

ANALYSIS AND COMPARISON OF VARIOUS LOWER-BOUNDS ON
SCHEDULE TIMES FOR THE SOLUTION OF FLOW-SHOP PROBLEMS

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CHAPTER I

INTRODUCTION

The importance of the production scheduling problems has long been recognized by various types of industrial organizations. The control of production in industry usually centers around two distinct types of manufacturing processes: batch; and continuous. These two types are usually represented by the classic models of the job-shop and the assembly-line production systems. Consequently, production scheduling problems may be classified as Shop Production Scheduling and Line Production Scheduling. This research is concerned with a special class of the shop production scheduling problem.

The job-shop usually consists of a limited number of multi-purpose machines. A finite number of jobs are to be processed on one or more of these machines. In processing these jobs, certain technological requirements may be specified in advance. These requirements are usually referred to as machine ordering or routing. The most common and frequently referred to scheduling problem consists of finding the job sequence for processing J jobs on M machines such that a certain criterion is optimized. Among the criteria usually considered are: (1) minimization of the total time required to process all jobs on all machines, i.e., minimization of schedule time or make-span; (2) maximization of the profit by meeting the dead lines or due-dates; (3) minimization of the in-process inventory; (4) minimization of the total idle time on all machines; (5) maximization of the facility utilization; and (6) minimization of the total cost. However, the criterion considered in this research is that of minimizing the schedule

time. This is because all bounding procedures considered for comparison compute lower-bounds on schedule time.

In shop scheduling problems, there exists a situation in which a certain number of jobs arrive simultaneously in a shop that is idle and immediately available for work. In this case, the number of jobs is considered fixed and known. Such a process refers to the static behavior of job-arrivals. There also exists other situation in which the jobs arrive continuously at random intervals. This process is therefore refers to the dynamic behavior of job-arrivals. The static situation usually leads to various deterministic models; however, the dynamic situation leads to several stochastic models.

In practice, the scheduling problem is usually of dynamic nature and hence stochastic models are of more interest. However, the deterministic models are not without inherent interest of their own. These models can be considered as a prelude to the more realistic stochastic models because of the following. First, it provides an approach to handle more complex dynamic situations as a series of deterministic models. Second, knowledge gained from work with static situations may be directly applicable to the dynamic situations. Thus it would be a wise step to attack more simple static problems because the experience gained from these experiments may direct the researchers to handle more complex and realistic situations.

1.1 Problem Formulation *

In shop scheduling problems, the order in which various machines perform a particular job provides a distinction between the two types of shops,

* Adapted from Ashour, S., Introduction to Scheduling, John Wiley & Sons, Inc., to appear.

usually referred to as flow-shop and job-shop. This research is concerned with the flow-shop scheduling problems in which each job is performed on a certain set of machines in an identical order. Due to this, the jobs are said to flow over machines along the same path. On the contrary, in job-shop scheduling problems, the machine ordering for each job may be different. To account for this, the job-shop problems are more complex than the flow-shop.

To help facilitate the formulation of this scheduling problem, a job is designated by an integer j and a machine by an integer m . Since an operation is defined as the processing of a job j on machine m , it may be symbolized by (jm) .

The indexing of jobs and machines is arbitrary and preconceived; it does not necessarily correspond to the sequence in which the jobs are performed on each machine or to the order in which the machines process each job. Since the jobs may be performed in a sequence other than the preconceived one, a sequence of jobs is usually designated as

$$j_1, j_2, \dots, j_k, \dots, j_J$$

where J is the total number of jobs. As an example, j_k indicates the job index which is in the k^{th} sequence-position, i.e., the k^{th} position in the job permutation (hereafter referred to as job j_k).

On the other hand, in considering a permutation of the machines with respect to the preconceived order, the machines may be designated as

$$m_1, m_2, \dots, m_\ell, \dots, m_M$$

where M is the total number of machines. For example, m_ℓ means the machine

index which is in the ℓ^{th} order-position, i.e., the ℓ^{th} position in the machine permutation. In general, the subscripts of j and m are used to denote the position in a job permutation and order in a machine permutation, respectively.

Consequently, since it will be necessary to consider permutations of the job-sequence on a particular machine, permutations of the machine-order for a particular job, and even permutations of both the job-sequence and the machine-order, the following set of operations are defined. First, the operation of a job in the k^{th} sequence-position, on machine m is designated

$$(j_k^m), \quad k = 1, 2, \dots, J.$$

Second, the operation of job j on a machine in the ℓ^{th} order-position is designated

$$(j m_\ell), \quad \ell = 1, 2, \dots, M.$$

Finally, a specific operation involving a particular job j_k and a particular machine m_ℓ is denoted

$$(j_k^m), \quad k = 1, 2, \dots, J, \\ \ell = 1, 2, \dots, M.$$

In scheduling problems it is necessary to consider the order relations for each job performed through the machines and the sequence relations between the jobs processed on each machine. This leads to define a binary relation, usually referred to as precedence relation.

Considering three operations $(j_p^{m_q})$, $(j_r^{m_s})$ and $(j_u^{m_v})$, if the processing of job j_p on machine m_q can not be started after the processing of job j_r on machine m_s , then operation $(j_p^{m_q})$ is said to precede operation $(j_r^{m_s})$. This relation is designated

$$(j_p^{m_q}) \prec (j_r^{m_s}) .$$

It can also be said that operation $(j_r^{m_s})$ follows operation $(j_p^{m_q})$. The precedence relation has the following properties

1. transitive which means that if

$$(j_p^{m_q}) \prec (j_r^{m_s}) \quad \text{and} \quad (j_r^{m_s}) \prec (j_u^{m_v}),$$

then

$$(j_p^{m_q}) \prec (j_u^{m_v});$$

2. nonreflexive which means that

$$(j_p^{m_q}) \not\prec (j_p^{m_q}) .$$

Or, in words, there is no operation which precedes itself; and

3. antisymmetric which means that if

$$(j_p^{m_q}) \prec (j_r^{m_s}) ,$$

then

$$(j_r^{m_s}) \not\prec (j_p^{m_q}) .$$

Now considering the two operations $(j_p^{m_q})$ and $(j_r^{m_s})$ having a job or a machine in common, i.e., $j_p = j_r$ or $m_q = m_s$, the operation $(j_p^{m_q})$ is

said to directly-precede operation $(j_{r^m_s})$ if there is no intermediary operations. Such a relation is designated

$$(j_{p^m_q}) \prec \prec (j_{r^m_s}) .$$

This implies that operation $(j_{r^m_s})$ next-follows operation $(j_{p^m_q})$.

The above statement implies that

1. $(j_{p^m_q}) \neq (j_{r^m_s})$,
2. $(j_{p^m_q}) \prec (j_{r^m_s})$, and
3. no operation, say $(j_{u^m_v})$, can exist such that

$$(j_{p^m_q}) \prec (j_{u^m_v}) \prec (j_{r^m_s}) .$$

It should be noted that direct precedence relation is intransitive, non-reflexive and antisymmetric. However, when this relation is extended to have the transitive property, it is called precedence relation.

The direct-precedence relations are usually prescribed in advance because of the technological requirements. For example, a hole drilling operation must precede, or can directly precede a boring operation.

In terms of the above definitions, the prescribed ordering of M machines for a particular job j may be arranged in a single chain of direct-precedences such that

$$(jm_1) \prec \prec (jm_2) \prec \prec \dots \prec \prec (jm_\ell) \prec \prec \dots \prec \prec (jm_M) .$$

For convenience, the above machine ordering for a particular job j is designated by a row vector such that

$$M_j = [jm_1 \quad jm_2 \quad \dots \quad jm_\ell \quad \dots \quad jm_M], \quad j = 1, 2, \dots, J.$$

These machine ordering vectors, one for each job, may be combined in a $(J \times M)$ matrix called the machine ordering matrix denoted by M . For example, consider a problem having two jobs to be processed on three machines. Let the jobs be $j = 1, 2$, and the machines be $m = 1, 2, 3$. The machine ordering matrix of this problem is shown below

$$M = \begin{bmatrix} M_1 \\ M_2 \end{bmatrix} = \begin{bmatrix} 1m_1 & 1m_2 & 1m_3 \\ 2m_1 & 2m_2 & 2m_3 \end{bmatrix} = \begin{bmatrix} 11 & 13 & 12 \\ 22 & 21 & 23 \end{bmatrix}$$

This matrix indicates that job 1 must be processed on machine 1 first, machine 3 second, and machine 2 last. However, job 2 must be performed on machine 2 first, machine 1 second, and machine 3 last. It should be noted that the machine m_1 in the element $1m_1$ is not necessarily the same as machine m_1 in the element $2m_1$. In terms of direct-precedence relations, the machine orderings for jobs 1 and 2 are

$$(11) \prec \prec (13) \prec \prec (12),$$

and

$$(22) \prec \prec (21) \prec \prec (23),$$

respectively.

Associated with each operation, (jm_ℓ) , there is a processing time, t_{jm_ℓ} ; that is, the time required to perform job j on a particular machine m_ℓ . The processing times of each job on the various machines are usually estimated in advance and known exactly. For convenience, the processing times for job j on all machines are designated

$$T_j = [t_{jm_1} \quad t_{jm_2} \quad \dots \quad t_{jm_\ell} \quad \dots \quad t_{jm_M}],$$

$$j = 1, 2, \dots, J.$$

The above set of processing time, one for each job, may be combined in a (JxM) matrix referred to as the processing time matrix and denoted by T .

The processing time matrix of the above example is shown below

$$T = \begin{bmatrix} T_1 \\ T_2 \end{bmatrix} = \begin{bmatrix} t_{1m_1} & t_{1m_2} & t_{1m_3} \\ t_{2m_1} & t_{2m_2} & t_{2m_3} \end{bmatrix} = \begin{bmatrix} 2 & 4 & 1 \\ 5 & 1 & 3 \end{bmatrix}$$

The above processing time matrix indicates that to perform job 1 on machines m_1 , m_2 , and m_3 , it requires 2, 4, and 1 units of time, respectively. Similarly, job 2 requires 5, 1, and 3 time units to be completed on machines m_1 , m_2 , and m_3 , respectively. It is obvious that if a job is not to be processed on a particular machine, a zero processing time can be placed in the corresponding element in the processing time matrix.

While the machine ordering specifies the order in which a particular job is processed on various machines, the job sequencing specifies the sequence in which a particular machine performs various jobs. Using the definition of direct-precedence relation, the series of operations on machine m may be designated

$$(j_1^m) \prec \prec (j_2^m) \prec \prec \dots \prec \prec (j_k^m) \prec \prec \dots \prec \prec (j_J^m)$$

Again, for convenience, the above sets of job sequencings on each machine can be arranged in a row vector

$$S_m = [j_1^m \ j_2^m \ \dots \ j_k^m \ \dots \ j_J^m], \quad m = 1, 2, \dots, M.$$

These job sequencings, one for each machine, may be combined in a $(M \times J)$ matrix called the job sequencing matrix and denoted by S . For example, one of the possible job sequencing matrices of the above problem is shown below

$$S = \begin{bmatrix} S_1 \\ S_2 \\ S_3 \end{bmatrix} = \begin{bmatrix} j_1^1 & j_2^1 \\ j_1^2 & j_2^2 \\ j_1^3 & j_2^3 \end{bmatrix} = \begin{bmatrix} 11 & 21 \\ 22 & 12 \\ 13 & 23 \end{bmatrix}$$

This matrix indicates that machines 1 and 3 process jobs 1 and 2 in the sequence {1 2}; however, machine 2 performs the two jobs in the sequence {2 1}. In other words machines 1 and 3 process job 1 first and then job 2 last; and machine 2 processes job 2 first and job 1 last. It should be noted that job j_1 in the element j_1^1 may or may not be the same job as in the elements j_1^2 or j_1^3 . In the above example, the elements j_1^1 and j_1^3 have the same job which differs from that in j_1^2 . In terms of precedence relations, for example, $(13) \prec \prec (23)$; or, in words, operation (13) directly precedes operation (23).

The above sequencing matrix may be represented by Gantt charts shown in Figure 1.1. In this figure, each machine is represented by a horizontal bar. The hatched portion in each bar indicates the processing of a job on the corresponding machine. Job indexes are marked on the top of these bars; however, the numbers below show the starting and completion times of the various operations.

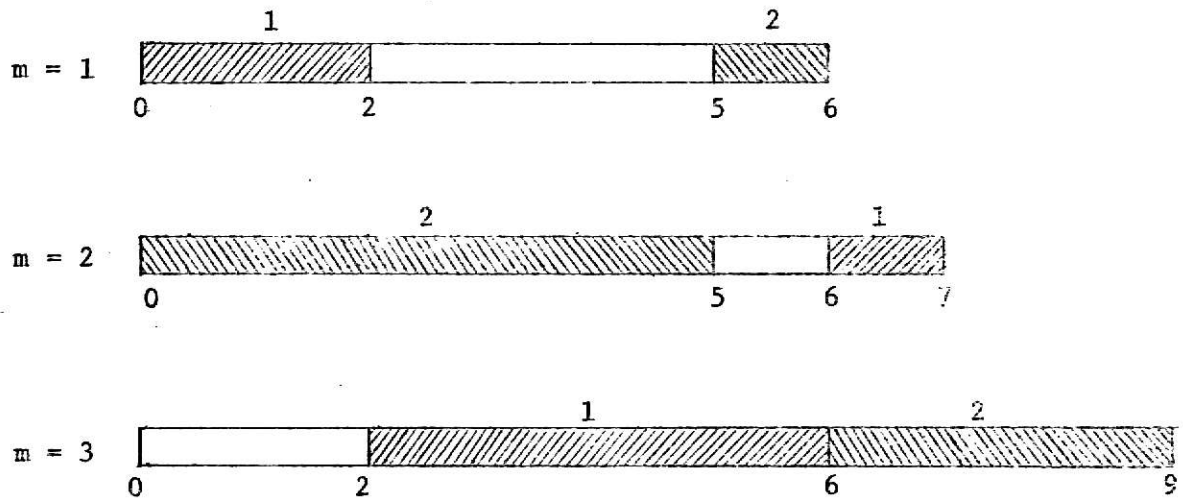


Figure 1.1

Gantt Charts Depicting the Job Sequencing Matrix

It is interesting to illustrate the precedence and direct-precedence relations discussed above, using the Gantt charts shown in Fig 1.1. For example, the precedence relation

$$(j_1^{m_1}) \prec (j_2^{m_3})$$

or

$$(11) \prec (23)$$

holds. In words, the processing of job 1 on machine 1 precedes the processing of job 2 on machine 3.

Similarly, the direct-precedence relation on machine 1

$$(j_1^1) \prec \prec (j_2^1)$$

or

$$(11) \rightarrow \rightarrow (21)$$

holds. This implies that operation (11) directly precedes operation (21) on machine 1.

The direct-precedence relation for job 1

$$(1m_1) \rightarrow \rightarrow (1m_2)$$

or

$$(11) \rightarrow \rightarrow (13)$$

holds. In words, machine 1 performs job 1 immediately before it is performed on machine 3. Note that in the direct-precedence relation, the operations have either the same job or the same machine.

In scheduling problems, the machine ordering matrix is usually specified and it is required to determine the job sequencing matrix, which optimizes some measure of performance. In general, the job sequencing matrix will be referred to as a sequence. A sequence may be defined as a collection or combination of machine orderings and job sequencings. Since the elements appearing in the machine ordering matrix M are the same as those in the job sequencing matrix S , the sequence relations given by S may be inconsistent, i.e., nonfeasible with the order relations specified in M . One of the characteristics of the required sequence is that it must be consistent or compatible with the machine orderings of all jobs.

In terms of the above formulation, the scheduling problem can be stated as: given both the machine ordering and processing time matrices M and T , it is required to find the optimal sequence S with respect to a

certain criterion.

The flow shop scheduling problem with which this paper is concerned, is subject to the following assumptions.

1. Assumptions regarding jobs:

- 1.1 All jobs are known, ready to be processed as soon as possible, according to specified machine orderings.
- 1.2 All jobs are equally important; i.e. no pre-emption, due dates or rush orders.
- 1.3 Each job must be processed by a designated machine ordering.
- 1.4 A job may not be processed by more than one machine at a time.
- 1.5 No job is processed more than once on any machine.
- 1.6 Each job, once started for processing in the shop, must be performed to completion; that is, no job cancellation.
- 1.7 Each job may have to wait between machines; that is, in-process inventory is allowed.

2. Assumptions regarding machines:

- 2.1 There is only one machine of each type in the shop.
- 2.2 All machines are ideal; i.e., they operate with constant efficiency, without breakdown, never lack operator, tool, or material, and always produce acceptable products.
- 2.3 Each machine can process at most one job at a time.

3. Assumptions regarding operations:

- 3.1 Each operation, once started on a machine, must be performed to completion before another operation can begin on that machine; that is, no pre-emptive priorities.
- 3.2 Each operation can be performed by only one machine in the shop.

4. Assumptions regarding processing times:

- 4.1 The processing times are known, finite and integers.
- 4.2 The processing times are independent of the sequence in which the jobs are performed.
- 4.3 The processing time also includes the set-up times and the transportation times between machines.

1.2 Proposed Research

The problem of scheduling J jobs on various machines with the same machine orderings, has been studied by several investigators. However, as yet no efficient algorithm has been found for determining an optimal sequence of jobs. In this paper, the branch-and-bound algorithm will be discussed. Various bounding procedures will be analyzed mathematically and evaluated empirically.

The basic concepts of the branch-and-bound was first realized by Land and Doig [9a] which has been named by Little et. al. [11] while solving the travelling salesman problem. This approach which gives an optimal or near optimal solution after the generation of only a small subset of the possible sequences, is considered one of the combinatorial approaches to the production scheduling problem.

Ignall and Schrage [8] have applied the above concept to the two-and three-machine flow shop problem using their sophisticated lower-bound. Their computational experience involves upto nine jobs. Brown and Lomnicki [3] have extended the branch-and-bound algorithm developed by Lomnicki [12] for three machine case to arbitrary number of machines. McMahon and Burton [13] have applied this technique to the three-machine problem, giving a new procedure of obtaining the bound referred by them as composite lower-bound.

Their experience involves upto 10 jobs and 2 machines. They have concluded that the use of composite bound is more efficient. Nabeshima [15] has reported a revised lower-bound and attempted to show the superiority of this lower-bound by three sample problems.

