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## INTRODUCTION

## Problem Statement and Scope

The objective of this thesis is to present an ultimate strength analysis of composite beams with web openings. A composite beam is defined as a steel W shape acting together with a concrete slab to resist transverse loads. An opening located in the web of the steel section is usually introduced to permit the passage of utility ducts and piping. Figures 1 and 2 show elevation and cross section views of a composite beam with a web opening.

The analysis is limited in scope by the physical characteristics of the beam, and the type of failure assumed at the opening. The slab thickness is limited to the range of values normally encountered in practice, and the slab width is taken to be the effective width, which is determined in the usual manner (11). A sufficient number of shear connectors are assumed to be present so that full composite action is attained. The opening is limited to a rectangular shape, which can be located anywhere on the span, and can be concentric (mid-depth of opening coincides with mid-depth of steel shape) or eccentric. Only unreinforced openings are considered. Failure is limited to yielding only, i.e., buckling and instability failures are not considered.

## Review of Previous Ultimate Strength Analyses

In the past decade a number of investigators have developed ultimate strength analyses of non-composite beams with rectangular web openings. All of these analyses lead to the development of an interaction diagram which shows the relationship between moment and shear acting at an opening at failure. Several basic assumptions are common to these
analyses. A failure mechanism is assumed to form with plastic hinges located at the sections above and below each edge of the opening. Failure due to instability is not considered. Equilibrium conditions are satisfied. Yielding occurs in the flanges due to tension or compression, and yielding in the web due to combined shear and normal stresses follows von Mises yield criterion (10). The presence of shear causes secondary moments in the top and bottom sections. None of the analyses take into consideration the beneficial effect of strain hardening.

The first analysis, which was concerned with concentric openings with no reinforcement, was developed by Bower (1). The possibility of the web and flanges having different yield stresses was provided for in this analysis. The shear force was applied only to that portion of the web which was also assigned the secondary moment. Later, in dealing with the same case, Redwood chose to have the same yield stress throughout the section, and also assigned the shear force uniformly along the total depth of the remaining web (7). Redwood's revisions were incorporated into subsequent analyses of concentric reinforced openings by Congdon and Redwood (2), eccentric unreinforced openings by both Frost (4) and Richard (8), and the most general case of eccentric reinforced openings by Wang (12).

New insight for the analysis of beams with web openings was presented in a report by McCormick (6). By the use of two new concepts, McCormick developed a much simpler analysis than any of those previously presented. One of these concepts is to assign a moment due to eccentricity, $M_{e}$, in the larger tee section to represent the stresses in that section. As in previous analyses, the shear force was assigned to the full web stub
length, but in applying von Mises criterion the web thickness was reduced according to the value of shear present, so that the effect of the shear stress can be ignored throughout the remainder of the calculations. Because of these new concepts--introduction of $\mathrm{M}_{\mathrm{e}}$ and reduction of the web thickness for shear--axial forces and moments, instead of stress blocks, were used in a statical method for a lower bound approach which leads to a simpler analysis.

A comparison between Redwood's and McCormick's analyses was made by Scritchfield, who concluded that "McCormick's method of analysis was found to be better suited for extension to the eccentric case" (9). Scritchfield applied McCormick's method to the case of eccentric unreinforced web openings by the use of a computer program, which when compared with earlier programs using Redwood's method, gave the same results. It was also proved that the points of contraflexure are at the center of the opening.

The only material reviewed pertaining to ultimate strength analysis of composite beams with web openings was that found in McCormick's report (6). In the report, McCormick performs an analysis of a specific composite beam with known dimensions and material properties, having two circular web openings with varying types of reinforcement. The assignment of internal forces is carried out in a manner similar to that used for non-composite beams. The concrete slab is assumed to carry no shear. An equivalent rectangular opening having a depth of 0.9 D and a width of 0.45 D , where $D$ is the diameter of the circular opening, is assumed for the failure mode consisting of a four hinge mechanism at one opening. McCormick also assumes a constant distance between the axial forces in the top and bottom tees instead of determining this distance from beam properties for each value of total shear force.

The analysis presented in this thesis has many assumptions in common with McCormick's analysis, but is developed for general beam geometry and material properties, and for a single rectangular opening of any practical depth, width, and position.

## ULTIMATE STRENGTH ANALYSIS

## Assumptions

The ultimate strength analysis is based on the following assumptions:

1. The compressive strength of the concrete in bending is assumed to be $0.85 f_{c}^{\prime}$ and the Whitney stress block is used.
2. The tensile strength of the concrete is neglected; therefore yielding in the concrete is by compression only.
3. Yielding in the steel flanges is by compression or tension only.
4. Shear, which causes secondary bending in the sections above and below the opening, is carried in the web only, and is uniformly distributed.
5. Yielding in the web of the steel section due to combined shear and normal stresses follows von Mises yield criterion.
6. Equilibrium is satisfied.
7. Points of contraflexure occur at the midpoints of the sections above and below the opening.
8. Failure occurs by the formation of a mechanism with hinges at sections above and below the edges of the opening. (Fig. 3).
9. The possibility of failure due to instability and the beneficial effects of strain hardening are not considered.

## Outline of Solution

The solution is divided into two parts, designated Case I and Case II. Case I is called the low shear case, during which all of the total shear force, $V$, assigned to the beam is carried by the top tee, i.e., the shear in the top tee, $\mathrm{V}_{\mathrm{T}}$, equals the total shear V . Because no shear force is assigned to the bottom tee in Case I, the capacity of the bottom tee is used solely for the axial force $P_{B}$, which, when combined with an equal force in the slab, gives the primary moment, $P_{B}{ }_{c}$.

A special situation to consider at the outset of Case I is that of pure bending, i.e. $V=0$, (Fig. 4a). The total capacity of the top tee is assigned to the axial force $P_{T}$, which, when combined with an equal
force in the slab, results in the moment due to eccentricity, $M_{e}=P_{T}{ }^{d} e$. The moment capacity at the centerline of the opening is the sum of the primary moment, $\mathrm{P}_{\mathrm{B}} \mathrm{d}_{\mathrm{c}}$, and $\mathrm{M}_{\mathrm{e}}$.

When the shear force in Case $I$ is non-zero, the web thickness, $t_{w}$, of the top tee is reduced to $\mathrm{w}_{\mathrm{T}}$ according to von Mises yield criterion, so that all the fibers in the reduced steel section will be at the yield stress. A secondary moment due to shear, $M_{V T}=V_{T} a$ is induced in the top tee (Fig. 4b). This causes a reduction in $\mathrm{P}_{\mathrm{T}}$ and likewise in $\mathrm{M}_{\mathrm{e}}$. The total moment capacity at the centerline of the opening is still the sum of the primary moment, $P_{B}{ }_{c}$, and $M_{e}$. The upper limit of Case $I$ is reached when the total top tee is yielded due to $V_{T}$ and $M_{V T}$, so that $M_{e}$ is equal to zero.

Case II (Fig. 4c) is called the high shear case during which part of the total shear goes to the top tee and the rest goes to the bottom tee. The amount of the total shear assigned to the top tee is governed by the capacity of the top tee section for $\mathrm{V}_{\mathrm{T}}$ and $\mathrm{M}_{\mathrm{VT}}=\mathrm{V}_{\mathrm{T}}$ a. The amount of shear remaining when this capacity is reached is the shear assigned to the bottom tee, $V_{B}$. With shear present, the web thickness of the bottom tee is reduced to $W_{B}$, and a secondary moment due to shear, $M_{V B}=V_{B} a$, is induced. The axial force $P_{B}$ is assigned to that portion of the bottom tee not used for $V_{B}$ or $M_{V B}$. The force $P_{B}$, along with an equal force in the concrete slab, gives the primary moment, which is the total moment capacity at the centerline of the opening, because $M_{e}$ is zero throughout Case II.

