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# Stability of solutions to abstract evolution equations with delay

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## Abstract

An equation  $\dot{u} = A(t)u + B(t)F(t, u(t-\tau))$ ,  $u(t) = v(t)$ ,  $-\tau \leq t \leq 0$  is considered, where  $A(t)$  and  $B(t)$  are linear operators in a Hilbert space  $H$ ,  $\dot{u} = \frac{du}{dt}$ ,  $F : H \rightarrow H$  is a non-linear operator, and  $\tau > 0$  is a constant. Under some assumptions on  $A(t)$ ,  $B(t)$  and  $F(t, u)$  sufficient conditions are given for the solution  $u(t)$  to exist globally, i.e. for all  $t \geq 0$ , to be globally bounded, and to tend to zero at a specified rate as  $t \rightarrow \infty$ .

**MSC:** 34G20, 34K20, 37L05, 47J35

**Keywords:** abstract evolution problems; delay; stability; differential inequality.

## 1 Introduction

Consider an abstract evolution problem

$$\dot{u} = A(t)u + B(t)F(t, u(t-\tau)), \quad (1)$$

$$u(t) = v(t), \quad -\tau \leq t \leq 0 \quad (2)$$

where  $u(t) \in H$ ,  $H$  is a Hilbert space,  $A(t)$  and  $B(t)$  are linear operators in  $H$ ,  $F(t, u)$  is a nonlinear operator in  $H$ , and  $\tau > 0$  is a constant.

Let us assume that  $A(t)$  is a closed densely defined operator,  $D(A(t)) = D(A)$ ,  $D(A)$  is the domain of  $A(t)$ , independent of  $t$ , and

$$\operatorname{Re}(A(t)u, u) \leq -\gamma(t)(u, u), \quad (3)$$

$$\|B(t)\| \leq b(t), \quad (4)$$

$$\|F(t, u)\| \leq \alpha(t, g), \quad g := \|u(t)\|. \quad (5)$$

We assume that problem (1)-(2) has a unique local solution. Sufficient conditions for this can be found in the literature, see, e.g., [1].

We assume that the function  $\alpha(t, g) \geq 0$  satisfies a local Lipschitz condition with respect to  $g$ , is continuous with respect to  $t$  on  $[-\tau, \infty)$  and is non-decreasing with respect to  $g$ , and that functions  $b(t)$  and  $\gamma(t)$  are continuous on  $[-\tau, \infty)$ .

Our aim is to give sufficient conditions for global existence, that is, existence for all  $t \geq 0$ , global boundedness, and stability of the solution to problem (1)-(2).

There is a large literature on functional differential equations, see [1]-[4], and references therein. The method that we propose is new. A version of our method was used in a study of the Dynamical Systems Method (DSM) for solving operator equations, see [5]-[8]. This method is generalized in [6] to the case of abstract differential equations without delay and with persistently acting perturbations, see also a recent paper [9].

Our approach is as follows: multiply equation (1) by  $u(t)$  in  $H$  and take the real part to get

$$\operatorname{Re}(\dot{u}, u) = \operatorname{Re}(A(t)u(t), u(t)) + \operatorname{Re}(B(t)F(t, u(t - \tau)), u), \quad t \geq 0. \quad (6)$$

Let  $g(t) := \|u(t)\|$ . Then equation (6) yields an inequality

$$g\dot{g} \leq -\gamma(t)g^2 + b(t)\alpha(t, g(t - \tau))g, \quad t \geq 0. \quad (7)$$

Since  $g(t) \geq 0$ , inequality (7) implies

$$\dot{g}(t) \leq l(g) := -\gamma(t)g(t) + b(t)\alpha(t, g(t - \tau)), \quad t \geq 0, \quad (8)$$

and  $g(t) := \|v(t)\|$ ,  $-\tau \leq t \leq 0$ . Indeed, at the points at which  $g(t) > 0$ , inequality (7) is equivalent to (8) and  $\dot{g}(t) = \operatorname{Re}(\dot{u}, \frac{u(t)}{\|u(t)\|})$ .