For comparison purposes all bounding procedures are generalized to an arbitrary number of machines by assuming that all jobs are performed on each machine in the same sequence. Thus, the computational algorithm discussed in this paper will develop optimal permutation-sequence and this will be referred to as optimal sequence or optimal solution in the discussion throughout this paper. It should be noted that the permutation sequences will always be optimal for cases involving upto three machines^{*}. However, for more than three machines, the solution is considered optimal within the set of permutation-sequences only.

As mentioned earlier the branch-and-bound technique has been first applied to flow shop scheduling problem by [8, 12]. Since then several researchers have developed various lower-bounds or bounding procedures which are vital in making the branch-and-bound technique efficient. Therefore, the success of the branch-and-bound technique depends on the quality of the lower-bounds. To the knowledge of author, no comparison among these lower-bounds has been yet made. The purpose of this paper is to present a mathematical analysis of the five promising lower-bounds referred to as bounding procedures LB I, LB II, LB III, LB IV, and LB V; to compare the quality of these bounding procedures. This comparison is based on the following: (1) the number of nodes explored; (2) the computational

^{*} See Theorems 5-1 and 5-2, in Conway, et al; Theory of Scheduling, 1967, pp. 81-83.

efficiency. To obtain fair comparison among these procedures and to minimize the variations, considerable experiments were conducted.

In Chapter II, the basic concepts of branch-and-bound technique are discussed. A more general computational algorithm is illustrated by a sample problem. Chapter III is devoted to the mathematical analysis of various bounding procedures under consideration. The various lower-bounds computed by each of the bounding procedures are also illustrated by a sample problem. In Chapter IV, the computational experiments and their results are reported. Finally, summary of results and conclusions are provided in Chapter V.

CHAPTER II

BRANCH-AND-BOUND TECHNIQUE

A survey of the approaches used in the solution of scheduling problems reveals that all the existing approaches can be classified into four basic categories: (1) combinatorial; (2) mathematical programming; (3) queueing; and (4) simulation. This report is concerned with the branch-and-bound technique which is based on combinatorial analysis. It seems reasonable to elaborate the explanation of combinatorial mathematics before discussing the basic concepts of the branch-and-bound technique.

2.1 Combinatorial Mathematics

Combinatorial mathematics, also referred to as combinatorial analysis or combinatorics, is one of the mathematical disciplines. The formal definition of combinatorics becomes difficult due to the diversified applications of combinatorial analysis in various areas of mathematics. Ryser [17] has defined the combinatorial analysis as the mathematics which deals with the study of the arrangement of elements into sets. The elements are usually finite in number, and the arrangement is restricted by certain constraints, if any, imposed by the specific problem under consideration. The problems tackled by combinatorial analysis are classified as: (1) existence problem, and (2) enumeration problem. Existence problems are those in which the existence of solution is doubtful and the study attempts to settle this issue. On the contrary, enumeration problems have the surity of existence of solution and the objective is to find the solutions, the number of such solutions, and their classifications. Thus, each enumeration problem is an extension of existence problem.

According to the definitions of combinatorial problems cited above, it is obvious that the scheduling problem is an enumeration problem. The combinatorial approach for solving the scheduling problem represents quasi-enumeration techniques. By applying many reliable heuristics, this approach has succeeded in arriving at the subset of optimal schedules through a shortest path. This subset is comparatively much smaller than the complete enumeration. The efficiency of the combinatorial techniques depends on how effectively enumeration is curtailed. A number of techniques developed within the concept of combinatorial analysis for solving scheduling problems can be listed as switch-and-check, branch-and-bound and bound-and-resolve technique.

2.2 Basic Concepts of Branch-and-Bound Technique

The branch-and-bound technique is an intelligently designed search to obtain the subset of optimal solutions from a larger set of feasible sequences. It has been pointed out in literature that for any particular scheduling problem, the number of optimal schedules is much smaller than the number of all possible feasible sequences. This fact revealed that even a technique discarding only non-feasible sequences will not be efficient in solving larger size problems. By using certain processes, the search is directed towards an optimal solution in a finite number of steps. The branch-and-bound algorithm described in this chapter assures that it will arrive at an optimal solution and it may be possible to do so in less than complete enumeration.

The basic philosophy behind this technique is the partitioning of the set of feasible sequences into smaller and smaller subsets. A lower-bound is calculated for the partial or complete sequence within each subset.

The objective of this technique is to find the optimal solution with less computational effort involved. The search should be systematically progressed through branching and bounding processes which may be easily discussed by using a scheduling tree.

The scheduling tree consists of nodes, each representing a partial or complete sequence, $\{j_1 j_2 \dots j_L\}$, where $L \leq J$. The scheduling tree starts with a node "ALL" which represents J unscheduled jobs at level 0. At level 1, the scheduling tree is initialized by J nodes, each of which consists of a partial sequence having one job, $\{j_1\}$. Each of these J nodes can be branched into $J-1$ nodes at level 2, each consisting of a partial sequence $\{j_1 j_2\}$. In general, at any level, L , there are $J-L+1$ new nodes emanating from each node at the preceding level. Each of these new nodes consists of a partial sequence having L jobs, $\{j_1 j_2 \dots j_L\}$. Note that the number of jobs in each node at level L is equal to L . As one moves down the tree, the index of levels increases by one; and the number of nodes branched from a node, decreases by one than that of the preceding level. The tree ends at level J with a number of nodes, each having a complete sequence of J jobs. Any of these complete sequences can be regarded as a solution to the scheduling problem. It should be pointed out that when all nodes at each level are generated, the maximum number of nodes in such a scheduling tree is $J + J(J-1) + J(J-1)(J-2) + \dots + J!$ which increases very rapidly as the number of jobs increases.

The process of generating a new set of nodes at level L , each having a partial sequence $\{j_1 j_2 \dots j_L\}$, from a node at the preceding level, $L-1$, is referred to as Branching process. Further, this node from which the branching takes place is called active node. The nodes are generated

by placing one of the unscheduled jobs as a candidate for the next sequence-position in the partial sequence of the active node. The branching characteristic of the branch-and-bound algorithm, used in this report, guarantees that if this algorithm is applied to a flow shop scheduling problem, an optimal solution will eventually be obtained. It merely promises the optimal solution by exploring all nodes of the scheduling tree.

Reduction in the generation of nodes at each level can be effectively achieved by bounding process. In this process a lower-bound for each node is computed and then according to the branching strategy, the active node is picked up for further branching. The various lower-bounds developed by several researchers will be analyzed in detail in Chapter III.

The lower-bound for a node is a lower limit on the schedule time which implies that any solution emanating from this node can not have schedule time less than the value of its lower-bound. In other words, all complete sequences resulted from a particular node under consideration will have schedule times either equal to or greater than the value of the lower-bound for that node. This concept helps select the promising node for branching to be carried down to the next level. As usual, the efficiency of the branch-and-bound algorithm depends on the quality of the bounding process, since this process has a characteristic of recognizing an optimal solution prior to complete enumeration. It is logical to look for a high lower-bound than a low lower-bound for the same node, computed by different lower-bound formulas developed so far. The higher the value of the lower-bound, the more powerful is the bound on the objective function. Five of the more promising possibilities for these bounds are developed in

[3, 8, 12, 13, 15] and discussed in Chapter III.

It should be pointed out that the lower-bounds which consider the idle times created by the scheduled and unscheduled jobs, usually yield higher and more realistic lower-bounds than those which consider the idle times created by the scheduled jobs only. The lower-bounds which do not consider idle times among the unscheduled jobs, assume that there is no overlapping or conflict among these jobs. The bounding process is more strong in recognizing direction of an optimal solution at higher levels down the tree than lower levels up the tree. This is because there are fewer jobs in the nodes at lower levels than those at higher levels. The larger the number of jobs in a partial sequence, the more closer will be the lower-bound to the minimum schedule time.

As one moves down the tree, the lower-bound will never decrease along the same branch of the tree. By moving down a level, an unscheduled job is added to the previous partial sequence and while computing a lower-bound for this newly created node, the idle time created by the last scheduled job is also accounted. Thus, the lower-bound of a node will be either equal to or greater than the lower-bound of the node from which branching took place at the preceding level, depending upon the idle time. However, it will never decrease, since the idle times can never take negative values.

The branching and bounding processes always yield a solution which may or may not be an optimal. However, in order to guarantee optimality a back-tracking process must be imbedded in the branch-and-bound technique. The function of the back-tracking process is to move upwards on the same branch which has led to the previously obtained solution. Then, by using

the branching and bounding processes, the unexplored node(s) at the immediately preceding level and having lower-bound less than the value of the previously obtained solution (hereafter referred to as updated solution), is investigated. In moving downwards until the last level, another solution may be obtained which again may or may not be better than the previous one. This updated solution is considered optimal when there is no unexplored node with a lower-bound less than that of the previous solution. The branching, bounding and back-tracking processes which are imbedded in the computational branch-and-bound algorithm stated in Section 2.3, will be illustrated by a sample problem.

2.3 A Computational Algorithm

The branch-and-bound algorithm described in this section is completely general in the sense that it consists of various phases to compute the lower-bounds; and to break the ties between the lower-bounds, if any. This algorithm has been designed to yield an optimal solution which has been guaranteed by back-tracking process.

The computational algorithm may be stated as follows:

Step 1: Set level index $L = 1$, and schedule time $T = +\infty$.

Step 2: Check L :

2.1. If $L < J$, go to step 3.

2.2. If $L = J$, check the minimum lower-bound at level $J - 1$, $J-1_B$:

2.2.1. If $J-1_B < T$, set $T = J-1_B$ and $L = L - 1$. Go to step 7.

2.2.2. If $J-1_B \geq T$, set $L = L - 1$ and go to step 7.

Step 3: Compute the lower-bounds at level L , for each node n , L_B^n , by a particular bounding process.

Step 4: Find the unexplored node(s) which has the minimum lower-bound at level L , L_B , such that

$$L_B = \min_n [L_B^n] ,$$

and compare L_B :

4.1. If $L_B < T$, go to step 5.

4.2. If $L_B \geq T$, go to step 7.

Step 5: Branch from an unexplored node with the minimum lower-bound:

5.1. If a tie exists, break it by a particular rule.

5.2. If a tie does not exist, branch from that node.

Step 6: Set $L = L + 1$, and go to step 2.

Step 7: Back-track along the same branch of the scheduling tree by setting $L = L - 1$. Compare the lower-bounds for all unexplored nodes at this level:

7.1. If there exist one or more nodes such that

$$L_B^n < T, \text{ go to step 4.}$$

7.2. If for all unexplored nodes, $L_B^n \geq T$, go to step 8.

Step 8: Check for an optimal solution:

8.1. If $L > 1$, go to step 7.

8.2. If $L = 1$, T is an optimal schedule time.

The lower-bound, in step 3 of the algorithm described above, can be computed by one of the five bounding processes summarized in Table 2.1. According to step 5 of the algorithm, a tie, if exists, can be resolved by one of the three rules: the Left Hand Rule (LHR) breaks a tie by selecting

the farthest-left node from the tie-set at that level in the scheduling tree. Similarly, the Right Hand Rule (RHR) picks the farthest-right node from the tie-set for branching. If the node is selected by random (RDM) from the tie-set, the tie is said to be resolved by random. It should be pointed out that the (LHR) has been used in this research for resolving the tie.

Table 2-1 Various Bounding Processes

Concept	Bounding Procedures	Discussed in Section	Investigator	Reference
Machine Based	LB I	3.1	Brown & Lomnicki	[3,12]
Machine Based	LB II	3.2	Ignall & Schrage	[8]
Job Based	LB III	3.3	McMahon & Burton	[13]
Composite Based	LB IV	3.4	McMahon & Burton	[13]
Machine Based	LB V	3.5	Nabeshima	[15]

2.4 Sample Problem

The computational algorithm described in the preceding section will be illustrated by a sample problem. The problem consists of six jobs to be processed on each of three machines. The machine ordering and processing time matrices are given below:

$$M = \begin{bmatrix} 11 & 12 & 13 \\ 21 & 22 & 23 \\ 31 & 32 & 33 \\ 41 & 42 & 43 \\ 51 & 52 & 53 \\ 61 & 62 & 63 \end{bmatrix}, \quad T = \begin{bmatrix} 6 & 7 & 3 \\ 12 & 2 & 3 \\ 4 & 6 & 8 \\ 3 & 11 & 7 \\ 6 & 8 & 10 \\ 2 & 14 & 12 \end{bmatrix}$$

The purpose of selecting this problem is to make clear to the reader how branching, bounding and back-tracking processes are imbedded in the branch-and-bound technique. The emphasis in this chapter is placed on how the branch-and-bound works, not on how the lower-bound is computed. The computation of the various lower bounds is left to be analyzed in Chapter III. The values of the lower-bounds are computed according to bounding procedure LBI. For convenience, LBI is stated mathematically as follows:

The lower-bound at level L for each node n , L_B^n , is given by

$$L_B^n = \max_m [L_{B_m}^n],$$

where $L_{B_m}^n$ is the bound on machine m , at level L , for node n and is computed such that

$$L_{B_m}^n = L_{C_m}^n + \sum_{k=L+1}^J t_{j_k^m} + \min_{j_k \notin n} \left[\sum_{m'=m+1}^M t_{j_k^{m'}} \right],$$

$$m = 1, 2, \dots, M-1$$

and

$$L_{B_M}^n = L_{C_M}^n + \sum_{k=L+1}^J t_{j_k^M}$$

where $L_{C_m}^n$ is the completion time of scheduled jobs in node n at level L on machine m . For convenience, the elements from which lower-bounds have been obtained, are displayed in Table 2.2. However, this lower-bound along with others will be analyzed mathematically and illustrated by another sample problem in Chapter III.

In solving this sample problem, a scheduling tree is initialized with a node "ALL" which may be considered as level zero. In order to follow the solution easily, Figure 2.1 should be followed throughout all the steps.

Step 1. Set level L equal to 1 and the initial schedule time T_0 equal to ∞ . Level 1 is initialized by generating the nodes having partial sequence $\{j_1\}$. Thus, there are $J - L + 1$ or 6 nodes with partial sequences $\{1\}$, $\{2\}$, $\{3\}$, $\{4\}$, $\{5\}$ and $\{6\}$.

Step 2. Check the level L . Since L is less than J , i.e., 1 is less than 6, go to step 3.

Step 3. The lower-bounds are computed for each node at level 1 by bounding procedure LBI such that

Node	(1)	(2)	(3)	(4)	(5)	(6)
Lower-bound	57	63	55	57	57	59

Step 4. Search for the minimum unexplored node(s) at level L . The minimum value of the lower-bound at level 1, 1B , is equal to 55 for node (3). According to step 4.1, go to step 5, since 1B is less than T_0 , i.e., 55 is less than ∞ .

Step 5. The tie does not exist for the minimum lower-bound. Therefore, the selected node, (3), is branched to generate the nodes (31), (32), (34), (35) and (36) at level 2.

Step 6. Set level L equal to 2 and go to step 2.

Step 2. Check level L . Since level L is less than J , i.e., 2 is less than 6, go to step 3.

Step 3. The lower-bounds for each node at level 2 are computed by bounding procedure LBI such that

Node	(31)	(32)	(34)	(35)	(36)
Lower-bound	55	61	56	55	59

Step 4. The minimum lower-bound at level 2, 2B , is 55 for nodes (31) and (35).

Step 5. The tie is resolved in favor of node (31) according to the LHR in step 5.1. This active node, (31), is then branched to form new nodes (312), (314), (315) and (316) at level 3.

Step 6. Set level L equal to 3 and go to step 2.

Step 2. Check level L. As L or 3 is less than J or 6, go to step 3.

Step 3. The lower-bounds are computed for all nodes at level 3 by bounding procedure LBI such that

Node	(312)	(314)	(315)	(316)
Lower-bound	64	60	57	63

Step 4. The node (315) has the minimum lower-bound at level 3, 3B , which is equal to 57. According to step 4.1, go to step 5 since 3B or 57 is less than T_0 or ∞ .

Step 5. The active node (315) is branched to create new set of nodes (3152), (3154) and (3156) at level 4.

Step 6. Set level L equal to 4 and go to step 2.

Step 2. Check level L. According to step 2.1 go to step 3 since L or 4 is less than J or 6.

Step 3. At level 4, the lower-bounds are computed for all nodes by bounding procedure LBI such that

Node	(3152)	(3154)	(3156)
Lower-bound	62	58	61

Step 4. At level 4, the node (3154) is picked up for branching since

it has the minimum lower-bound. According to step 4.1, go to step 5, since 4_B or 58 is less than T_0 or ∞ .

Step 5. The active node at this level, (3154), is branched to generate new nodes (31542) and (31546) at level 5.

Step 6. Set level L equal to 5 and go to step 2.

Step 2. Check level index L. Since L is less than J or 5 is less than 6, go to step 3.

Step 3. The lower-bounds are computed for all nodes at level 5 by bounding procedure LBI such that

Node	(31542)	(31546)
Lower-bound	64	65

Step 4. The minimum lower-bound at level 5, 5_B , is 64 for node (31542). Following step 4.1, go to step 5 because 5_B or 64 is less than T_0 or ∞ .

Step 5. The active node, (31542), at level 5 is branched to generate a node with complete sequence {3 1 5 4 2 6} at level 6.

Step 6. Set level L equal to 6 and go to step 2.

Step 2. Check level L. As level L or 6 is equal to J or 6, according to step 2.2, the minimum lower-bound at level 5 or 5_B is compared with the initial schedule time, T_0 or ∞ . Since 5_B or 64 is less than T_0 or ∞ , the initial schedule time is updated according to step 2.2.1 by setting $T_1 = {}^5_B = 64$. Set $L = L - 1$ or 5 and go to step 7.

Step 7. Back-track along the same branch of the scheduling tree if there is a possibility for a better solution. Set level index $L = L - 1$ or 4 and compare the lower-bounds of all unexplored nodes with the updated schedule time, T_1 . There are two nodes (3152) and (3156) having lower-bounds

62 and 61, respectively, which are less than T_1 or 64. According to step 7.1, go to step 4.

Step 4. At level 4, the minimum lower-bound, 4B , is 61 for node (3156). According to step 4.1, go to step 5 since 4B or 61 is less than T_1 or 64.

Step 5. The active node (3156) at level 4, is branched according to step 5.2 to create level 5 having nodes (31562) and (31564).

Step 6. Set level L equal to 5 and go to step 2.

Step 2. Check level L . Since L or 5 is less than J or 6, go to step 3.