## Development of Basic Equations

Reference Values. At the outset, a number of reference values are defined. The length of the web stubs above and below the opening are (Fig. 2)

$$
\begin{align*}
& s_{T}=\frac{1}{2} d-e-h-t  \tag{1}\\
& s_{B}=\frac{1}{2} d+e-h-t \tag{2}
\end{align*}
$$

The shear capacities of the top and bottom web stubs by definition are

$$
\begin{align*}
& \mathrm{v}_{\mathrm{yT}}=\frac{s_{T} \mathrm{t}_{\mathrm{w}} \mathrm{~F}_{\mathrm{y}}}{\sqrt{3}}  \tag{3}\\
& \mathrm{~V}_{\mathrm{yB}}=\frac{s_{B} \mathrm{t}_{\mathrm{w}} \mathrm{~F}_{\mathrm{y}}}{\sqrt{3}} \tag{4}
\end{align*}
$$

From Fig. 5a, the shear capacity of the web without the opening (the gross web area) is

$$
\begin{equation*}
V_{P}=\frac{(d-2 t) t_{w} F_{y}}{\sqrt{3}} \tag{5}
\end{equation*}
$$

The total plastic moment of the gross composite section, $\mathrm{M}_{\mathrm{Pc}}$, is the final reference value required. Two expressions for $M_{P c}$ are possible depending on the location of the plastic neutral axis, $N A_{p}$ of the gross composite section. To determine where this neutral axis is, a comparison is made between the total axial force capacity of the concrete slab

$$
\begin{equation*}
P_{y c}=b_{c} c F_{c} \tag{6}
\end{equation*}
$$

and the total axial force capacity of the gross steel section

$$
\begin{equation*}
P_{y s}=\left(t_{w}(d-2 t)+2 b t\right) F_{y} \tag{7}
\end{equation*}
$$

If $P_{y c}$ is greater than $P_{y s}$, then the $N A_{P}$ is in the concrete slab as shown in Fig. 5a. The thickness of concrete used to give a force in the concrete slab equal to that of the steel section is given by

$$
\begin{equation*}
c_{P_{s}}=\frac{P_{y s}}{b_{c} F_{c}} \tag{8}
\end{equation*}
$$

This is the thickness of the concrete above the $\mathrm{NA}_{\mathrm{P}}$; the concrete below the $N A_{P}$ is disregarded or "thrown away" because it is in tension. The
value of the total plastic moment is found by summing the moments about the $\mathrm{NA}_{\mathrm{P}}$ resulting in

$$
\begin{equation*}
M_{P c}=\left(\frac{1}{2} b c_{c} c_{s}^{2}\right) F_{c}+\left(\frac{3}{2} d+c-c_{P s}\right) P_{y s} \tag{9}
\end{equation*}
$$

If $P_{y c}$ is less than $P_{y s}$, the $N A_{P}$ is in the top steel flange as in Fig. 5b. To find its location, a thickness $t_{t}$ is assigned to the portion of the flange which is in tension below the $N A_{P}$. By setting the forces above and below the $N A_{P}$ equal to each other, the value of $t_{t}$ is

$$
\begin{equation*}
t_{t}=\frac{b_{c} c F_{c}-t_{w}(d-2 t) F_{y}}{2 b F_{y}} \tag{10}
\end{equation*}
$$

Now by summing moments about the $\mathrm{NA}_{\mathrm{P}}$, the total plastic moment is

$$
\begin{align*}
M_{P c}= & b_{c} c\left(\frac{1}{2} c+t-t_{t}\right) F_{c}+\left[t_{w}(d-2 t)\left(\frac{1}{2} d-t+t_{t}\right)\right. \\
& \left.+\frac{1}{2} b\left(t-t_{t}\right)^{2}+\frac{1}{2} b t_{t}^{2}+b t\left(d-\frac{3 t}{2}+t_{t}\right)\right] F_{y} \tag{11}
\end{align*}
$$

Low Shear Solution. The following discussion of the analysis is divided into two major parts: Case I being the low shear case and Case II being the high shear case. In Case I, the total shear force is applied to the top tee, i.e. $\mathrm{V}_{\mathrm{T}}=\mathrm{V}$. In assigning this shear force to the web, a portion of the web thickness is removed due to yielding in shear and with the use of von Mises yield criterion, the remaining web thickness used to carry normal stresses is

$$
\begin{equation*}
w_{T}=t_{w} \sqrt{1-3\left(\frac{V_{T}}{s_{T} t_{w} F_{y}}\right)^{2}} \tag{12}
\end{equation*}
$$

When $\mathrm{V}_{\mathrm{T}}$ is equal to zero the special case of pure bending occurs. In this case, the secondary moment due to shear, $\mathrm{M}_{\mathrm{VT}}$, is equal to zero and $\mathrm{w}_{\mathrm{T}}$ equals $t_{w}$.

Because no shear is applied to the bottom steel tee, it provides a constant axial tensile force, $P_{B}$, throughout the low shear case (Fig. 6)

$$
\begin{equation*}
P_{B}=\left(t_{w} s_{B}+b t\right) F_{y} \tag{13}
\end{equation*}
$$

Force $P_{B}$ has a corresponding compressive force in the concrete slab. The thickness of the concrete slab required for $P_{B}$ is assigned starting from the top of the slab and is determined by

$$
\begin{equation*}
c_{P B}=\frac{P_{B}}{b_{c} F_{c}} \tag{14}
\end{equation*}
$$

The forces in the bottom tee and concrete slab combine to give the primary moment. To find this moment, the distance between the centroids of the two forces must be found. From Fig. 6, the distance from the top edge of the opening to the line of action of the force in the concrete slab is

$$
\begin{equation*}
y_{c}=s_{T}+t+c-\frac{1}{2} c_{P B} \tag{15}
\end{equation*}
$$

while the distance from the bottom edge of the opening to the line of action of the force in the bottom tee is

$$
\begin{equation*}
y_{B}=\frac{\frac{1}{2} t_{w} s_{B}^{2}+b t\left(s_{B}+\frac{1}{2} t\right)}{t_{w} s_{B}+b t} \tag{16}
\end{equation*}
$$

The lever arm of these forces is

$$
\begin{equation*}
\mathrm{d}_{\mathrm{c}}=\mathrm{y}_{\mathrm{c}}+2 \mathrm{~h}+\mathrm{y}_{\mathrm{B}} \tag{17}
\end{equation*}
$$

thus the primary moment is defined as the product, $P_{B}{ }_{c}$.
There are two cases to consider in the low shear analysis of the top steel tee - concrete slab section shown in Fig. 7 after the portion of the slab due to the primary moment is removed. These are Case IA in which all the remaining slab in Fig. 7 is used and Case IB in which only part of the slab is used. The location of the $N A_{P}$ in the flange or the slab of the section in Fig. 7 determines at the outset which case applies. To determine this location, the axial force capacities of the slab with thickness

$$
\begin{equation*}
c_{r}=c-c_{P B} \tag{18}
\end{equation*}
$$

and the steel tee are required. They are respectively, (Fig. 7)

$$
\begin{equation*}
P_{y c r}=b_{c} c_{r} F_{c} \tag{19}
\end{equation*}
$$

and

$$
\begin{equation*}
p_{\overline{\mathbf{y}} T}=\left(s_{T} w_{T}+b t\right) F_{y} \tag{20}
\end{equation*}
$$

If $P_{y c r}$ is less than $P_{y T}$, then the $N A_{P}$ is in the flange. Referring to Fig. 8, the distance to the $N A_{P}$ in the flange is found by setting the forces above and below equal to each other resulting in

$$
\begin{equation*}
y=s_{T}+\frac{\gamma_{2}}{2} t-\frac{s_{T} w_{T}}{2 b}+\frac{b_{c} c_{r} F_{c}}{2 b F_{y}} \tag{21}
\end{equation*}
$$

Now the total moment capacity of this section by summing the moments about the $N A_{p}$ is

$$
\begin{align*}
M_{c a p}= & b_{c} c_{r}\left(s_{T}+t-y+\frac{1}{2} c_{r}\right) F_{c}+\left[s_{T} w_{T}\left(y-\frac{1}{2} s_{T}\right)\right. \\
& \left.+\frac{1}{2} b\left(y-s_{T}\right)^{2}+\frac{3}{2} b\left(s_{T}+t-y\right)^{2}\right] F_{y} \tag{22}
\end{align*}
$$

