 7
0159	Engine Speed for gear ratio 8
015A	Engine Speed for gear ratio 9
015B	Engine Speed for gear ratio 10
015C	Engine Speed for gear ratio 11
015D	Engine Speed for gear ratio 12
015E	Engine Speed for gear ratio 13
015F	Engine Speed for gear ratio 14
0160	Engine Speed for gear ratio 15
0161	Engine Speed for gear ratio 16
0162	Rack Position for gear ratio 1
0163	Rack Position for gear ratio 2
0164	Rack Position for gear ratio 3
0165	Rack Position for gear ratio 4
0166	Rack Position for gear ratio 5
0167	Rack Position for gear ratio 6
0168	Rack Position for gear ratio 7
0169	Rack Position for gear ratio 8
016A	Rack Position for gear ratio 9
016B	Rack Position for gear ratio 10
016C	Rack Position for gear ratio 11
016D	Rack Position for gear ratio 12
016E	Rack Position for gear ratio 13
016F	Rack Position for gear ratio 14
0170	Rack Position for gear ratio 15
0171	Rack Position for gear ratio 16

CALCULATED VALUES DURING OPTIMIZATION

Table 6d

Gear	Binary #	-----Display Lights-----							
		T/A		Range		Gear			
		ON	OFF	LO	HI	1	2	3	4
1	15	*		*		*			
2	16		*	*		*			
3	25	*		*			*		
4	26		*	*			*		
5	45	*		*				*	
6	46		*	*				*	
7	85	*		*					*
8	86		*	*					*
9	19	*			*	*			
10	1A		*		*	*			
11	29	*			*		*		
12	2A		*		*		*		
13	49	*			*			*	
14	4A		*		*			*	
15	89	*			*				*
16	8A		*		*				*

\* Indicates light is on

LOOK-UP TABLE TO CONVERT GEAR NUMBER  
TO DISPLAY OUTPUTS  
Table 6e

## Chapter 7

### TESTING

#### Laboratory Testing

Testing of the software and hardware was accomplished in two phases. The first phase of tests was conducted in the Agricultural Engineering Laboratories. The tractor was connected to a pto dynamometer to allow loading of the tractor. The transmission pulse input was connected to a signal generator to simulate different ground speeds. By selecting the load and transmission pulse input, different field conditions were simulated.

During the initial testing of the instrumentation the program was intermittently reset and data was lost. After observing the tractor operation it was determined that when the electric fuel transfer pump was activated the SYM-1 would reset. The reset was a result of the inductive voltage spikes on the power supply for the SYM-1. These inductive spikes were eliminated by the use of an LC filter between the 5 vdc supply and the SYM-1 computer.

After two days of testing, oil began to leak from the digital encoder. This was caused by the crankcase pressure forcing oil around the shaft seal of the encoder. The encoder was designed with a dust seal but without an oil seal. To eliminate this problem, the adapter plate for the encoder was machined to allow an oil seal between the adapter plate and the encoder. An oil drip line also was added between the seal and the engine to reduce the pressure against the seal and to discharge the accumulated oil. Returning the oil to the engine

would have required extensive design and the the quantity of oil was so small that the oil was allowed to drip below the engine to the ground.

### Field Testing

During the second phase of testing the tractor was operated by the research personnel on the Delbert Stadel farm near Manhattan. The purpose was to operate the tractor in as many different loading conditions as possible to check the program before putting the tractor in the field with the cooperators. During the first few days of the field tests the rack encoder failed. This failure went undetected until the data was analyzed due to the operation in lightly loaded field conditions. The encoder is a gray code to binary encoder so when the power source failed the failure mode created a binary output of 55. This rack reading corresponds to a low rack value. This resulted in the program always iterating until the engine speed was 1500 rpm. This failure indicates the need to add a test for the external sensors to the software if further development is pursued.

After replacing and recalibrating the encoder the testing was continued. The tractor was operated with a relatively light load by using an undersized field cultivator. The tractor was operated at a ground speed of 4 mph with a low gear ratio to allow wide open throttle operation. After the display came on to indicate the optimum operating gear, the tractor was shifted up one gear instead of changing to the recommended gear ratio. The engine speed was set to provide the same ground speed. This condition was maintained until the display came on again. By observing the outputs as the gear range was

changed, it was observed that if speed was held constant and the savings potential was above the .5 gph minimum the device would always indicate the same optimum gear and engine rpm independent of the operating gear. This test was repeated at different ground speeds and load conditions. The results were repeatable even with some variations of field conditions.

The tractor was operated in the Manhattan area for several days by Delbert and Lee Stadel. They were instructed to operate the tractor during different field operations and to implement any changes recommended by the optimization routines unless the tractor could not be operated in the recommended gear range and engine speed. This in field testing allowed for checking of reliability of the system and also provided verification of the optimization routines.

#### Collecting Operating Data

After testing the tractor and equipment in the Manhattan area, the tractor was taken to various locations throughout Kansas. During this testing the operators were allowed to operate the tractor for at least two days without the display. They were instructed to operate the tractor the same way they would operate their own tractor. During this period the instrumentation was recording all the data but without the display. This provided the base fuel consumption used in calculating the fuel savings during implementation. To determine the type of field operations and implements being used during the tests, each operator was given a log sheet (Fig. 7a) and was instructed to complete it at the end of each day or whenever implements were changed.



When the tractor was moved between cooperators the cassette tapes containing the field data were brought to the Agricultural Engineering Department and read using a data transfer routine. This routine was in ROM on a SYM-1 that was dedicated for data transfers. The routine read the tape and transferred the data into data files on the PDP/1134.

Estimated savings for the four operators during the first year was 19.8%, (Fig. 7b). The range of savings for each operator ranged from 0% to 37%. The operator that had no savings was proficient in the use of gear up and throttle down. Since he was operating within commented that he would periodically shift to a lower gear and higher engine speed so the display would come on and he could compare his previous setting to the optimum. The maximum savings occurred on the lightest loading when the tractor was operated at wide open throttle.

The reliability of the instrumentation was demonstrated by another researcher, Michael Blumanhourst. His research included improving the accuracy of the model over a wider range of loads. He operated the tractor and instrumentation over a period of two more years with no changes to the hardware. This further testing validated the durability and practicality of the design. A complete description of the data analysis is described in the research thesis by Michael Blumanhourst, Agricultural Engineering, 1984.

## Chapter 8

### CONCLUSION

A gear selection aid for agricultural tractors can be implemented, and it can increase fuel efficiency in a variety of field operations. By providing the operator with sufficient information, it was shown that savings up to 37 percent are possible, Blumanhourst (1979). The average savings for the first 10 operators using this aid was 12.5 percent. The savings is dependent upon the operator's knowledge and the nature of the loading of the tractor. Most operators noted the aid provided them additional savings, even if they were aware of the gear up and throttle down practice.

During the first two years of testing, the equipment experienced only a few problems. Most of the problems were correcting during the first few months of operation and were associated with the hardware. This low failure rate indicates the hardware used during this series of tests was able to withstand the harsh environments associated with field operations.

To prevent underloading, a method of determining load variability needs to be implemented. An example for this need would be a tractor operating with intermittent field loading such as turning around at the end of the field. When the tractor turns around, it may be operated within the ground speed criteria for field operations, but the implement will be out of the ground thus giving a false average loading. Unless the operator changes the gear ratio or clutches the tractor, the optimization routine would use these values and could

recommend an operating range that could cause overloading.

A recommendation made by several of the operators was to leave the fuel-flow display on all the time. This would give the operator an indication of engine loading and would indicate that the device was operating.

For this technology to be implemented economically and to gain widespread use, the manufacturers of tractors need to be involved. This would allow minimizing of equipment costs by integrating the hardware and software into the existing instrumentation. This would also provide credibility compared with an add-on device.

Further research is needed to allow more exact selection of the limits of the optimization routines. Because this project involved only one tractor, any estimations of savings for implementation to other tractors may be premature. By implementing this concept onto more tractors with different engine sizes, a better relationship between engine size and savings could be determined.

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5. Wu, T., and K.J. McAulay, Predicting Diesel Engine Performance at Various Ambient Conditions, SAE 730148, Warrendale, PA, 1973.
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APPENDIX

Appendix:

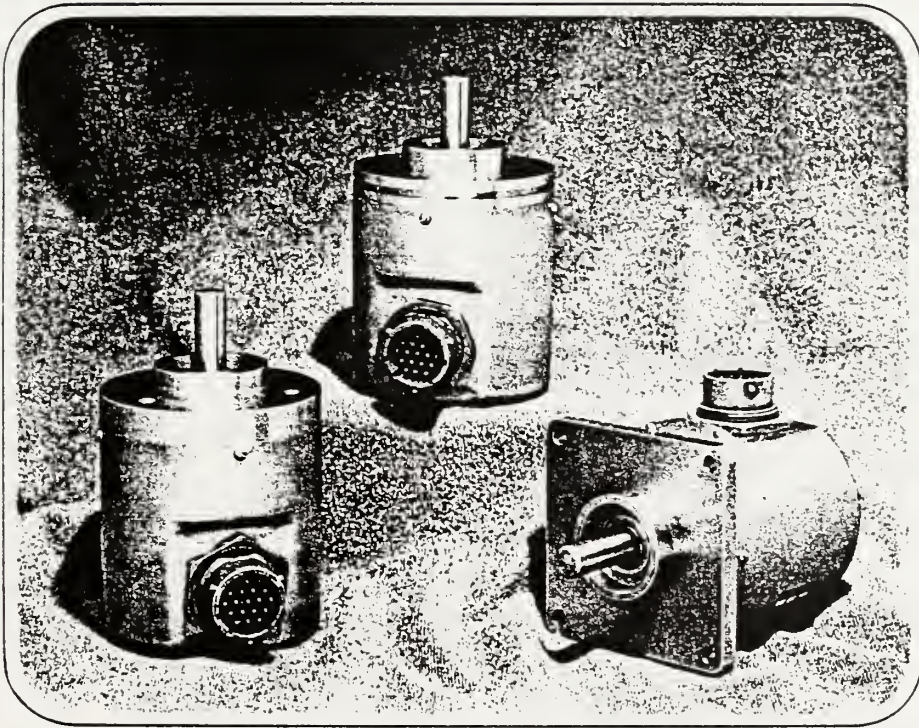
A - Litton Encoder Data Sheet . . . . .	54
B - Ametek Strain Gage Transducer Data Sheet . . . . .	59
C - Calnex V/F Converter Data sheet . . . . .	61
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Appendix A  
Litton Encoder Data Sheet



# MODEL 76

LOW COST - ABSOLUTE  
SHAFT POSITION ENCODER



Designed specifically for those demanding applications which require high immunity to mechanical stress, cannot tolerate a failure of the illumination source and where absolute (whole-word) encoding is essential.

**\*OUR GUARANTEE\***

LITTON ENCODER DIVISION WILL REPLACE  
ANY ILLUMINATION SOURCE WHICH FAILS  
WITHIN 5 YEARS FROM DATE OF SHIPMENT.



**ENCODER DIVISION**

## FEATURES

- LOW COST • ABSOLUTE ENCODING
- CHOICE OF 3 CODE FORMATS
- SOLID-STATE ILLUMINATION SOURCE
- SIMPLE DESIGN • HIGH RELIABILITY
- CHOICE OF 10 RESOLUTIONS
- DTL AND TTL COMPATIBLE OUTPUTS
- 3 MOUNTING CONFIGURATIONS
- 2 SHAFT SIZES

## APPLICATIONS

- NC MACHINE TOOLS
- COMPUTING SCALES
- PROCESS CONTROL
- DIVIDER HEADS
- PLOTTERS • PRINTERS
- ANTENNAS
- TRANSLATION STAGES
- NAVIGATION SYSTEMS

## GENERAL DESCRIPTION

MODEL 76 has been engineered to provide the potential user the maximum flexibility in selecting the physical and electrical characteristics dictated by the application. There is the choice of three mounting configurations with the input/output connector mounted on the end or side of the housing; two input shaft styles; three code formats to choose from — Gray Code, Natural Binary and 8421 Binary Coded Decimal — and 10 standard resolutions.

MODEL 76 uses solid-state illumination sources carrying Litton's 5 YEAR GUARANTEE against field failures; only a single 5VDC power supply is required for operation and the outputs are fully buffered to provide direct DTL and TTL compatibility.

Appendix B

Ametek Strain Gage Transducer Data Sheet

# BA SERIES *Low Range, Low Price, High Efficiency*

## Specifications

**RATED CAPACITIES (lbs.):**  
5, 10, 25, 50, 75, 100, 150, 200

**RATED OUTPUT:** 3 mV/V  $\pm 10\%$

**ZERO BALANCE:**  $\pm 1\%$  R.O.

**MAXIMUM EXCITATION:** 10 VDC

**NON-LINEARITY:**  $\pm 0.03\%$  R.O.

**HYSTERESIS:**  $\pm 0.02\%$  R.O.

**NON-REPEATABILITY:**  $\pm 0.01\%$  R.O.

**COMPENSATED TEMP. RANGE:**  
50 to 150° F (10 to 66° C)

**SAFE OPERATING TEMP. RANGE:**  
- 65 to 200° F (- 54 to 93° C)

**TEMP. EFFECT ON ZERO BALANCE:**  
 $\pm 0.5\%$  R.O.  
100° F (55.6° C)

**TEMP. EFFECT ON OUTPUT:**  
 $\pm 0.08\%$  R.O.  
100° F (55.6° C)

**CREEP:**  
 $\pm 0.03\%$  R.O.  
20 Min

**TERMINAL RESISTANCE:**  
**INPUT:** 418  $\pm 4$  ohms

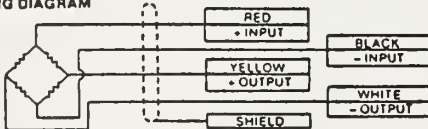
**OUTPUT:** 350 ohms  $\pm 2$  ohms

**INSULATION RESISTANCE:**  
2000 megohms @ 100 VDC

**OVERLOAD RATINGS:**  
Safe: 150% Rated Capacity  
Ultimate: 200% Rated Capacity

R.O. = Rated Output

## WIRING DIAGRAM



**NOTE:**  
1. POSITIVE OUTPUT IN THE DIRECTION OF TENSION LOADING

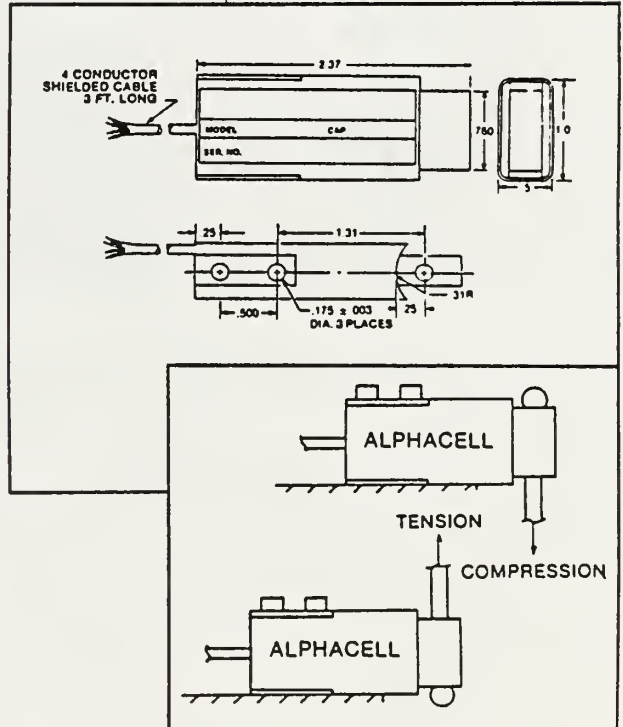
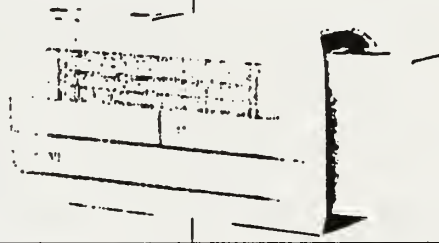
## Features

- UNIVERSAL — TENSION & COMPRESSION LOADS
- COMPACT
- LIGHTWEIGHT ALUMINUM
- EXCELLENT ACCURACY
- LOW FORCE RANGES

## ORDERING INFORMATION

Series	Capacity
BA	*

\* Capacities 5-lb., 10-lb., 25-lb., 50-lb., 75-lb., 100-lb., 150-lb., 200-lb.



Appendix C

Calex V/F Converter Data Sheet

# MODELS 166 and 167 BRIDGESENSORS

# CALEX

## GENERAL DESCRIPTION

The Models 166 and 167 Bridgesensors are complete load cell signal conditioners in modular form. They consist of three basic sections—an adjustable regulated power supply to drive the load cell, a differential input instrumentation amplifier, and a voltage to frequency converter to provide a frequency output. Figure 1 shows a simplified block diagram of the Bridgesensors. The Models 166 and 167 were designed with weighing applications in mind. When used with a counter and load cell they can form a complete system with minimum parts count. Provision is made to offset the output which makes it possible to easily subtract tare weight. The unit operates from a standard  $\pm 15$  volt power supply.

## INSTRUMENT AMPLIFIER

The instrumentation amplifier section of the Models 166/167 is a true differential, high input impedance, low drift amplifier. The design is optimized to perform well with low impedance sources such as a load cell. The drift of the amplifier offset voltage is less than  $0.5\mu\text{V}/^\circ\text{C}$  which is the type of performance needed for a strain gage load cell amplifier. For example, with a bridge supply voltage of 10 volts, a 2mV/Volt load cell has an output of 20mV full scale. Amplifier drift of  $0.5\mu\text{V}/^\circ\text{C}$  thus represents an error of 0.0025%/°C of full scale.

Common mode range is  $\pm 6$  volts which is adequate when using a 10 volt bridge supply. Amplifier output is brought out separately for use with or without the voltage to frequency converter. It is also possible to offset the amplifier output from an external low impedance source.



## BRIDGE POWER SUPPLY

The bridge power supply is an adjustable regulated supply specifically designed to drive load cell bridges from 120 to 350 ohms. A curve of maximum output current versus output voltage is shown in Figure 6. The voltage is adjusted by means of an external potentiometer.

Voltage stability is excellent and is derived from a zener reference with a  $0.002\%/^\circ\text{C}$  temperature coefficient. The power supply uses a series pass regulator together with a frequency stabilized op-amp to provide a ripple free and well regulated voltage source to drive the load cell.

Power supply sense lines are provided on the module so that remote sensing may be used. They can be used to compensate for the voltage drop in long leads to the transducer or to add an external current booster without degrading regulation.

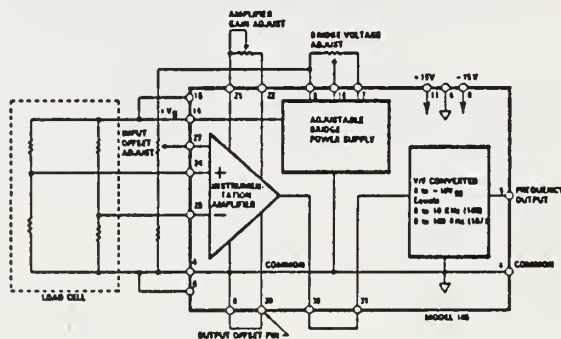


FIGURE 1. SIMPLIFIED BLOCK DIAGRAM

CALEX MFG. CO., INC., 3355 Vincent Road, Pleasant Hill, CA 94523  
Telephone: (415) 932-3911 Telex: 338 506



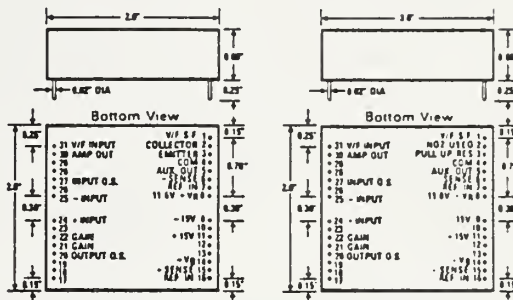
# SPECIFICATIONS

## ELECTRICAL

(Typical at +25°C rated supply unless otherwise noted).