Step 3. By bounding procedure LBI, the lower-bounds are computed for each node at level 5, such that

Node	(31562)	(31564)
Lower-bound	61	61

Step 4. At level 5, the minimum lower-bound, 5B , is 61 for nodes (31562) and (31564). According to step 4.1, since 5B or 61 is less than T_1 or 64, go to step 5.

Step 5. According to the (LHR) in step 5.1, the tie at level 5 is resolved in favor of node (31562). This node is then branched according to step 5.2 to generate a node having complete sequence {3 1 5 6 2 4}.

Step 6. Set level, L , equal to 6 and go to step 2.

Step 2. Check level L . The level, L or 6, is equal to J or 6; the minimum lower bound at level 5, 5B , is compared with the updated schedule time, T_1 , according to step 2.2. Since B^5 or 61 is less than T_1 or 64, the updated schedule time is modified by setting $T_2 = B^5 = 61$. Set level L equal to $L - 1$ or 5 and go to step 7.

Similarly, the back-tracking process is carried along the same branch of the scheduling tree to find the unexplored node(s) which has lower-bound less than the updated schedule time, T_2 . At level 3, the active node (314) which has lower-bound equal to 60, is branched to generate nodes (3142), (3145) and (3146) having lower-bounds 62, 61 and 67, respectively. Since any sequence derived from node (3145) can never have schedule time better than 61, the branching is terminated in this direction according to step 4.2. There is no unexplored node at level 3 which has lower-bound less than T_2 or 61. At level 2, the node (35) is picked up for branching which yields a sequence {3 5 1 4 2 6} having schedule time of 6.4. Back-tracking process selects another node (354) at level 3, for further branching. The branching is terminated at level 6 with no improved solution. The node (3542) at level 4, is branched to yield a sequence {3 5 4 2 6 1} with schedule time of 60 which is less than the updated schedule time, T_2 or 61. Now, the updated solution is modified such that $T_3 = 60$. The back-tracking along the same branch of the scheduling tree finds a node (356) at level 3 which is still unexplored and has lower-bound less than T_3 , i.e., ${}^3B^{356} < T_3$ or $57 < 60$. The branching from this node leads to a sequence {3 5 6 1 2 4} at level 6, having schedule time of 59. Since 59 is less than T_3 or 60 the updated schedule time is modified such that $T_4 = 59$. Back-tracking picks another node (3562) at level 4 which generates a sequence {3 5 6 2 4 1} with schedule time of 57. Again, the updated schedule time is modified according to step 2.2.1 such that $T_5 = 57$. The back-tracking reveals that there exists only one node (34) at level 2 which has lower-bound less than T_5 or that $56 < 57$. The branching is carried until level 3 where the nodes (3412), (3415) and (3416) having

lower-bounds 62, 61 and 67, respectively are generated. The branching in this direction is terminated, since the minimum lower-bound at this level is greater than the updated schedule time, T_5 or 57. The node (342) at level 3 is therefore branched but the branching is terminated at level 4. Now there is no unexplored node at any level which has lower-bound less than T_5 or 57. Hence, the schedule time, T_5 or 57, is the minimum schedule time and the corresponding sequence {3 5 6 2 4 1} is optimal. The problem is solved by exploring 58 nodes. It is interesting to know that 'paper and pencil' solution of this problem took around 5 hours while the author worked at normal pace.

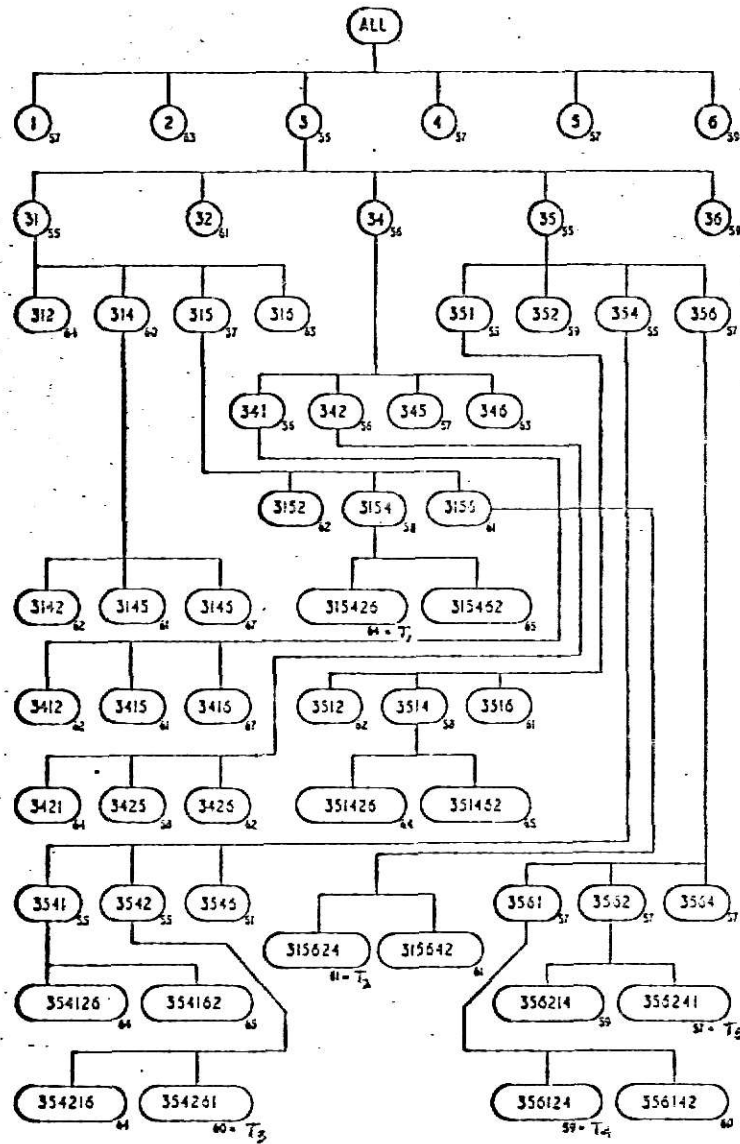


Figure 2.1

The Scheduling Tree

Table 2.2

Computation of Lower-Bounds

No. of Back- -track	Level	Node	L_C^n Machines			$\sum_{k=L+1}^J t_{j_k}^m$ Machines			$\min_{j_k \neq n} \left(\sum_{m'=m+1}^M t_{j_{k'}^{m'}} \right)$ Machines			L_B^n Machines			T_i
			1	2	3	1	2	3	1	2	3	1	2	3	
1	1	(1)	6	13	16	27	41	40	5	3	0	38	57	56	57
		(2)	12	14	17	21	46	40	10	3	0	43	63	57	63*
		(3)	4	10	18	29	42	35	5	3	0	38	55	53	55
		(4)	3	14	21	30	37	36	5	3	0	38	54	57	57
		(5)	6	14	24	27	40	33	5	3	0	38	57	57	57
		(6)	2	16	28	31	34	31	5	3	0	38	53	59	59
2	2	(31)	10	17	21	23	35	32	5	3	0	38	55	53	55*
		(32)	16	18	21	17	40	32	10	3	0	43	61	53	61
		(34)	7	21	28	26	31	28	5	3	0	38	55	56	56*
		(35)	10	18	28	23	34	25	5	3	0	38	55	53	55
		(36)	6	24	36	27	28	23	5	3	0	38	55	59	59
3	3	(312)	22	24	27	11	33	29	18	7	0	51	64	56	64
		(314)	13	28	35	20	24	25	5	3	0	38	55	60	60*
		(315)	16	25	35	17	27	22	5	3	0	38	55	57	57
		(316)	12	31	43	21	21	20	5	3	0	38	55	63	63
4	4	(3152)	28	30	38	5	25	19	18	7	0	51	62	57	62*
		(3154)	19	36	43	14	16	15	5	3	0	38	55	58	58
		(3156)	18	39	51	15	13	10	5	3	0	38	55	61	61
5	5	(31542)	31	38	46	2	14	12	26	12	0	59	64	59	64*
		(31546)	21	50	62	12	2	3	5	3	0	38	55	65	65
1	6	(315426)	33	52	64	0	0	0	0	0	0	33	52	64	64*
															T_1

Table 2.2 (continued)

Computation of Lower-Bounds

No. of Back- -track	Level	Node	$L_{C_m}^n$			$\sum_{k=L+1}^J t_{j_k}^m$			$\min \left\{ \sum_{m'=m+1}^M j_k^{m'} t_{j_k^{m'}}^{m'} \right\}$			$L_{B_m}^n$			T_i
			Machines			Machines			Machines			Machines			
			1	2	3	1	2	3	1	2	3	1	2	3	
5		(31562)	30	41	54	3	11	7	18	7	0	51	59	61	61*
		(31564)	21	50	58	12	2	3	5	3	0	38	55	61	51
2	6	(315624)	33	52	61	0	0	0	0	0	0	33	52	61	61*
4		(3142)	25	30	38	8	22	22	18	10	0	51	62	60	62*
		(3145)	19	36	46	14	16	15	5	3	0	38	55	61	61
		(3146)	15	42	54	18	10	13	5	3	0	38	55	67	67
3		(351)	16	25	31	17	27	22	5	3	0	38	55	53	55*
		(352)	22	24	31	11	32	22	10	3	0	43	59	53	59*
		(354)	13	29	36	20	23	18	5	3	0	38	55	54	55
	(356)	12	32	44	21	20	13	5	3	0	38	55	57	57	
4		(3512)	28	30	34	5	25	19	18	7	0	51	62	53	62*
		(3514)	19	36	43	14	16	15	5	3	0	38	55	58	58
		(3516)	18	39	51	15	13	10	5	3	0	38	55	61	61
5		(35142)	31	38	46	2	14	12	26	12	0	59	64	58	64*
		(35146)	21	50	62	12	2	3	5	3	0	38	55	65	65
4		(3541)	19	36	39	14	16	15	5	3	0	38	55	54	55*
		(3542)	25	31	39	8	21	15	10	3	0	43	55	54	55
		(3546)	15	43	55	18	9	6	5	3	0	38	55	61	61
5		(35412)	31	38	42	2	14	12	26	12	0	59	64	54	64*
		(35416)	21	50	62	12	2	3	5	3	0	38	55	65	65

Table 2.2 (continued)

Computation of Lower-Bounds

No. of Back- -track	Level	Node	$L_{C_m}^n$			$\sum_{k=L+1}^J t_{j_k}^m$			$\min \left(\sum_{m'=m+1}^M t_{j_{k'}^{m'}} \right)$			L_B^n			T_i
			Machines			Machines			Machines			Machines			
			1	2	3	1	2	3	1	2	3	1	2	3	
5	5	(35421)	31	38	42	2	14	12	26	12	0	59	64	54	64*
		(35426)	27	45	57	6	7	3	10	3	0	43	55	60	60
3	6	(354261)	33	52	60	0	0	0	0	0	0	33	52	60	60*
															T_3
4	4	(3561)	18	39	47	15	13	10	5	3	0	38	55	57	57*
		(3562)	24	34	47	9	18	10	10	3	0	43	55	57	57*
5	5	(3564)	15	43	51	18	9	6	5	3	0	38	55	57	57*
															T_4
4	6	(35612)	30	41	50	3	11	7	18	7	0	51	59	57	59*
		(35614)	21	50	57	12	2	3	5	3	0	38	55	60	60
5	6	(356124)	33	52	59	0	0	0	0	0	0	33	52	59	59*
															T_5
5	5	(35621)	30	41	50	3	11	7	18	7	0	51	59	57	59*
		(35624)	27	45	54	6	7	3	10	3	0	43	55	57	57*
5	6	(356241)	33	52	57	0	0	0	0	0	0	33	52	57	57*
															T_5
3	3	(341)	13	28	31	20	24	25	5	3	0	38	55	56	56*
		(342)	19	23	31	14	29	25	10	3	0	43	55	56	56*
4	4	(345)	13	29	39	20	23	18	5	3	0	38	55	57	57*
		(346)	9	35	47	24	17	16	5	3	0	38	55	63	63
4	4	(3412)	25	30	34	8	22	22	18	10	0	51	62	56	62*
		(3415)	19	36	46	14	16	15	5	3	0	38	55	61	61*
5	5	(3416)	15	42	54	18	10	13	5	3	0	38	55	67	67*
															T_5

Table 2.2 (continued)

Computation of Lower-Bounds

No. of Back- -track	Level	Node	L_C^n _m	$\sum_{k=L+1}^J t_{j_k}^m$	$\min_{j_k \neq n} \left(\sum_{m'=m+1}^M t_{j_{k,m'}} \right)$	L_B^n _m									T_i
						Machines			Machines			Machines			
						1	2	3	1	2	3	1	2	3	
4	(3421)	(3425)	25	32	35	8	22	22	18	10	0	51	64	57	64*
			25	33	43	8	21	15	10	3	0	43	57	58	58
			21	37	49	12	15	13	10	3	0	43	55	62	62

* indicates minimum lower-bound at that level.

CHAPTER III

LOWER-BOUNDS ON SCHEDULE TIME

As mentioned in the previous chapter, the bounding process reduces the number of explored nodes, and, thus decreases considerable amount of computation time involved. This chapter is devoted to the analytical study of the various lower-bounds which have been developed by several investigators. To illustrate the various bounding procedures, a sample problem will be solved in Section 3.6 employing the branch-and-bound algorithm discussed in Chapter II. The values of the lower-bounds for all nodes, at each level, will be summarized in the solution of this sample problem. However, the lower-bounds for only two nodes at different levels will be computed following the mathematical analysis of each bounding procedure. Since the bound on the schedule time is a function of the processing times of the jobs on the machines, the computation of the lower-bounds by the various bounding procedures requires the data in the processing time matrix. Thus, for convenience, the processing time matrix of the sample problem solved in Section 3.6 is reproduced below:

$$T = \begin{bmatrix} 9 & 13 & 6 \\ 7 & 7 & 20 \\ 6 & 4 & 8 \\ 8 & 3 & 10 \\ 20 & 7 & 2 \\ 10 & 2 & 13 \end{bmatrix}$$

The following notation is considered to discuss those bounding procedures:

- L level index of the scheduling tree, $L = 1, 2, \dots, J$
- n node at any level, L , consisting of a partial sequence of scheduled jobs, $\{j_1 j_2 \dots j_L\}$
- \bar{n} a set of unscheduled jobs, $j_{L+1}, j_{L+2}, \dots, j_J$
- C_m^n completion time on machine m , at level L , and for node n . It is also the earliest possible starting time for the first unscheduled job, j_{L+1} , if there is no conflict on preceding machines.
- L_B^n bound on the schedule time, on machine m , at level L , and for node n .
- L_B^n lower-bound on the schedule time, at level L , for node n .
- L_B minimum lower-bound on the schedule time at level L .

3.1 Bounding Procedure LB I

This bounding procedure has been developed by Lomnicki [12] for the 3-machine flow shop scheduling problem and then extended to an arbitrary number of machines by Brown and Lomnicki [3]. The extension is based on an assumption that all jobs are processed in the same sequence on each of m machines. This procedure is also referred to as machine-based bound [13], since it estimates a bound by finding a schedule time on each machine.

Mathematically; the bound, $L_{B_m}^n$, for each node n , on machine m , at level L , is given as

$$L_{B_m}^n = L_{C_m}^n + \sum_{k=L+1}^J t_{j_k^m} + \min_{j_k \in n} \left(\sum_{m'=m+1}^M t_{j_k^{m'}} \right),$$

$$k = 1, 2, \dots, J,$$

$$m = 1, 2, \dots, M-1, \quad (1)$$

and

$$L_{B_M}^n = L_{C_M}^n + \sum_{k=L+1}^J t_{j_k^M} \quad (2)$$

The completion time on machine m , at level L and for node n which has the partial sequence $\{j_1 j_2 \dots j_L\}$ is such that

$$L_{C_m}^n = \max \left\{ \begin{matrix} L \\ C_{m-1} \end{matrix} j_1 j_2 \dots j_L, \begin{matrix} L-1 \\ C_m \end{matrix} j_1 j_2 \dots j_{L-1} \right\} + t_{j_L^m},$$

$$m = 1, 2, \dots, M, \quad (3)$$

where

$$\begin{matrix} L \\ C_{m-1} \end{matrix} j_1 j_2 \dots j_L = 0, \quad m = 1$$

and

$$\begin{matrix} L-1 \\ C_m \end{matrix} j_1 j_2 \dots j_{L-1} = 0, \quad L = 1$$

The lower-bound at level L , for any node n is given by

$$L_B^n = \max \left(L_{B_1}^n, L_{B_2}^n, \dots, L_{B_M}^n \right)$$

$$= \max_m \left(L_{B_m}^n \right)$$

In words, Equation (1) consists of the sum of three terms. The first term, $L_{C_m}^n$, is the measure of time elapsed from the start of processing the job in the first sequence-position, j_1 , on machine 1, until the completion of the job in the last sequence-position, j_L , of the partial sequence, $\{j_1 j_2 \dots j_L\}$, on machine m . It should be noted that this term includes all idle times, if any, on machine m , for all jobs included in the partial sequence of node n .

The term, $L_{C_m}^n$, is calculated by employing Equation (3), the elements of which can be explained as follows:

$$L_{C_{m-1}}^{j_1 j_2 \dots j_L}$$

the completion time of job j_L in the partial sequence of node n , on machine $m-1$. In other words, this is the earliest possible time at which job j_L is ready to be processed on machine m .

$$L_{C_m}^{j_1 j_2 \dots j_{L-1}}$$

the completion time of job j_{L-1} , in the partial sequence of node n , on machine m . In other words, this gives the earliest possible time at which machine m will be ready to process job j_L .

The maximum of these two periods will give the starting time of job j_L on machine m .

The second term in Equation (1), is the total processing time for the remaining unscheduled jobs, $j_{L+1}, j_{L+2}, \dots, j_J$; on machine m , regardless of overlapping of these jobs on that machine. This assumes that there is no idle time on machine m for these unscheduled jobs.

The third term in Equation (1), is the sum of processing times of the last job in the complete sequence on the succeeding machines, $m+1, m+2, \dots, M$. Since the job which will fill up the last sequence-position of the required complete sequence, is not yet determined, a job with the minimum total processing time on all succeeding machines is selected to be in the last sequence-position so as to minimize L_B^n . The jobs in the partial sequence have already been scheduled; hence this last job is chosen from unscheduled jobs.

The following computations illustrate the bounding procedure LBI discussed above. For space limitation, the computation of the lower-bounds for only node (3) at level 1 and node (34) at level 2 will be shown below.