When a non-zero shear is imposed, a certain portion of the top steel tee is assigned a moment due to shear

$$
\begin{equation*}
M_{V T}=V_{T} a \tag{23}
\end{equation*}
$$

This shear moment is assigned to the extreme top and bottom edges of the steel tee moving inward and is restricted by the location of the $N A_{p}$ shown in Fig. 9. The portion of the flange above the $N A_{P}$ is

$$
\begin{equation*}
t_{V}=s_{T}+t-y \tag{24}
\end{equation*}
$$

and a depth of web

$$
\begin{equation*}
s_{V}=\frac{b t_{v}}{w_{T}} \tag{25}
\end{equation*}
$$

is found such that the area of the flange above the $N A_{P}$ is equal to the area of the web corresponding to the depth $s_{V}$. If $s_{V}$ is less than $s_{T}$ as
shown in Fig. 9a, then the distance between the centroids of the two forces is $s_{T}+t-\frac{1}{2} t V_{V}-\frac{1}{2} s_{V}$, and the maximum $M_{V T}$ allowed is the force times its lever arm

$$
\begin{equation*}
M_{V \max }=b t_{V}\left(s_{T}+t-\frac{2}{2} t_{V}-\frac{2}{2} s_{V}\right) F_{y} \tag{26}
\end{equation*}
$$

When $s_{V}$ is greater than $s_{T}$ (Fig. 9b), the bottom portion of $M_{V T}$ goes into the flange a thickness

$$
\begin{equation*}
t_{V W}=\frac{-s_{T} W_{T}+b t_{V}}{b} \tag{27}
\end{equation*}
$$

Summing moments about the $\mathrm{NA}_{\mathrm{P}}$ gives

$$
\begin{equation*}
M_{V \max }=\left[s_{T} w_{T}\left(y-\frac{1}{2} s_{T}\right)+\frac{2}{2} b t_{V}^{2}+b t_{V W}\left(t-\frac{1}{2} t_{V W}-t_{V}\right)\right] F_{y} \tag{28}
\end{equation*}
$$

In both cases ( $s_{V}$ greater than or less than $s_{T}$ ), if $M_{V T}$ is less than $M_{V_{\max }}$, then the moment due to eccentricity is

$$
\begin{equation*}
M_{e}=M_{c a p}-M_{V T} \tag{29}
\end{equation*}
$$

and the total moment capacity of the beam with the web opening is

$$
\begin{equation*}
M=P_{B} d_{c}+M_{e} \tag{30}
\end{equation*}
$$

When $M_{V T}$ is greater than $M_{V m a x}$, part of the slab is "thrown away" and Case IB is encountered.

Case IB with the NA $P$ in the slab also occurs when $P_{y c r}$ is greater than $P_{y T}$ (Fig. 7). This second major breakdown of the low shear case has two further divisions - if $s_{V}$ (as described previously) is less than or greater than $\mathbf{s}_{\mathrm{T}}$.

When $s_{V}$ is less than $s_{T}$ as in Fig. 10a, knowing that the areas in the web and flange must be equal, the thickness of the flange used for $M_{V T}$ is

$$
\begin{equation*}
t_{v}=\frac{s_{v} w_{T}}{b} \tag{31}
\end{equation*}
$$

Using the force and lever arm, M becomes

$$
\begin{equation*}
M_{V T}=s_{V} w_{T}\left(s_{T}+t-\frac{1}{2} t_{V}-\frac{1}{2} s_{V}\right) F_{y} \tag{32}
\end{equation*}
$$

but is also equal to $\mathrm{V}_{\mathrm{T}} \mathrm{a}$. Setting these two equations equal and substituting for ${ }{ }_{v}$ gives

$$
\begin{equation*}
\left(\frac{2}{2}+\frac{w_{T}}{2 b}\right) s_{V}^{2}-\left(s_{T}+t\right) s_{V}+\frac{V_{T} a}{w_{T} F_{y}}=0 \tag{33}
\end{equation*}
$$

This quadratic equation can be solved for $s_{V}$, after which $t_{V}$ can be determined from Eq. 31. Now the remaining portions of the web

$$
\begin{equation*}
s_{P}=s_{T}-s_{v} \tag{34}
\end{equation*}
$$

and the flange

$$
\begin{equation*}
t_{P}=t-t_{v} \tag{35}
\end{equation*}
$$

are used to find the axial tensile force component of $M_{e}$ which is

$$
\begin{equation*}
P_{T}=\left(s_{P} w_{T}+b t_{p}\right) F_{y} \tag{36}
\end{equation*}
$$

An equal force is assigned in the slab starting down at the point where $c_{P B}$ stops until the thickness as given by

$$
\begin{equation*}
c_{P T}=\frac{P_{T}}{b_{c} F_{c}} \tag{37}
\end{equation*}
$$

is reached. Summing the moments of these two forces about the $\mathrm{NA}_{P}$ (which is at the bottom of the slab being used) gives

$$
\begin{align*}
M_{e}= & \frac{1}{2} b_{c} c_{P T}{ }^{2} F_{c}+\left[s_{P} w_{T}\left(c_{r}-c_{P T}+t+\frac{1}{2} s_{P}\right)\right. \\
& \left.+b t_{P}\left(c_{r}-c_{P T}+t_{V}+\frac{3}{2} t_{P}\right)\right] F_{y} \tag{38}
\end{align*}
$$

When $s_{V}$ is greater than $s_{T}$, the bottom portion of ${ }^{M}{ }_{V T}$ goes into the bottom of the flange as in Fig. 10b. The thickness of flange above line XX on the top tee steel section now becomes by setting the forces above and below line XX equal

$$
\begin{equation*}
t_{V}=\frac{s_{T} w_{T}}{b}+t_{V w} \tag{39}
\end{equation*}
$$

Summing moments about the line XX gives

$$
\begin{equation*}
M_{V T}=\left[s_{T} w_{T}\left(t-t_{V}+\frac{3}{2} s_{T}\right)+\frac{3}{2} b t_{V}^{2}+b t_{V W}\left(t-t_{V}-\frac{1}{2} t_{V_{W}}\right)\right] F_{y} \tag{40}
\end{equation*}
$$

Equating Eqs. 23 and 40 and substituting for $t_{V}$ results in

$$
\begin{equation*}
b t_{V w}^{2}+\left(s_{T} w_{T}-b t\right) t_{V w}-s_{T} w_{T}\left(t+\frac{b_{2}}{} s_{T}\right)+\frac{V_{T} a}{F_{y}}+\frac{\left(s_{T} w_{T}\right)^{2}}{2 b}=0 \tag{41}
\end{equation*}
$$

which can be solved for ${ }^{t_{V_{w}}}$. Knowing ${ }^{t}{ }_{V_{w}}$, ${ }^{t_{V}}$ is found by Eq. 39 and the thickness of the flange assigned for the axial force, $\mathrm{P}_{\mathrm{T}}$, is

$$
\begin{equation*}
t_{P}=t-t_{V}-t_{V W} \tag{42}
\end{equation*}
$$

The magnitude of the axial force is

$$
\begin{equation*}
P_{T}=b t_{P} F_{y} \tag{43}
\end{equation*}
$$

and the corresponding force equal to it in the slab has thickness $c_{P T}$ as determined by Eq. 37. The moment due to eccentricity is found by summing the moments about the $\mathrm{NA}_{P}$ which gives

$$
\begin{equation*}
M_{e}=\frac{\frac{1}{2}}{} c_{P T} P_{T}+\left(c_{r}-c_{P T}+t_{V}+\frac{\frac{3}{2} t_{P}}{}\right) P_{T} \tag{44}
\end{equation*}
$$

In both cases when the slab is not completely used, the total plastic moment capacity is given by Eq. 30 .