MODEL	166	167
<b>INPUT AMPLIFIER</b>		
<b>GAIN</b>		
Range, Ext. Adj.	10 to 1000	
Equation	$G = 10 + 200k\Omega / R_g$	
Equation Accuracy	$\pm 2\%$	
Nonlinearity, Max.	$\pm 0.01\%$	
Temp. Coefficient	$\pm 50\text{ppm}/^\circ\text{C}$	
<b>INPUT</b>		
Input Impedance - Diff.	10M $\Omega$	
Input Impedance -CM	500M $\Omega$	
Input Voltage Range, Diff. & CM	$\pm 6\text{V}$	
Common-Mode Rejection, DC to 60Hz, G = 100	100dB typ	
<b>INPUT OFFSETS</b>		
Input Offset Voltage (RTI) @ G = 1000 and +25°C (Adj. to Zero) vs. Temperature, Max.	$\pm 100\mu\text{V}$ $\pm 0.5\mu\text{V}/^\circ\text{C}$	
vs. Supply (V <sub>-</sub> )	$50\mu\text{V}/\text{V}$	
Input Bias Current at +25°C, Max	$+250\text{nA}$	
Input Difference Current vs. Temperature, Max	$0.1\text{nA}/^\circ\text{C}$	
<b>OUTPUT</b>		
Rated Output Voltage	$\pm 10\text{V}$	
Rated Current-Output	$\pm 5\text{mA}$	
<b>FREQUENCY RESPONSE</b>		
Bandwidth, -3dB at G = 100	10kHz	
<b>REFERENCE OUTPUT</b>		
Nominal Value (+V <sub>R</sub> )	$+11.0\text{V}$ to $12.2\text{V}$	
Temperature Coefficient, max	$\pm 0.01\%/^\circ\text{C}$	
<b>BRIDGE SUPPLY (+V<sub>B</sub>)</b>		
Range of Adjustment	$+4\text{V}$ to $+10\text{V}$	
Temperature Coefficient	$\pm 0.01\%/^\circ\text{C}$ max	
Output Voltage Noise	$1\text{mV}_{\text{rms}}$	
Output Current (See Fig. 6)	$0$ to $+100\text{mA}$	
<b>REGULATION</b>		
Output Voltage vs. Supply ( $\Delta V_o / \Delta V_s$ )	$1\text{mV}/\text{V}$	
Regulation, No Load to Full Load	$0.01\%$ max.	
<b>V/F CONVERTER</b>		
Input Voltage	$0$ to $-10\text{V}$	
Input Impedance	100K $\Omega$	
Output Frequency	$0$ to $10\text{kHz}$   $0$ to $100\text{kHz}$	
Direct Output Transistor (Q <sub>1</sub> )		
V <sub>CE(sat)</sub>	25 Volts	
V <sub>CE(su)</sub>	5 Volts	
I <sub>c</sub>	50mA	
Isolated Output Transistor (Q <sub>2</sub> )		
V <sub>CE(sat)</sub>	30V	N.A.
V <sub>CE(su)</sub>	7V	N.A.
Max. Power Dissipation	150mW	
Pulse Width at Collector of Q <sub>2</sub>	$80\mu\text{S}$ typ	$8\mu\text{S}$ typ
<b>GENERAL SPECIFICATIONS</b>		
Supply Voltage (Rated Specs)	$\pm 15\text{V}$	
Supply Voltage Range	$\pm 14$ to $\pm 16\text{V}$	
Quiescent Current Drain	$+30\text{mA}$ and $-10\text{mA}$	
<b>TEMPERATURE RANGE</b>	$0^\circ\text{C}$ to $+70^\circ\text{C}$	
<b>SIZE (INCHES)</b>	$2 \times 2 \times 0.6$	
<b>UNIT PRICE 1-9</b>	\$138.00	
Model MK166/7	\$48.00	

## MECHANICAL



Model 166

Model 167

Shaded pins not installed. Shown for position only.

FIGURE 3. OUTLINE DIMENSIONS

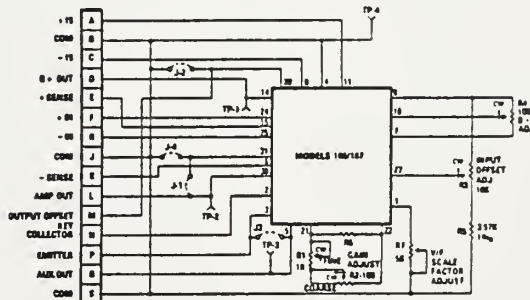


FIGURE 4. MK 166/7 MOUNTING KIT SCHEMATIC

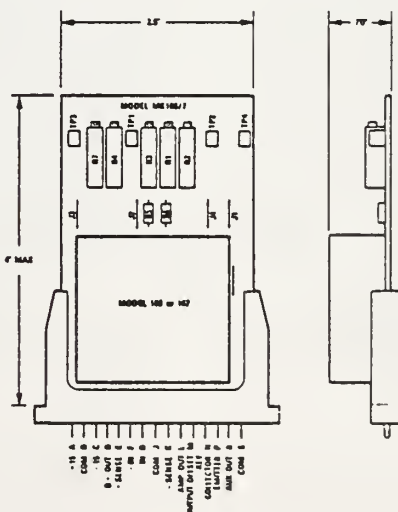


FIGURE 5. MK 166/7 MOUNTING KIT DIMENSIONS

## ADJUSTMENT PROCEDURES

### GAIN

Amplifier gain is set with one external resistor. The MK166/7 mounting kit provides two potentiometers in series for a fine and coarse gain adjustment. There is also a place on the P.C. card to install a single fixed resistor in place of the potentiometers. The gain equation is  $G = 10 + 200k\Omega/R_g$  where  $R_g$  is the external gain resistor. To illustrate, a gain of 500 would require an  $R_g$  of 408 ohms. The accuracy of the gain equation is  $\pm 2\%$ . If it is necessary to set the gain very accurately, the best procedure would be to calibrate the amplifier against a known voltage standard.



### BRIDGE POWER SUPPLY

The bridge power supply voltage is adjusted with a single 10K potentiometer. To reduce internal heating which could cause undesired amplifier drift, the load current should be kept within the limits indicated in Figure 6. The MK166/7 includes an adjustment potentiometer on the P.C. card. It is also possible to remotely adjust the bridge supply voltage by applying a positive reference voltage to pin 16 of the 166 or 167 modules. The output voltage will follow the reference voltage, that is, +8 volts applied to pin 16 will produce a +8 volt bridge supply voltage.

The + and - sense lines can be used to provide load regulation at the load. If it is necessary to drive more than one or two load cells, the sense lines in combination with a separate power supply and transistor will allow the same regulation and stability but with more output. For example, consider a typical case where four 120 ohm load cells were to be operated in parallel. Current required is 334mA at 10 volts. Figure 7 shows how to connect the Models 166/167 to solve this problem.

### INPUT OFFSET

The external adjustment circuit shown in Figures 1 and 2 will allow the amplifier input offset to be changed over a range of approximately  $\pm 2mV$  referred to the input. The primary purpose is to adjust the internal amplifier offset to zero; it is not intended to compensate for an unbalanced load cell bridge. When the Model 166 or 167 is purchased on an MK166/7 mounting kit, the offset potentiometer is factory set for minimum offset. If it is necessary to adjust input offset, first short the two inputs to common (pins F, H and J) and then adjust the Input offset potentiometer until the amplifier output voltage is minimum (zero volts).

If it is necessary to use this adjustment to compensate for an unbalanced load cell bridge, it can be done, but it should be remembered that in so doing, the amplifier offset drift with temperature will be degraded.

### OUTPUT OFFSET

The output of the instrumentation amplifier can be intentionally offset from zero by applying a voltage to pin 20 of the module. It should be noted that the offset introduced by this means is not amplified by the gain, while input offset is. The output can be offset to allow for tare weight compensation. For example, if the container weighs 50 pounds when using a load cell of 1000 pound range, the output of the amplifier may be offset to +0.5 volt. The weight of the container will then cause the amplifier output to go to zero volts and as load is added the amplifier output will increase in the negative direction causing the V/F converter to operate. In order to minimize the effect of degrading the common mode rejection ratio, the voltage applied to pin 20 should come from a low impedance source such as the output of an operational amplifier.

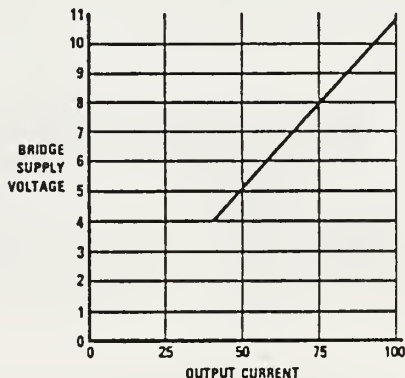


FIGURE 6. BRIDGE OUTPUT CURRENT

## V/F SCALE FACTOR ADJUST

To set the V/F scale factor, connect an external resistance from pin 1 of the module to common. The value of the resistance is approximately 3K ohms. Calibration is performed by applying -10.000 volts to pin 31 and then adjusting the external resistor until the output frequency is 10.000kHz or 100.00kHz as appropriate. When the Model 166/7 is purchased with a mounting kit, MK166/7, a multturn potentiometer is provided for this purpose on the MK166/7. It is factory set for a scale factor of 1kHz or 10kHz per volt. The temperature coefficient of the mounting kit pot is  $\pm 100\text{ppm}/^\circ\text{C}$ . If better temperature stability is required, the scale factor pot should be replaced with a precision, temperature stable resistor.

Scaling adjustment is done by changing the amplifier gain or by the V/F scale factor adjustment. These two adjustments allow the user to treat the amplifier and the V/F converter independently if desired. In Figure 2, the amplifier gain would be set so that -10 volts output would represent full scale, 1000 pounds for example. The V/F scale factor would be set for full scale output of 10kHz or 100kHz. If a 0.1 second time base were selected for the Model 166 and 0.01 second for the Model 167 then a load of 999 pounds would be displayed as 999.

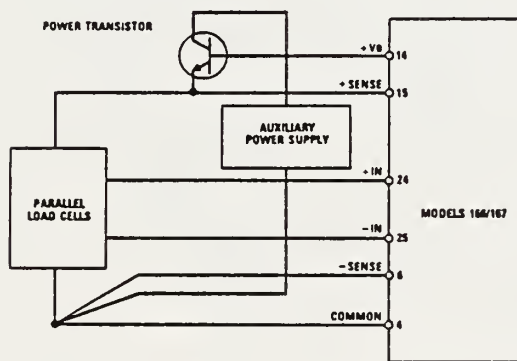
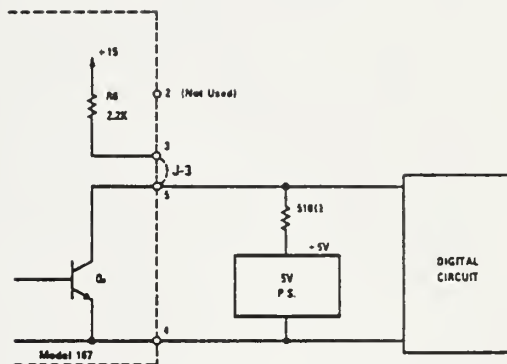


FIGURE 7. USING AN EXTERNAL CURRENT BOOSTER

## V/F CONVERTER OUTPUT

Model 166 provides for auxiliary output or optically isolated output. The auxiliary output is taken between the collector of  $Q_1$  and common.  $Q_1$  can sink 50mA. When used as a source, the auxiliary output can supply a 10 volt pulse into a 3K load resistor.



To drive CMOS, eliminate the 5V P.S. and the 510Ω resistor and install J-3

FIGURE 8. MODEL 167 OUTPUT CIRCUIT

Maximum current through the LED portion of the optical coupler is 13mA, which results in a minimum phototransistor current of 2mA. If the phototransistor is used to switch 5 volts, then its collector resistor should be limited to approximately 1K.

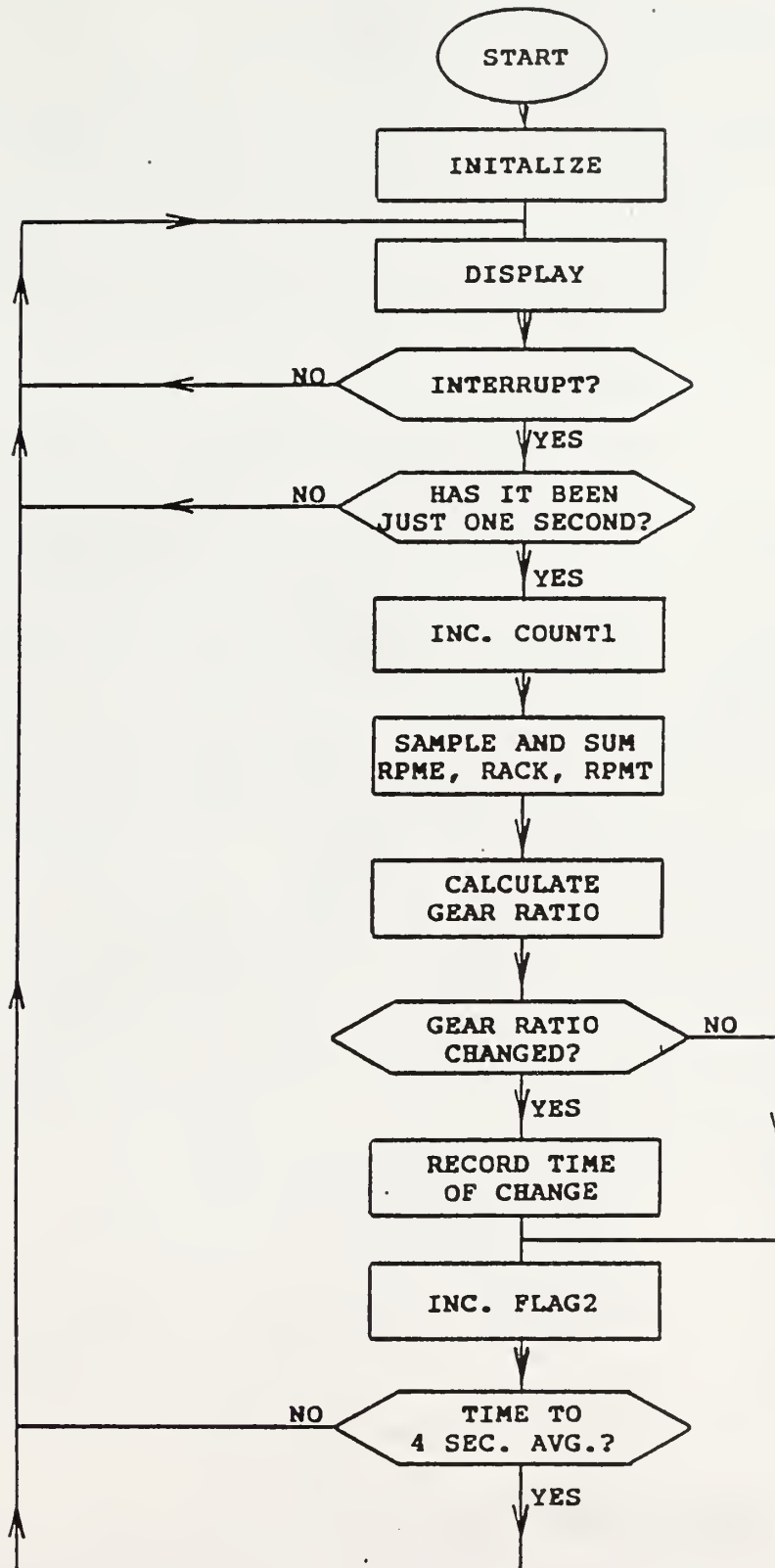
The Model 167 output circuit provides for sinking 50mA, sourcing 2mA into 5K or for using a separate collector supply. For example, if TTL digital circuitry is to be driven by the Model 167, the external jumper between pin 3 and 5 can be left out. Then a separate 5 volt source can be connected to the collector of  $Q_1$  through pin 5 and a load resistor. Figure 8 shows a typical application.

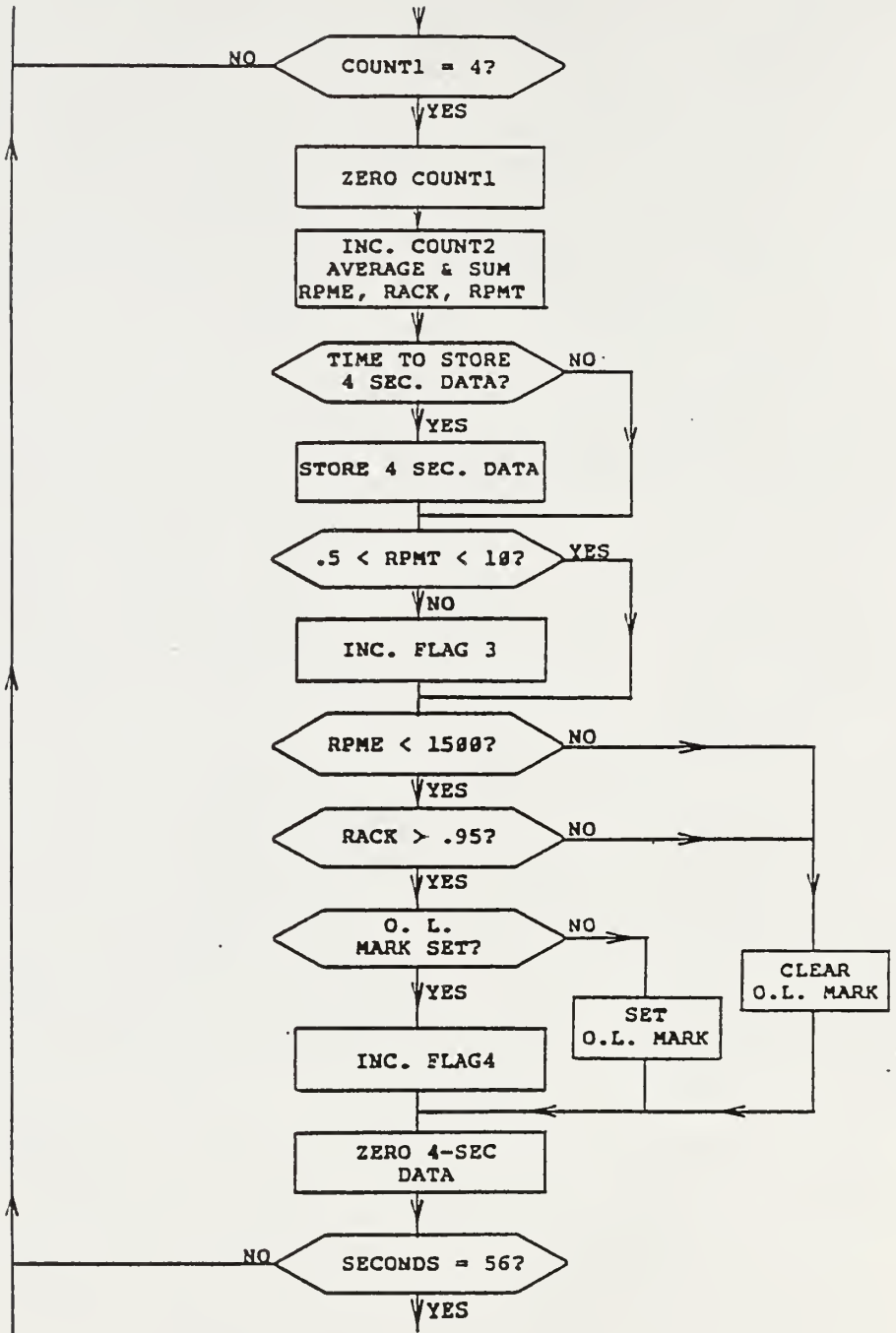
## AMPLIFIER FREQUENCY RESPONSE

The amplifier bandwidth is 10KHZ at a gain of 100. The rolloff response curve is 20db per decade so the 3db down frequency can be predicted by knowing the gain setting. For example, at a gain setting of 1000,  $BW = 1\text{KHZ}$ , and at 10,  $BW = 100\text{KHZ}$ . It is sometimes desirable to intentionally limit the amplifier frequency response in order to minimize the effect of high frequency noise. The input stage of the V/F converter is an active integrator with a time constant of about 0.5mS, (Model 166), it therefore does not require a bandwidth limit. However, if the amplifier output is also to be monitored by an external device such as a scope or recorder then the user may wish to use additional filtering. This can be done by connecting a simple RC network or an active filter between the monitoring device and the amplifier output. Capacitors should not be connected directly across the amplifier output since this may cause instability.