At level 1 and for the node n which consists of partial sequence $\{j_1\}$ or $\{3\}$, the completion time on each machine is computed such that

$${}^1C_1^3 = \max \left[{}^1C_0^3, {}^0C_1^0 \right] + t_{31},$$

$${}^1C_2^3 = \max \left[{}^1C_1^3, {}^0C_2^0 \right] + t_{32},$$

and

$${}^1C_3^3 = \max \left\{ {}^1C_2^3, {}^0C_3^0 \right\} + t_{33},$$

or

$${}^1C_1^3 = \max \left\{ 0, 0 \right\} + 6 = 6,$$

$${}^1C_2^3 = \max \left\{ 6, 0 \right\} + 4 = 10,$$

and

$${}^1C_3^3 = \max \left\{ 10, 0 \right\} + 8 = 18.$$

The bound for this node is computed on each machine such that

$${}^1B_1^3 = {}^1C_1^3 + \sum_{k=2}^6 t_{j_k 1} + \min_{j_k \neq 3} \left(\sum_{m'=2}^3 t_{j_k m'} \right),$$

$${}^1B_2^3 = {}^1C_2^3 + \sum_{k=2}^6 t_{j_k 2} + \min_{j_k \neq 3} (t_{j_k 3}),$$

and

$${}^1B_3^3 = {}^1C_3^3 + \sum_{k=2}^6 t_{j_k 3},$$

or

$${}^1B_1^3 = 6 + (9+7+8+20+10) + \min [13+6, 7+20, 3+10, 7+2, 2+13]$$

$$= 6 + 54 + 9$$

$$= 69,$$

$${}^1B_2^3 = 10 + (13+7+3+7+2) + \min [6, 20, 10, 2, 13]$$

$$= 10 + 32 + 2$$

$$= 44,$$

and

$${}^1B_3^3 = 18 + (6+20+10+2+13)$$

$$= 18 + 51$$

$$= 69.$$

Thus, the lower-bound for this node is

$${}^1B^3 = \max \left({}^1B_1^3, {}^1B_2^3, {}^1B_3^3 \right)$$

$$= \max \left(69, 44, 69 \right)$$

$$= 69.$$

Similarly, the lower-bounds for nodes (1), (2), (4), (5) and (6) is found to be 81, 73, 70, 86 and 71, respectively.

At level 2, the completion times for node having partial sequence $\{j_1 j_2\}$ or $\{3 4\}$ are computed such that

$${}^2C_1^{34} = \max \left({}^2C_0^{34}, {}^1C_1^3 \right) + t_{41},$$

$${}^2C_2^{34} = \max \left({}^2C_1^{34}, {}^1C_2^3 \right) + t_{42},$$

and

$${}^2C_3^{34} = \max \left\{ {}^2C_2^{34}, {}^1C_3^3 \right\} + t_{43},$$

or

$${}^2C_1^{34} = \max \left\{ 0, 6 \right\} + 8 = 14,$$

$${}^2C_2^{34} = \max \left\{ 14, 10 \right\} + 3 = 17,$$

and

$${}^2C_3^{34} = \max \left\{ 17, 18 \right\} + 10 = 28.$$

At this level, the bounds for this node on each machine are computed such that

$${}^2B_1^{34} = {}^2C_1^{34} + \sum_{k=3}^6 t_{j_k 1} + \min_{j_k \neq 3,4} \left\{ \sum_{m=2}^3 t_{j_k m} \right\},$$

$${}^2B_2^{34} = {}^2C_2^{34} + \sum_{k=3}^6 t_{j_k 2} + \min_{j_k \neq 3,4} (t_{j_k 3}),$$

and

$${}^2B_3^{34} = {}^2C_3^{34} + \sum_{k=3}^6 t_{j_k 3},$$

or

$$\begin{aligned}
2B_1^{34} &= 14 + (9+7+20+10) + \min [13+6, 7+20, 7+2, 2+13] \\
&= 14 + 46 + 9 = 69,
\end{aligned}$$

$$\begin{aligned}
2B_2^{34} &= 17 + (13+7+7+2) + \min [6, 20, 2, 13] \\
&= 17 + 29 + 2 = 48,
\end{aligned}$$

and

$$\begin{aligned}
2B_3^{34} &= 28 + (6+20+2+13) \\
&= 69.
\end{aligned}$$

Thus, the lower bound for this node is

$$\begin{aligned}
2B^{34} &= \max [69, 48, 69] \\
&= 69.
\end{aligned}$$

Similarly, the lower-bounds for each node at all levels are computed.

3.2 Bounding Procedure LB II

Ignall and Schrage [8] have developed the sophisticated bounding procedure LB II for 3-machine flow shop scheduling problem. For comparison purposes, this procedure is extended for an arbitrary number of machines, M . It differs with LB I only in the computation of the completion time. This procedure considers the bound on each machine independently, such as in LB I. It forms a bound from the total processing time remaining on that machine, together with the minimum run-out time for that machine.

In mathematical terms, the bound, $L B_m^n$, on machine m , at level L , for node n , can be stated as follows:

$$L_{B_m}^n = L_{D_m}^n + \sum_{k=L+1}^J t_{j_k^m} + \min_{j_k \in \bar{n}} \left(\sum_{m'=m+1}^M t_{j_k^{m'}} \right),$$

$$k = 1, 2, \dots, J,$$

$$m = 1, 2, \dots, M, \quad (4)$$

where

$$\min_{j_k \in \bar{n}} \left(\sum_{m'=m+1}^M t_{j_k^{m'}} \right) = 0, \quad m = M,$$

At level L , the earliest starting time of the first unscheduled job, j_{L+1} , on machine m , for each node n , $L_{D_m}^n$, is given by

$$L_{D_m}^n = \max_i \left(L_{C_m}^n, L_{C_{m-i}}^n + \min_{j_k \in \bar{n}} \left(\sum_{m'=m-i}^{m-1} t_{j_k^{m'}} \right) \right),$$

$$k = 1, 2, \dots, J,$$

$$m = 1, 2, \dots, M, \quad (5)$$

$$i = 1, 2, \dots, m-1$$

where

$$L_{C_{m-i}}^n + \min_{j_k \in \bar{n}} \left(\sum_{m'=m-i}^{m-1} t_{j_k^{m'}} \right) = 0, \quad m = 1$$

In words, Equation (4) states that at level L , for node n , the schedule time on machine m is bounded from below by the sum of three terms: the earliest starting time of the first unscheduled job, j_{L+1} , on machine m ,

plus the total processing time of all unscheduled jobs on the same machine, plus the minimum of the total processing times required to perform the unscheduled jobs on succeeding machines, $m+1, m+2, \dots, M$, i.e., the minimum run-out time on machine m . As in Equation (1), the last term becomes zero when the bound is computed on machine M . Thus, the lower-bound at level L and for each node n is such that

$$L_B^n = \max_m \left(L_{D_m}^n \right)$$

The first term, $L_{D_m}^n$, is obtained by the recursive Equation (5). This term computes the earliest possible starting time for the first unscheduled job on machine m . This is done by estimating the minimum idle time between the completion of last job, j_L , in the partial sequence of node n , and the start of the first unscheduled job, j_{L+1} .

As in LB I, it is sufficient to show the computation of the lower-bounds for node (3) at level 1 and node (34) at level 2.

At level 1 and for node (3), the completion time for scheduled job on each machine is computed according to Equation (3) such that

$${}^1C_1^3 = \max \left({}^1C_0^3, {}^0C_1^0 \right) + t_{31},$$

$${}^1C_2^3 = \max \left({}^1C_1^3, {}^0C_2^0 \right) + t_{32},$$

and

$${}^1C_3^3 = \max \left({}^1C_2^3, {}^0C_3^0 \right) + t_{33},$$

or

$$1_{C_1}^3 = \max \left(0, 0 \right) + 6 = 6,$$

$$1_{C_2}^3 = \max \left(6, 0 \right) + 4 = 10,$$

and

$$1_{C_3}^3 = \max \left(10, 0 \right) + 8 = 18 .$$

The earliest starting time of the first unscheduled job on each machine is obtained by using Equation (5), such that

$$1_{D_1}^3 = \max \left(1_{C_1}^3, 0 \right) ,$$

$$1_{D_2}^3 = \max \left(1_{C_2}^3, 1_{C_1}^3 + \min_{j_k \neq 3}^{j_k} (t_{j_k 1}) \right) ,$$

and

$$1_{D_3}^3 = \max \left(1_{C_3}^3, 1_{C_2}^3 + \min_{j_k \neq 3}^{j_k} (t_{j_k 2}) , 1_{C_1}^3 + \min_{j_k \neq 3}^{j_k} \left(\sum_{m'=1}^2 t_{j_k m'} \right) \right)$$

or

$$1_{D_1}^3 = \max \left(6, 0 \right) = 6,$$

$$1_{D_2}^3 = \max \left(10, 6 + \min [9, 7, 8, 20, 10] \right)$$

$$= \max \left(10, 6+7 \right) = 13,$$

and

$$\begin{aligned}
 l_{D_3}^3 &= \max \left(18, 10 + \min [13, 7, 3, 7, 2], 6 + \right. \\
 &\quad \left. \min [9+13, 7+7, 8+3, 20+7, 10+2] \right) \\
 &= \max [18, 10+2, 6+11] = 18.
 \end{aligned}$$

The bounds for node (3) at level 1 on each machine is given as follows:

$$l_{B_1}^3 = l_{D_1}^3 + \sum_{k=2}^6 t_{j_k 1} + \min_{j_k \neq 3} \left(\sum_{m'=2}^3 t_{j_k m'} \right),$$

$$l_{B_2}^3 = l_{D_2}^3 + \sum_{k=2}^6 t_{j_k 2} + \min_{j_k \neq 3} (t_{j_k 3}),$$

and

$$l_{B_3}^3 = l_{D_3}^3 + \sum_{k=2}^6 t_{j_k 3},$$

or

$$l_{B_1}^3 = 6 + (9+7+8+20+10) + \min [13+6, 7+20, 3+10, 7+2, 2+13]$$

$$= 6 + 54 + 9 = 69,$$

$$l_{B_2}^3 = 13 + (13+7+3+7+2) + \min [6, 20, 10, 2, 13]$$

$$= 13 + 32 + 2 = 47,$$

and

$$\begin{aligned}
 {}^1B_3^3 &= 18 + (6+20+10+2+13) \\
 &= 18 + 51 = 69.
 \end{aligned}$$

Thus, the lower-bound at level 1 for node (3) is

$$\begin{aligned}
 {}^1B^3 &= \max \left({}^1B_1^3, {}^1B_2^3, {}^1B_3^3 \right) \\
 &= \max \left(69, 47, 69 \right) \\
 &= 69.
 \end{aligned}$$

Following the same steps, the lower-bounds for nodes (1), (2), (4), (5) and (6) is found to be 81, 73, 70, 87 and 71, respectively.

At level 2 and for node (34), the completion time on each machines are computed such that

$${}^2C_1^{34} = \max \left({}^2C_0^{34}, {}^1C_1^3 \right) + t_{41},$$

$${}^2C_2^{34} = \max \left({}^2C_1^{34}, {}^1C_2^3 \right) + t_{42},$$

and

$${}^2C_3^{34} = \max \left({}^2C_2^{34}, {}^1C_3^3 \right) + t_{43},$$

or

$${}^2C_1^{34} = \max \left(0, 6 \right) + 8 = 14,$$

$${}^2C_2^{34} = \max \left(14, 10 \right) + 3 = 17,$$

and

$${}^2C_3^{34} = \max \left[17, 18 \right] + 10 = 28.$$

The earliest starting time of the first unscheduled job on each machine is given such that

$${}^2D_1^{34} = \max \left[{}^2C_1^{34}, 0 \right],$$

$${}^2D_2^{34} = \max \left[{}^2C_2^{34}, {}^2C_1^{34} + \min_{j_k \neq 3,4} \left(t_{j_k 1} \right) \right],$$

and

$${}^2D_3^{34} = \max \left[{}^2C_3^{34}, {}^2C_2^{34} + \min_{j_k \neq 3,4} \left(t_{j_k 2} \right), {}^2C_1^{34} + \min_{j_k \neq 3,4} \left(\sum_{m'=1}^2 t_{j_k m'} \right) \right],$$

or

$${}^2D_1^{34} = \max \left[14, 0 \right]$$

$$= 14,$$

$${}^2D_2^{34} = \max \left[17, 14 + \min [9, 7, 20, 10] \right]$$

$$= \max \left[17, 21 \right]$$

$$= 21,$$

and

$$\begin{aligned}
 2_{D_3}^{34} &= \max \{28, 17 + \min [13, 7, 7, 2], 14 + \min [9+13, 7+7, 20+7, 10+2]\} \\
 &= \max [28, 19, 26] \\
 &= 28.
 \end{aligned}$$

At level 2 and for node (34) the bounds on all machines are given such that

$$2_{B_1}^{34} = 2_{D_1}^{34} + \sum_{k=3}^6 t_{j_k 1} + \min_{\substack{j_k \\ j_k \neq 3,4}} \left(\sum_{m'=2}^3 t_{j_k m'} \right),$$

$$2_{B_2}^{34} = 2_{D_2}^{34} + \sum_{k=3}^6 t_{j_k 2} + \min_{\substack{j_k \\ j_k \neq 3,4}} (t_{j_k 3}),$$

and

$$2_{B_3}^{34} = 2_{D_3}^{34} + \sum_{k=3}^6 t_{j_k 3},$$

or

$$\begin{aligned}
 2_{B_1}^{34} &= 14 + (9+7+20+10) + \min [13+6, 7+20, 7+2, 2+13] \\
 &= 14 + 46 + 9 \\
 &= 69,
 \end{aligned}$$

$$\begin{aligned}
 2_{B_2}^{34} &= 21 + (13+7+7+2) + \min [6, 20, 2, 13] \\
 &= 21 + 29 + 2 \\
 &= 52,
 \end{aligned}$$

and

$$\begin{aligned} 2_{B_3}^{34} &= 28 + (6+20+2+13) \\ &= 69. \end{aligned}$$

Therefore, the lower-bound at level 2 and for the node (34) is

$$\begin{aligned} 2_{B_3}^{34} &= \max [69, 52, 69] \\ &= 69. \end{aligned}$$

Similarly, the remaining lower-bounds are computed for all nodes at each level.

3.3 Bounding Procedure LB III

This bounding procedure has been introduced by McMahon and Burton [13], which in some circumstances gives a larger value than that obtainable by other lower-bounds. The bounding procedure, LB III, has been referred to as job-based bound, since it expresses the fact that the schedule time may be determined by the total processing time for a job, rather than by the total processing time on one machine.

The bound on the schedule time, $L_{B_m}^n$, is expressed such that

$$L_{B_m}^n = L_{C_m}^n + \max_{j_k \in n} \left(\sum_{m'=m}^M t_{j_k m'} + \sum_{\substack{x=L+1 \\ j_x \neq j_k}}^J \min (t_{j_x m}, t_{j_x M}) \right),$$

$$k = L+1, L+2, \dots, J$$

$$m = 1, 2, \dots, M$$

$$L = 1, 2, \dots, J$$

(6)

where

$$\max_{j_k \in \bar{n}} \left(\sum_{m'=m}^M t_{j_k m'} + \sum_{\substack{x=L+1 \\ j_x \neq j_k}}^J \min(t_{j_x m}, t_{j_x M}) \right) = \sum_{k=L+1}^J t_{j_k M}, \quad m = M.$$

In words, Equation (6) states that at level L , the schedule time of each node n , on machine m , is bounded from below by the sum of the following two terms. The first term represents the completion time of all jobs included in the partial sequence of node n , at level L , on machine m . This is also an estimate of the earliest possible starting time for any unscheduled job on machine m , assuming no conflict for this job. The second term consists of two parts: (1) the total processing time on one of the unscheduled jobs, $j_k \in \bar{n}$, on machines $m, m+1, \dots, M$, assuming no conflict or overlapping for this job on any of these machines; (2) the sum of minimum processing time either on machine m or on machine M , for all remaining unscheduled jobs because each of these jobs must either precede job j_k on machine m or follow it on machine M .

Similar to the previous bounding procedures, the computation of LB III is shown for only node (3) at level 1 and node (34) at level 2.