High Shear Solution. The second major case, Case II, is called high shear, in which part of the total shear goes to the bottom tee and all the top tee capacity is utilized to resist $V_{T}$ and $M_{V T}$. Because the capacity of the top tee is used entirely for $V_{T}$ and $M_{V T}, M_{e}$ is zero throughout Case II. To find the capacity for $V_{T}$ and $M_{V T}$ of the top tee, a trial and error method is applied using four equations. The first is the expression for $w_{T}$ as given by Eq. 12. The second equation, referring to Fig. 11, gives the thickness of the flange below the $N A_{P}$ of the top

$$
\begin{equation*}
t_{x}=\frac{-s_{T} w_{T}+b t}{2 b} \tag{45}
\end{equation*}
$$

Equation 23 is the third equation required, and the last one is found by summing moments about the $\mathrm{NA}_{\mathrm{p}}$ in Fig. 11

$$
\begin{equation*}
M_{V T 1}=\left[s_{T} W_{T}\left(t_{x}+\frac{3}{2} s_{T}\right)+\frac{1}{2} b t_{x}^{2}+\frac{1}{2} b\left(t-t_{x}\right)^{2}\right] F_{y} \tag{46}
\end{equation*}
$$

Assuming a value of $\mathrm{V}_{\mathrm{T}}, \mathrm{M}_{\mathrm{VT}}$ and $\mathrm{M}_{\mathrm{VTI}}$ are calculated and compared and $\mathrm{V}_{\mathrm{T}}$ is adjusted until they are equal, giving the capacity of the top tee for $V_{T}$ and $M_{V T}$. These values of $V_{T}$ and $M_{V T}$ are constant throughout the high shear case. With the shear assigned to the top tee known, the shear assigned to the bottom tee is

$$
\begin{equation*}
\mathrm{V}_{\mathrm{B}}=\mathrm{V}-\mathrm{V}_{\mathrm{T}} \tag{47}
\end{equation*}
$$

and the moment due to shear in the bottom tee is

$$
\begin{equation*}
M_{V B}=V_{B} a \tag{48}
\end{equation*}
$$

Because the bottom tee now has shear assigned to it, it has a reduced web thickness

$$
\begin{equation*}
w_{B}=t_{w} \sqrt{1-3\left(\frac{v_{B}}{s_{B} t_{w} F_{y}}\right)^{2}} \tag{49}
\end{equation*}
$$

At this point, the treatment of the bottom tee is very similar to that of the top tee in the low shear case where the $N A_{P}$ of the top tee remaining concrete slab section was in the slab. The calculations are the same for the bottom tee as the top tee in both cases ( $s_{V}$ greater than or less than $s_{T}$ ) to the point where the portions of the tee used for the axial force $P_{B}$ are found.

When $s_{V}$ is less than $s_{T}$, the axial force is (Fig. 12a)

$$
\begin{equation*}
P_{B}=\left(s_{p} W_{B}+b t_{p}\right) F_{y} \tag{50}
\end{equation*}
$$

The corresponding axial force in the concrete is assigned to the slab
starting at the top and having thickness $c_{P B}$ as given by Eq. 14. The distance, $y_{c}$, from the top edge of the opening to the line of action of the force $P_{B}$ in the concrete is expressed by Eq. 15 and the distance from the bottom edge of the opening to the centroid of the force $P_{B}$ in the bottom steel tee is

$$
\begin{equation*}
y_{B}=\frac{\frac{3}{2} s_{p}{ }^{2} w_{B}+b t_{P}\left(s_{P}+\frac{3}{2} t_{p}\right)}{s_{p} w_{B}+b t_{p}}+s_{V} \tag{51}
\end{equation*}
$$

The moment arm, $\mathrm{d}_{c}$, of the forces is determined by Eq. 17 , and is used to find the total plastic moment, which is

$$
\begin{equation*}
\mathrm{M}=\mathrm{P}_{\mathrm{B}} \mathrm{~d}_{\mathrm{c}} \tag{52}
\end{equation*}
$$

because $\mathrm{Me}_{\mathrm{e}}$ is zero.
In the other case of $s_{V}$ being greater than $s_{T}$, the axial force is (Fig. 12b)

$$
\begin{equation*}
P_{B}=b t_{P} F_{y} \tag{53}
\end{equation*}
$$

Again the same force in the concrete is assigned starting at the top of the slab and having thickness $c_{P B}$, which is calculated from Eq. 14. The distance $y_{c}$ to the line of action of the force $P_{B}$ in the concrete from the top edge of the opening is given by Eq. 15, while the distance from the bottom edge of the opening to the centroid of the force $P_{B}$ in the bottom steel tee is

$$
\begin{equation*}
y_{B}=s_{B}+t_{V w}+\frac{1}{2} t_{P} \tag{54}
\end{equation*}
$$

The moment arm $d_{c}$ of the two forces is determined by Eq. 17 , and the total moment capacity as before is found using Eq. 52.

## Calculation of Interaction Diagrams

This section presents the sequence of calculations used in developing
a shear-moment interaction diagram. A broad view of the entire sequence with all cases will be presented first, with the details of each individual case considered later.

Figure 13 is the overall flow diagram of the procedure followed in developing an interaction diagram. First, after input data is read, reference values for a composite beam with known dimensions and material properties are calculated. One limit set on the solution at the outset is that the total axial force capacity of the bottom tee, $P_{B}$, must be less than the total axial force capacity of the concrete slab, $\mathrm{P}_{\mathrm{yc}}{ }^{\circ}$. This limit is used since a composite beam with the force $P_{B}$ greater than the force $P_{y c}$ is an impractical case, and therefore not considered here.

If $P_{B}$ is less than $P_{y c}$, the input and reference values are printed, after which the total shear, $\mathrm{V},\left(\mathrm{V}=\mathrm{V}_{\mathrm{T}}\right.$ in Case I$)$ is initialized to zero. The value by which the total shear is incremented is 1.0 and is labeled $\mathrm{V}_{\text {inc }}$. Later, as the interaction diagram is developed, its slope becomes steeper, requiring a smaller increment of shear, i.e., $\mathrm{v}_{\text {inc }}=0.1$.

At this point a program control, "check", is also set equal to zero. When "check" is equal to zero, a further decision is needed before going to Case IA or IB. When Case IB is used once, "check" is set equal to one, so that the solution process returns to Case IB.

The next decision deals with the total axial force capacities of the top steel tee and the remaining concrete slab (thickness $c_{r}$ ), which are $P_{y T}$ and $P_{y c r}$, respectively. Details of this decision step were discussed in the previous section. After this decision, the solution continues to either Case IA or Case IB, both of which are shown in more detail in Figs. 14 and 15, respectively.

At the end of either case, the required output for the interaction diagram is printed. The value of shear is incremented by $\mathrm{V}_{\text {inc }}$ and the
new shear, $V$, is compared with the total allowable shear on the top web stub, $\mathrm{V}_{\mathrm{yT}}$. If the value of shear is less than $\mathrm{V}_{\mathrm{yT}}$, then the process is repeated in the appropriate case giving more coordinates for the interaction diagram. The solution is stopped if $V$ is greater than $V_{y T}$, since it is not applicable to failure in shear.

Case IA or Case IB will eventually give way to Case II. Figure 16 is a detailed flow chart of the solution process within Case II. At the end of Case II, data for the interaction diagram is printed after which the shear is increased by $\mathrm{V}_{\text {inc }}$, which is now 0.1. The value of the shear on the bottom tee, $V_{B}$, is now found and compared with the total shear the bottom tee stub will allow, $V_{y B}$. If the shear force $V_{B}$ is less than $\mathrm{V}_{\mathrm{yB}}$, then Case II is repeated. If $\mathrm{V}_{\mathrm{B}}$ is greater than $\mathrm{V}_{\mathrm{yB}}$, this solution is not applicable and the calculations cease. At the end, enough coordinates will have been computed to plot the entire interaction diagram.

Figure 14 shows the steps involved within Case IA, all of which have been discussed earlier except for the decision of whether $M_{e}$ is greater than zero. $M_{e}$ must be greater than zero in Case IA by definition, and if it is not Case II takes over. At the end of each cycle through Case IA, the coordinates of the interaction diagram are computed.

Case IB (Fig. 15) is activated when $P_{y T}$ is less than $P_{y c r}$ or $M_{\text {Vmax }}$ is less than $M_{V T}$. The value of "check" is changed to equal 1.0 so that the Case IA is by-passed through the remainder of the solution. The terms $A_{s V}, B_{s V}, C_{s V}$, and $Q_{s V}$ deal with the quadratic equation for $s_{V}$ (Eq. 33). $A_{s V}, B_{s V}$, and $C_{s V}$ are the coefficients, and $Q_{s V}$ is the portion under the square root of the quadratic. If $Q_{s V}$ is less than zero, an imaginary number results, so the solution is directed to solve for $t_{V_{w}}$ in a manner similar to that for $s_{V}$. If $Q_{t V_{w}}$ results in an imaginary number, the solution is switched to Case II. If either $s_{V}$ or $t_{V_{w}}$ are
found, the remaining calculations are performed, and coordinates for the interaction diagram are computed. Again, a check for $\mathrm{M}_{\mathrm{e}}$ is made in Case IB similar to that in Case IA.