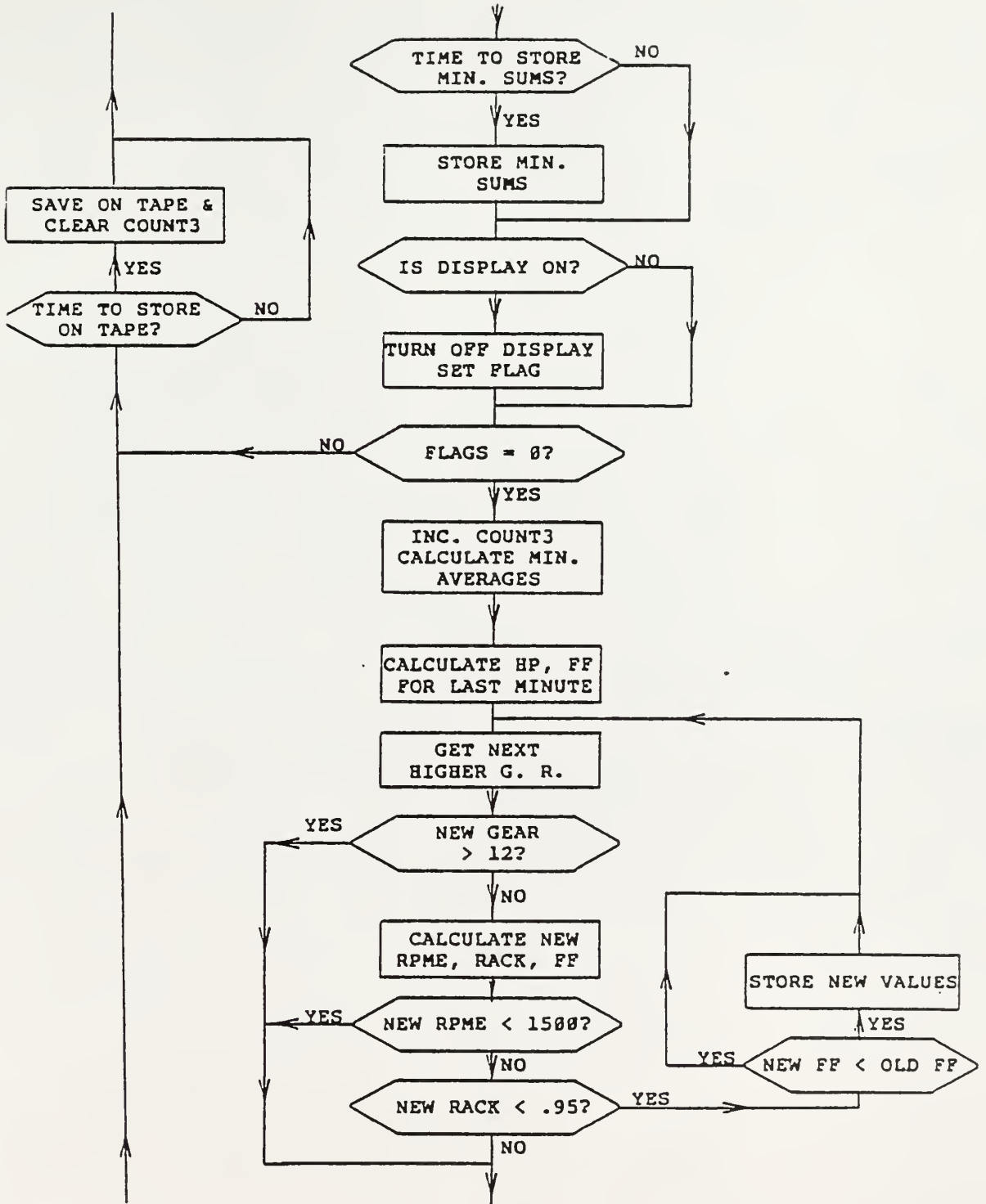
Appendix D  
Software Flow Diagram

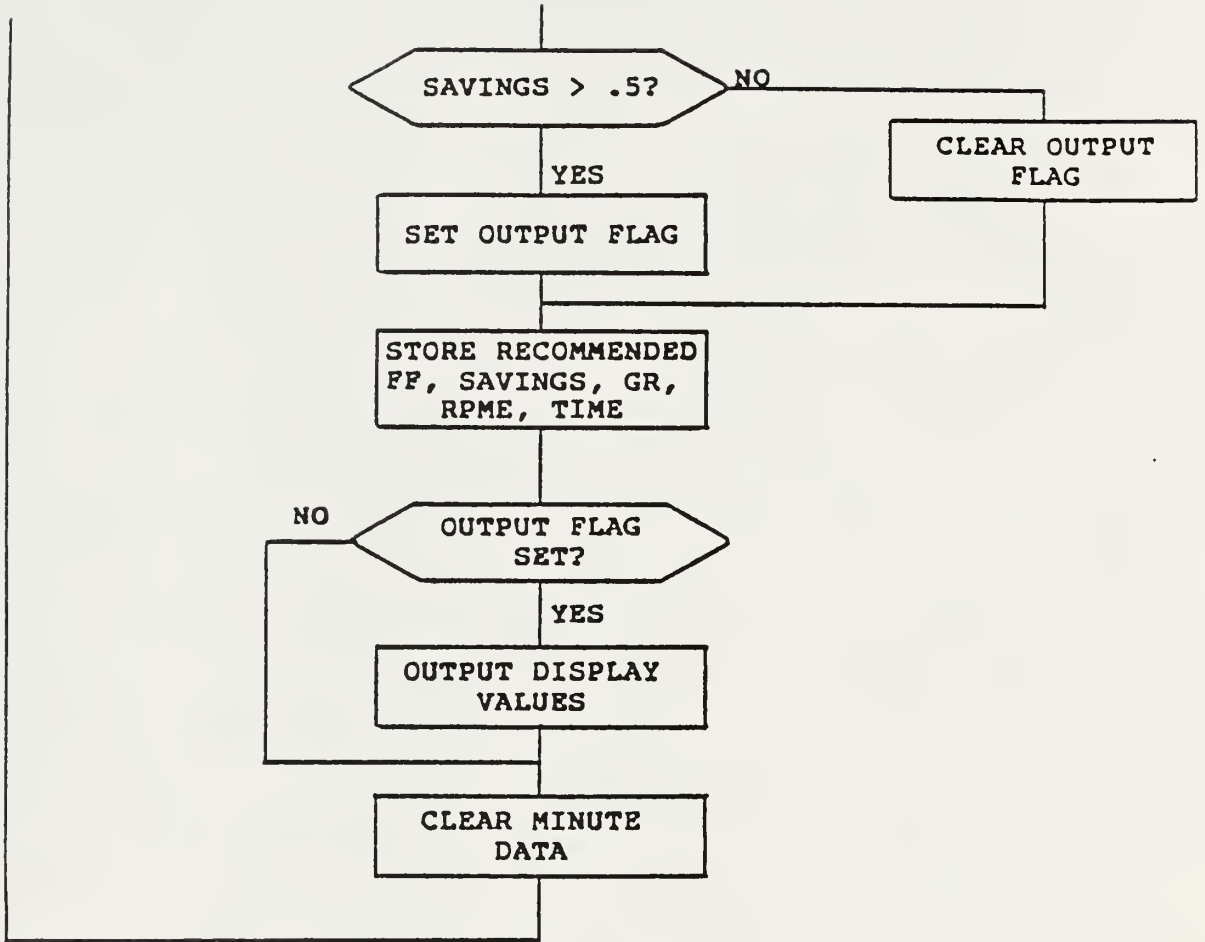
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Appendix E  
Program Listing

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IAS I.

10-10-82  
ASSEMBLY OF IH PERFORMANCE IMPROVER

0B6A 324A-3DB4 IHADDRES.SD

01E1 324A-342B FPVARS.R  
^G 0030 INPRDI ^B  
!02 AT LINE 0030  
^G A8DB 99  
!0C AT LINE A8DB  
^G A8DB 9:  
!0C AT LINE A8DB  
^G DC88 X  
!06 AT LINE DC88  
^G D8C6 -  
!06 AT LINE D8C6  
^G A6A8 L  
!06 AT LINE A6A8  
^G A8DB 9;  
!0C AT LINE A8DB  
^G DC88 X  
!06 AT LINE DC88  
^G D8C5 -  
!06 AT LINE D8C5  
^G A6A8 L  
!06 AT LINE A6A8  
^G A8DB 9<  
!0C AT LINE A8DB  
^G DC88 X  
!06 AT LINE DC88

0A73 324A-3CB0 IHNAIN.SP

0589 324A-37D3 IHHACRO.P

065E 37D3-3E31 IHSEC.P

063B 37D3-3E0E IH4SEC.P

0242 3703-3A15 IHXIN.P

074E 3703-3F21 IHFILE.P

0284 3703-3A87 IHHPHAT.P

0369 3703-3B3C IHFFHAT.P

0826 3703-42F9 IHNEWVAL.P

0761 3703-3F34 IHFUEL.P

02B6 3703-3A89 IHOUTPUT.P

088E 3703-4361 IHSHOW.S

0D34 3703-4507 IHCLKSUBS

0106 3703-38D9 IHSETPORT

00B0 37D3-3883 IHSTARTCNT

0335 37D3-3B08 IHREADPORT

03D5 37D3-3B48 IHCONSTANTS.D

END OF MAE PASS!

```

0010 ;PUT 'IHASSEHRL.E'
0020
0030                .CE
0040                .CT
0050                .DS
0060                .ES                ; CAUSES MACROS TO BE EXPA
0064                .PR '10-10-82'
0070
0080                .PR 'ASSEMBLY OF IH PERFORMANCE IMPROVER'
0090                .BA $0
0100                .FI 'IHADDRES.SD'

```

0B6A 324A-3DB4 IHADDRES.SD

```

0010 ;PUT 'IHADDRES.SD'
0020 ; **** THESE ARE STORED IN RAM ****
0030 ; BEGINNING OF 1 SECOND DATA *****
0000- 0040 RPNTH                .DS 2
0002- 0050 RPHEH                .DS 2
0004- 0060 RACKH                .DS 2
0006- 0070 LIMITS                .DS 1
0080 ; END OF 1 SECOND DATA *****
0090 ; BEGINNING OF 4 SEC DATA *****
0007- 0100 SRPNTH                .DS 2                ;SUM OF 1 SECOND READINGS
0009- 0110 SRPEH                .DS 2
000B- 0120 SRACKH                .DS 2
000D- 0130 COUNT1                .DS 1                ;1 SECOND COUNT
0140 ; END OF 4 SEC DATA *****
0150 ; BEGINNING OF MINUTE DATA *****
000E- 0160 SFLG2                .DS 1                ;SIGN BIT IS USED TO PREVE
000F- 0180 SFLG3                .DS 1                ;COUNTS
0010- 0185 SFLG4                .DS 1
0011- 0190 HRPKTX                .DS 3
0014- 0200 HRPHEX                .DS 3
0017- 0210 HRACKX                .DS 3
001A- 0220 COUNT2                .DS 1                ;4 SEC AVG, COUNT
001B- 0230 HFLG                .DS 1
001C- 0240 SFLG1                .DS 1                ;SUM OF FLAGS FOR SAVED TI
0250 ; END OF MINUTE DATA *****
0260 ; BEGINNING OF DATA CLEARED ON SAVE
001D- 0270 OUTPNT                .DS 1                ;POINTER FOR OUTTIME RECOR
001E- 0280 OUTTIME                .DS 20                ;TIME DISPLAY WAS OUTPUT
0032- 0290 RSPTIME                .DS 20                ;TIME RESPONSE WAS MADE
0046- 0300 OFF                .DS 10                ;OUTPUT VALUES
0050- 0310 OFS                .DS 10
005A- 0320 ORPH                .DS 10

```



```

0064-      0330 DGR          .DS 10
           0340 ; *****BEGINNING OF STORE SAVE*****
006E-      0350 DAY          .DS 6
           0360 ; ***** END OF SAVE VALUES *****
0074-      0370 DISPFLG     .DS 1          ;DISPLAY FLAG
0075-      0380 SFLG        .DS 1          ;LAST 8 SECOND FLAG INDICA
0076-      0390 NEWPNT      .DS 1
0077-      0400 HGEAR       .DS 1          ;MINUTE GR
0078-      0410 NGR         .DS 1          ;NEW GEAR USED IN CALCULAT
0079-      0420 DGR         .DS 1          ;DECODED GEAR RATIO FOR LI
007A-      0430 DATAEND   .DS 2
007C-      0440 DATASTART .DS 2
007E-      0450 MEMEND     .DS 2
0080-      0460 LENGTH     .DS 2
0082-      0470 DISVEL     .DS 1
0083-      0480 DTSCNT     .DS 2
0085-      0490 JHPVEC     .DS 2
0087-      0500 CYCLE      .DS 1
0088-      0510 LCNT1      .DS 1
0089-      0520 LCNT2      .DS 1
008A-      0530 KEYCNT     .DS 1
008B-      0540 FULL       .DS 2
008D-      0550 LASTSEC    .DS 1
008E-      0560 NUMBER     .DS 1
008F-      0570 LATCH      .DS 1
           0580 .BA $100
           0590 ; FP NUMBERS MUST BE ADJUSTED TO GIVE CORRECT DECIMAL 0
0100-      0600 FPTEMP     .DS 4
0104-      0610 FHRPMT     .DS 4          ;MINUTE AVG. CALCULATED
0108-      0620 FHRPME     .DS 4          ;BY USING MINUTE SUMS
010C-      0630 FHRACK     .DS 4
0110-      0640 FHGR       .DS 4          ;MINUTE AVG. CALCULATED BY
0114-      0650 FHFF       .DS 4          ;USING THE EQUATIONS
0118-      0660 FHHP       .DS 4
011C-      0670 FNGR       .DS 4          ;NEW CALCULATIONS
0120-      0680 FNRE       .DS 4
0124-      0690 FHRAC     .DS 4
0128-      0700 FNFF       .DS 4
012C-      0710 BLNFF     .DS 4          ;LAST MINUTE FF
0130-      0720 BHFF       .DS 1          ;BINARY MINIMUM FUEL FLOW
0131-      0730 BHFG       .DS 1          ;GEAR FOR MIN FF
0132-      0740 BFFS       .DS 16         ;CALCULATED FUEL SAVINGS
0142-      0750 BFF        .DS 16         ;CALCULATED FF
0152-      0760 BRE        .DS 16         ;CALCULATED RPME
0162-      0770 BRAC       .DS 16         ;CALCULATED RACK
0172-      0780 COUNT3     .DS 1          ;MINUTE COUNT
           0790 ; ***** DON'T ZERO PAST HERE *****
           0800 ; ***** ON THE SAVE *****
0173-      0810 FLGTIME    .DS 3          ;TIME LAST FLAG WAS RECORD
0176-      0820 GEAR        .DS 1          ;LAST CALCULATED GEAR (RAN
0177-      0830 FSGR       .DS 4          ;1 SEC. GEAR RATIO
017B-      0840 FNSGR      .DS 4          ;NEW 1 SEC. GEAR RATIO
           0850
0860 VIA1      .DE $A000
0870 VIA2      .DE $A800          ;RPNT(6),LIMIT(0),DOWNSHIF
0880 ; VIA2+1 IS RACK
0890 VIA3      .DE $AC00          ;RPME(6),LATCHES(0-3),RLIN
0900 ; DISPLAY DETECT(5), DISPLAYINDICAT (7)
0910 ; VIA3+1 IS DISPLAY DIGITS
0920 OUTBYT    .DE $B2FA
0930 OUTXAH    .DE $B2F4
0940 DISBUF    .DE $A640
0950 PARK      .DE $R220
0960 PARN      .DE $A64A
0970 PARRR     .DE $A649
0980 ACCESS    .DE $B886
0990 INTVEC    .DE $A678
1000 SCAND     .DE $8906
1010 GOVEC     .DE $A659
1020 MONITOR   .DE $8000
1030 BEEP      .DE $8972
1040 TAPDEL    .DE $A630
1050 SAVE2     .DE $87EA
1060 NON       .DE $8003
1070 EPR0H2    .DE $D000
1080 FP10      .DE EPR0H2+0
1090 SAVTIME   .DE EPR0H2+8
1100 FGARS     .DE EPR0H2+12

```

```

1110 FPBASE      .DE $DC00
1120 FPNORM      .DE FPRASE+$024
1130 FPADD       .DE FPBASE+$0C7
1140 FPSUB       .DE FPBASE+$0C0
1150 FPNULT      .DE FPBASE+$12F
1160 FPDIV       .DE FPRASE+$1A5
1170 FPOUT      .DE FPRASE+$257
1180 FPDISP      .DE FPRASE+$323
1190 ; PUT 'IHADDRESS,SD'
0110
0120             .BA $D0
0130             .FI D26 'FPVARS.B'
    
```

01E1 324A-342B FPVARS.B

```

0001 ;PUT 'FPVARS.B'
0002
0003 ;VARIABLES FOR MATH ROUTINES
0004
00D0- 0005 FKPNT      .DS 2
00D2- 0006 TOPNT     .DS 2
00D4- 0007 CNTR      .DS 1
00D5- 0008 OVFL      .DS 1
00D6- 0009 SIGNS     .DS 1
00D7- 0010 FPLSWE    .DS 1
00D8- 0011 FPLSW     .DS 1
00D9- 0012 FPNSW     .DS 1
00DA- 0013 FPNSW     .DS 1
00DB- 0014 FPACCE    .DS 1
00DC- 0015 WORK0     .DS 1
00DD- 0016 WORK1     .DS 1
00DE- 0017 WORK2     .DS 1
00DF- 0018 WORK3     .DS 1
00E0- 0019 FOLSWE    .DS 1
00E1- 0020 FOPLSW    .DS 1
00E2- 0021 FOPNSW    .DS 1
00E3- 0022 FOPMSW    .DS 1
00E3- 0023 FOPEXP    .DS 1
00E4- 0024 ;          VARIABLES FOR I/O ROUTINES
00E4- 0025 IOSIGN     .DS 1
00E5- 0026 IOEXPD     .DS 1
00E5- 0027
00E6- 0028 OUTBUF     .DS 1
00E7- 0029 TEMPI      .DS 1
00E7- 0030 INPRDI     .DS 1
00E8- 0031 TPLSW      .DS 1
00E9- 0032 TPNSW      .DS 1
00EA- 0033 TPMSW      .DS 1
00EB- 0034 TPEXP      .DS 1
00EC- 0035             .DS 10
0036
0037 ;PUT 'FPVARS.B'
0140             .BA $C000
0150             .MC $1000
0160             .FI 'IHMAIN.SP'
    
```

0A73 324A-3CB0 IHMAIN.SP

```

0010 ;PUT 'IHMAIN.SP'
0020
0030 MAIN
C000- 20 86 8B 0040 JSR ACCESS
C003- 20 1A C0 0050 JSR INIT ;INITIAL DATA IF NECESSARY
C006- A9 50 0060 LDA #L,INTERRUPT
C008- 8D 78 A6 0070 STA INTVEC
C00B- A9 C0 0080 LDA #H,INTERRUPT
C00D- 8D 79 A6 0090 STA INTVEC+1
C010- 20 C6 CC 0100 JSR SETUPCLOCK
    
```

```

C013- 58          0110          CLI
C014- 20 54 CA   0120          JSR OFFOUT
C017- 20 72 CA   0130          JSR SHOW
                   0140
                   0150 ;THIS ROUTINE INITIALIZES THE VALUES
                   0160
                   0170 INIT
C01A- A9 00      0180          LDA #0
C01C- AA          0190          TAX
C01D- 95 00      0200          STA #0,X
C01F- E8          0210          INX
C020- E0 F8      0220          CPX #F8
C022- D0 F9      0230          BNE INIT1
C024- AA          0240          TAX
                   0250 INIT2
C025- 9D 00 01   0260          STA FPTEHP,X
C028- E8          0270          INX
C029- E0 F8      0280          CPX #F8
C02B- D0 F8      0290          BNE INIT2
C02D- A2 08      0300          LDX #8
C02F- BD 47 CO   0310          LDA INITVAL,X
C032- 95 7A      0320          STA #DATAEND,X
C034- CA          0330          DEX
C035- 10 F8      0340          BPL --7
                   0350 INIT3
C037- A9 00      0360          LDA #0
C039- A0 FF      0370          LDY #FF
                   0380 INI3
C03B- 91 7C      0390          STA (DATASTART),Y
C03D- 88          0400          DEY
C03E- D0 F8      0410          BNE INI3
C040- 20 05 CD   0420          JSR SETPORT
C043- 20 28 CD   0430          JSR STRCNT
C046- 60          0440          RTS
                   0450 ;
                   0460 INITVAL
C047- 27 07      0470          .SE $727
C049- 00 02      0480          .SE $200
C04B- FF 0F      0490          .SE $FFF
C04D- 0A 00      0500          .SE $0A
C04F- 10          0510          .BY $10
                   0520 ;
                   0530 ;THIS ROUTINE SERVICES THE CLOCK INTERRUPTS.
                   0540 ;IT CALLS SAMPLE, AVERAGE, AND STORE AT THE
                   0550 ;PROPER TIMES
                   0560 ;
                   0570 INTERRUPT
C050- 48          0580          PHA
C051- 8A          0590          TXA
C052- 48          0600          PHA
C053- 98          0610          TYA
C054- 48          0620          PHA
C055- 20 3F CC   0630          JSR READCLOCK
C058- 20 37 CD   0640          JSR GTDATA
C05R- 20 28 CD   0650          JSR STRCNT
C05E- 20 34 C1   0660          JSR CKLIMIT
                   0670 SECSUM
C061- F8          0680          SED
C062- 18          0690          CLC
C063- A5 8D      0700          LDA #LASTSEC
C065- 69 01      0710          ADC #1
C067- C9 60      0720          CMP #60
C069- D8          0730          CLD
C06A- 90 02      0740          BCC SECSU
C06C- A9 00      0750          LDA #0
                   0760 SECSU
C06E- 85 8D      0770          STA #LASTSEC
C070- C5 73      0780          CMP #DAY+5
C072- F0 07      0790          BEQ SEC
C074- A5 73      0800          LDA #DAY+5
C076- 85 8D      0810          STA #LASTSEC
C078- 4C 09 C1   0820          JNP ENDINT
                   0830 SEC
C07B- 20 6C C1   0840          JSR SECS
                   0850 FOUR
C07E- A5 73      0860          LDA #DAY+5
C080- 20 0F C1   0870          JSR BINARY
C083- 29 03      0880          AND #03