At level 1 and for node (3), the completion time for scheduled jobs on each machine is computed such that

$${}^1C_1^3 = \max \left({}^1C_0^3, {}^0C_1^0 \right) + t_{31},$$

$${}^1C_2^3 = \max \left({}^1C_1^3, {}^0C_2^0 \right) + t_{32},$$

and

$${}^1C_3^3 = \max \left({}^1C_2^3, {}^0C_3^0 \right) + t_{33},$$

or

$${}^1C_1^3 = \max \left(0, 0 \right) + 6 = 6,$$

$${}^1C_2^3 = \max \left(6, 0 \right) + 4 = 10,$$

and

$${}^1C_3^3 = \max \left(10, 0 \right) + 8 = 18.$$

Bounds on schedule time, at level 1 and for node (3) on each machine is given by

$${}^1B_1^3 = {}^1C_1^3 + \max_{\substack{j_k \\ j_k \neq 3}} \left(\sum_{m'=1}^3 t_{j_k m'} + \sum_{\substack{x=2 \\ j_x \neq j_k}}^6 \min(t_{j_x 1}, t_{j_x 3}) \right),$$

$${}^1B_2^3 = {}^1C_2^3 + \max_{\substack{j_k \\ j_k \neq 3}} \left(\sum_{m'=2}^3 t_{j_k m'} + \sum_{\substack{x=2 \\ j_x \neq j_k}}^6 \min(t_{j_x 2}, t_{j_x 3}) \right),$$

and

$${}^1B_3^3 = {}^1C_3^3 + \sum_{k=2}^6 t_{j_k 3},$$

or

$$\begin{aligned} {}^1B_1^3 &= 6 + \max [(9+13+6) + (7+8+2+10), (7+7+20) \\ &\quad + (6+8+2+10), (8+3+10) + (6+7+2+10), (20+7+2) \\ &\quad + (6+7+8+10), (10+2+13) + (6+7+8+2)] \end{aligned}$$

$$= 6 + \max [55, 60, 46, 60, 48]$$

$$= 66,$$

$${}^1_{B_2}{}^3 = 10 + \max [19+14, 27+13, 13+17, 9+18, 15+18]$$

$$= 10 + \max [33, 40, 30, 27, 33]$$

$$= 50,$$

and

$${}^1_{B_3}{}^3 = 18 + (6 + 20 + 10 + 2 + 13)$$

$$= 18 + 51$$

$$= 69 .$$

The lower-bound for this node is given by

$${}^1_B{}^3 = \max [66, 50, 69]$$

$$= 69.$$

At level 2 and for node (34), the completion times for scheduled jobs on each machine is computed such that

$${}^2_{C_1}{}^{34} = \max \left[{}^2_{C_0}{}^{34}, {}^1_{C_1}{}^3 \right] + t_{41},$$

$${}^2_{C_2}{}^{34} = \max \left[{}^2_{C_1}{}^{34}, {}^1_{C_2}{}^3 \right] + t_{42},$$

and

$${}^2C_3^{34} = \max \left[{}^2C_2^{34}, {}^1C_3^3 \right] + t_{43},$$

or

$${}^2C_1^{34} = \max \left[0, 6 \right] + 8$$

$$= 14,$$

$${}^2C_2^{34} = \max \left[14, 10 \right] + 3$$

$$= 17,$$

and

$${}^2C_3^{34} = \max \left[17, 18 \right] + 10$$

$$= 28 .$$

The bounds for this node on each machine' is given by

$${}^2B_1^{34} = {}^2C_1^{34} + \max_{j_k \neq 3,4} \left(\sum_{m=1}^3 t_{j_k^m}, + \sum_{\substack{x=3 \\ j_x \neq j_k}}^6 \min (t_{j_x 1}, t_{j_x 3}) \right) ,$$

$${}^2B_2^{34} = {}^2C_2^{34} + \max_{j_k \neq 3,4} \left(\sum_{m=2}^3 t_{j_k^m}, + \sum_{\substack{x=3 \\ j_x \neq j_k}}^6 \min (t_{j_x 2}, t_{j_x 3}) \right) ,$$

and

$${}^2B_3^{34} = {}^2C_3^{34} + \sum_{k=3}^6 t_{j_k 3} ,$$

or

$$\begin{aligned}
2_{B_1}^{34} &= 14 + \max [(9+13+6) + (7+2+10), (7+7+20) + (6+2+10), (20+7+2) \\
&\quad + (6+7+10), (10+2+13) + (6+7+2)] \\
&= 14 + \max [47, 52, 52, 40] \\
&= 14 + 52 \\
&= 66,
\end{aligned}$$

$$\begin{aligned}
2_{B_2}^{34} &= 17 + \max [19+11, 27+10, 9+15, 15+15] \\
&= 17 + \max [30, 37, 24, 30] \\
&= 54,
\end{aligned}$$

and

$$\begin{aligned}
2_{B_3}^{34} &= 28 + (6 + 20 + 2 + 13) \\
&= 28 + 41 \\
&= 69 .
\end{aligned}$$

Thus the lower-bound for node (34) at level 2 is

$$\begin{aligned}
2_B^{34} &= \max [66, 54, 69] \\
&= 69 .
\end{aligned}$$

Similarly, the other lower-bounds for all nodes at each level are computed.

3.4 Bounding Procedure LB IV

This procedure has been developed by McMahon and Burton [13] with the idea of selecting the more powerful bound from the machine-based bound and

the job-based bound. The bounding procedure, LB IV, has been referred to as a composite lower-bound, which is computed such that

$$LB\ IV = \max [LB\ I, LB\ III] .$$

To obtain composite lower-bound for any node n , the lower-bounds by bounding procedures LB I and LB III are first computed for that node. The maximum of these two lower-bounds is the composite lower-bound for that particular node.

3.5 Bounding Procedure LB V

This procedure has been developed by Nabeshima [15], referred to as revised lower-bound. This may be considered as a machine-based bound. Nabeshima has claimed that the bounding procedure, LB V, is superior over the other bounding procedures because it reduces the number of explored nodes in his sample problem.

This bounding procedure utilizes Johnson's criterion [9] of finding the optimal sequences on 2 machines, for the purpose of estimating powerful lower-bound. It has already been pointed out that LB I does not account for any idle time for the unscheduled jobs while computing total processing time for these jobs on machine m . However, LB V takes into consideration the estimation of this idle time by applying Johnson's criterion for the two-machine case as explained below.

The estimation of the idle time for the unscheduled jobs requires that they should have a specific sequence determined by any reasonable rule. LB V considers the sequence of the unscheduled jobs on consecutive two machines m and $m+1$, where $m = 1, 2, \dots, M-1$; by using criterion given by Johnson for independent two machines $m, m+1$. For any two jobs

j_r, j_s in \bar{n} , if

$$\min \left(t_{j_r m}, t_{j_s m+1} \right) \leq \min \left(t_{j_r m+1}, t_{j_s m} \right) \quad (7)$$

holds, then job j_r must precede job j_s in order to minimize the schedule time of the sequence of $J-L$ jobs in \bar{n} on machines m and $m+1$. The sequence constructed according to Johnson's criterion is referred to as preliminary sequence. Thus for M -machine problem, there will be $M-1$ preliminary partial sequences, $\bar{n}_{m,m+1}$ or $\{(j_{L+1} j_{L+2} \dots j_J)_{m,m+1}\}$, $m = 1, 2, \dots, M-1$, of unscheduled jobs in \bar{n} . Hence, the sequence $\{j_1 j_2 \dots j_L (j_{L+1} j_{L+2} \dots j_J)_{m,m+1}\}$, must be processed on machines $m, m+1$ in this order. Due to the nature of this sequence, it is referred to as dynamic sequence. The first L jobs in this dynamic sequence do not interchange their sequence-positions on any of the M machines, but the remaining $J-L$ jobs may interchange their sequence-positions on some or all of the M machines. The bounding procedure, LB V is stated below.

At level L , for node n , on machine m , the bound $L B_m^n$ is given by

$$L B_m^n = L C_m^n + L F_m^{\bar{n}_{m-1,m}} + \min_{j_k \in \bar{n}} \left(\sum_{m'=m+1}^M t_{j_k m'} \right),$$

$$m = 2, 3, \dots, M-1 \quad (8)$$

and

$$L B_M^n = L C_M^n + L F_M^{\bar{n}_{M-1,M}}$$

where $L F_m^{\bar{n}_{m-1,m}}$ is the total processing time of jobs in the preliminary partial sequence, $\{(j_{L+1} j_{L+2} \dots j_J)_{m-1,m}\}$, on machine m after the

completion time, $L_{C_m}^n$.

Equation (8) may further be simplified by combining the first two terms in the right hand side such that

$$L_{B_m}^n = L_{C_m}^{n_{m-1,m}} + \min_{j_k \in n} \left(\sum_{m'=m+1}^M t_{j_k^{m'}} \right)$$

$$m = 2, 3, \dots, M-1, \quad (9)$$

and

$$L_{B_M}^n = L_{C_M}^{n_{M-1,M}}$$

where $n_{m-1,m}$ is the dynamic sequence of J jobs on machines $m-1$ and m ,

$$\{j_1 j_2 \dots j_L (j_{L+1} j_{L+2} \dots j_J)_{m-1,m}\}.$$

The completion time for the scheduled jobs, $L_{C_m}^n$, is computed such that

$$L_{C_m}^n = \max \left(L_{C_{m-1}}^{j_1 j_2 \dots j_L}, L_{C_m}^{j_1 j_2 \dots j_{L-1}} \right) + t_{j_L^m},$$

$$m = 1, 2, \dots, M, \quad (10)$$

where

$$L_{C_{m-1}}^{j_1 j_2 \dots j_L} = 0, \quad m = 1$$

and

$$L_{C_m}^{j_1 j_2 \dots j_{L-1}}, \quad L = 1$$

The completion times for the unscheduled jobs which are arranged according to preliminary sequence, are computed by the following recurrent relation:

$$L_{C_m}^n(j_{L+1}, j_{L+2}, \dots, j_{L+h}) = \max \left[L_{C_m}^n(j_{L+1}, \dots, j_{L+h-1}), L_{C_{m-1}}^n + \sum_{\ell=1}^h t_{j_{L+\ell}}^{m-1} \right] + t_{j_{L+h}}^m,$$

$$h = 1, 2, \dots, J-L,$$

$$m = 2, 3, \dots, M, \quad (11)$$

where

$$L_{C_m}^n(j_{L+1}, \dots, j_{L+h-1}) = L_{C_m}^n, \quad h = 1$$

The lower-bound, L_B^n , at level L , for node n is given by

$$L_B^n = \max_m \left[L_{B_m}^n \right].$$

In words, Equation (9) is composed of two terms: The first term is the measure of the completion time of job j_J in the last sequence-position of the dynamic sequence, $\{j_1 j_2 \dots j_L (j_{L+1} j_{L+2} \dots j_J)_{m-1,m}\}$, on machine m . This is the time elapsed between the start of job j_1 on machine 1 and completion of job j_J on machine m , where j_1 and j_J belong to the same dynamic sequence. In addition to the sum of processing times of all jobs on machine m , this term also includes the exact idle time for jobs in the partial sequence of node n , and an estimate of idle time for unscheduled

jobs, \bar{n} . This term is computed by recursive Equations (10) and (11) which are similar to the Equation (3) of LB I.

The second term in Equation (9) computes the minimum run-out time for machine m . Run-out time is the duration of time between the completion of last job, j_J , on machine m and the completion of the same job on the last machine M . This term does not include idle time on any of the succeeding machines, $m+1, m+2, \dots, M$. It is obvious from definition that the run-out time on machine M is zero.

Theoretically, it may be stated that this lower-bound is more powerful in reducing the total number of nodes explored. This will always estimate bound which is equal to or greater than that computed by LB I, since

$$L \bar{n}_{F_m^{m-1,m}} \geq \sum_{k=L+1}^J t_{j_k^m}$$

Again, as in the previous bounding procedures, the computation of the lower-bounds for node (3) at level 1 and node (34) at level 2 will be shown below.

As required in the bounding procedure LB V, the preliminary sequence on machines 1 and 2 is {2 1 5 3 4 6}, and on machines 2 and 3 is {6 4 3 2 1 5}. For more detail refer to Appendix A in which Johnson's algorithm is applied.

At level 1 and for node (3), the completion time for scheduled job is computed according to Equation (10) such that

$$1C_1^3 = \max \left(1C_0^3, 0C_1^0 \right) + t_{31},$$

and

$$1C_2^3 = \max \left(1C_1^3, 0C_2^0 \right) + t_{32},$$

or

$$\begin{aligned} 1C_1^3 &= \max \left(0, 0 \right) + 6 \\ &= 6, \end{aligned}$$

and

$$\begin{aligned} 1C_2^3 &= \max \left(6, 0 \right) + 4 \\ &= 10. \end{aligned}$$

The completion time for the last job in the dynamic sequence, $\{3(2 \ 1 \ 5 \ 4 \ 6)_{1,2}\}$, is obtained such that

$$1C_2^{3(2)} = \max \left(1C_2^3, 1C_1^3 + t_{j_2 1} \right) + t_{j_2 2},$$

$$1C_2^{3(21)} = \max \left(1C_2^{3(2)}, 1C_1^3 + \sum_{\ell=1}^2 t_{j_{1+\ell} 1} \right) + t_{j_3 2},$$

$$1C_2^{3(215)} = \max \left(1C_2^{3(21)}, 1C_1^3 + \sum_{\ell=1}^3 t_{j_{1+\ell} 1} \right) + t_{j_4 2},$$

$$1C_2^{3(2154)} = \max \left(1C_2^{3(215)}, 1C_1^3 + \sum_{\ell=1}^4 t_{j_{1+\ell} 1} \right) + t_{j_5 2},$$

and

$$1_{C_2}^3(21546) = \max \left[1_{C_2}^3(2154), 1_{C_1}^3 + \sum_{\ell=1}^5 t_{j_{1+\ell}1} \right] + t_{j_62} ,$$

or

$$1_{C_2}^3(2) = \max \left[10, 6+7 \right] + 7 = 20 ,$$

$$1_{C_2}^3(21) = \max \left[20, 6+7+9 \right] + 13 = 35 ,$$

$$1_{C_2}^3(215) = \max \left[35, 6+7+9+20 \right] + 7 = 49 ,$$

$$1_{C_2}^3(2154) = \max \left[49, 6+7+9+20+8 \right] + 3 = 53 ,$$

and

$$1_{C_2}^3(21546) = \max \left[53, 6+7+9+20+8+10 \right] + 2 = 62 .$$

Similarly, the completion time for the job in the last sequence-position of the dynamic sequence, $\{3(6 \ 4 \ 2 \ 1 \ 5)_{2,3}\}$, on machine 3 is computed.

Firstly, the time within which all jobs included in the partial sequence of node n are completed on machine 3, is computed by using Equation (10) such that

$$\begin{aligned} 1_{C_3}^3 &= \max \left[1_{C_2}^3, 0_{C_3}^0 \right] + t_{33} , \\ &= \max \left[10, 0 \right] + 8 = 18 . \end{aligned}$$

Using Equation (11),

$$1_{C_3}^{3(6)} = \max \left[1_{C_3}^3, 1_{C_2}^3 + t_{j_2 2} \right] + t_{j_2 3},$$

$$1_{C_3}^{3(64)} = \max \left[1_{C_3}^{3(6)}, 1_{C_2}^3 + \sum_{\ell=1}^2 t_{j_{1+\ell} 2} \right] + t_{j_3 3},$$

$$1_{C_3}^{3(642)} = \max \left[1_{C_3}^{3(64)}, 1_{C_2}^3 + \sum_{\ell=1}^3 t_{j_{1+\ell} 2} \right] + t_{j_4 3},$$

$$1_{C_3}^{3(6421)} = \max \left[1_{C_3}^{3(642)}, 1_{C_2}^3 + \sum_{\ell=1}^4 t_{j_{1+\ell} 2} \right] + t_{j_5 3},$$

and

$$1_{C_3}^{3(64215)} = \max \left[1_{C_3}^{3(6421)}, 1_{C_2}^3 + \sum_{\ell=1}^5 t_{j_{1+\ell} 2} \right] + t_{j_6 3},$$

or

$$1_{C_3}^{3(6)} = \max \left[18, 10+2 \right] + 13 = 31,$$

$$1_{C_3}^{3(64)} = \max \left[31, 10+2+3 \right] + 10 = 41,$$

$$1_{C_3}^{3(642)} = \max \left[41, 10+2+3+7 \right] + 20 = 61,$$

$$1_{C_3}^{3(6421)} = \max \left[61, 10+2+3+7+13 \right] + 6 = 67,$$

and

$$1_{C_3}^3(64215) = \max \left\{ 67, 10+2+3+7+13+7 \right\} + 2 = 69 .$$

The bounds for node (3) at level 1 are computed on machines 2 and 3 such that

$$1_{B_2}^3 = 1_{C_2}^3(21546) + \min_{j_k \neq 3}^{j_k} (t_{j_k 3}) ,$$

and

$$1_{B_3}^3 = 1_{C_3}^3(64215) ,$$

or

$$\begin{aligned} 1_{B_2}^3 &= 62 + \min [6, 20, 10, 2, 13] \\ &= 64 , \end{aligned}$$

and

$$1_{B_3}^3 = 69 .$$

The lower-bound for this node at level 1 is then given by

$$\begin{aligned} 1_B^3 &= \max [64, 69] \\ &= 69 . \end{aligned}$$

Similarly, the lower-bounds for nodes (1), (2), (4), (5) and (6) at level 1 are found to be 81, 73, 70, 86, and 71, respectively.

At level 2, for node (34) the completion time for all scheduled jobs is computed on machines 1, 2 and 3 by Equation (10) such that

$$2_{C_1}^{34} = \max \left\{ 2_{C_0}^{34}, 1_{C_1}^3 \right\} + t_{41} ,$$

$${}^2C_2^{34} = \max \left[{}^2C_1^{34}, {}^1C_2^3 \right] + t_{42},$$

and

$${}^2C_3^{34} = \max \left[{}^2C_2^{34}, {}^1C_3^3 \right] + t_{43},$$

or

$${}^2C_1^{34} = \max \left[0, 6 \right] + 8 = 14,$$

$${}^2C_2^{34} = \max \left[14, 10 \right] + 3 = 17,$$

and

$${}^2C_3^{34} = \max \left[17, 18 \right] + 10 = 28.$$

The completion time for the job in the last sequence-position of the dynamic sequence, $\{3\ 4\ (2\ 1\ 5\ 6)_{1,2}\}$, on machine 2 is computed, such that

$${}^2C_2^{34(2)} = \max \left[{}^2C_2^{34}, {}^2C_1^{34} + t_{j_3 1} \right] + t_{j_3 2},$$

$${}^2C_2^{34(21)} = \max \left[{}^2C_2^{34(2)}, {}^2C_1^{34} + \sum_{\ell=1}^2 t_{j_{2+\ell} 1} \right] + t_{j_4 2},$$

$${}^2C_2^{34(215)} = \max \left[{}^2C_2^{34(21)}, {}^2C_1^{34} + \sum_{\ell=1}^3 t_{j_{2+\ell} 1} \right] + t_{j_5 2},$$

and

$${}^2C_2^{34(2156)} = \max \left[{}^2C_2^{34(215)}, {}^2C_1^{34} + \sum_{\ell=1}^4 t_{j_{2+\ell} 1} \right] + t_{j_6 2},$$

or

$${}^2C_2^{34(2)} = \max \left\{ 17, 14+7 \right\} + 7 = 28 ,$$

$${}^2C_2^{34(21)} = \max \left\{ 28, 14+7+9 \right\} + 13 = 43 ,$$

$${}^2C_2^{34(215)} = \max \left\{ 43, 14+7+9+20 \right\} + 7 = 57,$$

and

$${}^2C_2^{34(2156)} = \max \left\{ 57, 14+7+9+20+10 \right\} + 2 = 62 .$$

Similarly, the completion time for the job in the last sequence-position of the dynamic sequence, $\{3 \ 4 \ (6 \ 2 \ 1 \ 5)_{2,3}\}$, on machine 3 is computed such that

$${}^2C_3^{34(6)} = \max \left\{ {}^2C_3^{34}, {}^2C_2^{34} + t_{j_3 2} \right\} + t_{j_3 3} ,$$

$${}^2C_3^{34(62)} = \max \left\{ {}^2C_3^{34(6)}, {}^2C_2^{34} + \sum_{\ell=1}^2 t_{j_{2+\ell} 2} \right\} + t_{j_4 3} ,$$

$${}^2C_3^{34(621)} = \max \left\{ {}^2C_3^{34(62)}, {}^2C_2^{34} + \sum_{\ell=1}^3 t_{j_{2+\ell} 2} \right\} + t_{j_5 3} ,$$

and

$${}^2C_3^{34(6215)} = \max \left\{ {}^2C_3^{34(621)}, {}^2C_2^{34} + \sum_{\ell=1}^4 t_{j_{2+\ell} 2} \right\} + t_{j_6 3} ,$$

or

$${}^2C_3^{34(6)} = \max \left[28, 17+2 \right] + 13 = 41,$$

$${}^2C_3^{34(62)} = \max \left[41, 17+2+7 \right] + 20 = 61,$$

$${}^2C_3^{34(621)} = \max \left[61, 17+2+7+13 \right] + 6 = 67,$$

and

$${}^2C_3^{34(6215)} = \max \left[67, 17+2+7+13+7 \right] + 2 = 69.$$

The bounds for node (34) at level 2 are computed on machines 2 and 3 such that

$${}^2B_2^{34} = {}^2C_2^{34(2156)} + \min_{\substack{j_k \\ j_k \neq 3,4}} (t_{j_k 3}),$$

and

$${}^2B_3^{34} = {}^2C_3^{34(6215)},$$

or

$$\begin{aligned} {}^2B_2^{34} &= 62 + \min \left[6, 20, 2, 13 \right] \\ &= 64, \end{aligned}$$

and

$${}^2B_3^{34} = 69$$

The lower-bound for this node is given by

$$\begin{aligned} {}^2B^{34} &= \max \left[64, 69 \right] \\ &= 69. \end{aligned}$$

Similarly, the lower-bounds for each node in the scheduling tree are computed.