Case II (Fig. 16) occurs when $M_{e}$ is less than or equal to zero, or when $Q_{t V w}$ is less than zero. At the beginning $M_{e}$ is set equal to zero, the bottom shear to top shear ratio is set equal to zero and the value of shear increment, $V_{i n c}$, is changed to 0.1 for reasons given earlier. With the given shear ratio, $V_{T}$ and $V_{B}$ are found and the moments $M_{V T}$ and $M_{V T I}$ are computed and compared. Adjustments are made to the shear ratio until $M_{V T}$ and $M_{V T 1}$ are equal. Then, as in Case IB, calculations and decisions are made concerning $Q_{S V}$ and $Q_{t V w}$. If $Q_{t V w}$ is less than zero, the solution terminates. Again calculations are made if values for $s_{V}$ or $t_{V w}$ are found, and the last of the coordinates for the interaction diagram are determined.

## TYPICAL RESULTS AND DISCUSSION

## Interaction Diagrams

The computer solution which is shown in Appendix III follows the flow diagrams discussed in the previous chapter, and results in a shearmoment interaction diagram as in Fig. 17. This diagram is the predicted failure envelope for a specific beam of known dimensions and material properties. Shear and moment are non-dimensionalized by the total shear capacity of the gross web section, $\mathrm{V}_{\mathrm{P}}$, and the total plastic moment capacity of the gross section, $M_{P c}$, respectively. For any given set of loading conditions and opening location, the theoretical failure load can be determined.

As indicated in Fig. 17, two possibilities for the top portion of the curve were investigated based on two different methods of distributing the moment due to shear in the top tee. For the bottom curve, Distribution $I$, the moment due to shear was assigned at the top of the tee section as shown in Fig. 18a. The interaction diagram from this distribution had a rather sharp downward curve at the beginning. For Distribution II (top curve) the moment due to shear was assigned at opposite ends of the top steel tee (Fig. 18b), resulting in a higher moment capacity initially, but ending with a slope discontinuity as the two curves meet at the end of Case I. Because Distribution II gives a higher moment capacity, and it is consistent with the distribution assumed in the bottom tee, it was adopted for this analysis.

The slope discontinuity in the interaction diagram appears to be related to the assignment of the moment due to shear in both steel tees. In Case I the total moment capacity is composed of the primary moment, which is constant, and the moment due to eccentricity, $M_{e}$, which varies.

Because the primary moment is constant it will not bring about a change in the rate of decrease of the total moment in the interaction diagram, whereas $M_{e}$ will. The change in $M_{e}$ is brought about by several factors, the first of which deals with web thickness. As shear is added in equal increments, the change in web thickness should be at a constant rate thus giving a constant rate of change in the interaction diagram. A second factor is the change in the moment arm of $M_{e}$. At the concrete end, the arm would be increasing as less concrete is used for larger shear loads, while the end in the steel will become shorter. The concrete is not "thrown away" faster than the centroid in the steel moves, so the moment arm for $\mathrm{M}_{\mathrm{e}}$ decreases at a slight rate as shear is increased. Since the magnitude of $M_{e}$ gets smaller as its moment arm gets smaller, no considerable change would occur in the slope of the interaction diagram. The final factor deals with the rate at which area of steel is used for $M_{V T}$ (or $M_{V B}$ ) as shear is added. At first, a small portion of the top tee is required for $M_{V T}$ because of a large moment arm, but as more shear is added, more area of steel is used in each increment because of decreasing moment arm length (Fig. 19). This would cause $\mathrm{M}_{\mathrm{e}}$ as well as the total moment to become smaller at an increasing rate, giving an increased rate of change in the slope of the interaction diagram. The slope reaches its steepest point at the end of Case I, after which in Case II the bottom tee is assigned MVB in the same manner as the top tee, so the slope is fairly flat at first but later gets very steep.

Figure 20 shows a comparison of the interaction diagrams for a non-composite beam and a composite beam. Both curves are for the same W shape and have the same material properties and opening dimensions.

The plot for the non-composite beam was produced using a computer program developed by Scritchfield (9). Because the beams have unequal total plastic moment capacities, the $M / M_{P}$ coordinates for the noncomposite beam have been multiplied by $\mathrm{M}_{\mathrm{P}} / \mathrm{M}_{\mathrm{Pc}}$ to permit a comparison. Since the composite beam has a higher $M / M_{P_{c}}$ value, it would appear to be the more effective section. At the lower end of the interaction diagram the two curves coincide, which should be expected since it was assumed that the concrete does not carry any of the shear force.

## Effects of Varying Key Parameters

A series of interaction diagrams have been prepared to investigate the effect of some of the key parameters. In this parametric study, a W $18 \times 50$ beam, $F_{y}=36 \mathrm{ksi} ., f_{c}^{\prime}=3.5 \mathrm{ksi}$. and a slab width of 48 in . were adopted, while slab thickness and opening length, height and eccentricity were varied one at a time. In the following discussion, an interaction diagram for $c=4 \mathrm{in} ., \mathrm{h}=4.5 \mathrm{in} ., \mathrm{a}=6.75 \mathrm{in}$, and $e=0$ is common to all of the figures.

When the slab thickness is varied, not much change is effected in the interaction diagram as can be seen in Fig. 21. For each larger thickness, the moment capacity for any value of shear force is increased because of longer moment arms for both $M_{e}$ and the primary moment, but the total moment capacity, $\mathrm{M}_{\mathrm{Pc}}$, is also increased, resulting in little variation in the $M / M_{P C}$ ratio. Because $M_{P C}$ does not increase faster than the moment capacity as larger thicknesses are used, the smaller thicknesses have larger $M / M_{P_{C}}$ values. All curves meet at the same value of shear, showing that the shear load is independent of the slab thickness, since it is assumed that the slab carries no shear.

Figure 22 shows the variation in the interaction diagram for changes in opening length. With a shear force of zero, all the curves have the same $M / M_{P_{c}}$ ratio, which shows that change in opening length does not affect the moment capacity in pure bending. The longer the opening length, the less shear load the beam will withstand. This occurs due to the fact that moments due to shear, $M_{V T}=V_{T}$ a and $M_{V B}=V_{B} a$, increase with opening length, thus with a longer opening the steel section is spent more quickly as shear force is increased. The effect of varying opening height is illustrated by the interaction diagrams in Fig. 23. The smaller the opening height, the greater the $M / M_{P_{c}}$ ratio will be, because less of the beam cross section is lost to the opening. Similarly, with the smaller opening height, a larger shear force can be applied to the beam since more of the cross section is left at the opening.

Figure 24 shows the effects on the interaction diagrams due to variation of opening eccentricity (positive eccentricity is upward and negative eccentricity is downward). The largest positive eccentricity gives the highest initial $M / M_{P c}$ ratio. This ratio is high because steel that is in the bottom tee will have a larger moment arm than if it were in the top tee. As the eccentricity decreases, the solution remains in Case $I$ longer since more steel is available in the top tee to resist shear. Curves with equal but opposite eccentricity, closely converge toward the bottom portion, suggesting that the shear capacity of the beam is not significantly affected by the direction of eccentricity.

## Comparison with Experimental Results

Two tests of composite beams with web openings have been performed by Granade (5). An interaction diagram for the beams is shown in Fig. 25,
and the experimental ultimate loads are also plotted. A large discrepancy exists between the theoretical and experimental values of the failure loads. There are several factors which might contribute to this discrepancy; however their effects are uncertain because the test conditions are not described fully.

A small factor to consider would be the manner in which the material properties of the steel and concrete were determined. This factor would cause only minor changes in the interaction diagram. Another small change might occur from the method of loading the beam. If a dynamic loading process were used, a higher ultimate load would occur giving a higher test point on the interaction diagram. A static loading process would give a lower ultimate load. The effect of strain hardening on the test results could have a significant effect. Since the ultimate strength analysis does not take into account the effects of strain hardening, the experimental ultimate loads would have to be adjusted (3) to give a good comparison between theory and experiment.