```

;IS ALL STORAGE ZEROED  
;NO

;2\*LENGTH +\$200

;PUT NEW TIME IN DAY+...  
;GET DATA FROM PORTS  
;CHECK FOR OVER LIMITS

;HAS IT BEEN 1 SEC.

```

CO85- F0 03      0890      BEQ =+4
CO87- 4C 09 C1   0900      JMP OUT
CO8A- A5 0D      0910      LDA *COUNT1
CO8C- C9 04      0920      CMP #04                ;ARE THERE 4 ONE SEC. SAMPL
CO8E- D0 1C      0930      BNE SUHFOUR
CO90- 20 7B C1   0940      JSR CALCG              ;CHECK FOR GEAR CHANGE
CO93- 20 02 C2   0950      JSR AVG4
CO96- 20 12 C2   0960      JSR TRANCHK           ;CHECK TRANS. SPEED
CO99- 20 4B C2   0970      JSR OVLCHK           ;CHECK FOR OVERLOAD
CO9C- 20 73 C2   0980      JSR FOURSUM          ;ADD TO MINUTE SUM
CO9F- A5 72      0990      LDA *DAY+4           ;TIME FOR 4 SEC RECORD
COA1- 29 0F      1000      AND #0F
COA3- F0 04      1010      BEQ STOS              ;YES
COA5- C9 05      1020      CMP #5
COA7- D0 03      1030      BNE SUHFOUR          ;NO
                                1040      STOS
COA9- 20 B2 C2   1050      JSR STOSEC           ;STORE 4 SECOND DATA FOR R
                                1060      SUHFOUR
COAC- 20 A6 C2   1070      JSR CLRSECSM
COAF- A5 73      1080      LDA *DAY+5           ;CHECK FOR TIME TO MIN. AV
COG1- C9 56      1090      CMP #56
COB3- D0 54      1100      BNE OUT              ;NOT TIME TO MIN. AVG.
COB5- A5 72      1110      LDA *DAY+4
COB7- 29 0F      1120      AND #0F
COB9- F0 07      1130      BEQ SUHFO
COBB- C9 05      1140      CMP #5
COBD- F0 03      1150      BEQ SUHFO
                                1160      SUHF
COBF- 20 45 C3   1170      JSR STONIN
                                1180      SUHFO
COC2- A5 74      1190      LDA *DISPFLG         ;IS DISPLAY ON?
COC4- 10 07      1200      BPL SUHFOU           ;NO
COC6- 20 54 CA   1210      JSR OFFOUT           ;YES, SO TURN OFF AND SET
COC9- E6 1B      1220      INC *NFLG
COCB- E6 1D      1230      INC *OUTPNT
                                1240      SUHFOU
COCd- A5 1B      1250      LDA *NFLG            ;ANY FLAGS LAST MIN?
COCF- F0 06      1260      BEQ CHF
COD1- 38         1270      SEC
COD2- 26 75      1280      ROL *SFLG
                                1290      CH
COD4- 38         1300      SEC
COD5- B0 1B      1310      BCS STKIN
                                1320      CHF
COD7- 18         1330      CLC
COD8- 26 75      1340      ROL *SFLG
CODA- A9 01      1350      LDA #1
CODC- 25 75      1360      AND *SFLG
CODE- D0 12      1370      BNE STKIN
COE0- 20 C3 C2   1380      JSR MINAVE           ;CALCULATE MIN, AVG, COUNT
COE3- 20 03 C4   1390      JSR HPHAT            ;CALCULATE LAST MIN. AVG.
COE6- 20 E8 C4   1400      JSR FFHAT            ;CALCULATE LAST MIN. AVG.
COE9- 20 0D C6   1410      JSR GRCHK            ;CHECK FOR OPTIMUM OPERATI
COEC- 20 81 C6   1420      JSR NXTGR
COEF- 20 4B C9   1430      JSR FUELSAV          ;CHECK POSSIBLE SAVINGS
                                1440      STKIN
COF2- 20 1E CA   1450      JSR OUTPUT
COF5- 20 F4 C9   1460      JSR CLRHINSM         ;CLEAR ALL MINUTE SUHS
COF8- A2 03      1470      LDX #3
                                1480      STM
COFA- A5 72      1490      LDA *DAY+4
COFC- DB 08 D0   1500      CHP SAVTIME,X        ;TIME TO SAVE ON TAPE?
COFF- F0 05      1510      BEQ TAPE             ;YES
C101- CA         1520      DEX
C102- 10 F6      1530      BPL STM
C104- 30 03      1540      BHT OUT
                                1550      TAPE
C106- 20 56 C3   1560      JSR SAVE
                                1570      ; NEED TO HAVE LATCH RELAY IN PARALLEL WITH
                                1580      ; VIA3 RELAY
                                1590      OUT
                                1600      ENDINT
C109- 6B         1610      PLA
C10A- AB         1620      TAY
C10B- 6B         1630      PLA
C10C- AA         1640      TAX
C10D- 6B         1650      PLA
C10E- 40         1660      RTI

```

```

1670
1680 ;DO A BCD TO BINARY CONVERSION
1690
1700 BINARY
C10F- 4B 1710 PHA
C110- 4A 1720 LSR A
C111- 4A 1730 LSR A
C112- 4A 1740 LSR A
C113- 4A 1750 LSR A
C114- AA 1760 TAX
C115- 6B 1770 PLA
C116- CA 1780 DEX
C117- 10 01 1790 BPL =+2
C119- 60 1800 RTS
C11A- 3B 1810 SEC
C11B- E9 06 1820 SBC #$06
C11D- B0 F7 1830 BCS =-8 ;ALWAYS
1840
1850 ; PUT 'IHMAIN.SP'
0170 .FT 'IHMACRO.P'

```

0589 324A-37D3 IHMACRO.P

```

0010 ;PUT 'IHMACRO.P'
0020
0030 ; **** THESE ARE THE ROUTINES USED TO MOVE ****
0040 ; **** AND NORMALIZE DATA USED IN THE PROGRAM ****
0050
0060 .MG
0070 !!!MV4 .MD (...GET ...PUT) ;MOVE 4 BYTES FROM GET TO P
0080 LDX #03
0090 LDA ...GET,X
0100 STA ...PUT,X
0110 DEX
0120 BPL =-8
0130 .ME
0140 !!!MV2H .MD (...FRM) ;MOVE 2 BYTES AND NORMALIZE
0150 LDX ...FRM
0160 LDA ...FRM+1
0170 JSR I2TOF
0180 .ME
0190 !!!MV3H .MD (...FROM) ;MOVE 3 BYTES AND NORMALIZ
0200 LDY ...FROM
0210 LDX ...FROM+1
0220 LDA ...FROM+2
0230 JSR I3TOF
0240 .ME
0250 !!!MV4T .MD (...GET ...PUT) ;GET 4 BYTES INDEXED FROM G
0260 ASL A
0270 ASL A
0280 TAY
0290 LDX #0
0300 LDA ...GET,Y ;AND MOVE THEM INDEXED FROM
0310 STA ...PUT,X
0320 INY
0330 INX
0340 CPX #4
0350 BNE =-10
0360 .ME
0370 !!!M4I .MD (...GT ...PT) ;GET 4 BYTES BEGINNING AT GT
0380 ASL A
0390 ASL A ;MULT BY 4
0400 TAY
0410 LDX #0
0420 LDA ...GT,X ;AND MOVE THEM INDEXED FROM
0430 STA ...PT,Y
0440 INY
0450 INX
0460 CPX #4
0470 BNE =-10
0480 .ME
0490 !!!MV2 .MD (...FROM ...TO)
0500 LDA ...FROM

```



```

0510          STA *...TO
0520          LDA $...FRO+1
0530          STA *...TO+1
0540          ,HE
0550 !!!IHV1H  ,HD (...FR)           ;MOVE 1 BYTE AND NORMALIZE
0560          LDA ...FR
0570          JSR I1TOF
0580          ,HE
0590 !!!CHP2   ,HD (...LIMIT ...VAR) ;COMPARE VARIABLES TO THEI
0600          LDA ...LIMIT           ;HIGH BYTE
0610          CMP *...VAR           ;RETURN WITH CARRY AS INDI
0620          BNE -+6
0630          LDA ...LIMIT+1
0640          CMP *...VAR+1         ;LOW BYTE
0650          ,HE
0660
0670          I1TOF
C11F- A2 00   0680          LDX #0
0690          I2TOF
C121- A0 00   0691          LDY #0
0700          I3TOF
C123- 85 D8   0710          STA *FPLSW
C125- 86 D9   0720          STX *FPNSW
C127- 84 DA   0730          STY *FPNSW
C129- A9 00   0740          LDA #0
C12B- 85 D7   0750          STA *FPLSWE
C12D- A9 17   0760          LDA #23
C12F- 85 DB   0770          STA *FPACCE
C131- 4C 24 DC 0780          JMP FPNORM
0781
0790          ;PUT 'IHMACRO.P'
0180          ,FI 'IHSEC.P'

```

065E 3703-3E31 IHSEC.P

```

0010 ;PUT 'IHSEC.P'
0020 ; **** IHSEC ****
0030 ; **** THIS ROUTINE HAPPENS EVERY SECOND ****
0040 CKLIMIT
C134- A5 06   0050          LDA *LIKITS           ;EGT WITHIN LIMITS?
C136- F0 15   0060          BEQ LIM           ;YES
C138- 20 5C C1 0070          JSR SETFTIME        ;NO
C13B- A5 1C   0080          LDA *SFLG1         ;WAS FLAG SET LAST SECOND
C13D- 10 01   0090          BPL DOWNSHIFT      ;NO
C13F- 60      0100          RTS
0110          DOWNSHIFT
C140- E6 1C   0120          INC *SFLG1           ;NO
C142- E6 1B   0130          INC *HFLG
C144- A9 80   0140          LDA #80
C146- 0D 00 AB 0150          ORA VIA2           ;OUTPUT DOWNSHIFT
C149- 8D 00 AB 0160          STA VIA2
C14C- 60      0170          RTS
0180          LIM
C14D- A9 7F   0190          LDA #7F
C14F- 25 1C   0200          AND *SFLG1           ;CLEAR LAST SECOND INDICAT
C151- 85 1C   0210          STA *SFLG1
C153- A9 7F   0220          LDA #7F
C155- 2D 00 AB 0230          AND VIA2           ;CLEAR DOWNSHIFT LIGHT
C158- 8D 00 AB 0240          STA VIA2
C15B- 60      0250          RTS
0260          SETFTIME
C15C- A5 71   0270          LDA *DAY+3
C15E- 8D 73 01 0280          STA FLGTIME
C161- A5 72   0290          LDA *DAY+4           ;RECORD TIME WHEN FLAG WAS
C163- 8D 74 01 0300          STA FLGTIME+1
C166- A5 73   0310          LDA *DAY+5
C168- 8D 75 01 0320          STA FLGTIME+2
C16B- 60      0330          RTS
0340          SECS
C16C- E6 0D   0350          INC *COUNT1
C16E- A2 05   0360          LDY #5
C170- 18      0370          CLC
0380          SSUM

```



```

C171- B5 00      0390      LDA *SRPPTH,X          ;SUM SECONDS DATA
C173- 75 07      0400      ADC *SRPPTH,X
C175- 95 07      0410      STA *SRPPTH,X
C177- CA         0420      DEX
C178- 10 F7      0430      BPL SSUM
C17A- 60         0440      RTS          ;REMOVE WHEN FIXED
                0450      CALCG
C17B- A5 07      0460      LDA *SRPPTH          ;IS TRACTOR MOVING?
C17D- D0 11      0470      BNE CGR
C17F- A5 08      0480      LDA *SRPPTH+1
C181- D0 0D      0490      BNE CGR          ;YES
C183- A9 00      0500      LDA #0            ;NO
C185- A2 03      0510      LDX #3
                0520      GRZ
C187- 9D 7B 01   0530      STA FNSGR,X
C18A- CA         0540      DEX
C18B- 10 FA      0550      BPL GRZ
C18D- 4C EE C1   0560      JMP GRCHG          ;NO
                0570      CGR
                0580      MV2N (SRPHEH)      ;YES

C190- AE 09 00
C193- AD 0A 00
C196- 20 21 C1

                0590      MV4 (FPLSW FOPLSW)

C199- A2 03
C19B- BD D8 00
C19E- 9D E0 00
C1A1- CA
C1A2- 10 F7

                0600      MV2N (SRPPTH)

C1A4- AE 07 00
C1A7- AD 08 00
C1AA- 20 21 C1
C1AD- 20 A5 DD   0610      JSR FPNIV
                0620      MV4 (FPLSW FNSGR) ;STORE NEW ONE SECOND GEAR RA

C1B0- A2 03
C1B2- BD D8 00
C1B5- 9D 7B 01
C1B8- CA
C1B9- 10 F7

                0630      MV4 (FPLSW FHGR)

C1BB- A2 03
C1BD- BD D8 00
C1C0- 9D 10 01
C1C3- CA
C1C4- 10 F7
C1C6- 20 48 C6   0640      JSR GRCALC
C1C9- A5 77      0650      LDA *NGEAR
C1CB- CD 76 01   0660      CMP GEAR
C1CE- D0 1E      0670      BNE GRCHG
C1D0- A5 0E      0680      LDA *SFLG2          ;NO, DID GR CHANGE BEFORE
C1D2- 30 01      0690      BMI OUTOFF      ;YES
C1D4- 60         0700      RTS          ;NO
                0710      OUTOFF
C1D5- A9 7F      0720      LDA #7F
C1D7- 25 0E      0730      AND *SFLG2          ;CLEAR G.R. CHANGE FLAG
C1D9- 85 0E      0740      STA *SFLG2
C1DB- A5 74      0750      LDA *DISPFLG      ;IS DISPLAY ON
C1DD- 30 01      0760      BMI OUTOF      ;YES
C1DF- 60         0770      RTS          ;NO
                0780      OUTOF
C1E0- A5 1D      0790      LDA *OUTPNT
C1E2- 0A         0800      ASL A
C1E3- AA         0810      TAX
C1E4- A5 72      0820      LDA *DAY+4
C1E6- 95 32      0830      STA *RSPTIME,X
C1E8- E8         0840      INX
C1E9- A5 73      0850      LDA *DAY+5

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```

C1EB- 95 32      0860      STA *RSPTIME,X
C1ED- 60         0870      RTS
                   0880      GRCHG
C1EE- 8D 76 01   0890      STA GEAR
C1F1- 20 5C C1   0900      JSR SETFTIME
C1F4- A5 0E      0910      LDA *SFLG2
C1F6- 10 01      0920      BPL GRCH           ;GR CHANGED OR WAS ZERO LA
C1F8- 60         0930      RTS
                   0940      GRCH
C1F9- A9 80      0950      LDA *$80
C1FB- 03 0E      0960      ORA *SFLG2       ;SET GEAR CHANGE INDICATOR
C1FD- 85 0E      0970      STA *SFLG2
C1FF- E6 0E      0980      INC *SFLG2
                   0990      ;INC *MFLG
C201- 60         1000      RTS
                   1010      ;PUT 'IHSEC.P'
                   0190      .FI 'IH4SEC.P'
    
```

0638 37D3-3E0E IH4SEC.P

```

0010 ;PUT 'IH4SEC.P'
0020 ; ***** THIS HAPPENS EVERY 4 SECONDS*****
0030 AVG4
C202- 20 05 C2   0040      JSR AVG4+3
C205- 46 09      0050      LSR *SRPHEH       ;YES, SO DIVIDE BY 4
C207- 66 0A      0060      ROR *SRPHEH+1
C209- 46 07      0070      LSR *SRPHTH
C20R- 66 08      0080      ROR *SRPHTH+1
C20D- 46 0B      0090      LSR *SRACKH
C20F- 66 0C      0100      ROR *SRACKH+1
C211- 60         0110      RTS
                   0120      TRANCHK
                   0130      CMP2 (HLRPKTH SRPKTH)

C212- AD C8 CD
C215- C5 07
C217- D0 05
C219- AD C9 CD
C21C- C5 08

C21E- 90 15      0140      BCC FLG3           ;AVERAGE TO HIGH
                   0150      HTOK
                   0160      CMP2 (LLRPKTH SRPHTH)

C220- AD CA CD
C223- C5 07
C225- D0 05
C227- AD CB CD
C22A- C5 08

C22C- B0 07      0170      BCS FLG3           ;AVERAGE RPKT TO LOW
                   0180      ZT
                   0190      LDA *$7F           ;CLEAR LAST SECOND INDICAT
C22E- A9 7F      0200      AND *SFLG3
C230- 25 0F      0210      STA *SFLG3
C232- 85 0F      0220      RTS
C234- 60         0230      FLG3
C235- 20 5C C1   0240      JSR SETFTIME
C238- A5 0F      0250      LDA *SFLG3       ;WAS IT OUT OF RANGE LAST
C23A- 10 01      0260      BPL SFL3         ;NO
C23C- 60         0270      RTS           ;YES
                   0280      SFL3
C23D- E6 0F      0290      INC *SFLG3       ; INC. COUNTER FOR OUT OF
C23F- E6 1B      0300      INC *MFLG
C241- A9 80      0310      LDA *$80
C243- 05 0F      0320      ORA *SFLG3
C245- 85 0F      0330      STA *SFLG3       ;SET LAST SEC. INDICATOR
C247- 60         0340      RTS
                   0350      OVLCHK       ;CHECK FOR ENGINE OVERLOAD
                   0360      CMP2 (LRACKH SRACKH)

C248- AD CE CD
C24B- C5 0B
    
```

```

C24D- D0 05
C24F- AD CF CD
C252- C5 0C

C254- B0 16      0370      BCS CLRHRK      ;RACK OK
                  0380      CKHRK
C256- A5 10      0390      LDA #SFLG4      ;IS MARK4 SET
C258- 10 0B      0400      BPL SETHRK      ;NO
C25A- E6 10      0410      INC #SFLG4      ;YES
C25C- E6 1B      0420      INC #NFLG
C25E- 20 40 C1   0430      JSR DOWNSHIFT
C261- 20 5C C1   0440      JSR SETFTIME
C264- 60          0450      RTS
                  0460      SETHRK
C265- A9 50      0470      LDA #80         ;SET LAST SECOND MARKER
C267- 05 10      0480      ORA #SFLG4
C269- 85 10      0490      STA #SFLG4
C26B- 60          0500      RTS
                  0510      CLRHRK
C26C- A9 7F      0520      LDA #17F        ;CLEAR LAST SECOND MARKER
C26E- 25 10      0530      AND #SFLG4
C270- 85 10      0540      STA #SFLG4
C272- 60          0550      RTS
                  0560      FOURSUM
C273- A2 01      0570      LDX #01         ;SUM 4 SEC. AVE. INTO MIR.
C275- 18          0580      CLC
                  0590      TSUM
C276- B5 07      0600      LDA #SRPMTX,X
C278- 75 12      0610      ADC #HRPMTX+1,X
C27A- 95 12      0620      STA #HRPMTX+1,X
C27C- CA          0630      DEX
C27D- 10 F7      0640      BPL TSUM
C27F- 90 02      0650      BCC +=3
C281- E6 11      0660      INC #HRPMTX
C283- A2 01      0670      LDX #01
C285- 18          0680      CLC
                  0690      FSUM
C286- B5 09      0700      LDA #SRPNEH,X
C288- 75 15      0710      ADC #HRPNEH+1,X
C28A- 95 15      0720      STA #HRPNEH+1,X
C28C- CA          0730      DEX
C28D- 10 F7      0740      BPL FSUM
C28F- 90 02      0750      BCC +=3
C291- E6 14      0760      INC #HRPNEH
C293- A2 01      0770      LDX #1
C295- 18          0780      CLC
                  0790      RSUM
C296- B5 0B      0800      LDA #SRACKX,X
C298- 75 18      0810      ADC #HRACKX+1,X
C29A- 95 18      0820      STA #HRACKX+1,X
C29C- CA          0830      DEX
C29D- 10 F7      0840      BPL RSUM
C29F- 90 02      0850      BCC +=3
C2A1- E6 17      0860      INC #HRACKX
                  0870      CNT2
C2A3- E6 1A      0880      INC #COUNT2
C2A5- 60          0890      RTS
                  0900      CLRSECSM
C2A6- A2 00      0910      LDX #00
C2A8- A9 00      0920      LDA #00
                  0930      CLS
C2AA- 95 07      0940      STA #SRPMTX,X
C2AC- E8          0950      INX
C2AD- E0 07      0960      CPX #7
C2AF- D0 F9      0970      BNE CLS
C2B1- 60          0980      RTS
                  0990      STOSEC
C2B2- 20 EF C3   1000      JSR CLRDATA
C2B5- A0 09      1010      LDY #9
C2B7- B9 07 00   1020      LDA SRPMTX,Y
C2BA- 91 7C      1030      STA (DATASTART),Y
C2BC- 88          1040      DEY
C2BD- 10 F8      1050      BPL STOSEC+5
C2BF- 20 6C C3   1060      JSR MOVEDATA
C2C2- 60          1070      RTS
                  1080      ;PUT 'IH4SEC,P'
                  0200      ;FI 'IHMIN,P'