3.6 Sample Problem

As mentioned earlier, a sample problem is solved to illustrate the various bounding procedures. In order to be fair in the illustration of the bounding procedures, this problem is selected in which the solution is obtained by exploring the minimum number of nodes, using the various bounding procedures. However, the quality of the lower-bounds will be investigated by several computational experiments reported in Chapter IV. The sample problem is solved by the branch-and-bound algorithm stated in Section 2.3.

The sample problem consists of sequencing six jobs on three machines such that the schedule time is minimized. The machine ordering and processing time matrices are given below:

$$M = \begin{bmatrix} 11 & 12 & 13 \\ 21 & 22 & 23 \\ 31 & 32 & 33 \\ 41 & 42 & 43 \\ 51 & 52 & 53 \\ 61 & 62 & 63 \end{bmatrix} ; \quad T = \begin{bmatrix} 9 & 13 & 6 \\ 7 & 7 & 20 \\ 6 & 4 & 8 \\ 8 & 3 & 10 \\ 20 & 7 & 2 \\ 10 & 2 & 13 \end{bmatrix}$$

Following the branch-and-bound algorithm, level 1 is initialized by generating the nodes (1), (2), (3), (4), (5), and (6). The lower-bounds obtained by the various bounding procedures are tabulated for all nodes at level 1 as follows:

<u>Level</u>	<u>Node</u>	<u>LB I</u>	<u>LB II</u>	<u>LB III</u>	<u>LB IV</u>	<u>LB V</u>
1	(1)	81	81	81	81	81
	(2)	73	73	73	73	73
	(3)	69*	69*	69*	69*	69*
	(4)	70	70	70	70	70
	(5)	86	87	86	86	86
	(6)	71	71	71	71	71

Note that * indicates the minimum lower-bound in each bounding procedures.

Node (3) has the least lower-bound. Therefore, this node is branched to form the nodes (31), (32), (34), (35), and (36) at level 2.

At level 2, the computed lower-bounds for each of the above nodes are summarized as follows:

<u>Level</u>	<u>Node</u>	<u>LB I</u>	<u>LB II</u>	<u>LB III</u>	<u>LB IV</u>	<u>LB V</u>
2	(31)	79	79	79	79	79
	(32)	71	71	71	71	71
	(34)	69*	69*	69*	69*	69*
	(35)	84	86	84	84	84
	(36)	69*	69*	69*	69*	69*

Upon examining the above lower-bounds, the tie exists between the nodes (34) and (36) which have the least lower-bounds, 69. The tie is resolved in favor of node (34).

At level 3, node (34) is branched to create the nodes (341), (342), (345), and (346). The lower-bounds are computed and tabulated below.

<u>Level</u>	<u>Node</u>	<u>LB I</u>	<u>LB II</u>	<u>LB III</u>	<u>LB IV</u>	<u>LB V</u>
3	(341)	77	77	77	77	77
	(342)	69*	69*	69*	69*	69*
	(345)	82	85	84	84	82
	(346)	69*	69*	69*	69*	69*

Again, the minimum lower-bound is 69 and a tie exists between those nodes (342) and (346). The tie is resolved in favor of node (342).

At level 4, node (342) is branched to generate the nodes (3421), (3425), and (3426). The lower-bound for each of these newly created nodes is computed and summarized below.

<u>Level</u>	<u>Node</u>	<u>LB I</u>	<u>LB II</u>	<u>LB III</u>	<u>LB IV</u>	<u>LB V</u>
4	(3421)	69*	69*	69*	69*	69*
	(3425)	75	75	79	79	71
	(3426)	69*	69*	69*	69*	69*

The nodes (3421) and (3426) have the least lower-bound. The tie is broken and the node (3421) is selected for branching.

At level 5, the newly created nodes are (34215), and (34216); and the lower-bounds are tabulated below.

<u>Level</u>	<u>Node</u>	<u>LB I</u>	<u>LB II</u>	<u>LB III</u>	<u>LB IV</u>	<u>LB V</u>
5	(34215)	75	75	75	75	75
	(34216)	69*	69*	69*	69*	69*

At this level, the node having the least lower-bound is selected. By adding the only remaining job to the partial sequence of that node, a complete sequence is obtained. The minimum lower-bound at level 5 is 69 for node (34216), and the unscheduled job for this node is job 5. Thus

the feasible sequence {3 4 2 1 6 5} is a solution with schedule time T or 69.

Now, the back-tracking process is carried over all preceding levels and since there is no node having lower-bound less than 69, the sequence {3 4 2 1 6 5} is an optimal solution with minimum schedule time of 69. It should be noted that the solution is obtained after exploring 20 nodes.

CHAPTER IV

COMPUTATIONAL EXPERIMENTS

To establish a fair comparison among the various bounding procedures discussed in Chapter III, a series of computational experiments were conducted on IBM 360/50 computer. The computational algorithm presented in Section 2.3 was programmed in FORTRAN IV language. The flow chart and the computer program will appear in Appendix B. This chapter is devoted to the computational experiments and their results.

4.1 Experiments I - X

The experiments performed in this research consist of 395 problems which were selected with six to twelve jobs and three to five machines. The entries of the processing time matrices were generated at random from a uniform distribution between one and 30, inclusive. The number of problems in these experiments varied from 10 to 50. These computational experiments were designed in order to investigate the effects of changes in both the number of jobs and the number of machines. A summary of these experiments is tabulated below.

Experiment No.	Problem Size (JxM)	Number of Problems	Experiment No.	Problem Size (JxM)	Number of Problems
I	6x3	50	VII	8x3	35
II	6x4	50	VIII	8x4	25
III	6x5	50	IX	8x5	25
IV	7x3	50	X	12x3	10
V	7x4	50			
VI	7x5	50			

4.2 Experimental Results

This section is devoted to the results of the various computational experiments. These results will help explore empirically the performance of the various bounding procedures. The number of nodes and computation time of all experiments are summarized in Tables 4.1 - 4.5 and discussed below. Various statistics such as the minimum, maximum, mean and standard deviation are reported for both the number of nodes explored and the computation time spent to obtain the solution.

The results of Experiments X which consists of 10 problems solved by Ashour [2] are summarized in Table 4.6. The purpose of this experiment was to note the feasibility and efficiency of various bounding procedures for larger problems. The solutions obtained by LB I, LB II, LB III, LB IV and LB V were for 9, 9, 6, 10 and 5 problems, respectively. On comparing this result from that given in [2], it is obvious that branch-and-bound technique worked more efficiently than the various other techniques discussed therein.

As mentioned earlier, the branch-and-bound algorithm requires the exploration of at least $J + (J-1) + \dots + 2$ nodes; however in many cases more nodes may be explored; their number can be regarded as a measure of computational effort required in arriving at the solution for a specific bounding procedure. It is of interest to point out that the size of the scheduling tree, i.e., the number of all the possible nodes for exploration is $J + J(J-1) + \dots + J!$ which increases with the increase of J . For problems of various sizes, the minimum and maximum number of nodes which might be explored are shown below.

	Number of Jobs			
	<u>6</u>	<u>7</u>	<u>8</u>	<u>12</u>
Minimum number of explored nodes	20	27	35	77
Maximum number of explored nodes*	1,236	8,659	69,280	3,297,901,344

*That is the size of the scheduling tree.

In analyzing the results obtained by various bounding procedures, the effects of the changes in the number of jobs and machines are as follows:

The number of nodes explored to reach an optimal solution increases rapidly as the number of jobs increases. It was also noticed that the rate of change of increase in the number of nodes, increases rapidly with the increase in the number of jobs. For example in Table 4.1, Experiments I, IV and VII having problems of sizes (6x3), (7x3), and (8x3), the number of nodes explored increases by 127.28 and 235.45 nodes as the number of jobs increases from 6 to 7 and 7 to 8, respectively. It should be noted that the increase of similar nature is also reported for other bounding procedures in Tables 4.2 - 4.5. As an example, for LB III the number of explored nodes increases by factors of about 4.43 and 5.48 when the problem sizes change from (6x3) to (7x3) and from (7x3) to (8x3), respectively. However, these factors vary greatly with both the bounding procedure and the problem size. The steep increase in the rate of change of the explored nodes with increase in the number of jobs, is observed for each bounding procedure in all the experiments. Table 4.7 shows the various factors α for all bounding procedures obtained

from different problem sizes. The reason for the increase in the number of nodes explored with the increase of the number of jobs is that the addition of one job to the problem increases the level by one in the scheduling tree. Since nodes are formed by various permutations of these jobs, the number of nodes formed should increase rapidly with the increase in the number of jobs. Thus by intuition, an increase must be expected.

The computation time spent to find an optimal solution also increases rapidly with increase of the number of jobs and for fixed number of machines. As in Table 4.1, the computation times increase from 0.68 to 2.00 seconds and from 2.00 to 4.99 seconds when the problem's size changes from (6x3) to (7x3) and from (7x3) to (8x3), respectively. This is because the computation time depends on the number of nodes explored. The number of these nodes vary greatly from one problem to another of the same size. Tables 4.1 - 4.5 show how the number of nodes explored varies within each experiment. For example, the number of nodes explored in Experiment VII, shown in Table 4.3, ranges between 35 and 26,984. The variation in the computation time is also due to the variation in the elements of the processing time matrices of problems of the same size, since the processing times affect the amount of computational time involved. The reason is that the criterion used in this research is the schedule time which is a function of the processing times. The rate of change of increase in the computation time seems to increase rapidly as the number of jobs increases. The effects of variation in the number of jobs on both the number of nodes explored and the computation time are shown in Figures 4.1 - 4.3. The factors (β) by which the computation time changes are shown in Tables 4.7 and 4.8 for various bounding procedures.

The number of nodes explored to obtain an optimal solution increases as the number of machines increases with a fixed number of jobs. However, when problems were solved by LB III in all experiments but V and VI, the number of nodes explored decreases as the number of machines increases. LB V also show a similar reduction in the number of explored nodes except for Experiments II, III, V and VI. The increase in the number of nodes depends upon the quality of the various bounding procedures used to compute the lower-bounds. If the bounding procedure works efficiently, it will recognize the optimal solution by exploring small number of nodes. Otherwise, the optimal solution is reached after a number of back-tracking which in turn increases the number of nodes explored. By similar reasoning a decrease in the number of nodes may be expected. For example, as shown in Table 4.8, the number of nodes explored changes by factors about 2.34 and 0.83 when the problem size changes from (8x3) to (8x4) and from (8x4) to (8x5), respectively.

As the number of machines increases the computation times increases in most of the cases; however, in some experiments it appears to take negative changes. Comparing the results of Experiments VIII and IX in which each problem has 8 jobs, a reduction in the number of nodes was realized by all bounding procedures. For the same experiments, the computation times also seem to decrease for all bounding procedures except LB II, which shows an increase of 3.05 seconds. Similarly, in Experiments IV and V having problems of size (7x3) and (7x4), only LB III shows a decrease in computation time from 20.30 to 15.92 seconds when the number of machines changes from 3 to 4, respectively. It should be noted that for same experiments, the number of nodes decreases from 622.72 to 357.92. The increase in the number of machines causes an increase in the number

of bounds computed since the lower-bound for each node is selected as the maximum value of the bounds for all machines. Thus, the computation time depends upon the number of machines.

In all bounding procedures, the computation time spent per node increases as the number of machines increases from M to $M+1$. For example in Experiments I and II, an increase of 0.0019 second is observed when number of machines changes from 3 to 4. This is due to the reason mentioned above.

In all bounding procedures, the computation time spent per node increases as the number of jobs increases from J to $J+1$. In Experiments I and IV having problems of sizes (6×3) and (7×3) respectively, the computation time per node increases from 0.0087 to 0.0097 second as the number of jobs changes from 6 to 7.

It is observed that the change in the computation time per node is more due to one unit change in the number of machines than one unit change in the number of jobs.

It should be pointed out that for some problems LB V produced better solutions. The LB V considers the permutations of unscheduled jobs on each pair of machines. These permutations change from one machine to another and help estimate a powerful lower-bound. Other bounding procedures can not reach that solution since they do not permute among the unscheduled jobs. For example, a flow shop problem of size (7×4) having the following processing time matrix:

$$T = \begin{bmatrix} 11 & 11 & 5 & 5 \\ 19 & 23 & 26 & 13 \\ 30 & 19 & 4 & 18 \\ 25 & 25 & 10 & 3 \\ 28 & 7 & 23 & 25 \\ 5 & 2 & 4 & 22 \\ 16 & 21 & 17 & 20 \end{bmatrix}$$

The optimal permutation-sequences and their schedule times of this problem, when solved using bounding procedures LB I - V, are as follows:

Bounding Procedure	Sequence	Schedule Time
LB I	{6 3 7 5 2 4 1}	169
LB II	{6 3 7 5 2 4 1}	169
LB III	{6 7 2 3 5 4 1}	169
LB IV	{6 7 2 3 5 4 1}	169
LB V	{6 7 2 3 5 1 4}	161

The number of solutions obtained by LB V found different from those obtained by the other bounding procedures are

Experiment	Problem Size	Number of Problems	Number of Different Solutions by LB V
II	(6x4)	50	16
III	(6x5)	50	20
V	(7x4)	50	13
VI	(7x5)	50	21
VIII	(8x4)	25	5
IX	(8x5)	25	11

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Table 4.1

Results for Bounding Procedure LB I

Experiment Number	Problem Size (JxM)	Number of Problems	Number of Nodes Explored				Computation Time Spent*					
			Minimum	Frequency of the Minimum	Maximum	Mean	Standard Deviation	Minimum	Maximum	Mean	Standard Deviation	Per Node
I	(6x3)	50	20	13	477	77.98	86.89	0.18	3.78	0.68	0.70	0.0087
II	(6x4)	50	20	7	440	117.00	112.08	0.23	4.89	1.24	1.14	0.0106
III	(6x5)	50	20	2	425	129.40	103.00	0.28	5.24	1.64	1.27	0.0127
IV	(7x3)	50	27	12	1465	205.26	302.91	0.29	14.08	2.00	2.85	0.0097
V	(7x4)	50	27	4	1322	243.44	297.67	0.34	15.69	2.89	3.43	0.0115
VI	(7x5)	50	27	3	2643	332.76	429.89	0.43	35.58	4.70	5.83	0.0141
VII	(8x3)	35	35	12	6148	440.71	1172.93	0.43	67.84	4.99	12.93	0.0113
VIII	(8x4)	25	35	3	4884	1031.56	1495.85	0.55	68.55	14.24	20.52	0.0138
IX	(8x5)	25	35	1	4793	862.04	999.23	0.64	75.68	13.83	15.80	0.0160

* Computation time in seconds (IBM 360/50 computer)

Table 4.2

Results for Bounding Procedure LB II

Experiment Number	Problem Size (JxM)	Number of Problems	Number of Nodes Explored				Computation Time Spent #					
			Frequency of the		Standard		Standard		Deviation			
			Minimum	Maximum	Mean	Deviation	Minimum	Maximum	Mean	Deviation		
I	(6x3)	50	20	17	468	74.18	84.62	0.73	14.27	2.45	2.65	0.033
II	(6x4)	50	20	9	436	104.20	103.85	1.06	19.92	4.93	4.66	0.047
III	(6x5)	50	20	3	389	118.62	96.64	1.50	24.15	7.72	5.96	0.065
IV	(7x3)	50	27	12	1350	193.12	291.00	1.16	48.51	7.34	10.56	0.038
V	(7x4)	50	27	6	1210	227.16	286.45	1.67	63.79	12.09	14.67	0.053
VI	(7x5)	50	27	3	2443	292.90	399.88	2.31	162.39	20.78	26.91	0.070
VII	(8x3)	35	35	15	5504	410.31	1085.79	1.80	231.83	17.77	45.26	0.043
VIII	(8x4)	25	35	3	4719	986.68	1447.81	2.55	274.07	58.64	84.03	0.059
IX	(8x5)	25	35	1	4113	776.64	877.06	3.50	319.89	61.69	68.23	0.079

* Computation time in seconds (IBM 360/50 computer)

Table 4.3

Results for Bounding Procedure LB III

Experiment Number	Problem Size (JxM)	Number of Problems	Number of Nodes Explored				Computation Time Spent*					
			Minimum	Frequency of the Minimum	Maximum	Mean	Standard Deviation	Minimum	Maximum	Mean	Standard Deviation	Per Node
I	(6x3)	50	20	17	791	140.44	187.57	0.73	19.40	3.88	4.67	0.0271
II	(6x4)	50	20	9	418	112.04	116.22	1.00	4.14	4.39	15.53	0.0392
III	(6x5)	50	20	9	527	100.38	107.91	1.26	22.63	4.92	4.63	0.0490
IV	(7x3)	50	27	5	3210	622.72	800.53	1.30	100.69	20.30	24.53	0.0326
V	(7x4)	50	27	6	2140	357.92	468.30	1.73	80.92	15.92	18.61	0.0445
VI	(7x5)	50	27	1	2633	396.98	525.16	0.54	128.71	21.97	26.45	0.0553
VII	(8x3)	35	35	10	26984	3417.71	6657.66	2.13	978.18	122.39	234.20	0.0358
VIII	(8x4)	25	35	2	6875	1347.20	1975.57	2.85	346.96	68.99	94.98	0.0512
IX	(8x5)	25	35	2	2490	638.80	626.48	3.58	169.06	43.20	41.12	0.0676