A final factor concerns one of the key assumptions made in the analysis presented in this report. The assumption states that no shear force will be assigned to the concrete slab. If part of the shear force were assigned to the slab, ultimate loads predicted from the interaction diagram would be much higher.

An ultimate strength analysis of composite beams with web openings has been developed based on McCormick's method. This analysis was used to make a comparison with a non-composite beam, and the composite beam was found to be more effective. Ultimate loads based on this solution were also compared with those observed in two laboratory tests. The theoretical results were found to be very conservative in their predictions of the strength of the test beams.

The effect of variation of certain parameters of a composite beam were studied using the analysis. Observations from this study are as follows:

1. Changes in the slab thickness do not affect the interaction diagram to a large extent.
2. The longer the opening is, the smaller the failure load.
3. As the opening is made deeper, the moment and shear capacity decrease.
4. An opening with the highest positive eccentricity has the highest moment capacity.

## RECOMMENDATIONS FOR FURTHER RESEARCH

Further study is needed in regard to the slope discontinuity in the interaction diagram. This study should be directed toward determining if an assignment of forces can be made such that the slope discontinuity is removed. Also, the assignment of shear force to the concrete slab should be considered in future analytical work. The analysis presented in this report could be expanded so that it could be applied to composite beams with reinforcement at the web opening.

More experimental tests on composite beams with web openings would be helpful for comparison with theoretical work.

## ACKNOWLEDGMENTS

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## APPENDIX II NOTATION

```
        a - one-half length of opening
        b - width of steel flange
        b
        c - thickness of concrete slab
    c
    c}\mp@subsup{P}{s}{}\mathrm{ - thickness of concrete used to equal axial force P ys
    c
    c
        subtracted from original thickness c
        d - depth of steel section
        dc - moment arm between axial force in bottom tee and corresponding
        force in slab
        de - moment arm between axial force in top tee and corresponding
        force in slab
        e - eccentricity of opening
        Fc}-.85\mp@subsup{f}{c}{\prime
        f
        F
        h - one-half opening depth
    M - total moment capacity of beam at centerline of opening
Mcap - total moment capacity of top tee-concrete slab (crer) section
    Me - moment due to eccentricity
    MP - total moment capacity of non-composite beam without opening
MPc - total moment capacity of composite beam without opening
M}\mp@subsup{\textrm{VB}}{~}{-}\mathrm{ -moment due to shear in bottom tee
```

```
M}\mp@subsup{V}{\mathrm{ max }}{}\mathrm{ - maximum M MT allowed in top tee due to location of NAP
    M MT - moment due to shear in top tee
    M
        compare with value MVT
        P}\mp@subsup{B}{B}{- axial force in bottom tee which contributes to primary moment
        P
        P
        P
        Pys - total axial force capacity of steel section at opening
        P
    S}\mp@subsup{B}{B}{- depth of web section in bottom tee at opening
    s
    s}\mp@subsup{T}{}{\mathrm{ - depth of web section in top tee at opening}
    s
        t - steel flange thickness
    t
    t
        without opening
    t}\mp@subsup{V}{V}{}\mathrm{ - thickness of outside edge of flange assigned to M}\mp@subsup{M}{VT}{}\mathrm{ or M M NB
    t}\mp@subsup{}{VW}{}\mathrm{ - thickness of flange adjacent to web assigned to M}\mp@subsup{M}{VT}{}\mathrm{ or M M
    t
    t
    V - total shear applied to composite beam web with opening
    V
```

$V_{P}$ - total shear capacity of web of steel section with no opening
$\mathrm{V}_{\mathrm{T}}$ - shear assigned to top tee
$V_{y B}$ - total shear capacity of web of bottom tee section at opening
$\mathrm{V}_{\mathrm{yT}}$ - total shear capacity of web of top tee section at opening
$W_{B}$ - reduced web thickness for bottom tee
$\mathrm{w}_{\mathrm{T}}$ - reduced web thickness for top tee
$y$ - distance from bottom of web of top tee section to the $N A_{p}$ of top tee-concrete slab $\left(c_{r}\right)$ section
$y_{B}$ - distance from top of web of bottom tee to centroid of portion assigned to axial force $P_{B}$
$y_{c}$ - distance from bottom of web of top tee to centroid of slab thickness $c_{P B}$ used to resist force $P_{B}$