If  $g(t) = 0$  on an open interval,  $t \in (a, b)$ , then  $\dot{g}(t) = 0$ ,  $t \in (a, b)$ , and inequality (8) holds since  $b(t) \geq 0$  and  $\alpha(t, g) \geq 0$ .

If  $g(s) = 0$  but in any neighborhood  $(s - \delta, s) \cup (s, s + \delta)$ ,  $g(t) \neq 0$  provided that  $\delta > 0$  is sufficiently small, then by  $\dot{g}(s)$  we understand the derivative from the right:

$$\dot{g}(s) = \lim_{h \rightarrow +0} g(s + h)h^{-1} = \|\dot{u}(s)\|. \quad (9)$$

Inequality (8) then follows from (7) by continuity as  $t \rightarrow s + 0$ .

The following lemma is key for our results.

**Lemma 1.** *If there exists a function  $\mu(t) > 0$ , defined for all  $t \geq -\tau$ , such that*

$$b(t)\alpha\left(t, \frac{1}{\mu(t-\tau)}\right)\mu(t) \leq \gamma(t) - \frac{\dot{\mu}(t)}{\mu(t)}, \quad t \geq 0, \quad (10)$$

and

$$\mu(t)g(t) \leq 1, \quad t \in [-\tau, 0], \quad (11)$$

then any solution  $g(t) \geq 0$  to inequality (8) exists for all  $t \geq 0$  and satisfies the following inequality:

$$0 \leq g(t) \leq \frac{1}{\mu(t)}, \quad \forall t \geq 0. \quad (12)$$

**Remark 1.** *If one proves inequality (12) for any  $t \geq 0$  for which  $g$  is defined, then, since  $\mu(t)$  is defined on all of  $\mathbb{R}_+ = [0, \infty)$ , inequality (12) implies that  $g(t) \geq 0$  is defined on all of  $\mathbb{R}_+$ . Moreover, if  $\lim_{t \rightarrow \infty} \mu(t) = +\infty$ , then  $\lim_{t \rightarrow \infty} g(t) = 0$ .*

*In section 2, we show how to choose  $\mu(t)$  and to use Lemma 1 in order to obtain estimates for the solution to problem (1)-(2).*

**Proof of Lemma 1.** Let us use inequality (8)

$$\dot{g}(t) \leq l(g). \quad (13)$$

Then inequalities (10) and (11) can be written as

$$l\left(\frac{1}{\mu(t)}\right) \leq \frac{d\mu^{-1}(t)}{dt}, \quad t \geq 0; \quad \mu^{-1}(t) \geq g(t) \quad t \in [-\tau, 0]. \quad (14)$$

Let  $w_n$  solve the problem

$$\begin{aligned} \dot{w}_n &= l(w_n) - \frac{1}{n}, \quad t \geq 0; \quad w_n(t) = g(t), \quad t \in [-\tau, 0], \\ n &= 1, 2, 3, \dots \end{aligned} \quad (15)$$

Let us prove that

$$w_n(t) \leq \mu^{-1}(t), \quad \forall t \geq 0. \quad (16)$$

If (16) is proved, then one takes into account that  $\lim_{n \rightarrow \infty} w_n = w$ , where

$$\dot{w} = l(w), \quad t \geq 0; \quad w(t) = g(t), \quad t \in [-\tau, 0], \quad (17)$$

and concludes, passing to the limit  $n \rightarrow \infty$ , that

$$w(t) \leq \mu^{-1}(t), \quad \forall t \geq 0. \quad (18)$$

An argument similar to the one that will lead to inequality (16) will also yield the inequality  $g(t) \leq w(t)$ ,  $t \geq 0$ . This inequality and (18) imply the desired conclusion (12).