* Computation time in seconds (IBM 360/50 computer)

Table 4.4

Results for Bounding Procedure LB IV

Experiment Number	Problem Size (JxM)	Number of Problems	Number of Nodes Explored				Computation Time Spent*					
			Minimum	Frequency of the Minimum	Maximum	Mean	Standard Deviation	Minimum	Maximum	Mean	Standard Deviation	Per Node
I	(6x3)	50	20	25	196	40.54	37.49	0.88	6.73	1.64	1.34	0.0406
II	(6x4)	50	20	16	218	48.42	39.82	1.18	10.52	2.59	1.90	0.0539
III	(6x5)	50	20	11	371	58.34	70.49	1.50	20.38	3.78	3.90	0.0648
IV	(7x3)	50	27	17	980	109.22	177.92	1.50	38.69	5.10	7.19	0.0467
V	(7x4)	50	27	10	664	104.44	120.14	2.00	36.02	6.48	6.58	0.0620
VI	(7x5)	50	27	4	938	149.02	167.19	2.16	62.93	11.03	11.27	0.0740
VII	(8x3)	35	35	17	3889	291.77	749.29	2.43	182.51	14.85	34.99	0.0509
VIII	(8x4)	25	35	6	2992	424.84	748.87	3.23	194.75	29.27	48.58	0.0689
IX	(8x5)	25	35	4	1254	308.76	346.24	4.07	97.40	26.18	26.71	0.0848

* Computation time in seconds (IBM 360/50 computer)

Table 4.5

Results for Bounding Procedure LB V

Experiment Number	Problem Size (JxM)	Number of Problems	Number of Nodes Explored				Computation Time Spent [*]					
			Minimum	Frequency of the Minimum	Maximum	Mean	Standard Deviation	Minimum	Maximum	Mean	Standard Deviation	Per Node
I	(6x3)	50	20	14	566	106.30	133.43	0.40	9.90	1.86	2.23	0.017
II	(6x4)	50	20	9	323	95.32	84.82	0.59	8.38	2.46	2.09	0.025
III	(6x5)	50	24	1	432	123.26	85.32	0.92	14.01	4.17	2.73	0.033
IV	(7x3)	50	27	14	2706	314.92	534.39	0.61	50.90	6.22	10.18	0.019
V	(7x4)	50	27	3	1087	230.96	241.86	0.90	30.95	6.65	6.76	0.028
VI	(7x5)	50	27	3	2936	370.34	469.64	1.21	102.92	13.64	16.58	0.036
VII	(8x3)	35	35	14	12741	1240.37	3278.86	0.90	295.46	27.80	72.82	0.022
VIII	(8x4)	25	35	4	8610	1237.32	2082.05	1.31	264.59	38.91	64.24	0.031
IX	(8x5)	25	63	1	2731	570.52	577.00	3.00	113.64	23.98	23.92	0.042

* Computation time in seconds (IBM 360/50 computer)

Table 4.6

Results for Experiment X

Problem No.	Optimal Schedule Time	Number of Nodes Explored					Computation Time Spent [†]				
		LB I	LB II	LB III	LB IV	LB V	LB I	LB II	LB III	LB IV	LB V
1	230	141	141	*	77	77	3.17	12.68	#	12.21	2.96
2	197	77	77	*	77	*	2.06	8.23	#	12.26	#
3	257	206	77	192	192	206	4.84	7.92	20.84	24.20	7.92
4	201	77	77	77	77	224	2.02	8.14	10.74	12.25	8.39
5	229	77	77	77	77	77	1.89	7.91	10.47	11.91	3.13
6	227	*	*	98	86	*	#	#	11.89	12.49	#
7	222	93	93	*	93	*	2.15	8.85	#	13.02	#
8	262	77	77	77	77	77	1.92	7.88	10.61	11.81	3.43
9	186	522	458	*	237	*	10.31	34.53	#	25.60	#
10	248	86	77	408	77	*	2.03	7.65	28.78	11.74	#

[†] Computation time on IBM 360/50 computer in seconds.

* Solutions were not obtained because of computer time limitation.

Computer was stopped after 1200 seconds without obtaining the solutions to problems labeled with #.

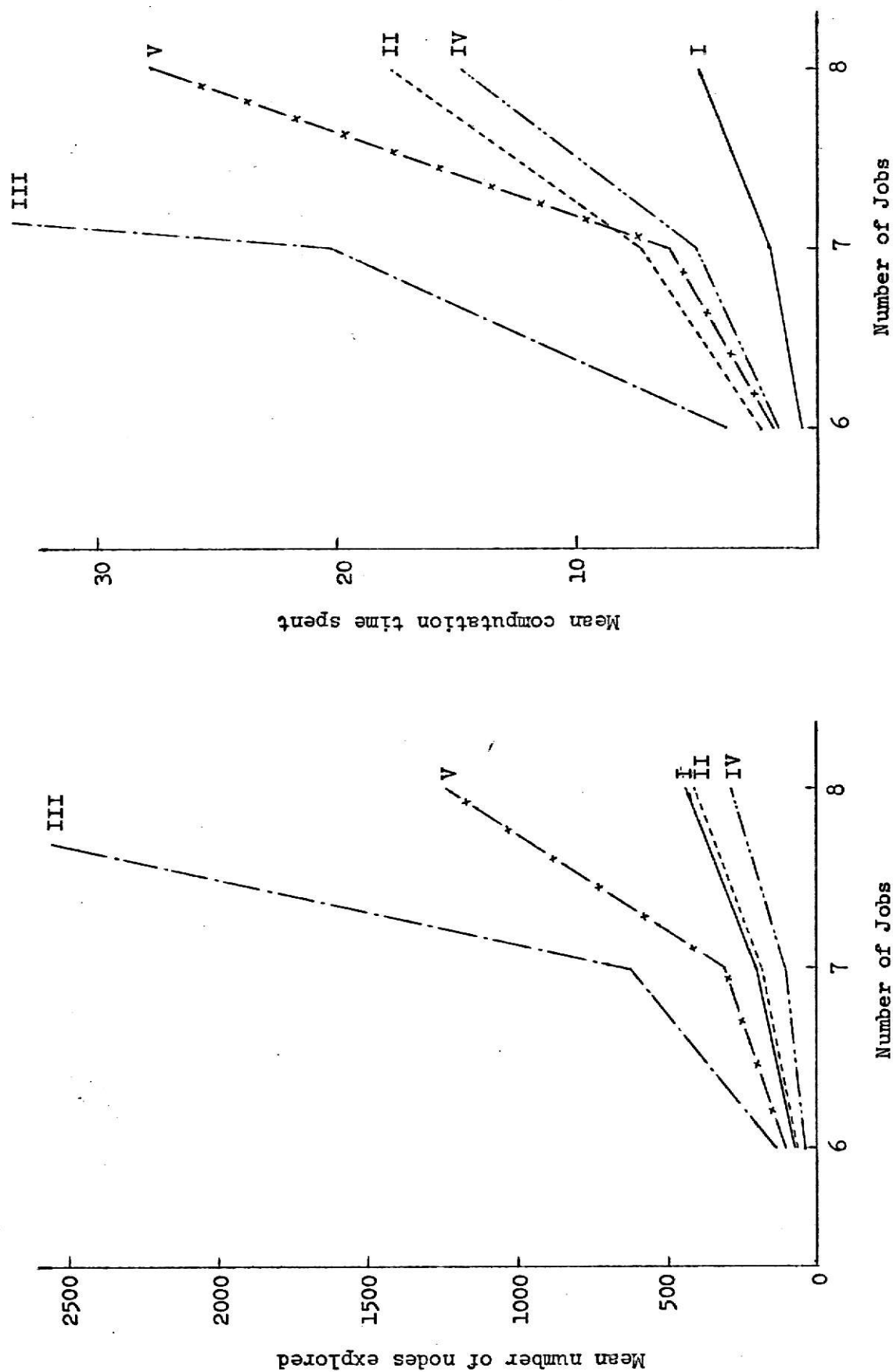


Fig. 4.1 The Effect of Problem Size Having Three Machines

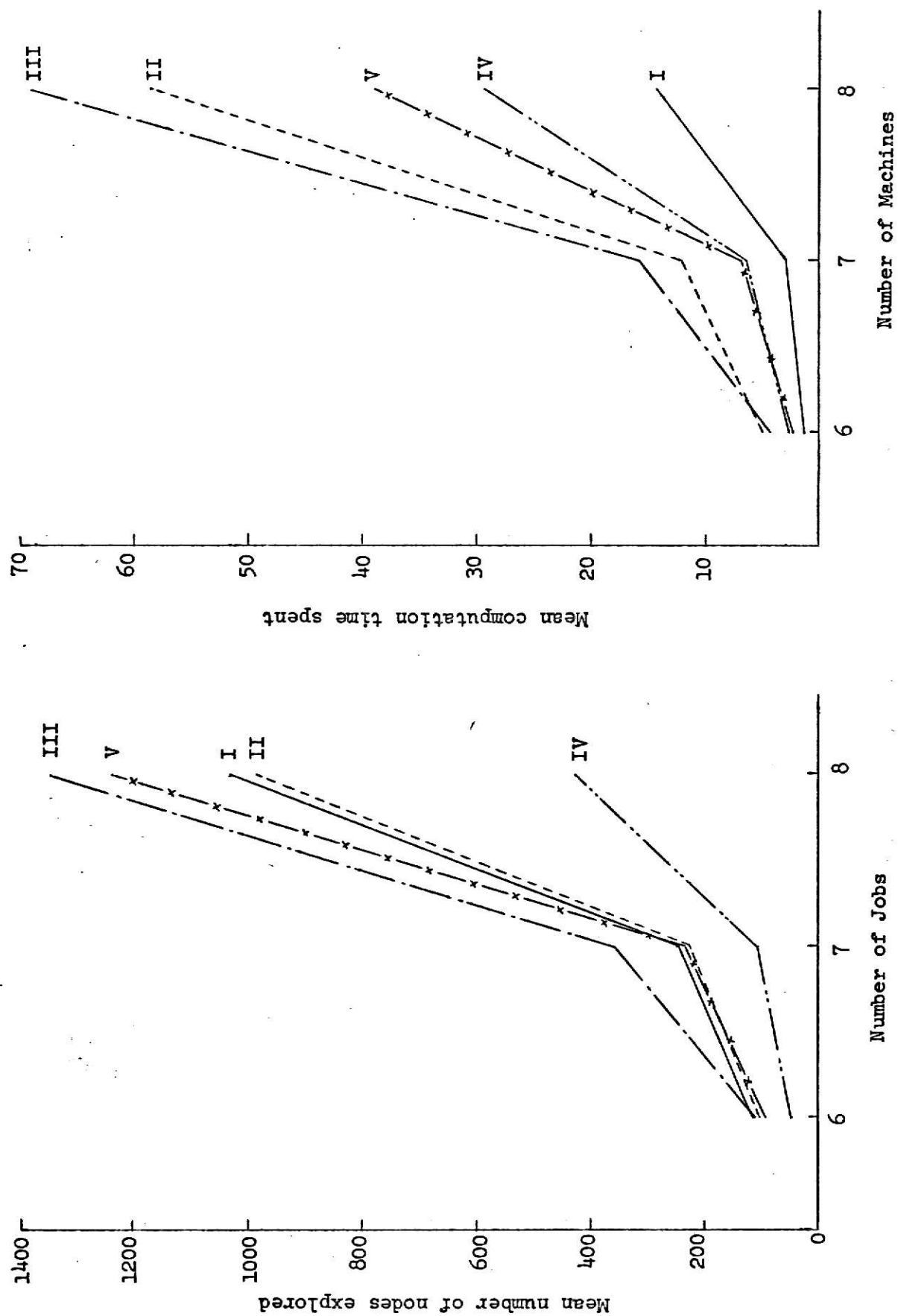


Fig. 4.2 The Effect of Problem Size Having Four Machines

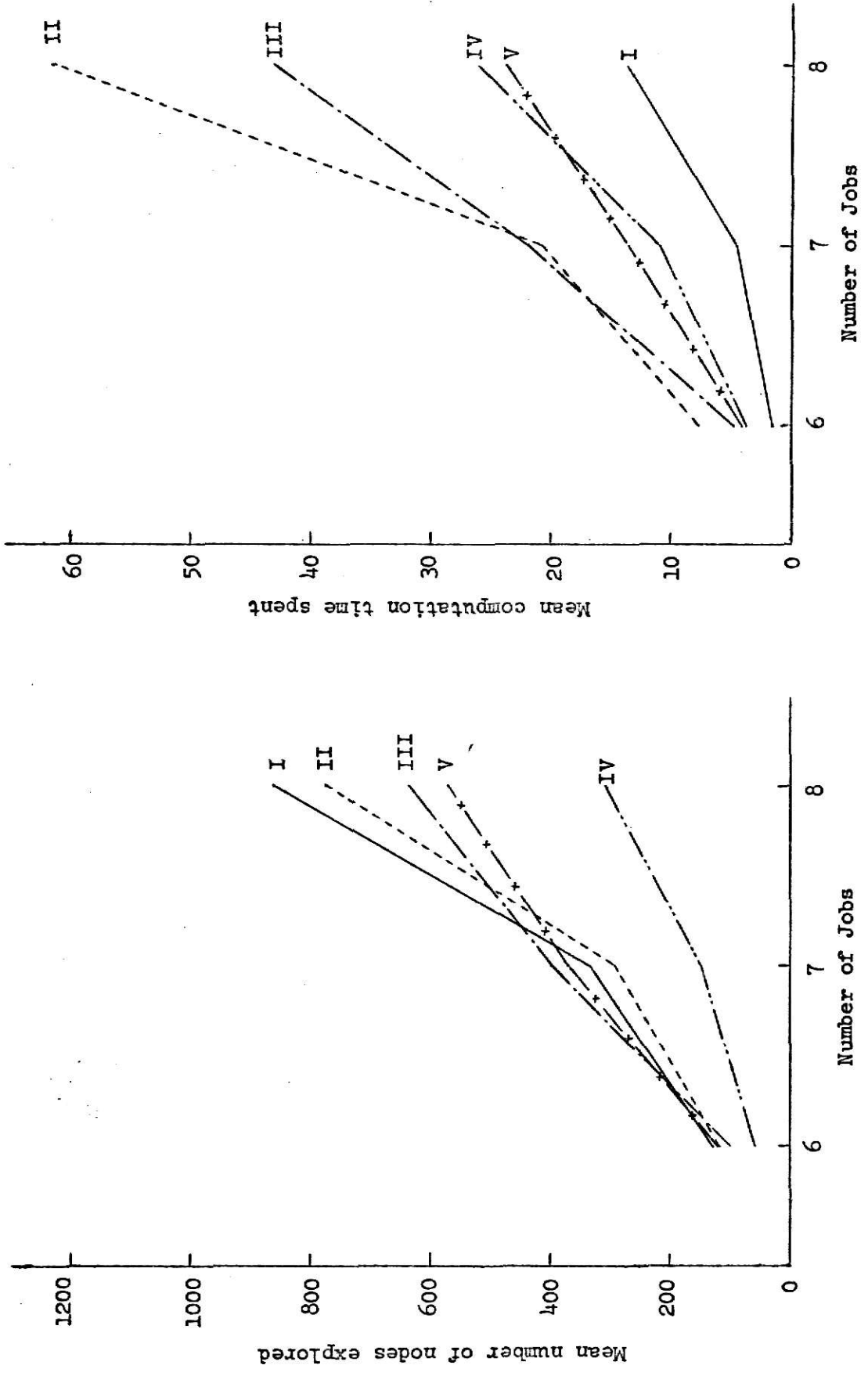


Fig. 4.3 The Effect of Problem Size Having Five Machines

Table 4.7

The Effect of Change in the Number of Jobs

Number of jobs changes from J \rightarrow J+1	Number of machines	LB I		LB II		LB III		LB IV		LB V	
		Factor *		Factor *		Factor *		Factor *		Factor *	
		α	β	α	β	α	β	α	β	α	β
6 \rightarrow 7	3	2.63	2.94	2.60	2.99	4.43	5.23	2.69	3.10	2.96	3.34
	4	2.08	2.33	2.18	2.45	3.19	3.62	2.15	2.50	2.42	2.70
	5	2.57	2.86	2.46	2.69	3.95	4.46	2.55	2.91	3.00	3.27
7 \rightarrow 8	3	2.14	2.49	2.12	2.42	5.48	6.02	2.67	2.91	3.93	4.46
	4	4.23	4.92	4.34	4.85	3.76	4.33	4.06	4.51	5.35	5.85
	5	2.59	2.94	2.65	2.96	1.60	1.96	2.07	2.37	1.54	1.75

* α factor by which the mean number of explored nodes changes. β factor by which the mean computation time changes.

Table 4.8

The Effects of Change in the Number of Machines

Number of machines changes from M \rightarrow M+1	LB I			LB II			LB III			LB IV			LB V		
	Factor α	Factor β	Factor *	Factor α	Factor β	Factor *	Factor α	Factor β	Factor *	Factor α	Factor β	Factor *	Factor α	Factor β	Factor *
3 \rightarrow 4	1.50	1.82		1.40	2.01		0.79	1.13		1.19	1.57		0.89	1.32	
7	1.18	1.44		1.17	1.64		0.57	0.78		0.95	1.27		0.73	1.06	
8	2.34	2.85		2.40	3.29		0.39	0.56		1.45	1.97		0.99	1.39	
4 \rightarrow 5	1.10	1.32		1.13	1.56		0.89	1.12		1.20	1.45		1.29	1.69	
7	1.36	1.62		1.28	1.71		1.10	1.38		1.42	1.70		1.60	2.05	
8	0.83	0.97		0.78	1.05		0.47	0.62		0.72	0.89		0.46	0.61	

*

 α factor by which the mean number of explored nodes changes. β factor by which the mean computation time changes.