## APPENDIX III COMPUTER PROGRAM



| $\begin{aligned} & 54 \\ & 55 \end{aligned}$ | ```15 Y=ST+T/2.-ST*WT/(2.*R) +(FC/FY)*(CR*BC/(2.*B)) MCAP=FY*(ST*WT*(Y-ST/2*)*B/2**(Y-ST)**2*B/2**(ST*T-Y)**2)*CR*BC*(S CI+T-Y+CR/Z.)*FC``` |
| :---: | :---: |
| $\begin{aligned} & 56 \\ & 57 \\ & 58 \end{aligned}$ | $\begin{aligned} & \text { TV }=S T+T-Y \\ & S V=T V \text { \& } \\ & \text { IE SVV.GT, STIGC TC } 17 \end{aligned}$ |
| $\begin{aligned} & 59 \\ & 60 \\ & 61 \end{aligned}$ | $\begin{aligned} & \text { MVMAX=TV*B*(ST+T-TV/2,-SV/2.) *FY } \\ & \text { IT (CHECKB EC, 1.JGC TO } 19 \\ & \text { WRITEIG,16). } \end{aligned}$ |
| $\begin{aligned} & 62 \\ & 63 \\ & 64 \end{aligned}$ | 16 FRRMATIIHO, $4 X, 24$ MME EXTENDS (NTC THE WEB.) CHECKB $=1$ <br> GO TO 19 |
| $\begin{aligned} & 65 \\ & 66 \\ & 67 \end{aligned}$ | 17 TVW=(TV*Q-ST*WT)/B <br> MVNAX=(TV**2/2.*P+TVW* $\mathrm{g} *(\mathrm{~T}-\mathrm{TVW} / 2 .-T V)+S T * W T *(Y-S T / 2.1) * F Y$ <br> IFICHECKC.EC. 1.160 TO 19 |
| $\begin{aligned} & 68 \\ & 69 \\ & 70 \end{aligned}$ | WRITE $(6,18)$ <br> 18 FORMATI $1 H 0,4 \mathrm{X}, 29 \mathrm{HME}$ IS CCNFINED TD THE FLANGE.) CHECKC $=1$ |
| $\begin{aligned} & 71 \\ & 72 \\ & 73 \\ & \hline \end{aligned}$ | 19 (FIMVMAX.GT. MVTIGC TO 21 <br> WRITE $\mathbf{~ 6 , 2 0 )}$ <br> 20 FORMAT ( 140,36 HMVYAX 15 LESS THAA MVT, GO TO CASE IB.) |
| $\begin{aligned} & 74 \\ & 75 \\ & 76 \\ & \hline \end{aligned}$ | ```GO TO 27 21 ME=MC AP -4VT 22 (FIME .GT. O.) GC TO 24``` |
| $\begin{array}{r} 77 \\ 78 \\ 79 \\ \hline \end{array}$ | WR (TE (6.23) <br> 23 FORMATIIHO, 36HME IS LESS THAN ZERC. GO TO CASE 11.) GO TO 33 |
| $\begin{aligned} & 80 \\ & 81 \\ & 82 \end{aligned}$ | $24 \begin{aligned} & M=P B * D C+M E \\ & V V P=V / V P \\ & M M P C=M / M P C \end{aligned}$ |
| 83 | MR, ITE (6,25) V,VRT, DC, M, ME, VVP, MMPC |
| 84 <br> 85 | $\begin{aligned} & 25 \text { FCRMAT }(7 F 15.4) \\ & V=V T=V \text { VINC } \end{aligned}$ |
| $\begin{aligned} & 86 \\ & 87 \\ & 88 \\ & \hline \end{aligned}$ | IFIVT ©LT. VYTIGO TO 10 WRITE 6.26 ) 26 FORMAT $(1 H 0.61$ HWHEN VT 15 GREATER THAN VYT, THIS SOLUTICN IS NCT AP |
| $\begin{aligned} & 89 \\ & 90 \\ & \hline \end{aligned}$ | ```IPLICABLE.) GC TO 2000 7) CHECK=1``` |
| $\begin{aligned} & 91 \\ & 92 \\ & 93 \end{aligned}$ | $\begin{aligned} & A S V=.5+W T /(2 * * B) \\ & B S V=-(S T+T) \\ & C S V=V \neq A /(\mathrm{kT}+F Y) \end{aligned}$ |
| $\begin{aligned} & 94 \\ & 95 \\ & 96 \end{aligned}$ | $\begin{aligned} & \text { OSV=RSV**2-4.*ASV*CSV } \\ & 1 F(O S V \text {. LT. O. } 16 C \text { TO } 29 \\ & S V=(-E S V-S C R T(10 S V) / /(2 . * A S V) \end{aligned}$ |
| $\begin{aligned} & 57 \\ & 98 \\ & 99 \\ & \hline \end{aligned}$ | $\begin{aligned} & \text { IF SVV GT: STIGC TC } 29 \\ & \text { TV }=S V+W T / 8 \\ & S P=S T-S V \end{aligned}$ |
| $\begin{aligned} & 100 \\ & 101 \\ & 107 \\ & \hline \end{aligned}$ | $\begin{aligned} & T P=T-T V \\ & P T=F Y *(T P * B+S P * W T) \\ & C P T=P T /(B C * F C) \end{aligned}$ |
| 103 | ```MF =(BC*CPT**2/2.)*FC+(SP*WT*(CR-CPT +T+SP/2.T*TP*B*TCR-CPT+TV TP/2. C) *FY IFICHCCKD.EC. 1.IGC TC 22``` |
| $\begin{aligned} & 105 \\ & 106 \\ & 167 \end{aligned}$ | WR(TE (E.28) <br> $2 R$ FORMAT $\mathrm{I}^{2} 1 \mathrm{HO}, 4 \mathrm{X}, 44 \mathrm{HSV}$ IS LESS THAN ST: ME EXTENDS INTC THE WE日. <br> CHECKO 1 |
| $\begin{array}{r} 108 \\ 109 \\ 110 \end{array}$ | $\begin{aligned} & \text { GO T0 } 22 \\ & \text { ATVW=q } \\ & \text { BTVH= } S T * W T-B * T) \end{aligned}$ |



```
169 IFICTVh GT. O.1GC TC 42
    WRITE (6,41)
171. 4L FORMAT(IH2.E5HSGUARE ROLT IN ILE GUAOKATIC F IVR IV IS NEGATIVE,ST
        10P.1
177 4. GC TO 2))0. 
173 42 TVW={-EIVW-STRTIC
175 TP=T-TV-TVM
176 PR=TP*Q*FY
177 Y Y = SA +TVh+TP/2.
    Y3=SS+TVh+TP/2. .IGC TC 44
    179 WRITEIE.43)
    178 IFICHECKG EO. 1.IGC TC 44
    180 43 FORHATI 14J.4X,52HSV 1S GKEATER IHAN SB: PS IS GCNFIAEC TC THE FLAN
        1GF.1
    CHECKG=1
    181 CHECKG=1
    182 
    184 YC=ST+T+C-CPB/2.
    185 OC=Y3+2.*H+YC
    ES }\quad\=PD*O
    187 VVP=V/VP
    188 MMPC=P/MPC
    MMPC=M/MPC 
    45 FORMAT(7F15.4)
        V=V+VIAC
    VS=V-VT
    If(VB LT. VYB)GO TO 27
    WR(TE(E.46)
        46 FORMATIIHI.GIHWHEN VE IS GREATER THAN VYS. THIS SCLUTICN IS NCT AP
            plucarle.)
        2000 R.CATINUE
    STOP
    ENO
```

        SENTRY
    | 6 | 0 | T | TW | BC | E | H | $\Delta$ | FY | C | FPC |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 7.500 | 18.300 | 0.570 | 0.358 | 49.990 | 0.030 | 4.5 CO | 6.753 | 36.030 | 4.300 | 3.536 |


| $S T$ | $S E$ | $V Y T$ | $V Y B$ | VP | MPC |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 3.930 | 3.930 | 29.843 | 29.243 | 125.453 | $586 C .773$ |

PYCR IS GREATEP THAN PYT, GC TC GASE IE.


| $\begin{aligned} & 7.0000 \\ & 8.0 .770 \\ & 9.0279 \\ & \hline \end{aligned}$ | $\begin{array}{r} 0.0000 \\ 0.0009 \\ 0.0000 \\ \hline \end{array}$ | $\begin{aligned} & 20.4416 \\ & 20.9416 \\ & 20.4416 \\ & \hline \end{aligned}$ | $\begin{aligned} & 4650.1440 \\ & 4036.1600 \\ & 4621.3400 \end{aligned}$ | $\begin{aligned} & 468.8159 \\ & 454.8251 \\ & 446.6558 \end{aligned}$ | $\begin{aligned} & 0 . C 558 \\ & 0.0638 \\ & 0.0717 \end{aligned}$ | $\begin{aligned} & 0.7934 \\ & 0.7910 \\ & 0.7885 \end{aligned}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 10.0000 | 0.2000 | 20.4416 | $46 C 5.655 C$ | 424.3635 | 0.6797 | 0.7859 |
| :1.03) 3 | 2.1313 | 23.4410 | 4588.8590 | 4 ¢7.5286 | J. 6877 | 0.7830 0.7799 |
| 12.0000 | 0.0cuo | 20.4416 | 4570.546 C | 3EG. 2168 | 0.2557 | 0.7799 |
| 13.0330 | $0.3 C J 3$ | 29.7416 | 4550.1640 | $3 ¢ 6.8323$ | 0.1636 | 0.7764 |
| 14.33.30 | 2.23)0 | 20.4416 | 4526.7410 | 345.1118 | 0.1116 | C.7723 |
| 15.0000 | 3.2000 | 20.4410 | 4495.563 C | 314.1726 | C. 1196 | 0.7670 |


SOUARE RCOT IN GUACRATIC TCP TVM IS REGATIVE, CO TO CASE II.