Therefore, to complete the proof of (12), it is sufficient to prove (16). In order to prove (16), note that if  $w_n(0) < \mu^{-1}(0)$ , then there exists an interval  $(0, t_1)$ ,  $t_1 > 0$ , such that  $w_n(t) < \mu^{-1}(t)$  when  $t \in [0, t_1)$ . If  $w_n(0) = \mu^{-1}(0)$ , then

$$\dot{w}_n(0) = l(w_n)|_{t=0} - \frac{1}{n} < l(w_n)|_{t=0} = l(g)|_{t=0} \leq \frac{d\mu^{-1}(t)}{dt}|_{t=0},$$

where we have used the assumption about non-decreasing of  $a(t, g)$  with respect to  $g$  and the inequality  $\mu^{-1}(-\tau) \geq g(-\tau)$ , that follows from assumption (11). Consequently, one has

$$w_n(0) = \mu^{-1}(0), \quad \dot{w}_n(0) < \frac{d\mu^{-1}(t)}{dt}|_{t=0}.$$

Therefore, in this case there exists a number  $t_2 > 0$  such that on the interval  $(0, t_2)$  one has

$$w_n(t) < \mu^{-1}(t), \quad 0 < t < t_2. \quad (19)$$

Let  $t_3 := \min(t_1, t_2)$ . Let us prove that  $t_3 = \infty$ . Assume the contrary. Then there exists a (minimal)  $s > 0$ ,  $s = \sup t_3$ , such that

$$w_n(t) < \mu^{-1}(t), \quad t < s; \quad w_n(s) = \mu^{-1}(s). \quad (20)$$

At the point  $s$  the following inequalities hold:

$$\dot{w}_n(s) = l(w_n(s)) - \frac{1}{n} < l(w_n(s)) \leq l(\mu^{-1}(s)) \leq \frac{d\mu^{-1}(t)}{dt}|_{t=s}, \quad (21)$$

where the non-decreasing of  $a(t, g)$  with respect to  $g$  was used, and the inequality  $w_n(s - \tau) < \mu^{-1}(s - \tau)$ , which is a consequence of inequality (20), was taken into account. Thus,

$$\dot{w}_n(s) < \frac{d\mu^{-1}(t)}{dt}|_{t=s}.$$

By continuity, one has

$$\dot{w}_n(t) < \frac{d\mu^{-1}(t)}{dt}, \quad s - \delta \leq t \leq s, \quad (22)$$

for a sufficiently small  $\delta > 0$ .

Integrate (22) on the interval  $[s - \delta, s]$  and get

$$w_n(s) - w_n(s - \delta) < \mu^{-1}(s) - \mu^{-1}(s - \delta). \quad (23)$$

Since  $w_n(s) = \mu^{-1}(s)$ , inequality (23) implies

$$\mu^{-1}(s - \delta) < w_n(s - \delta). \quad (24)$$

This inequality contradicts inequality (20). This contradiction proves that the assumption  $t_3 < \infty$  is false, so  $t_3 = \infty$ . Consequently,

$$w_n(t) < \mu^{-1}(t), \quad \forall t > 0. \quad (25)$$

Passing to the limit  $n \rightarrow \infty$  in (25), one gets (18).

A similar argument proves that

$$g(t) \leq w(t), \quad \forall t \geq 0. \quad (26)$$

Combining inequalities (18) and (26), one obtains (12).

Lemma 1 is proved.  $\square$

## 2 Estimates of solutions to evolution problem

Let us apply Lemma 1 to the solution of problem (1) - (2).

In order to choose  $\mu(t)$ , let us assume that

$$\gamma(t) = \gamma = \text{const} > 0, \quad b(t) \leq \frac{\gamma}{2}, \quad \alpha(t, g) \leq c_0 g^p, \quad (27)$$

where  $c_0 > 0$  and  $p > 1$  are constants, and  $b(t) \geq 0$ ,  $\alpha(t, g) \geq 0$  and  $\alpha(t, g)$  is non-decreasing with respect to  $g$ .