```

0242 37D3-3A15 IHMIN.P

```

0010 ;PUT 'IHMIN.P'
0020 ; *** THIS IS THE ROUTINES THAT RUN EVERY MINUTE ***
0030 MINAVE ;CALCULATE THE MINUTE AVERAGES FROM THE MINUTE
0040 MV3N (MRPMTX)

```

```

C2C3- AC 11 00
C2C6- AE 12 00
C2C9- AD 13 00
C2CC- 20 23 C1

```

0050 MV4 (FPLSW FOPLSW)

```

C2CF- A2 03
C2D1- BD D8 00
C2D4- 9D E0 00
C2D7- CA
C2D8- 10 F7

```

0060 MV1N (COUNT2)

```

C2DA- AD 1A 00
C2DD- 20 1F C1

```

C2E0- 20 A5 DD

0070  
0080

```

JSR FPDIV
MV4 (FPLSW FHRPHT) ;STORE AVG. RPHT

```

```

C2E3- A2 03
C2E5- BD D8 00
C2E8- 9D 04 01
C2ER- CA
C2EC- 10 F7

```

0090 MV3N (MRPHEX)

```

C2EE- AC 14 00
C2F1- AE 15 00
C2F4- AD 16 00
C2F7- 20 23 C1

```

0100 MV4 (FPLSW FOPLSW)

```

C2FA- A2 03
C2FC- BD D8 00
C2FF- 9D E0 00
C302- CA
C303- 10 F7

```

0110 MV1N (COUNT2)

```

C305- AD 1A 00
C308- 20 1F C1

```

C308- 20 A5 DD

0120  
0130

```

JSR FPDIV
MV4 (FPLSW FHRPHE) ;STORE AVG. RPHE

```

```

C30E- A2 03
C310- BD D8 00
C313- 9D 08 01
C316- CA
C317- 10 F7

```

0140 MV3N (MRACKX)

```

C319- AC 17 00
C31C- AE 18 00
C31F- AD 19 00
C322- 20 23 C1

```

0150 MV4 (FPLSW FOPLSW)

C325- A2 03

C327- 8D D8 00  
 C32A- 9D E0 00  
 C32D- CA  
 C32E- 10 F7

0160 MVIN (COUNT2)

C330- AD 1A 00  
 C333- 20 1F C1

C336- 20 A5 DD 0170 JSR FPDIV  
 0180 MV4 (FPLSW FHRACK) ;STORE AVG. RACK

C339- A2 03  
 C33R- 8D D8 00  
 C33E- 9D 0C 01  
 C341- CA  
 C342- 10 F7

C344- 60 0190 RTS

0200 STOMIN  
 0210 JSR CLRDATA  
 0220 LDY #9  
 0230 LDA HRPMTX,Y  
 0240 STA (DATASTART),Y  
 0250 DEY  
 0260 BPL STOMIN+5  
 0270 JSR MOVEDATA  
 0280 RTS  
 0290 ;PUT 'IHMIN.P'  
 0210 .FI 'IHFILE.P'

074E 3703-3F21 IHFILE.P

0010 ;PUT 'IHFILE.P'  
 0020  
 0030 ;INIT STORAGE (IN ORDER)  
 0040 ; \*DATAEND 2  
 0050 ; \*DATASTART 2  
 0060 ; \*HEXEND 2  
 0070  
 0080 ;INTERFACE ROUTINES CALLED FROM THE INTERRUPT  
 0090 ;ROUTINE, ANY ROUTINE TO BE CALLED AT THE APPROPRIATE  
 0100 ;TIME SHOULD BE HERE.  
 0110  
 0120 SAVE

C356- 20 EF C3 0130 JSR CLRDATA  
 C359- 20 D7 C3 0150 JSR MOVEOUT  
 C35C- 20 EF C3 0154 JSR CLRDATA  
 C35F- 20 CA C3 0155 JSR MOVECLOCK ;SAVE HEADER IN DATA  
 C362- 20 AF C3 0160 JSR STORE  
 C365- 20 6C C3 0165 JSR MOVEDATA  
 C368- 20 F9 C3 0170 JSR CLRSAVE  
 C36B- 60 0180 RTS

0190 ;MOVE DATA UP IN STORAGE AREA SO NEWEST  
 0200 ;DATA IS KEPT AT THE BEGINNING  
 0210  
 0220 MOVEDATA

C36C- 38 0230 SEC  
 C36D- A5 7E 0240 LDA \*HEXEND ;SET POINTERS TO END  
 C36F- 85 D2 0250 STA \*TOPNT  
 C371- E5 80 0260 SBC \*LENGTH ;POINTER TO MOVE FROM  
 C373- 85 D0 0270 STA \*FHPNT  
 C375- A5 7F 0280 LDA \*HEXEND+1  
 C377- 85 D3 0290 STA \*TOPNT+1  
 C379- E5 81 0300 SBC \*LENGTH+1  
 C37B- 85 D1 0310 STA \*FHPNT+1  
 0320  
 C37D- 38 0330 SEC ;SUB REMAINDER OF A PAGE  
 C37E- A5 D0 0340 LDA \*FHPNT  
 C380- E5 7C 0350 SBC \*DATASTART  
 C382- 85 D0 0360 STA \*FHPNT ;TEMPORARY; PARTIAL PAGE  
 C384- A8 0370 TAY



```

C385- 80 02      0380      BCS  =+3
C387- C6 D1      0390      DEC  *FHPNT+1
C389- 38        0400      SEC
C38A- A5 D2      0410      LDA  *TOPNT
C38C- E5 D0      0420      SBC  *FHPNT
C38E- 85 D2      0430      STA  *TOPNT
C390- 80 02      0440      BCS  =+3
C392- C6 D3      0450      DEC  *TOPNT+1
C394- A5 7C      0460      LDA  *DATASTART
C396- 85 D0      0470      STA  *FHPNT          ;FINISHED WITH POINTERS
C398- 4C 9C C3   0480      JMP  @MOVEDATA
                0490
C398- 88        0500      DEY
                0510 @MOVEDATA
C39C- B1 D0      0520      LDA  (FHPNT),Y      ;TRANSFER A PAGE
C39E- 91 D2      0530      STA  (TOPNT),Y
C3A0- C0 00      0540      CPY  #0
C3A2- D0 F7      0550      BNE  @MOVEDATA-1
C3A4- C6 D1      0560      DEC  *FHPNT+1      ;NEXT PAGE
C3A6- C6 D3      0570      DEC  *TOPNT+1
C3A8- A5 D1      0580      LDA  *FHPNT+1
C3AA- C5 7D      0590      CNP  *DATASTART+1  ;END OF TRANSFER
C3AC- 80 ED      0600      BCS  @MOVEDATA-1
C3AE- 60        0610      RTS
                0620
                0630 ;THIS ROUTINE SAVES THE DATA ON CASSETTE
                0640 ;IN HS FORMAT.
                0650
                0660 STORE
C3AF- A9 01      0670      LDA  #1
C3B1- 8D 4E A6   0680      STA  PARN+4
C3B4- A2 03      0690      LDX  #3
C3B6- B5 7A      0700      LDA  *DATAEND,X
C3B8- 9D 4A A6   0710      STA  PARN,X
C3BB- CA        0720      DEX
C3BC- 10 F8      0730      BPL  =-7
C3BE- A9 01      0740      LDA  #1
C3C0- 8D 30 A6   0750      STA  TAPDEL      ;SHORTEN LEADER TO 1.5 SEC
C3C3- 08        0760      PHP
C3C4- 78        0770      SEI
C3C5- 20 EA 87   0780      JSR  SAVE2      ;SAVE ON TAPE
C3C8- 28        0790      PLP
C3C9- 60        0800      RTS
                0810
                0820 ;MOVE CLOCK TO DATA FIELD
                0830
                0840 MOVECLOCK
C3CA- A0 05      0850      LDY  #5
C3CC- A2 05      0860      LDX  #5
C3CE- B5 6E      0870      LDA  *DAY,X
C3D0- 91 7C      0880      STA  (DATASTART),Y
C3D2- 88        0890      DEY
C3D3- CA        0900      DEX
C3D4- 10 F8      0910      BPL  MOVECLOCK+4
C3D6- 60        0920      RTS
                0930 MOVEOUT
C3D7- A2 06      0940      LDX  #6
                0950 MOVEOU
C3D9- 20 6C C3   0960      JSR  MOVEOUT
C3DC- CA        0970      DEX
C3DD- 10 FA      0980      BPL  MOVEOU
C3DF- A2 4F      0990      LDX  #79
C3E1- A0 4F      1000      LDY  #79
                1010 MOVEO
C3E3- B5 1E      1020      LDA  *OUTTIME,X
C3E5- 91 7C      1030      STA  (DATASTART),Y
C3E7- CA        1040      DEX
C3E8- 88        1050      DEY
C3E9- 10 F8      1060      BPL  MOVEO
C3EB- 20 6C C3   1070      JSR  MOVEOUT
C3EE- 60        1080      RTS
                1090 CLRDATA
C3EF- A9 00      1100      LDA  #0
C3F1- A0 09      1110      LDY  #9
                1120 CLRDA
C3F3- 91 7C      1130      STA  (DATASTART),Y
C3F5- 88        1140      DEY
C3F6- 10 FB      1150      BPL  CLRDA

```



```

C3FB- 60          1160          RTS
                  1170
                  1180 CLRSAVE
C3F9- A2 50      1190          LDX #80
C3FB- A9 00      1200          LDA #0
                  1210 CLRSA
C3FD- 85 1D      1220          STA *OUTPNT, X          ;RESET OUTPUT POINTER
C3FF- CA         1230          DEX
C400- 10 FB      1240          BPL CLRSA
C402- 60         1250          RTS
                  1260
                  1270 ;PUT 'IHFILE.P'
                  0220          ,FI 'IHHPHAT.P'
    
```

02B4 37D3-3A87 IHHPHAT.P

```

0010 ;PUT 'IHHPHAT.P'
0020
0030 ;   *** THIS CALCULATES THE HP USING THE VALUES ***
0040 ;   *** FROM MINUTE AVERAGES IN THE ZERO PAGE ADDRESSES ***
0050
0060 HPHAT          ;CALCULATE HORSEPOWER
0070 MV4 (FHRPME FPLSW)
    
```

C403- A2 03  
 C405- BD 08 01  
 C408- 9D D8 00  
 C40B- CA  
 C40C- 10 F7

0080 MV4 (C2H FOPLSW)

C40E- A2 03  
 C410- BD 88 CD  
 C413- 9D E0 00  
 C416- CA  
 C417- 10 F7

C419- 20 2F DD 0090 JSR FPHULT  
 0100 MV4 (FPLSW FPTEMP)

C41C- A2 03  
 C41E- BD D8 00  
 C421- 9D 00 01  
 C424- CA  
 C425- 10 F7

0110 MV4 (FHRACK FPLSW)

C427- A2 03  
 C429- RD 0C 01  
 C42C- 9D D8 00  
 C42F- CA  
 C430- 10 F7

0120 MV4 (C3H FOPLSW)

C432- A2 03  
 C434- BD 8C CD  
 C437- 9D E0 00  
 C43A- CA  
 C43B- 10 F7

C43D- 20 2F DD 0130 JSR FPHULT  
 0140 MV4 (FPTEMP FOPLSW)

C440- A2 03  
 C442- BD 00 01  
 C445- 9D E0 00  
 C448- CA  
 C449- 10 F7

C44B- 20 C7 DC 0150 JSR FPADD

	0160		MV4 (C1N FOPLSW)
C44E-	A2 03		
C450-	BD 84 CD		
C453-	9D E0 00		
C456-	CA		
C457-	10 F7		
C459-	20 C7 DC	0170	JSR FPADD
		0180	MV4 (FPLSW FPTEHP)
C45C-	A2 03		
C45E-	BD D8 00		
C461-	9D 00 01		
C464-	CA		
C465-	10 F7		
		0190	MV4 (C4N FPLSW)
C467-	A2 03		
C469-	BD 90 CD		
C46C-	9D D8 00		
C46F-	CA		
C470-	10 F7		
		0200	MV4 (FHRPHE FOPLSW)
C472-	A2 03		
C474-	BD 08 01		
C477-	9D E0 00		
C47A-	CA		
C47B-	10 F7		
C47D-	20 2F DD	0210	JSR FPKULT
		0220	MV4 (FHRPHE FOPLSW)
C480-	A2 03		
C482-	BD 08 01		
C485-	9D E0 00		
C488-	CA		
C489-	10 F7		
C48R-	20 2F DD	0230	JSR FPKULT
		0240	MV4 (FPTEMP FOPLSW)
C48E-	A2 03		
C490-	BD 00 01		
C493-	9D E0 00		
C496-	CA		
C497-	10 F7		
C499-	20 C7 DC	0250	JSR FPADD
		0260	MV4 (FPLSW FPTEHP)
C49C-	A2 03		
C49E-	BD D8 00		
C4A1-	9D 00 01		
C4A4-	CA		
C4A5-	10 F7		
		0270	MV4 (C5N FPLSW)
C4A7-	A2 03		
C4A9-	BD 94 CD		
C4AC-	9D D8 00		
C4AF-	CA		
C4B0-	10 F7		
		0280	MV4 (FHRPHE FOPLSW)
C4B2-	A2 03		
C4B4-	BD 08 01		
C4B7-	9D E0 00		
C4BA-	CA		
C4BB-	10 F7		
C4BD-	20 2F DD	0290	JSR FPKULT
		0300	MV4 (FHRACK FOPLSW)

C4C0- A2 03  
 C4C2- BD 0C 01  
 C4C3- 9D E0 00  
 C4C8- CA  
 C4C9- 10 F7

C4CR- 20 2F DD 0310 JSR FPMULT  
 0320 MV4 (FPTEHP FOPLSW)

C4CE- A2 03  
 C4D0- RD 00 01  
 C4D3- 9D E0 00  
 C4D6- CA  
 C4D7- 10 F7

C4D9- 20 C7 DC 0330 JSR FPADD  
 0340 MV4 (FPLSW FMHP)

C4DC- A2 03  
 C4DE- BD 08 00  
 C4E1- 9D 18 01  
 C4E4- CA  
 C4E5- 10 F7

C4E7- 60 0350 RTS  
 0360  
 0370 ;PUT 'IHHPHAT.P'  
 0230 ,FI 'IHFFHAT.P'

0369 37D3-383C IHFFHAT.P

0010 ;PUT 'IHFFHAT.P'  
 0020  
 0030 ; \*\*\* THIS ROUTINE CALCULATES THE FUEL FLOW \*\*\*  
 0040 ; \*\*\* USING THE MINUTE AVERAGES IN ZERO PAGE ADDRESSES \*\*\*  
 0050 ; \*\*\* AND THE ADJUSTED VALUES FROM H.P. CALCULATIONS \*\*\*  
 0060  
 0070 FFHAT  
 0080 MV4 (C9N FPLSW)

C4E8- A2 03  
 C4EA- BD 9C CD  
 C4ED- 9D 08 00  
 C4F0- CA  
 C4F1- 10 F7

0090 MV4 (FMRPHE FOPLSW)

C4F3- A2 03  
 C4F5- RD 08 01  
 C4F8- 9D E0 00  
 C4FB- CA  
 C4FC- 10 F7

C4FE- 20 2F DD 0100 JSR FPMULT  
 0110 MV4 (C8N FOPLSW)

C501- A2 03  
 C503- BD 98 CD  
 C506- 9D E0 00  
 C509- CA  
 C50A- 10 F7

C50C- 20 C7 DC 0120 JSR FPADD  
 0130 MV4 (FPLSW FPTEHP)

C50F- A2 03  
 C511- RD 08 00  
 C514- 9D 00 01  
 C517- CA  
 C518- 10 F7

0140 HV4 (C10N FPLSW)

C51A- A2 03  
C51C- BD A0 CD  
C51F- 9D 08 00  
C522- CA  
C523- 10 F7

0150 HV4 (FHRACK FOPLSW)

C525- A2 03  
C527- BD 0C 01  
C52A- 9D E0 00  
C52D- CA  
C52E- 10 F7

C530- 20 2F DD 0160 JSR FPHULT  
0170 HV4 (FPTEMP FOPLSW)

C533- A2 03  
C535- BD 00 01  
C538- 9D E0 00  
C53B- CA  
C53C- 10 F7

C53E- 20 C7 DC 0180 JSR FPADD  
0190 HV4 (FPLSW FPTEMP)

C541- A2 03  
C543- BD 08 00  
C546- 9D 00 01  
C549- CA  
C54A- 10 F7

0200 HV4 (FHRPHE FOPLSW)

C54C- A2 03  
C54E- BD 08 01  
C551- 9D E0 00  
C554- CA  
C555- 10 F7

0210 HV4 (FHRPHE FPLSW)

C557- A2 03  
C559- BD 08 01  
C55C- 9D 08 00  
C55F- CA  
C560- 10 F7

C562- 20 2F DD 0220 JSR FPHULT  
0230 HV4 (C11N FOPLSW)

C565- A2 03  
C567- BD A4 CD  
C56A- 9D E0 00  
C56D- CA  
C56E- 10 F7

C570- 20 2F DD 0240 JSR FPHULT  
0250 HV4 (FPTEMP FOPLSW)

C573- A2 03  
C575- BD 00 01  
C578- 9D E0 00  
C57B- CA  
C57C- 10 F7

C57E- 20 C7 DC 0260 JSR FPADD  
0270 HV4 (FPLSW FPTEMP)

C581- A2 03  
C583- BD 08 00  
C586- 9D 00 01  
C589- CA  
C58A- 10 F7

0280 HV4 (FHRACK FPLSW)

C58C- A2 03  
 C58E- BD 0C 01  
 C591- 9D D8 00  
 C594- CA  
 C595- 10 F7

0290

HV4 (FHRACK FOPLSW)

C597- A2 03  
 C599- BD 0C 01  
 C59C- 9D E0 00  
 C59F- CA  
 C5A0- 10 F7

C5A2- 20 2F DD 0300  
 0310

JSR FPHULT  
 HV4 (C12N FOPLSW)

C5A5- A2 03  
 C5A7- BD A8 CD  
 C5AA- 9D E0 00  
 C5AD- CA  
 C5AE- 10 F7

C5B0- 20 2F DD 0320  
 0330

JSR FPHULT  
 HV4 (FPTEMP FOPLSW)