| 21.3996 | 0.2721 | 20.5998 | 3897.5000 | c. 0000 | 0.1706 | 0.6650 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 21.4996 | 0.2781 | 20.6037 | 3893.4870 | 0.0030 | 0.1714 | 0.6638 |
| 21.6996 | 0.2900 | 20.6114 | -3876.3400 | -0.0000 | 0.1720 | 0.66614 |
| 21.7996 | 3.2959 | 20.6153 | 3869.206 C | 0.3003 | 0.1738 | 0.6602 |
| 21.8996 | 0.3015 | 20.6192 | 3862.0316 | c. 0000 | 0.1746 | 0.6590 |
| 21.9995 | 0.3078 | 20.6232 | 3854.8150 | 0.0000 | 0.1754 | 0.6577 |
| 22.0995 | 3.3138 | 20.6271 | 3847.5540 | c. 6000 | 0.1762 | 0.6565 |
| 22.1995 | 0.3197 | 20.6311 | 3840.2510 | c. $\mathrm{coco}^{\text {c }}$ | 0.1770 | 0.6552 |
| 22.2995 22.3995 | 0.3256 | 20.6351 | 3832.9360 3825.5130 | 0.0300 | 0.1778 | 0.6540 |
| 22.3995 | 0.3316 | 20.6351 | 3825.5130 | 0.1000 | 0.1785 | 0.6527 |
| 22.4995 | 0. 3375 | 20.6432 | 3818.0790 | C.0000 | 0.1793 | 0.6515 |
| 22.5095 | 2.3435 | 20.6473 | 3810.6010 | 0.0333 | 0.1901 | 0.6502 |
| 22.6995 | 0.3494 | 20.6514 | 3803.0750 | c. 0000 | 0.1809 | 0.6489 |
| 22.7995 | -. 3554 | 20.6555 | 3795.5030 | 0.0000 | 0.1817 | 0.6476 |
| 22.8995 | J.3613 | 20.6596 | 3787.8820 | 0.000 | 0.1825 | 0.6463 |
| 22.9995 | 0.3672 | 20.6637 | 3780.218 C | c.0000 | 0.1833 | 0.6450 |
| 23.1994 | 0.3791 | 20.6721 | 3764.7410 | c. Coco | 0.1849 | 0.6424 |
| 23.2994 | 0.3851 | 20.6763 | 3756.9260 | 0.0000 | 0.1857 | 0.6410 |
| 23.3994 | 2.3910 | 20.6806 | 3749.0630 | 0.0005 | 0.1865 | 0.6397 |
| 23.4994 | 0.3970 | 20.6848 | 3741.1510 | c.coco | 0.1873 | 0.6383 |
| 23.5994 | 0.4029 | 20.6891 | 3733.1820 | 0.0000 | 0.1881 | 0.6370 |
| 23.6994 | J.4089 | 20.6934 | 3725.165 C | c. 0000 | 0.1889 | 0.6356 |
| 23.7994 | 0.4148 | 20.6578 | 3717.0540 | c.0000 | 0.1897 | 0.6342 |
| 23.8994 | 0.4207 | 20.7321 | 3728.5689 | 0.0303 | 0.1935 | 0.6328 |
| 23.0904 | 0.4267 | 20.7665 | 3700,787C | c. 0000 | 0.1913 | 0.6315 |
| 24.0993 | 0.4326 | 20.7109 | 3692.5500 | 0.0000 | 0.1921 | 0.6300 |
| 24.1993 | 0.4386 | 20.7153 | 3684.2560 | 0.0030 | 0.1929 | 0.6286 |
| 24.2993 | 0.4445 | 20.7198 | 3675.9C30 | c. 0000 | 0.1937 | 0.6272 |
| 24.2993 | 0.4505 | 20.7243 | 3667.4940 | 0.0000 | 0.1945 | 0.6258 |
| 24.4993 | 3.4564 | 20.7283 | 3659.0260 | 0.0008 | 0.1953 | 0.6243 |
| 24.5993 | 0.4624 | 20.7333 | 3650.4950 | c. 0000 | 0.1961 | 0.6229 |
| 24.6993 | 0.4683 | 20.7379 | 3641.902 J | 0.0303 | 0.1969 | 0.6214 |
| 24.7993 | 0.4742 | 20.7425 | 3633.2440 | c. $\mathrm{cocos}^{\text {a }}$ | 0.1977 | 0.6199 |
| 24.8993 | 0.4802 | 20.7471 | 3624.5260 | 0.0000 | 0.1985 | 0.6184 |
| 24.9993 | 0.4861 | 20.7517 | 3615.7410 | 0.0305 | 0.1993 | 0.6169 |
| 25.0993 | 0.4521 | 20.7564 | 3606.8890 | c. coco | 0.2001 | 0.6154 |
| 25.1992 | 0.4980 | 20,7611 | 3597.9700 | 0.0000 | 0.2009 | 0.6139 |
| 25.2992 | 0.5040 | 20.7658 | 3588.9820 | c. 0000 | 0.2017 | 0.6124 |
| 25.3992 | 0.5099 | 20.7706 | 3579.9240 | c. coco | 0.2025 | 0.6108 |
| 25.4992 | 0.5159 | 20.7754 | 3570.7540 | 0.0300 | 0.2033 | 0.6093 |
| 25.5992 | 0.5218 | 20.7802 | 3561.5880 | c. 0000 | 0.2041 | 0.6077 |
| 25.6992 | 0.5277 | 20.7850 | 3552.3100 | 0.0000 | 0.2049 | 0.6061 |
| 25.8992 | 0.5337 | 20.7899 | 3542.956 ) | 3.0033 | 0.2056 | 0.6045 |
| 25.9992 | 0.5456 | 20.7598 | 3524.0070 | 0.0009 | 0.2072 | 0.6013 |
| 26.0992 | J. 55515 | 20.8047 | 3514.4110 | c. 0000 | 0.2080 | 0.5996 |
| 26.1992 | 0.5575 | 20.8097 | 3504.7330 | c. 0000 | 0.2088 | 0.5980 |
| 26.2991 | 0.5634 | 20.8148 | 3494.9680 | 0.0303 | 0.2096 | 0.5963 |
| 26.3991 | 0.5694 | 20.8199 | 3485.1180 3475.1770 | c.0000 | 0.2104 | 0.5947 |
| 26.4991 | 0.5753 | 20.8250 | 3475.1770 | 0.0000 | 0.2112 | 0.5930 |
| 26.5991 | 3.5812 | 20.8351 | 3465.1440 | 0.0300 | 0.2120 | 0.5912 |
| 26.6991 | 0.5872 | 20.8353 | 3455.0150 | c. 0000 | 0.2128 | 0.5895 |
| 26.7991 | 0.5931 | 20.8405 | 3444.7900 | 0.0000 | 0.2136 | 0.5878 |
| 26.8991 26.9991 | 3.5991 0.6050 | 20.8457 | 3434.4670 | 0.0000 | 0.2144 | 0.5860 |
| 27.0091 | 0.6110 | 20.8564 | 3413.5100 | c. 0.0000 | 0.2152 | 0.5842 |
| 27.1991 | 0.6169 | 20.8617 | 3402.8740 | c. 0000 | 0.2168 | 0.5806 |
| 27.2991 | 0.6228 | 20.8671 | 3392.1250 | 0.0000 | 0.2176 | 0.5788 |





Fig. 1 Elevation of Composite Beam with Web Opening


Fig. 2 Section of Composite Beam with Web Opening


Fig. 3 Four Hinge Failure Mechanism

a. Case $I$ Pure Bending ( $\left.V=0, M=P_{B} d_{c}+M_{e}, M_{e}=P_{T} d_{e}\right)$

b. Case I General ( $M_{V T}=V_{T} a, M=P_{B}{ }_{c}+M_{e}, M_{e}=P_{T} d_{e}$ )

c. Case II General ( $V=V_{T}+V_{B}, M_{V T}=V_{T} a, M_{V B}=V_{B} a, M=P_{B} d_{c}$ )

Fig. 4 Internal Forces at Opening


Fig. 5 Sections for $M_{P_{C}}$


Fig. 6 Axial Force in Bottom Tee - Case I


Fig. 7 Top Tee - Remaining Concrete Section


Fig. 8 Case $I A-N A_{P}$ in Flange


Fig. 9 Case IA

a. $\mathrm{s}_{\mathrm{V}}<\mathrm{s}_{\mathrm{T}}$

b. $s_{V}>s_{T}$

Fig. 10 Case IB


Fig. 11 Top Tee Case II

$\longrightarrow+{ }^{w_{B}}$
$\mathrm{s}_{\mathrm{B}}{ }_{\square}^{+}$

b. $\mathrm{s}_{\mathrm{V}}>\mathrm{s}_{\mathrm{T}}$

Fig. 12 Case II


Fig. 13 General Flow Diagram


Fig. 14 Flow Diagram for Case IA


Fig. 15 Flow Diagram for Case IB



Fig. 17 Interaction Diagram

a. Distribution I

b. Distribution II

Fig. 18 Methods of Shear Moment Distribution

b. Increased Shear


Fig. 19 Changes in Moment Arm for $M_{V T}$


Fig. 20 Interaction Diagrams for Composite and Non-composite Beams


Fig. 21 Effect of Varying Slab Thickness


Fig. 22 Effect of Varying Opening Length


Fig. 23 Effect of Varying Opening Height


Fig. 24 Effect of Varying Eccentricity


Fig. 25 Test Results from Reference 5

## by

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AN ABSTRACT OF A MASTER'S THESIS

Submitted in partial fullfillment of the requirements for the degree

MASTER OF SCIENCE

Department of Civil Engineering

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1979

## ABSTRACT

The purpose of this thesis is to present an ultimate strength analysis of composite beams with web openings. With the use of this analysis certain variables were studied and the following conclusions were drawn:

1. Changes in the slab thickness do not affect the interaction diagram to a large extent.
2. The longer the opening is, the smaller the failure load,
3. As the opening is made deeper, the moment and shear capacity decrease.
4. An opening with the highest positive eccentricity has the highest moment capacity.

Theoretical results based on the analysis provide a very conservative prediction of the strength of test beams. This is thought to be primarily due to the assumption that the concrete slab does not carry any shear force.