Let us choose

$$\mu(t) = \lambda e^{\nu t},$$

where  $\lambda$  and  $\nu$  are positive constants. Then  $\frac{\dot{\mu}}{\mu} = \nu$ . Choose  $\nu = 0.5\gamma$ . Inequality (10) holds if

$$c_0 \lambda^{1-p} e^{0.5\gamma(p-1)\tau} \leq 1. \quad (28)$$

Define  $\Gamma := \max_{t \in [-\tau, 0]} |g(t)|$ . Then inequality (11) holds if

$$\Gamma \leq \lambda^{-1}. \quad (29)$$

Choose  $\lambda = \Gamma^{-1}$ . Then inequality (29) holds. Inequality (28) holds if

$$c_0 \Gamma^{p-1} e^{0.5(p-1)\gamma\tau} \leq 1. \quad (30)$$

Inequality (30) holds if  $c_0$  is sufficiently small, or if  $\Gamma$  is sufficiently small. The last conclusion is based on the assumption  $p > 1$ .

We have proved the following theorem.

**Theorem 1.** *Assume that (3) holds with  $\gamma(t) = \gamma = \text{const} > 0$ , (4) holds with  $b(t) \leq \frac{\gamma}{2}$ , (27) and (30) hold. Then the solution to problem (1)-(2) exists for all  $t \geq 0$  and satisfies the following inequality*

$$\|u(t)\| \leq \Gamma^{p-1} e^{-0.5\gamma t}, \quad \forall t \geq 0. \quad (31)$$

Estimate (31) of Theorem 1 implies *exponential stability* of the solution to problem (1)-(2). One could assume that  $\gamma$  depends on  $t$ . This will be done in the next example.

Consider now the case when  $\gamma = \gamma(t)$  tends to zero as  $t \rightarrow \infty$ .

Assume that

$$\gamma(t) = \frac{c_1}{(1+t)^{m_1}}, \quad b(t) \leq \frac{c_2}{(1+t)^{m_2}}, \quad \alpha(t, g) \leq \frac{c_3}{(1+t)^{m_3}} g^p, \quad (32)$$

where  $c_j, m_j > 0$ ,  $j = 1, 2, 3$ , and  $p > 1$  are constants, and  $\alpha(t, g)$  is non-decreasing with respect to  $g$ .

Choose  $\mu(t)$  of the form

$$\mu(t) = \lambda(1+t+\tau)^\nu, \quad \lambda, \nu > 0, \quad (33)$$

where  $\lambda$  and  $\nu$  are positive constants. Then

$$\frac{\dot{\mu}(t)}{\mu(t)} = \frac{\nu}{1+t+\tau} \leq \frac{\nu}{1+\tau}, \quad t \geq 0.$$

Denote, as above,  $\Gamma := \max_{t \in [-\tau, 0]} |g(t)|$ . Then inequalities (10) and (11) hold if

$$\frac{c_2 c_3 \Gamma^{p-1}}{(1+t)^{m_2+m_3+(p-1)\nu}} \leq \frac{c_1}{(1+t)^{m_1}} - \frac{\nu}{1+t}, \quad t \geq 0, \quad (34)$$

$$\lambda \Gamma \leq 1. \quad (35)$$

Inequality (35) holds if  $\lambda = \Gamma^{-1}$ .

Assume that

$$m_2 + m_3 + (p-1)\nu \geq 1, \quad m_1 \leq 1. \quad (36)$$

Then inequality (34) holds for all  $t \geq 0$  provided that

$$c_2 c_3 \Gamma^{p-1} \leq c_1 - \nu. \quad (37)$$

Inequality (37) holds if  $\nu < c_1$  and  $c_2 c_3$  is sufficiently small. If these conditions are satisfied then, by Lemma 1, one gets

$$\|u(t)\| \leq \frac{\Gamma}{(1+t+\tau)^\nu}, \quad \forall t \geq 0. \quad (38)$$

We have proved the following theorem

**Theorem 2.** *Assume that (32) and (36) hold,  $\lambda = \frac{1}{\Gamma}$ ,  $\nu < c_1$ , and  $c_2 c_3$  is sufficiently small that (37) holds. Then the solution to problem (1)-(2) exists for all  $t \geq 0$ , and estimate (38) holds.*

Our method, based on lemma 1, is very flexible and applicable to many other problems, see, for example, [6]-[8]. If the delay is absent in the abstract differential equation (1), then the assumption that  $\alpha(t, g)$  is non-decreasing with respect to  $g$  can be dropped, see [6].

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