C5B3- A2 03  
 C5B5- BD 00 01  
 C5B8- 9D E0 00  
 C5BB- CA  
 C5BC- 10 F7

C5BE- 20 C7 DC 0340  
 0350

JSR FPADD  
 HV4 (FPLSW FPTEMP)

C5C1- A2 03  
 C5C3- BD D8 00  
 C5C6- 9D 00 01  
 C5C9- CA  
 C5CA- 10 F7

0360

HV4 (FHRPHE FPLSW)

C5CC- A2 03  
 C5CE- BD 08 01  
 C5D1- 9D D8 00  
 C5D4- CA  
 C5D5- 10 F7

0370

HV4 (FHRACK FOPLSW)

C5D7- A2 03  
 C5D9- BD 0C 01  
 C5DC- 9D E0 00  
 C5DF- CA  
 C5E0- 10 F7

C5E2- 20 2F DD 0380  
 0390

JSR FPHULT  
 HV4 (C13N FOPLSW)

C5E5- A2 03  
 C5E7- BD AC CD  
 C5EA- 9D E0 00  
 C5ED- CA  
 C5EE- 10 F7

C5F0- 20 2F DD 0400  
 0410

JSR FPHULT  
 HV4 (FPTEMP FOPLSW)

C5F3- A2 03  
 C5F5- BD 00 01  
 C5F8- 9D E0 00  
 C5FB- CA  
 C5FC- 10 F7

C5FE- 20 C7 DC 0420  
 0430

JSR FPADD  
 HV4 (FPLSW FHFF)

C601- A2 03  
C603- BD D8 00  
C606- 9D 14 01  
C609- CA  
C60A- 10 F7

C60C- 60 0440 RTS  
0450  
0460 ;PUT 'IHFFHAT.P'  
0240 ;FI 'IHNEWVAL.P'

0B26 3703-42F9 IHNEWVAL.P

0010 ;PUT 'IHNEWVAL.P'  
0020 ; \*\*\* GEAR RATIO IS RATIO OF RPHE OVER RPHT \*\*\*  
0030 ; \*\*\* TO KEEP INTEGER NUMBERS \*\*\*  
0040 GRCHK

C60D- A9 00 0050 LDA #0  
C60F- A2 56 0060 LDX #COUNT3-FNGR  
0070 GRC  
C611- 9D 1C 01 0080 STA FNGR,X ;ZERO  
C614- CA 0090 DEX  
C615- 10 FA 0100 BPL GRC  
0110 MV3N (MRPMEX)

C617- AC 14 00  
C61A- AE 15 00  
C61D- AD 16 00  
C620- 20 23 C1

0120 MV4 (FPLSW FOPLSW)

C623- A2 03  
C625- BD D8 00  
C628- 9D E0 00  
C62B- CA  
C62C- 10 F7

0130 MV3N (MRPHTX)

C62E- AC 11 00  
C631- AE 12 00  
C634- AD 13 00  
C637- 20 23 C1

C63A- 20 A5 DD 0140 JSR FPDIV  
0150 MV4 (FPLSW FNGR) ;STORE MINUTE GEAR RATIO

C63D- A2 03  
C63F- BD D8 00  
C642- 9D 10 01  
C645- CA  
C646- 10 F7

C648- A9 10 0155 GRCALC  
C64A- 85 78 0160 LDA #16 ;LOAD WITH HIGH GEAR  
0170 STA #NGR  
0180 LOWER  
C64C- C4 78 0190 DEC #NGR  
C64E- 10 01 0200 BPL LOW  
C650- 60 0210 RTS  
0220 LOW  
C651- A5 78 0230 LDA #NGR  
0240 MV4I (FGEAR5 FOPLSW)

C653- 0A  
C654- 0A  
C655- A8  
C656- A2 00  
C658- 89 0C DO  
C65B- 95 E0  
C65D- C8



C65E- E8  
C65F- E0 04  
C661- D0 F5

C663- 18 0241  
C664- A9 01 0242  
C666- 65 DA 0243  
C668- 85 DA 0244  
0250

CLC  
LDA \*\$01  
ADC \*FPMSW  
STA \*FPMSW  
MV4 (FHGR FPLSW)

C66A- A2 03  
C66C- BD 10 01  
C66F- 9D D8 00  
C672- CA  
C673- 10 F7

C675- 20 C0 DC 0260  
C678- A5 DA 0270  
C67A- 30 D0 0280  
C67C- A5 78 0290  
C67E- 85 77 0300  
C680- 60 0305

JSR FPSUR ;COMPARE MIN. AVG. TO GEAR  
LDA \*FPMSW ;IS G.R. LOWER  
BMI LOWER ;YES  
LDA \*NGR  
STA \*NGEAR ;NO. STORE GEAR NUMBER  
RTS

0310 NXTGR  
C681- E6 78 0320  
C683- A9 0C 0330  
C685- C5 78 0340  
C687- B0 01 0350  
C689- 60 0360  
0370

INC \*NGR  
LDA #12 ;THIS IS MAX FIELD GEAR  
CMP \*NGR  
BCS =+2  
RTS  
MV4 (FMRPHT FPLSW)

C68A- A2 03  
C68C- BD 04 01  
C68F- 9D D8 00  
C692- CA  
C693- 10 F7

C695- A5 78 0380  
0390

LDA \*NGR  
MV4I (FGears FOPLSW)

C697- 0A  
C698- 0A  
C699- A8  
C69A- A2 00  
C69C- 89 0C D0  
C69F- 95 E0  
C6A1- C8  
C6A2- E8  
C6A3- E0 04  
C6A5- D0 F5

C6A7- 20 2F DD 0400  
0410

JSR FPKULT ;CALC. NEW RPHE  
MV4 (FPLSW FNRE) ;STORE NEW RPHE

C6AA- A2 03  
C6AC- BD D8 00  
C6AF- 9D 20 01  
C6B2- CA  
C6B3- 10 F7

0420

MV4 (FLRE FOPLSW)

C6B5- A2 03  
C6B7- RD D0 CD  
C6BA- 9D E0 00  
C6BD- CA  
C6BE- 10 F7

C6C0- 20 C0 DC 0430  
C6C3- A5 DA 0440  
C6C5- 30 01 0450  
C6C7- 60 0460  
0470 NRCHAT  
0520

JSR FPSUB  
LDA \*FPMSW  
BMI =+2  
RTS  
MV4 (FNHP FPLSW)

C6C8- A2 03  
C6CA- RD 18 01  
C6CD- 9D D8 00  
C6D0- CA

C6D1- 10 F7  
0530 HV4 (C16H FOPLSW)

C6D3- A2 03  
C6D5- BD B8 CD  
C6D8- 9D E0 00  
C6DB- CA  
C6DC- 10 F7

C6DE- 20 2F DD 0540 JSR FPKULT  
0550 HV4 (FPLSW FPTEHP)

C6E1- A2 03  
C6E3- BD D8 00  
C6E6- 9D 00 01  
C6E9- CA  
C6EA- 10 F7

0560 HV4 (FHRE FPLSW)

C6EC- A2 03  
C6EE- BD 20 01  
C6F1- 9D D8 00  
C6F4- CA  
C6F5- 10 F7

0570 HV4 (C15H FOPLSW)

C6F7- A2 03  
C6F9- BD B4 CD  
C6FC- 9D E0 00  
C6FF- CA  
C700- 10 F7

C702- 20 2F DD 0580 JSR FPKULT  
0590 HV4 (FPTEMP FOPLSW)

C705- A2 03  
C707- BD 00 01  
C70A- 9D E0 00  
C70D- CA  
C70E- 10 F7

C710- 20 C7 DC 0600 JSR FPADD  
0620 HV4 (C14H FOPLSW)

C713- A2 03  
C715- BD B0 CD  
C718- 9D E0 00  
C71R- CA  
C71C- 10 F7

C71E- 20 C7 DC 0630 JSR FPADD  
0640 HV4 (FPLSW FPTEMP)

C721- A2 03  
C723- BD D8 00  
C726- 9D 00 01  
C729- CA  
C72A- 10 F7

0650 HV4 (FHRE FPLSW)

C72C- A2 03  
C72E- BD 20 01  
C731- 9D D8 00  
C734- CA  
C735- 10 F7

0660 HV4 (FHRE FOPLSW)

C737- A2 03  
C739- BD 20 01  
C73C- 9D E0 00  
C73F- CA  
C740- 10 F7

C742- 20 2F DD 0670  
0680

JSR FPHULT  
MV4 (C17H FOPLSW)

C745- A2 03  
C747- BD BC CD  
C74A- 9D E0 00  
C74D- CA  
C74E- 10 F7

C750- 20 2F DD 0690  
0700

JSR FPHULT  
MV4 (FPTEMP FOPLSW)

C753- A2 03  
C755- BD 00 01  
C758- 9D E0 00  
C75R- CA  
C75C- 10 F7

C75E- 20 C7 DC 0710  
0720

JSR FPADD  
MV4 (FPLSW FPTEMP)

C761- A2 03  
C763- BD D8 00  
C766- 9D 00 01  
C769- CA  
C76A- 10 F7

0730

MV4 (FMHP FPLSW)

C76C- A2 03  
C76E- BD 18 01  
C771- 9D D8 00  
C774- CA  
C775- 10 F7

0740

MV4 (FNRE FOPLSW)

C777- A2 03  
C779- BD 20 01  
C77C- 9D E0 00  
C77F- CA  
C780- 10 F7

C782- 20 2F DD 0750  
0760

JSR FPHULT  
MV4 (C18N FOPLSW)

C785- A2 03  
C787- BD C0 CD  
C78A- 9D E0 00  
C78D- CA  
C78E- 10 F7

C790- 20 2F DD 0770  
0780

JSR FPHULT  
MV4 (FPTEMP FOPLSW)

C793- A2 03  
C795- BD 00 01  
C798- 9D E0 00  
C79B- CA  
C79C- 10 F7

C79E- 20 C7 DC 0790  
0800

JSR FPADD  
MV4 (FPLSW FNRAC)

C7A1- A2 03  
C7A3- BD D8 00  
C7A6- 9D 24 01  
C7A9- CA  
C7AA- 10 F7

0810

MV4 (FLRAC FOPLSW)

C7AC- A2 03  
C7AE- BD D4 CD  
C7B1- 9D E0 00  
C7B4- CA  
C7B5- 10 F7

C787-	20	C0	DC	0820	JSR	FPSUB
C78A-	AD	DA	00	0830	LDA	FPSW
C78D-	10	01		0840	BPL	=+2
C78F-	60			0850	RTS	
				0860	NFFHAT	
				0870		HV4 (C9N FPLSW)
C7C0-	A2	03				
C7C2-	BD	9C	CD			
C7C5-	9D	D8	00			
C7C8-	CA					
C7C9-	10	F7				
				0880		HV4 (FHRE FOPLSW)
C7CB-	A2	03				
C7CD-	RD	20	01			
C7D0-	9D	E0	00			
C7D3-	CA					
C7D4-	10	F7				
C7D6-	20	2F	DD	0890	JSR	FPHULT
				0900		HV4 (C8N FOPLSW)
C7D9-	A2	03				
C7DB-	BD	98	CD			
C7DE-	9D	E0	00			
C7E1-	CA					
C7E2-	10	F7				
C7E4-	20	C7	DC	0910	JSR	FPADD
				0920		HV4 (FPLSW FPTEHP)
C7E7-	A2	03				
C7E9-	BD	D8	00			
C7EC-	9D	00	01			
C7EF-	CA					
C7F0-	10	F7				
				0921		HV4 (FHRAC FOPLSW)
C7F2-	A2	03				
C7F4-	BD	24	01			
C7F7-	9D	E0	00			
C7FA-	CA					
C7FB-	10	F7				
				0930		HV4 (C10N FPLSW)
C7FD-	A2	03				
C7FF-	RD	A0	CD			
C802-	9D	D8	00			
C805-	CA					
C806-	10	F7				
C808-	20	2F	DD	0950	JSR	FPHULT
				0960		HV4 (FPTEMP FOPLSW)
C808-	A2	03				
C80D-	BD	00	01			
C810-	9D	E0	00			
C813-	CA					
C814-	10	F7				
C816-	20	C7	DC	0970	JSR	FPADD
				0980		HV4 (FPLSW FPTEHP)
C819-	A2	03				
C81R-	BD	D8	00			
C81E-	9D	00	01			
C821-	CA					
C822-	10	F7				
				0990		HV4 (FHRE FOPLSW)
C824-	A2	03				
C826-	BD	20	01			
C829-	9D	E0	00			

C82C- CA			
C82D- 10 F7			
	1000		NV4 (FNRE FPLSW)
C82F- A2 03			
C831- BD 20 01			
C834- 9D D8 00			
C837- CA			
C838- 10 F7			
C83A- 20 2F DD	1010		JSR FPHULT
	1020		NV4 (C11N FOPLSW)
C83D- A2 03			
C83F- BD A4 CD			
C842- 9D E0 00			
C845- CA			
C846- 10 F7			
C848- 20 2F DD	1030		JSR FPHULT
	1040		NV4 (FPTEMP FOPLSW)
C84B- A2 03			
C84D- BD 00 01			
C850- 9D E0 00			
C853- CA			
C854- 10 F7			
C856- 20 C7 DC	1050		JSR FPADD
	1060		NV4 (FPLSW FPTEMP)
C859- A2 03			
C85B- BD D8 00			
C85E- 9D 00 01			
C861- CA			
C862- 10 F7			
	1070		NV4 (FNRAC FPLSW)
C864- A2 03			
C866- BD 24 01			
C869- 9D D8 00			
C86C- CA			
C86D- 10 F7			
	1080		NV4 (FNRAC FOPLSW)
C86F- A2 03			
C871- BD 24 01			
C874- 9D E0 00			
C877- CA			
C878- 10 F7			
C87A- 20 2F DD	1090		JSR FPHULT
	1100		NV4 (C12N FOPLSW)
C87D- A2 03			
C87F- BD A8 CD			
C882- 9D E0 00			
C885- CA			
C886- 10 F7			
C888- 20 2F DD	1110		JSR FPHULT
	1120		NV4 (FPTEMP FOPLSW)
C88B- A2 03			
C88D- BD 00 01			
C890- 9D E0 00			
C893- CA			
C894- 10 F7			
C896- 20 C7 DC	1130		JSR FPADD
	1140		NV4 (FPLSW FPTEMP)
C899- A2 03			
C89B- BD D8 00			
C89E- 9D 00 01			

C8A1- CA  
C8A2- 10 F7

1150 MV4 (FHRE FPLSW)

C8A4- A2 03  
C8A6- BD 20 01  
C8A7- 9D D8 00  
C8AC- CA  
C8AD- 10 F7

1160 MV4 (FNRAC FOPLSW)

C8AF- A2 03  
C8B1- BD 24 01  
C8B4- 9D E0 00  
C8B7- CA  
C8B8- 10 F7

C8BA- 20 2F DD 1170  
1180

JSR FPHULT  
MV4 (C13N FOPLSW)

C8BD- A2 03  
C8BF- BD AC CD  
C8C2- 9D E0 00  
C8C5- CA  
C8C6- 10 F7

C8CB- 20 2F DD 1190  
1200

JSR FPHULT  
MV4 (FPTENP FOPLSW)

C8CC- A2 03  
C8CD- BD 00 01  
C8D0- 9D E0 00  
C8D3- CA  
C8D4- 10 F7

C8D6- 20 C7 DC 1210  
1220

JSR FPADD  
MV4 (FPLSW FNFF)

C8D9- A2 03  
C8DB- BD D8 00  
C8DE- 9D 28 01  
C8E1- CA  
C8E2- 10 F7

1230 SVAL  
1240 ;THIS ROUTINE TAKES THE FP CALCULATED VALUES  
1250 ;AND CONVERTS THEM TO BINARY NUMBERS AND  
1260 ;STORES THE VALUES IN A TABLE STARTING AT BFF  
1270 MV4 (FP10 FOPLSW)

C8E4- A2 03  
C8E6- BD 00 DD  
C8E9- 9D E0 00  
C8EC- CA  
C8ED- 10 F7

C8EF- 20 2F DD 1280  
C8F2- 20 37 C9 1290  
C8F5- A5 DA 1300  
C8F7- A6 78 1310  
C8F9- 9D 42 01 1320  
1330

JSR FPHULT ;CONVERT TO TENTHS  
JSR FT0B  
LDA \*FPMSW  
LDX \*NGR  
STA BFF,X  
MV4 (FNRE FOPLSW)

C8FC- A2 03  
C8FE- BD 20 01  
C901- 9D E0 00  
C904- CA  
C905- 10 F7

1340 MV4 (FP100 FPLSW)

C907- A2 03  
C909- BD C4 CD  
C90C- 9D D8 00  
C90F- CA  
C910- 10 F7



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C912- 20 A5 DD 1350 JSR FPDIV ;CONVERT TO RPM*100
C915- 20 37 C9 1360 JSR FTQB
C918- A5 DA 1370 LDA *FPMSW
C91A- A6 78 1380 LDX *HGR
C91C- 9D 52 01 1390 STA BRAC,X
1400 HV4 (FNRAC FPLSW)

C91F- A2 03
C921- BD 24 01
C924- 9D 08 00
C927- CA
C928- 10 F7

C92A- 20 37 C9 1410 JSR FTQB
C92D- A5 DA 1420 LDA *FPMSW
C92F- A6 78 1430 LDX *HGR
C931- 9D 62 01 1440 STA BRAC,X
C934- 4C 81 C6 1450 JMP NXTGR
1470 ; *****MOVE THIS TO THE FP ROUTINES*****
1480 FTQB
C937- A5 DB 1490 LDA *FPACCE ;THIS ROUTINE CONVERTS A F
C939- 38 1491 SEC ;IN FPACCUKILATOR TO A BIN
C93A- E9 08 1500 SBC #8 ; OF THE FPMANTESSA
C93C- B0 0A 1510 BCS OVRFLO
C93E- AA 1520 TAX
1530 LABELA
C93F- E8 1540 INX
C940- D0 01 1550 BNE =+2
C942- 60 1560 RTS
C943- 46 DA 1570 LSR *FPMSW
C945- 4C 3F C9 1580 JMP LABELA
1590 OVRFLO
C948- A9 99 1591 LDA #99
C94A- 60 1600 RTS
1610 ;PUT 'IHNEWVAL.P'
0250 ;FI 'IHFUEL.P'
    
```

0761 37D3-3F34 IHFUEL.P

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0010 ;PUT 'IHFUEL.P'
0020 ; *****THIS ROUTINE GETS THE MINIMUM FUEL USAGE*****
0030 ; *****AND CHECKES TO SEE IF IT SHOULD BE OUTPUT*****
0040 FUELSAV
C948- A9 FF 0050 LDA #FF
C94D- BD 30 01 0060 STA BHFF ;SET THE MINIMUM FUEL HIGH
C950- A6 78 0070 LDX *NGR ;START IN HIGHEST GEAR
0080 FUELSA
C952- CA 0090 DEX ;ARE WE OUT OF GEARS
C953- EC 77 00 0100 CPX HGEAR
C956- 90 13 0110 BCC FUELS ;YES
C958- BD 42 01 0120 LDA BFF,X ;NO
C95B- F0 F5 0130 BEQ FUELSA ;NO FF VALUE
C95D- CD 30 01 0140 CMP BHFF ;IS IT LESS THAN PRESENT V
C960- B0 F0 0150 BCS FUELSA ;NO
C962- BD 30 01 0160 STA BHFF ;YES, SO STORE
C965- BE 31 01 0170 STX BHFG ;SAVE MINIMUM FF GEAR
C968- 4C 52 C9 0180 JMP FUELSA
0190 FUELS
C96B- AE 31 01 0200 LDX BHFG ;GET OPTIMUM GEAR
C96E- D0 01 0210 BNE FUEL
C970- 60 0220 RTS
0230 FUEL
C971- CA 0240 DEX ;GET NEXT LOWER GEAR
C972- BD 42 01 0250 LDA BFF,X
C975- F0 0B 0260 BEQ FUE-1
C977- 38 0270 SEC
C978- ED 30 01 0280 SBC BHFF ;DOES HIGHEST GEAR HAVE EN
C978- F0 06 0290 BEQ FUE ;NO
C97D- CD D9 CD 0300 CMP HFFG
C980- 90 01 0310 BCC FUE ;NO
C982- E8 0320 INX ;YES
0330 FUE
    
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C983- 86 78      0340      STX *NGR                ;STORE NEW GEAR RATIO
C985- BD DA CD   0350      LDA GRTAB,X
C988- A6 1D      0360      LDX *OUTPNT
C98A- 95 64      0370      STA *NGR,X            ;RECORD OUTPUT GR
C98C- A6 78      0380      LDX *NGR
C98E- RD 52 01   0390      LDA RRE,X
C991- F0 5A      0400      BEQ NOOUT
C993- 20 FE C9   0410      JSR BTOD
C996- A6 1D      0420      LDX *OUTPNT
C998- 95 5A      0430      STA *ORPK,X          ;STORE OUTPUT RPM
                        0440      FU
                        0450      MV4 (FHFF FPLSW) ;GET LAST MINUTE FUEL FLOW

C99A- A2 03
C99C- BD 14 01
C99F- 9D D8 00
C9A2- CA
C9A3- 10 F7

                        0460      MV4 (FP10 FOPLSW)

C9A5- A2 03
C9A7- BD 00 D0
C9AA- 9D E0 00
C9AD- CA
C9AE- 10 F7

C9B0- 20 2F DD   0470      JSR FPHULT
C9B3- 20 37 C9   0480      JSR FTOD
C9B6- A5 DA      0490      LDA *FFPSW
C9B8- 20 FE C9   0500      JSR BTOD
C9BB- A6 1D      0510      LDX *OUTPNT
C9BD- 95 46      0520      STA *OFF,X          ;STORE OUTPUT FUEL FLOW
C9BF- 38         0530      SEC
C9C0- A6 78      0540      LDX *NGR
C9C2- A5 DA      0550      LDA *FFPSW          ;GET BINARY FF FOR LAST MI
C9C4- FD 42 01   0560      SBC BFF,X
C9C7- 20 FE C9   0570      JSR BTOD
C9CA- A6 1D      0580      LDX *OUTPNT
C9CC- 95 50      0590      STA *OFS,X          ;STORE OUTPUT FF SAVINGS
C9CE- D5 46      0600      CMP *OFF,X
C9D0- 10 1B      0610      BPL NOOUT
C9D2- CD D8 CD   0620      CMP #FFC          ;IS THERE ENOUGH SAVINGS
C9D5- 90 16      0630      BCC NOOUT          ;NO
C9D7- A9 80      0640      LDA #80            ;YES
C9D9- 05 74      0650      ORA *DISPFLG
C9DB- 85 74      0660      STA *DISPFLG
C9DD- E6 74      0670      INC *DISPFLG
C9DF- A5 1D      0680      LDA *OUTPNT
C9E1- 0A         0690      ASL A
C9E2- AA         0700      TAX
C9E3- A5 72      0710      LDA *DAY+4
C9E5- 95 1E      0720      STA *OUTTIME,X
C9E7- E8         0730      INX
C9E8- A5 73      0740      LDA *DAY+5
C9EA- 95 1E      0750      STA *OUTTIME,X
C9EC- 60         0760      RTS
                        0770      NOOUT
C9ED- A9 7F      0780      LDA #17F
C9EF- 25 74      0790      AND *DISPFLG
C9F1- 85 74      0800      STA *DISPFLG
C9F3- 60         0810      RTS
                        0820      CLRINSM
C9F4- A9 00      0830      LDA #0
C9F6- A2 0E      0840      LDX #14
                        0850      CLRHE
C9F8- 95 0E      0860      STA *SFLG2,X
C9FA- CA         0870      DEX
C9FB- 10 FB      0880      BPL CLRHE
C9FD- 60         0890      RTS
                        0900      BTOD
C9FE- 38         0910      SEC
C9FF- A2 FF      0920      LDX #1FF          ;FOR COMPENSATION
CA01- EB         0930      INX
CA02- E9 64      0940      SBC #100          ;SUBTRACT 100
CA04- B0 FB      0950      BCS RTOD+3
CA06- 69 64      0960      ADC #100          ;ADD BACK 100.
CA08- 48         0970      PHA

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088E 3703-4361 IHSHOW.S

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0010 ;PUT 'IHSHOW.S'
0020
0030 ;DISPLAY ROUTINE. THIS ROUTINE
0040 ;WILL DISPLAY ONE VALUE OR CYCLE
0050 ;THROUGH ALL VALUES ON DEMAND.
0060 ;INDIVIDUAL ROUTINES ARE CALLED FROM
0070 ;JUMPTABLE TO PUT THE DIFFERENT
0080 ;PARAMETERS INTO THE DISPLAY BUFFER
0090 ;
0100 SHOW
0110 JSR ACCESS
0120 LDA *DISCNT
0130 ASL A ;MULT BY 2
0140 TAX
0150 LDA JHPTAB,X ;GET ROUTINE ADDRESS
0160 STA *JHPVEC
0170 LDA JHPTAB+1,X ;2ND BYTE
0180 STA *JHPVEC+1
0190 CMP #FF
0200 BNE AHEAD
0210 LDA #00
0220 STA *DISCNT ;START AT ZERO IF AT END
0230 STA *DISCNT+1
0240 BEQ SHOW
0250 AHEAD
0260 SEI
0270 JSR SHOWDISP
0280 CLI
0290 BCC SHOWLOOP ;VALID IF CARRY CLEAR
0300 LDA #00
0310 STA *DISCNT+1 ;INCREMENT TO NEXT #
0320 CMP *CYCLE
0330 BNE SHOW ;SAME ROUTINE IF NONZERO
0340 INC *DISCNT
0350 JMP SHOW
0360 SHOWDISP
0370 JMP (JHPVEC) ;PUT VALUES IN DISPLAY BUF
0380 SHOWLOOP ;DISPLAY VALUES
0390 JSR LOOP
0400 BIT *CYCLE
0410 BHI SHOW
0420 INC *DISCNT+1
0430 JMP SHOW
0440 ;
0450 ;THIS ROUTINE SCANS DISPLAY WITH
0460 ;VALUES STORED IN DISPLAY BUFFER
0470 ;
0480 LOOP
0490 LDA *DISVEL ;DISPLAY VELOCITY
0500 STA *LCNT2
0510 LOOP1
0520 LDA #56
0530 STA *LCNT1
0540 LOOP2
0550 JSR SCAND ;SCAN DISPLAY
0560 BNE KEY ;IF KEY DEPRESSED, KEY
0570 LDA #40
0580 STA *KEYCNT
0590 DEC *LCNT1
0600 BNE LOOP2
0610 DEC *LCNT2
0620 BNE LOOP1
0630 RTS
0640 ;
0650 ;KEY ROUTINE. CHECKS FOR VALID
0660 ;KEY INPUTS, AND DETERMINES WHAT
0670 ;KEY IS DEPRESSED.
0680 ;
0690 KEY
0700 DEC *KEYCNT
0710 BNE LOOP2
0720 LDA #FF
0730 STA *CYCLE ;STOP CYCLING

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CAD4- 20 20 82 0740      JSR PARM          ;GET PARAMETERS
CAD7-  D0 1C 0750      BNE KEY2         ;CR? NO,KEY2
CAD9-  AE 49 A6 0760      LDX PARNR       ;GET NUMBER OF PARAMETERS
CADC-  F0 52 0770      BEQ GOHON       ;IF NO PARAK THEN GOTO KON
CADE-  AD 4A A6 0780      LDA PARN
CAE1-  85 84 0790      STA *DISCNT+1
CAE3-  CA 0800      DEX
CAE4-  D0 01 0810      BNE =+2         ;IF NOT 0 SKIP RTS STATEKE
CAE6-  60 0820      RTS
CAE7-  AD 4C A6 0830      LDA PARN+2
CAEA-  0A 0840      ASL A          ;MULT BY 2
CAEB-  C9 0A 0850      CMP #L,NUCHAN  ;OUT OF RANGE?
CAED-  30 02 0860      BHI =+3
CAEF-  10 2D 0870      B' L ERROR1
CAF1-  4A 0880      LSR A
CAF2-  85 83 0890      STA *DISCNT    ;SET ROUTINE #
CAF4-  60 0900      RTS
          0910      KEY2
CAF5-  C9 3C 0920      CMP #'<        ;BACK UP ONE CHANNEL
CAF7-  D0 07 0930      BNE =+8
CAF9-  A6 84 0940      LDX *DISCNT+1  ;DON'T DEC IF ZERRO
CAF8-  F0 02 0950      BEQ =+3
CAF0-  C6 84 0960      DEC *DISCNT+1
CAFF-  60 0970      RTS
CB00-  C9 3E 0980      CMP #'>        ;NEXT CHANNEL
CB02-  D0 03 0990      BNE =+4
CB04-  E6 84 1000      INC *DISCNT+1
CB06-  60 1010      RTS
CB07-  C9 4D 1020      CMP #'M        ;STOP CYCLING
CB09-  D0 01 1030      BNE =+2
CB0R-  60 1040      RTS
CB0C-  C9 52 1050      CMP #'R        ;CYCLE ONLY ONE TYPE
CB0E-  D0 05 1060      BNE =+6
CB10-  A9 40 1070      LDA #40
CB12-  85 87 1080      STA *CYCLE
CB14-  60 1090      RTS
CB15-  C9 47 1100      CMP #'G        ;CYCLE ON EVERYTHING
CB17-  D0 05 1110      BNE ERROR1
CB19-  A9 00 1120      LDA #00
CB1B-  85 87 1130      STA *CYCLE
CB1D-  60 1140      RTS
          1150      ;
          1160      ERROR1
CB1E-  A2 05 1170      LDX #5
          1180      ERRMES
CB20-  BD 4C CB 1190      LDA ERRTAB,X
CB23-  9D 40 A6 1200      STA DISBUF,X
CB26-  CA 1210      DEX
CB27-  10 F7 1220      BPL ERRMES
CB29-  A9 80 1230      LDA #80
CB2B-  85 89 1240      STA $LCNT2
CB2D-  4C B6 CA 1250      JHP LOOP1
          1260      ;
          1270      GOHON
CB30-  38 1280      SEC
CB31-  68 1290      PLA          ;PULL LOOP RETURN
CB32-  68 1300      PLA
CB33-  68 1310      PLA          ;SHOW RETURN
CB34-  E9 02 1320      SBC #02      ;BACKUP TO CALL
CB36-  8D 59 A6 1330      STA GOVEC
CB39-  68 1340      PLA
CB3A-  E9 00 1350      SBC #00      ;SUB ANY BORROW
CB3C-  8D 5A A6 1360      STA GOVEC+1
CB3F-  4C 00 80 1370      JMP MONITOR   ;GO CR WILL CONT.
          1380      JHPTAB
CB42-  A0 CB 1390      .SE CLOCKDISPLAY
CB44-  52 CB 1400      .SE DATADISPLAY
CB46-  FF FF 1410      .SE $FFFF
CB48-  90 CB 1420      .SE MEMDISP
CB4A-  FF FF 1430      .SE $FFFF
          1440      NUCHAN
CB4C-  79 50 50 1450      .DE --JHPTAB
CB4F-  5C 50 00 1460      .BY $79 $50 $50 $5C $50 $00
          1470      DATADISPLAY
CB52-  AD 84 00 1480      LDA DISCNT+1
CB55-  C9 00 1490      CMP #0
CB57-  F0 0A 1500      BEQ FUELDISP   ;0: FUEL DISPLAY
    
```

```

CB59- C9 01      1510      CNP  ##1
CB5R- F0 14      1520      BEQ  RPHEDISP
CB5D- C9 02      1530      CNP  ##2
CB5F- F0 1E      1540      BEQ  RACKDISP
CB61- 38         1550      SEC
CB62- 60         1560      RTS
                        1570      FUELDISP
CB63- A9 01      1580      LDA  ##01
CB65- 20 FA 82   1590      JSR  OUTBYT
CB68- A6 00      1600      LDX  *RPMTH
CB6A- A5 01      1610      LDA  *RPMTH+1
CB6C- 20 F4 82   1620      JSR  OUTXAH
CB6F- 18         1630      CLC                      ;DISCNT OK
CB70- 60         1640      RTS
                        1650      RPHEDISP
CB71- A9 02      1660      LDA  ##02
CB73- 20 FA 82   1670      JSR  OUTBYT
CB76- A6 02      1680      LDX  *RPHEH
CB78- A5 03      1690      LDA  *RPHEH+1
CB7A- 20 F4 82   1700      JSR  OUTXAH
CB7D- 18         1710      CLC                      ;DISCNT OK
CB7E- 60         1720      RTS
                        1730      RACKDISP
CB7F- A9 03      1740      LDA  ##03
CB81- 20 FA 82   1750      JSR  OUTBYT
CB84- A9 00      1760      LDA  #0
CB86- 20 FA 82   1770      JSR  OUTBYT
CB89- A5 05      1780      LDA  *RACKH+1
CB8B- 20 FA 82   1790      JSR  OUTBYT
CB8E- 18         1800      CLC
CB8F- 60         1810      RTS
                        1820      MEHDISP
CB90- A2 00      1830      LDX  #00
CB92- A5 84      1840      LDA  *DISCNT+1
CB94- 20 F4 82   1850      JSR  OUTXAH
CB97- A6 84      1860      LDX  *DISCNT+1
CB99- B5 00      1870      LDA  *#00,X
CB9B- 20 FA 82   1880      JSR  OUTBYT
CB9E- 18         1890      CLC
CB9F- 60         1900      RTS
                        1910
                        1920      ;PUT 'IHSHOW.S'
                        0280      .FI 'IHCLKSUBS'

```

0D34 37D3-4507 IHCLKSUBS

```

0010 ;PUT 'IHCLKSUBS'
0020
0030 CLOCKDISPLAY
CBA0- A5 84      0040      LDA  *DISCNT+1
CBA2- C9 00      0050      CNP  ##00
CBA4- F0 15      0060      BEQ  DATEDISP
CBA6- C9 01      0070      CNP  ##01
CBA8- F0 24      0080      BEQ  TIMEDISP
CBAA- C9 10      0090      CNP  ##10
CBAC- F0 06      0100      BEQ  DATEDISP-7
CBAE- C9 11      0110      CNP  ##11
CBB0- F0 15      0120      BEQ  TIMEDISP-7
CBB2- 38         0130      SEC
CBB3- 60         0140      RTS
                        0150
CBB4- 20 14 CC   0160      JSR  SETDATE
CBB7- A9 00      0170      LDA  ##00                      ;RESET CNTR TO DATEDISP
CBB9- 85 84      0180      STA  *DISCNT+1
                        0190      DATEDISP
CBBR- A5 6F      0200      LDA  *DAY+1
CBBD- 20 FA 82   0210      JSR  OUTBYT
CBC0- A6 70      0220      LDX  *DAY+2
CBC2- A5 6E      0230      LDA  *DAY
CBC4- 4C D7 CB   0240      JMP  TIMEDISP+9
                        0250
CBC7- 20 EC CB   0260      JSR  SETTIME
CBCA- A9 01      0270      LDA  ##01                      ;RESET CNTR TO TIMEDISP

```



```

CBCC- 85 84      0280      STA *DISCNT+1
                  0290      TIMEDISP
CBCE-  A5 71      0300      LDA *DAY+3
CBDO- 20 FA 82    0310      JSR OUTBYT
CBDS-  A6 72      0320      LDX *DAY+4
CBDS-  A5 73      0330      LDA *DAY+5
CBDS- 20 F4 82    0340      JSR OUTXAH
CBDA- AD 41 A6    0350      LDA DISBUF+1
CBDD- 09 80      0360      ORA *$80
CBDF- 8D 41 A6    0370      STA DISBUF+1
CBE2- AD 43 A6    0380      LDA DISBUF+3
CBE5- 09 80      0390      ORA *$80
CBE7- 8D 43 A6    0400      STA DISBUF+3
CBEA- 18          0410      CLC
CBEB- 60          0420      RTS
                  0430
                  0440      ;SET THE TIME HOURS AND MINUTES AND
                  0450      ;RESET THE SECONDS TO ZERO
                  0460
                  0470      SETIME
CBEC-  A2 0B      0480      LDX $11
CBEE- 20 EC CC    0490      JSR OUTMSG
CBF1- 20 20 82    0500      JSR PARM
                  0510      LDA *$02
CBF4-  A9 02      0520      CMP PARNR
CBF6-  CD 49 A6    0530      BNE READCLOCK
CBF9- D0 44      0540      LDA *$04
CBFB-  A9 04      0550      JSR STOPCLOCK
CBFD- 20 A3 CC    0560      LDX *$05
CC00- A2 05      0570      LDA PARN+2
CC02- AD 4C A6    0580      ORA *$80
CC05- 09 80      0590      JSR SETBYTE
CC07- 20 82 CC    0600      LDA PARN
CC0A- AD 4A A6    0610      JSR SETBYTE
CC0D- 20 82 CC    0620      LDA *$00
CC10- A9 00      0630      BEQ READCLOCK-6
CC12- F0 25      0640
                  0650      ;SET THE YEAR, MONTH, AND DAY TO THE CLOCK
                  0660      ;WITHOUT THE HOLD.
                  0670
                  0680      SETDATE
CC14- A2 05      0690      LDX $5
CC16- 20 EC CC    0700      JSR OUTMSG
CC19- 20 20 82    0710      JSR PARM
CC1C- A9 03      0720      LDA *$03
CC1E-  CD 49 A6    0730      CMP PARNR
CC21- D0 1C      0740      BNE READCLOCK
CC23- A9 04      0750      LDA *$04
CC25- 20 A3 CC    0760      JSR STOPCLOCK
CC28- A2 0C      0770      LDX $12
CC2A- AD 4A A6    0780      LDA PARN
CC2D- 20 82 CC    0790      JSR SETBYTE
CC30- AD 4E A6    0800      LDA PARN+4
CC33- 20 82 CC    0810      JSR SETBYTE
CC36- AD 4C A6    0820      LDA PARN+2
CC39- 20 82 CC    0830      JSR SETBYTE
CC3C- 20 C6 CC    0840      JSR SETUPCLOCK
                  0850
                  0860      ;SETIME AND SETDATE FALL THRU TO READCLOCK HERE
                  0870      ;SUBROUTINE TO READ TIME FROM CLOCK
                  0880      ;AND STORE IT IN 6 BYTES AT DAY
                  0890
                  0900      READCLOCK
CC3F-  A9 06      0910      LDA *$06
CC41- 20 A3 CC    0920      JSR STOPCLOCK
CC44- A2 05      0930      LDX $5
CC46-  A9 00      0940      LDA $0
CC48- 8D 01 A0    0950      STA VIA1+1
CC4B- 20 63 CC    0960      JSR READ3
CC4E- EE 01 A0    0970      INC VIA1+1
CC51- 20 63 CC    0980      JSR READ3
CC54- A5 71      0990      LDA *DAY+3
CC56- 29 3F      1000      AND *$3F
CC58- 85 71      1010      STA *DAY+3
CC5A- A5 70      1020      LDA *DAY+2
CC5C- 29 3F      1030      AND *$3F
CC5E- 85 70      1040      STA *DAY+2
CC60- 4C C6 CC    1050      JMP SETUPCLOCK

```



```

1060
1070 ;READ 3 BYTES OF DATA FROM THE CLOCK
1080 ;AND PUT IT AT DAY,X TO DAY,X-2
1090 ;LEAVE X = X-3.
1100
1110 READ3
CC63- A0 03          1120          LDY #03
CC65- AD 01 A0      1130          LDA VIA1+1
CC68- FE 01 A0      1140          INC VIA1+1          ;NEXT NIBBLE
CC6R- 4A           1150          LSR A
CC6C- 4A           1160          LSR A
CC6D- 4A           1170          LSR A
CC6E- 4A           1180          LSR A
CC6F- 95 6E        1190          STA *DAY,X          ;LOWER NIBBLE
CC71- AD 01 A0      1200          LDA VIA1+1
CC74- EE 01 A0      1210          INC VIA1+1          ;NEXT NIBBLE
CC77- 29 F0        1220          AND #Z11110000     ;HIGH NIBBLE
CC79- 15 6E        1230          ORA *DAY,X          ;MERGE NIBBLES
CC7B- 95 6E        1240          STA *DAY,X
CC7D- CA           1250          DEX
CC7E- 88           1260          DEY
CC7F- D0 E4        1270          BNE READ3+2
CC81- 60           1280          RTS
1290
1300 ;SET 1 BYTE TO CLOCK AT LOCATION IN X
1310 ;AND X-1.
1320
1330 SETBYTE
CC82- 48           1340          PHA
CC83- 29 F0        1350          AND #F0
CC85- 20 8D CC     1360          JSR =+8
CC88- 68           1370          PLA
CC89- 0A           1380          ASL A
CC8A- 0A           1390          ASL A
CC8B- 0A           1400          ASL A
CC8C- 0A           1410          ASL A
CC8D- 86 6E        1420          STX *DAY          ;USE AS TMP LOC
CC8F- 05 6E        1430          ORA *DAY
CC91- 8D 01 A0     1440          STA VIA1+1
CC94- AD 00 A0     1450          LDA VIA1
CC97- 29 FE        1460          AND #Z11111110     ;WRITE PULSE
CC99- 8D 00 A0     1470          STA VIA1          ;WRITE
CC9C- 09 01        1480          ORA #X00000001     ;CLR WRITE(INV)
CC9E- 8D 00 A0     1490          STA VIA1
CCA1- CA           1500          DEX
CCA2- 60           1510          RTS
1520
1530 ;THIS ROUTINES DISABLES THE INTERRUPTS
1540 ;AND SETS THE OUTPUT LINES AS SET IN A
1550 ;2 PB IS SET TO OUTPUT IF WRITE FLAG IS SET
1560
1570 STOPCLOCK
CCA3- 78           1580          SEI
CCA4- 85 6E        1590          STA *DAY
CCA6- A9 10        1600          LDA #10
CCA8- 8D 0F A0     1610          STA VIA1+14        ;DISABLE CBI INT
CCA8- AD 00 A0     1620          LDA VIA1          ;DISABLE INTERRUPTS
CCAE- 09 07        1630          ORA #07
CC80- 45 6E        1640          EOR *DAY          ;SET STATUS BITS
CCR2- 8D 00 A0     1650          STA VIA1          ;INV NEW STAT BITS
CCB5- A9 02        1660          LDA #02
CCB7- 24 6E        1670          BIT *DAY          ;READ BIT
CCB9- D0 05        1680          BNE =+6          ;SET FOR READ?
CCBR- A9 FF        1690          LDA #FF
CCBD- 8D 03 A0     1700          STA VIA1+3        ;ALL OUTPUTS
CCC0- A2 1E        1710          LDX #30          ;DELAY FOR HOLD SETUP
CCC2- CA           1720          DEX
CCC3- D0 FD        1730          BNE =-2
CCC5- 60           1740          RTS
1750
1760 ;ROUTINE TO SETUP THE VIA'S FOR THE CLOCK
1770 ;SUBROUTINES
1780
1790 SETUPCLOCK
CCC6- AD 00 A0     1800          LDA VIA1
CCC9- 29 F8        1810          AND #Z11111000     ;CLR STAT
CCCB- 09 05        1820          ORA #Z00000101     ;SET NEG STAT
CCCD- 8D 00 A0     1830          STA VIA1          ;SET READ ONLY MODE

```

```

CCD0- AD 02 A0 1840 LDA VIA1+2
CCD3- 09 07 1850 ORA #200000111 ;STAT BITS OUT
CCD5- 8D 02 A0 1860 STA VIA1+2
CCD8- A9 0F 1870 LDA #0F
CCDA- 8D 01 A0 1880 STA VIA1+1 ;SET FOR INTERRUPTS
CCDD- 8D 03 A0 1890 STA VIA1+3 ;DATA DIRECTION REG.
CCE0- A9 10 1900 LDA #10 ;CB1 INT
CCE2- 8D 0D A0 1910 STA VIA1+13 ;RESET INTERRUPTS
CCE5- A9 90 1920 LDA #90 ;CB1 INT
CCE7- 8D 0E A0 1930 STA VIA1+14 ;ENABLE INTERRUPTS
CCEA- 58 1940 CLI
CCEB- 60 1950 RTS
1960
1970 ;PRINT A MESSAGE ON DISPLAY
1980
1990 OUTHSG
CCEC- A0 05 2000 LDY #405
CCEE- 8D F9 CC 2010 LDA OUTHSGS,X
CCF1- 99 40 A6 2020 STA DISBUF,Y
CCF4- CA 2030 DEX
CCF5- 88 2040 DEY
CCF6- 10 F6 2050 BPL OUTHSG+2
CCF8- 60 2060 RTS
2070
2080 OUTHSGS
2090 ;DATE?
CCF9- 00 5E 77 2100 .BY $00 $5E $77 $78 $79 $53
CCFC- 78 79 53 2110 ;TIME?
CCFF- 00 78 06 2120 .BY $00 $78 $06 $54 $79 $53
CD02- 54 79 53 2130
2140 ;PUT 'IHCLKSURS'
0290 .FI 'IHSETPORT'

```

## 0106 37D3-38D9 IHSETPORT

```

0010 ; SET INPUT PORTS FOR DATA COLLECTION
0020 SETPORT
CD05- A9 BF 0030 LDA #BF
CD07- 8D 02 AB 0040 STA VIA2+2 ;RPM TRANS.
CD0A- A9 9F 0050 LDA #9F
CD0C- 8D 02 AC 0060 STA VIA3+2 ;RPM ENGINE
CD0F- A9 00 0070 LDA #00
CD11- 8D 03 AB 0080 STA VIA2+3
CD14- A9 FF 0085 LDA #FF
CD16- 8D 03 AC 0090 STA VIA3+3
CD19- A9 20 0140 LDA #20
CD18- 8D 0B AB 0150 STA VIA2+11
CD1E- 8D 0B AC 0160 STA VIA3+11
CD21- 0D 0B A0 0170 ORA VIA1+11
CD24- 8D 0B A0 0180 STA VIA1+11
CD27- 60 0190 RTS
0200
0210 ;PUT 'IHSETPORT'
0300 .FI 'IHSTARTCNT'

```

## 00B0 37D3-3883 IHSTARTCNT

```

0010 ; PUT 'IHSTARTCNT'
0020 ; THIS ROUTINE SETS THE COUNTERS TO $FF TO BEGIN COUNTING
0030 STRCNT LDA #$FF
CD2A- 8D 09 AB 0040 STA VIA2+9
CD2D- 8D 08 AB 0050 STA VIA2+8
CD30- 8D 09 AC 0060 STA VIA3+9
CD33- 8D 08 AC 0070 STA VIA3+8
CD36- 60 0080 RTS
0090 ; PUT 'IHSTARTCNT'

```

0310 .FI 'Ihreadport'

0335 37D3-3B08 Ihreadport

```

0010 ;PU 'Ihreadport'
0020 ; READ DATA FROM PORTS AND STORE IN RAM
0030 GTO DATA
CD37- AD 09 AB 0040 RPH1 LDA VIA2+9 ; HIGH BYTE OR TRANSMISSIO
CD3A- 85 00 0050 STA *RPH1H
CD3C- AD 08 AB 0060 LDA VIA2+8 ; LOW BIT
CD3F- 85 01 0070 STA *RPH1H+1
CD41- AD 09 AB 0080 LDA VIA2+9
CD44- C5 00 0090 CMP *RPH1H ; CHECK IF BIT HAS CHANGED
CD46- F0 07 0100 BEQ RPKH ; NO
CD48- 85 00 0120 STA *RPH1H
CD4A- AD 08 AB 0130 LDA VIA2+8
CD4D- 85 01 0140 STA *RPH1H+1
CD4F- AD 09 AC 0150 RPKH LDA VIA3+9 ; HIGH BYTE OF ENGINE
CD52- 85 02 0160 STA *RPH1H
CD54- AD 08 AC 0170 LDA VIA3+8 ; LOW
CD57- 85 03 0180 STA *RPH1H+1
CD59- AD 09 AC 0190 LDA VIA3+9
CD5C- C5 02 0200 CMP *RPH1H ; CHECK IF BYTE HAS CHANGE
CD5E- F0 07 0210 BEQ LIM1 ; NO
CD60- 85 02 0230 STA *RPH1H
CD62- AD 08 AC 0240 LDA VIA3+8
CD65- 85 03 0250 STA *RPH1H+1
0260 ; THIS ROUTINE GETS THE LIM1 DATA
0270 LIM1
CD67- A9 03 0280 LDA #3
CD69- 2D 00 AB 0290 AND VIA2
CD6C- 8D 06 00 0300 STA LIM1H
0310 ; THIS ROUTINE GETS THE RACK DATA AND STORES IT IN RAM
0320 GTRAK
CD6F- AD 01 AB 0330 LDA VIA2+1
CD72- 85 05 0340 STA *RACKH+1
CD74- A9 FF 0341 LDA #$FF
CD76- 85 04 0342 STA *RACKH
0350 COMP
CD78- A2 05 0360 ; THIS ROUTINE COMPLIMENTS THE TIMER DATA AND THE RACK
CD7A- A9 FF 0365 LDX #5
CD7C- 55 00 0370 LDA #$FF
CD7E- 95 00 0400 EOR *RPH1H,X
CD80- CA 0410 STA *RPH1H,X
CD81- 10 F7 0420 DEX
CD83- 60 0430 RPL COMP+2
0440 RTS
0450 ;PU 'Ihreadport'
0320 .FI 'Ihconstants.D'
```

03D5 37D3-3BA8 Ihconstants.D

```

0010 ;PUT 'Ihconstants.D'
0020
0030 ; *****THESE ARE EPROM LARLES*****
0040 ;***THESE SHOULD BE AT END OF PROGRAM IN FORM C1N ,BY **
CD84- C6 CA A7 0050 C1N .BY $C6 $CA $A7 $05
CD87- 05
CD88- AA 11 70 0060 C2N .BY $AA $11 $70 $F9
CD8B- F9
CD8C- 35 51 BE 0070 C3N .BY $35 $51 $RE $FF
CD8F- FF
CD90- 0A 7A 93 0080 C4N .BY $0A $7A $93 $EF
CD93- EF
CD94- ED 30 78 0090 C5N .BY $ED $30 $78 $F5
CD97- F5
CD98- FA 53 60 0100 C8N .BY $FA $53 $60 $04
CD9B- 04
```

```

CD9C- D5 2A 54 0110 C9N      .BY $D5 $2A $54 $F8
CD9F- F8
CD40- 88 3E 98 0120 C10N     .BY $8R $3E $98 $FF
CDA3- FF
CDA4- 46 84 B3 0130 C11N     .BY $46 $84 $B3 $ED
CDA7- ED
CDA8- F6 6E 41 0140 C12N     .BY $F6 $6E $41 $F8
CDAB- F8
CDAC- C2 0E 78 0150 C13N     .BY $C2 $0E $78 $F3
CDAF- F3
CDB0- 48 AE 78 0160 C14N     .BY $48 $AE $78 $07
CDB3- 07
CDB4- 92 0B B2 0170 C15N     .BY $92 $0B $B2 $FC
CDB7- FC
CDB8- 37 33 55 0180 C16N     .BY $37 $33 $55 $01
CDBB- 01
CDBC- 7C 5A 60 0190 C17N     .BY $7C $5A $60 $EF
CDBF- EF
CDC0- 89 3R A7 0200 C18N     .BY $89 $3B $A7 $F4
CDC3- F4
CDC4- 00 00 6E 0210 FP100    .BY $00 $00 $6E $08 ;100*132/60
CDC7- 08
CDCR- 02          0220 HLRPHTH .BY $02
CDC9- BC          0230 HLRPHTL .BY $BC
CDCA- 00          0240 LLRPHTH .BY $00
CDCB- 8C          0250 LLRPHTL .BY $8C
CDCC- 05          0260 LRPHEH  .BY $05
CDCD- 78          0270 LRPHEL  .BY $78
CDCE- 00 8C      0280 LRACKH  .BY $00 $8C
CDD0- 00 00 6A  0290 FLRE    .BY $00 $00 $6A $0C ;1500 RPM
CDD3- 0C
CDD4- 00 00 41  0300 FLRAC    .BY $00 $00 $41 $08
CDD7- 08
CDD8- 05          0310 KFFC    .BY $05
CDD9- 02          0320 HFFG    .BY $02
                   0330
CDDA- 15 16 25  0340 GRTAB    .BY $15 $16 $25 $26
CDDD- 26
CDDE- 45 46 85  0350          .BY $45 $46 $85 $86
CDE1- 86
CDE2- 19 1A 29  0360          .BY $19 $1A $29 $2A
CDE5- 2A
CDE6- 49 4A 89  0370          .BY $49 $4A $89 $8A
CDE9- 8A
                   0380
                   0390 ;PUT 'IHCONSTANTS.D'
                   0400 ; TO SAVE SPACE ONLY USE GEARS
                   0410 ; 3-12 AND CHECK OUT OF RANGE
                   0330          .EN

```

END OF HAE PASS!

--- LABEL FILE: ---

```

@MOVEDATA =C39C      ACCESS =8B86      AHEAD =CABF
AVG4 =C202           BEEP =8972       BFF =0142
BFFS =0132          BINARY =C10F    RLHFF =012C
BNFF =0130          BNF0 =0131      BRAC =0162
BRE =0152           BTOD =C9FE      C10N =CDA0
C11N =CDA4          C12N =CDA8      C13N =CDAC
C14N =CDB0          C15N =CDB4      C16N =CDB8
C17N =CDBC          C18N =CDC0      C1N =CDB4
C2N =CD88           C3N =CD8C       C4N =CD90
C3N =CD94           C8N =CD98       C9N =CD9C
CALCG =C17B        CGR =C190       CH =C0D4
CHF =C0D7           CKLIMIT =C134   CKHRK =C256
CLOCKDISPLAY =CBA0 CLRDA =C3F3      CLRDATA =C3EF
CLRHE =C9F8        CLRMINSH =C9F4  CLRHRK =C26C
CLRSA =C3FD        CLRSAVE =C3F9   CLRSECSH =C2A6
CLS =C2AA          CNT2 =C2A3      CNTR =00D4
COMP =CD78         COUNT1 =000D    COUNT2 =001A
COUNT3 =0172     CYCLE =0087     DATADISPLAY =CB52
DATAEND =007A     DATASTART =007C DATEDISP =CB8R
DAY =006E          DGR =0079       DISBUF =A640
DISCNT =0083      DISPFLG =0074   DISVEL =0082
DOWNSHIFT =C140   ENDINT =C109    EPRON2 =0000
ERRHES =CB20      ERROR1 =CR1E    ERRTAB =CR4C
ESUM =C286        FFHAT =C4E8     FGEARS =D00C
FLG3 =C235        FLGTIME =0173   FLRAC =CDD4

```



```

FLRE =CDD0
FNHF =0118
FHRPHE =0108
FNGR =011C
FNSGR =017B
FDFLSW =00E0
FOUR =C07E
FP100 =CDC4
FFRASE =DC00
FPLSW =00DB
FPHULT =DD2F
FPOUT =DE57
FSGR =0177
FUE =C983
FUELS =C96B
FULL =008B
GOVEC =A659
GRCH =C1F9
GRTAB =CDDA
GTRAK =CD6F
HPHAT =C403
I2TOF =C121
INIT =C01A
INIT3 =C037
INTERRUPT =C050
IOSIGN =00E4
KEY =CACC
L =00E7
LATCH =008F
LENGTH =0080
LIMITS =0006
LOOP =CAB2
LOW =C651
LRPHEH =CDCC
MEMDISP =CB90
MFFG =CDD9
MINAVE =C2C3
MOVECLOCK =C3CA
MOVEQU =C3D9
MRPNEX =0014
MFFHAT =C7C0
NRACHAT =C6C8
NXTGR =C681
OFS =0050
OUT =C109
OUTMSG =CCEC
OUTOFF =C1D5
OUTT =CA36
OVFL =00D5
P =00E7
PARNR =A649
READ3 =CC43
RPHEMISP =CB71
RPHTH =0000
SAVE =C356
SCAND =B906
SECSU =C06E
SETDATE =CC14
SETHRK =C265
SFL3 =C23D
SFLG2 =000E
SHOW =CA72
SIGNS =00D6
SRPHTH =0007
STHIN =C0F2
STORE =C3AF
STRICNT =CD28
SUMFOU =C0CD
TAPDEL =A630
TIMDISP =CBCE
TSUM =C276
VIA3 =AC00
WORK2 =00DE
ZT =C22E
//0000,CDEA,1DEA

FNHF =0114
FHPHT =00D0
FHRPHT =0104
FNRC =0124
FOLSW =00DF
FOPMSW =00E2
FOURSUM =C273
FPACCE =00DB
FPDISP =DF23
FPLSWE =00D7
FPNORH =DC24
FPSUB =DCC0
FTOB =C937
FUEL =C971
FUELSA =C952
GEAR =0176
GRC =C611
GRCHG =C1EE
GRZ =C187
HLRPHTH =CDC8
HTOK =C220
I3TOF =C123
INIT1 =C01D
INITIAL =C047
INTVEC =A678
JMPTAB =CB42
KEY2 =CAF5
LABELA =C93F
LCNT1 =0088
LIM =C14D
LIRPHTH =CDCA
LOOP1 =CAB6
LOWER =C64C
LRPHEL =CDCC
MEMEND =007E
MFLG =001B
NON =8003
MOVEDATA =C36C
MOVEOUT =C3D7
MRPHTX =0011
NGR =0078
NUCHAN =000A
OFF =0046
OGR =0064
OUTBUF =00E6
OUTMSGS =CCF9
OUTPNT =001D
OUTTIME =001E
OVLCHK =C248
PARM =8220
RACKDISP =CB7F
READCLOCK =CC3F
RPHEH =0002
RSPTIME =0032
SAVE2 =87EA
SEC =C07B
SECSUM =C061
SEIFTIME =C15C
SETPORT =CD05
SFLG =0075
SFLG3 =000F
SHOWDISP =CAA3
SRACKH =000B
SSUM =C171
STOHIN =C345
STOS =C0A9
SUNF =C0BF
SUMFOUR =C0AC
TAPE =C106
TOPHT =00D2
VIA1 =A000
WORK0 =00DC
WORK3 =00DF
- =00E7

FNGR =0110
FNRCACK =010C
FNFF =0128
FNRE =0120
FDPEXP =00E3
FOPNSW =00E1
FP10 =D000
FPADD =DCC7
FPDIY =DDA5
FPMSW =00DA
FPNSW =00D9
FPTEMP =0100
FIJ =C99A
FUELDISP =CB63
FUELSAV =C94B
GONON =CB30
GRCALC =C648
GRCHK =C60D
GTDATA =CD37
HLRPHTL =CDCC9
I1TOF =C11F
INI3 =C03B
INIT2 =C025
INPRDI =00E7
IOEXPD =00E5
JMPVEC =0085
KEYCNT =008A
LASTSEC =008D
LCNT2 =0089
LIMIT =CD67
LIRPHTL =CDCB
LOOP2 =CABA
LRACKH =CDCE
MAIN =C000
MFFC =CDD8
MGEAR =0077
MONITOR =8000
MOVED =C3E3
NRACKX =0017
NEWHT =0076
NOOUT =C9ED
NUMBER =008E
OFFOUT =CA54
ORPH =005A
OUTBYT =82FA
OUTOF =C1E0
OUTPUT =CA1E
OUTXAH =82F4
OVRFLO =C948
PARM =A64A
RACKH =0004
RPHE =CD4F
RPHT =CD37
RSUM =C296
SAVTIME =D008
SECS =C16C
SETBYTE =CC82
SETIME =CBEC
SETUPCLOCK =CCC6
SFLG1 =001C
SFLG4 =0010
SHOWLOOP =CAA6
SRPHEH =0009
SIH =C0FA
STOPCLOCK =CCA3
STOSEC =C2R2
SUMFO =C0C2
SVAL =CRE4
TEMP1 =00E6
TRANCHK =C212
VIA2 =A800
WORK1 =00DD
X =00E7

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A Gear Selection Aid  
For Agricultural Tractors

by

DENNIS K. MATTESON

B.S., Kansas State University, 1979

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AN ABSTRACT OF A MASTERS THESIS

submitted in partial fulfillment of the  
requirements for the degree

MASTER OF SCIENCE

Department of Mechanical Engineering

KANSAS STATE UNIVERSITY  
Manhattan, Kansas

1987



A gear selection aid for agricultural tractors can be implemented and provide a savings to the operator. The technology necessary to implement the optimization is readily available and the financial incentive is rising as the cost of fuel prices increase. The purpose of this work was to design the hardware and develop the software required to assist the operators of a Model 3588 International Harvester tractor to operate the tractor at a more efficient engine speed and gear ratio.

The main criteria for development of the aid was 1) the unit be able to withstand the harsh environment associated with field equipment, 2) the unit easily be understood by the operator, 3) the unit have the confidence of the operator, 4) and the unit record data for analysis of savings. The unit consisted of three boxes and implemented some of the existing electronics on the tractor. The box containing the recording equipment would not be needed for final implementation. The design criteria was met, and the results were encouraging enough that research in the area of variable speed transmissions is now being pursued.

VITA

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Candidate for the Degree of

MASTER OF SCIENCE

Thesis: A Gear Selection Aid For Agricultural Tractors

Major Field: Mechanical Engineering

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