CHAPTER V

SUMMARY AND CONCLUSION

The basic objective of this report is to analyze and compare various bounding procedures used in branch-and-bound technique to obtain the lower-bounds for the solution of flow shop scheduling problem. In flow shop certain jobs are performed on various machines in an identical routing. This problem is first defined and formulated mathematically. The branch-and-bound concept, and branching, bounding and back-tracking processes are also discussed in detail. The bounding procedures subject to comparison in this report are analyzed. Various computational experiments were performed to carry out the investigation. The comparison was based on both the number of nodes explored and the computation time spent in obtaining an optimal solution.

For convenience, the summarized results of Experiments I - IX are given in Table 5.1. This will help analyze the results vertically and horizontally. The vertical analysis means the study of the effects in the changes of the number of jobs or machines in each bounding procedure. However, by horizontal analysis, is meant the study of the performance (number of nodes explored and computation time) of the various bounding procedures in each experiment.

In analyzing the results of all bounding procedures, most significant observations are obtained -

1. The number of nodes explored and the computation time increases with the increase of the number of jobs.
2. The computation time is proportional to the number of nodes explored.

3. In general, the number of explored nodes, and, thus the computation time increase as the number of machines increases with a fixed number of jobs; however, this was not the case in few experiments.
4. Computation time required to explore a node depends upon the number of machines.
5. Computation time is a better criterion for comparing various bounding procedures, since the computation time required to explore a node varies from one bounding procedure to another. For example, in Table 5.1, LB I and LB IV explored on the average 77.98 and 40.54 nodes, respectively, to solve a problem having 6 jobs and 3 machines. At first glance, it appears that on the average LB IV is more efficient than LB I, since it reached the optimal after exploring comparatively less number of nodes. On the other hand, LB I and LB IV require on the average 0.68 and 1.64 seconds to solve a (6x3) problem. Thus, the LB I is more efficient than LB IV, though it requires to explore more nodes. The reason is that LB I spends less computation time in calculating a lower-bound for each node than that by LB IV.
6. The ranking according to the number of explored nodes and the computational time are shown in Table 5.2 and 5.3. Bounding procedure LB IV is ranked first according to the number of explored nodes in all experiments; however, it is ranked second in Table 5.3. This is because the computation of lower-bound for a node by LB IV requires the lower-bounds computed by LB I and LB III, and, hence, more computation effort is required. LB III is generally ranked last according to both the number of explored nodes and the computation time. As

Table 5.1

Summary of Results for All Bounding Procedures

Experiment Number	Problem Size	Mean Number of Nodes Explored					Mean Computation Time Spent*				
		LB I	LB II	LB III	LB IV	LB V	LB I	LB II	LB III	LB IV	LB V
I	(6x3)	77.98	74.18	140.44	40.54	106.30	0.68	2.45	3.88	1.64	1.86
IV	(7x3)	205.26	193.12	622.72	109.22	314.92	2.00	7.34	20.30	5.10	6.22
VII	(8x3)	440.71	410.31	3417.71	291.77	1240.37	4.99	17.77	122.39	14.85	27.80
II	(6x4)	117.00	104.20	112.04	48.42	95.32	1.24	4.93	4.39	2.59	2.46
V	(7x4)	243.44	227.16	357.92	104.44	230.96	2.89	12.09	15.92	6.48	6.65
VIII	(8x4)	1031.56	986.68	1347.20	424.84	1237.32	14.24	58.64	68.99	29.27	38.91
III	(6x5)	129.40	118.62	100.38	58.34	123.26	1.64	7.72	4.92	3.78	4.17
VI	(7x5)	332.76	292.90	396.98	149.02	370.34	4.70	20.78	21.97	11.03	13.64
IX	(8x5)	862.04	776.64	638.80	308.76	570.52	13.83	61.69	43.20	26.18	23.98
X	(12x3)	150.66	128.22	154.83	107.00	132.20	3.37	11.53	15.55	14.74	5.16

* Computation time on IBM 360/50 computer, in seconds.

Table 5.2

Rank of Bounding Procedures Based on Number of Explored Nodes

Rank	Experiment								
	(6x3)	(6x4)	(6x5)	(7x3)	(7x4)	(7x5)	(8x3)	(8x4)	(8x5)
1	LB IV	LB IV	LB IV	LB IV	LB IV	LB IV	LB IV	LB IV	LB IV
2	LB II	LB V	LB III	LB II	LB II	LB II	LB II	LB II	LB V
3	LB I	LB II	LB II	LB I	LB V	LB I	LB I	LB I	LB III
4	LB V	LB III	LB V	LB V	LB I	LB V	LB V	LB V	LB II
5	LB III	LB I	LB I	LB III	LB III	LB III	LB III	LB III	LB I

Table 5.3

Rank of Bounding Procedures Based on Computation Time

Rank	Experiment								
	(6x3)	(6x4)	(6x5)	(7x3)	(7x4)	(7x5)	(8x3)	(8x4)	(8x5)
1	LB I	LB I	LB I	LB I	LB I	LB I	LB I	LB I	LB I
2	LB IV	LB V	LB IV	LB IV	LB IV	LB IV	LB IV	LB IV	LB V
3	LB V	LB IV	LB V	LB V	LB V	LB V	LB II	LB V	LB IV
4	LB II	LB III	LB III	LB II	LB II	LB II	LB V	LB II	LB III
5	LB III	LB II	LB II	LB III	LB III	LB III	LB III	LB III	LB II

clear from Table 5.3, LB V and LB II are ranked third and fourth, respectively in most of the experiments. However, these rankings vary from one experiment to another as shown in tables.

APPENDIX A

In this appendix, an algorithm for finding an optimal sequence for two-machine flow shop problem is stated. This algorithm is based on Johnson's criterion [9] for two machines which can be restated as: job j_r must precedes job j_s on machines m and $m+1$ in order to minimize the schedule time, if

$$\min \left(t_{j_r m}, t_{j_s m+1} \right) \leq \min \left(t_{j_r m+1}, t_{j_s m} \right)$$

holds.

The algorithm may be summarized in the following steps.

Step 1: Arrange the processing times of the jobs on machines m and $m+1$, as follows:

<u>Job Index</u>	<u>Machine m</u>	<u>Machine m+1</u>
1	t_{1m}	t_{1m+1}
2	t_{2m}	t_{2m+1}
.	.	.
.	.	.
.	.	.
J	t_{Jm}	t_{Jm+1}

Step 2: Examine all processing times for the minimum value.

2.1 If the minimum processing time is t_{jm} , schedule the corresponding job first on machine m .

2.2 If the minimum processing time is t_{jm+1} , schedule the corresponding job last on machine m .

2.3 If a tie exists among the processing times on the same machine, schedule the job with the smallest designation first.

2.4 If a tie exists for the same job on both machines, consider it as in step 2.1.

Step 3: Cross off the job just assigned and repeat step 2 on the reduced set of processing times.

To illustrate the algorithm, the processing time matrix of the sample problem solved in Section 3.6 is reproduced below

$$T = \begin{bmatrix} 9 & 13 & 6 \\ 7 & 7 & 20 \\ 6 & 4 & 8 \\ 8 & 3 & 10 \\ 20 & 7 & 2 \\ 10 & 2 & 13 \end{bmatrix}$$

To find the preliminary sequence on machines 1 and 2, the first two columns of the processing time matrix are considered. Thus, according to step 1 the processing times are arranged as follows:

<u>j</u>	<u>t_{j1}</u>	<u>t_{j2}</u>
1	9	13
2	7	7
3	6	4
4	8	3
5	20	7
6	10	2

According to step 2, the minimum processing time is 2 units for job 6 on machine 2. Therefore, job 6 is scheduled in the last sequence-position.

According to step 3, job 6 is crossed off, since it has been already scheduled.

Repeating steps 2-3 on the reduced set of processing times, the preliminary sequence {2 1 5 3 4 6} is obtained. Similarly, the preliminary sequence on machines 2 and 3 is found to be {6 4 3 2 1 5}.

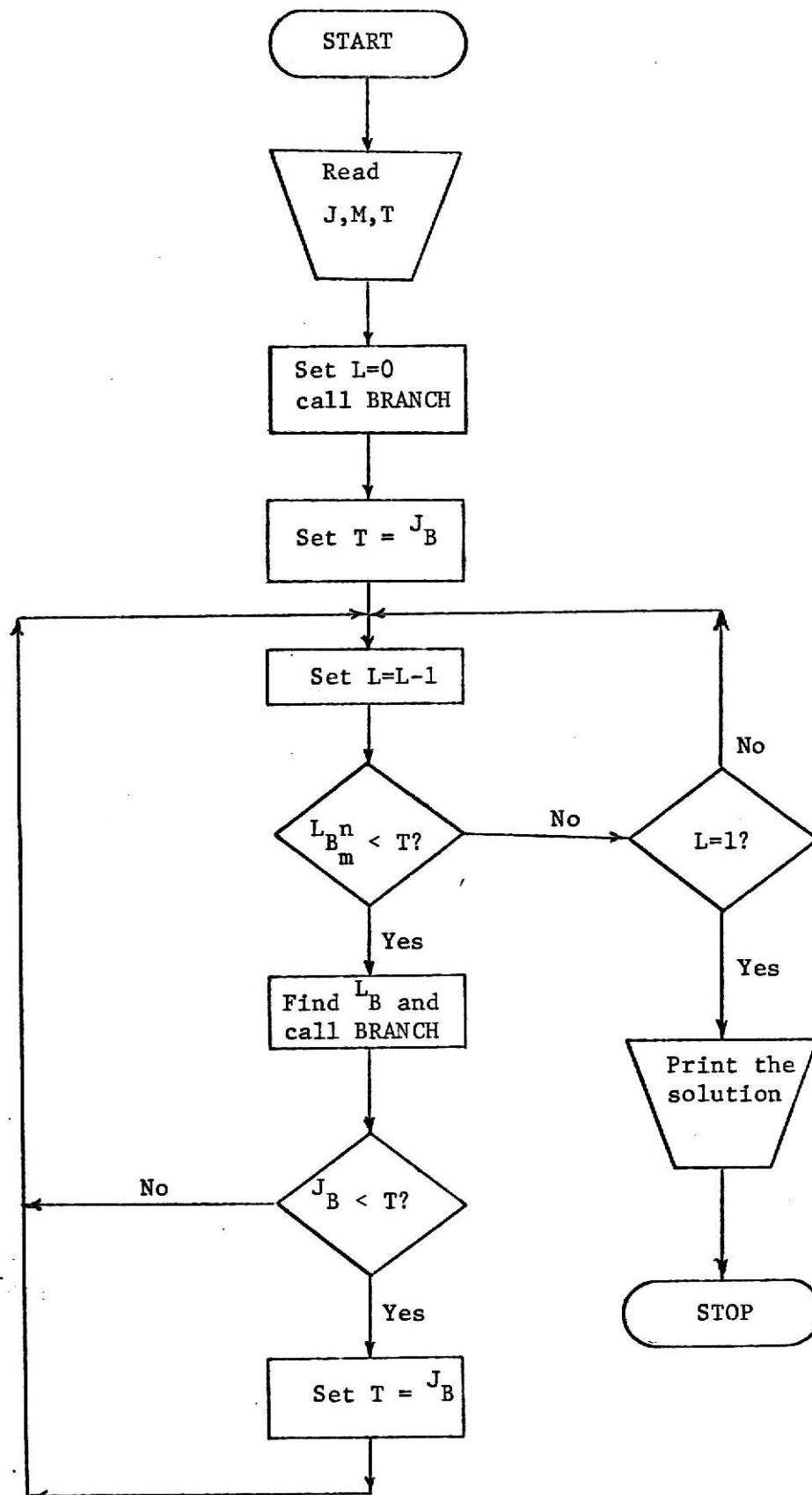


Figure B.1

Flow Chart for Branch-and-Bound Algorithm

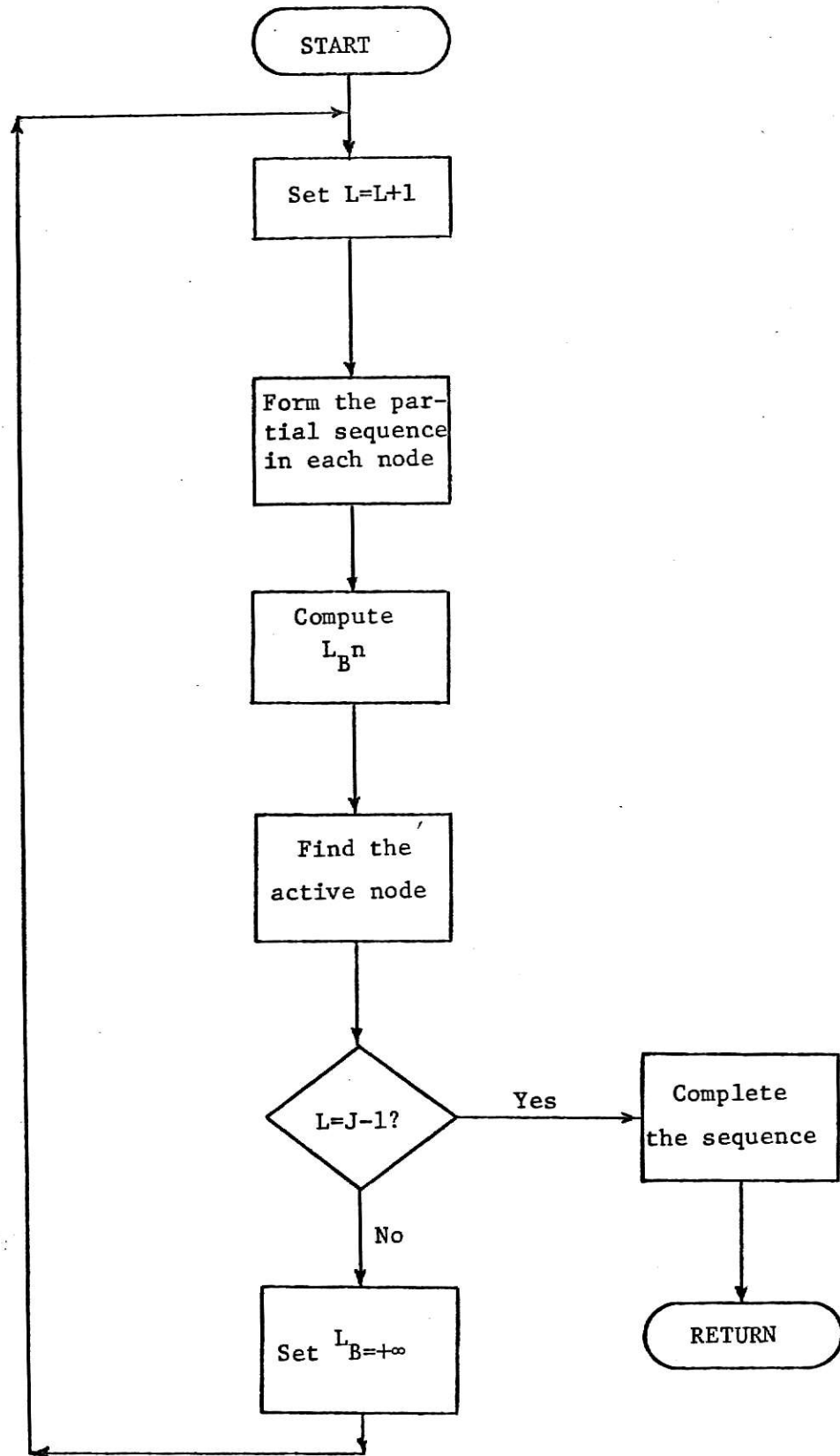


Figure B.2

Flow Chart for Branch Subroutine


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7 1503 FORMAT(1H ,10I5)
8 1511 FORMAT(1H ,10X,'COMPUTATION TIME =',F10.2,' SECONDS')
9 1512 FORMAT(1H ,10X,'THIS SOLUTION IS OBTAINED BY BOUND',I1)
10 1513 FORMAT(1H ,10X,'TOTAL NUMBER OF NODES FOR WHICH ',
    1'COMPOSITE BOUND IS PICKED UP FROM MACHINE BASED BOUND',
    1' ONLY = ',I9)
11 1514 FORMAT(1H ,10X,'TOTAL NUMBER OF NODES FOR WHICH ',
    1'COMPOSITE BOUND IS PICKED UP FROM JOB BASED BOUND ',
    1'ONLY = ',I9)
12 1515 FORMAT(1H ,10X,'TOTAL NUMBER OF NODES FOR WHICH COMP',
    1'OSITE BOUND IS PICKED UP FROM BOTH BOUNDS = ',I9)
13 1516 FORMAT(1H0,130(1H*))
14 1517 FORMAT(1H ,10X,'NUMBER OF TIMES THE SCHEDULE TIME IS',
    1' IMPROVED BY BACK-TRACKING = ',I9)
15 1518 FORMAT(1H ,10X,'TOTAL NUMBER OF NODES EXPLORED = ',I9)
16 1519 FORMAT(1H0,130(1H*))
17 1520 FORMAT(I10,F10.2,I10)
18 1521 FORMAT(I10,F10.2,4I10)
19 1600 FORMAT(1H ,10X,'SCHEDULE TIME = ',I5,10X,'OPTIMAL ',
    1'SEQUENCE = ',20I4)
20 READ(1,1500) JOBS,MACH,IREAD,LIMIT1,LIMIT2,ISKIP,
    1IPRINT,ICARD,NPROB,IY,NBF,NBL
21 DO 14 NP = 1,NPROB
22 IF(IREAD.EQ.0) GO TO 990
C
C READ PROCESSING TIME MATRIX FROM CARDS IF IREAD = 1
C
23 DO 1 JC = 1,JOBS
24 1 READ(1,1501) (IT(JC,M),M = 1,MACH)
25 GO TO 992
C
C GENERATE PROCESSING TIME MATRIX IT(J,M)
C
26 990 DO 991 K = 1,MACH
27 DO 991 JA = 1,JOBS
28 IT(JA,K) = BANDNO(IY)*LIMIT2 + LIMIT1
29 991 CONTINUE
30 992 CONTINUE
C
C PRINT THE PROCESSING TIME MATRIX
C
31 WRITE(3,1502) NP
32 DO 993 JC = 1,JOBS
33 993 WRITE(3,1503)(IT(JC,M), M = 1,MACH)
34 JOB = JOBS - 1
35 DO 15 IB = NBF,NBL
36 ITERM = 0
37 LV = 0
38 KOUNT = 0
39 KONT = 0
40 KONTMJ = 0
41 KONTMB = 0
42 KONTJB = 0
43 NREPET = 0
44 ISTMN = 99999
45 CALL INTIME(ITIME1)
46 CALL BRANCH (LV,JOBS,KONT,NACTIV,ITERM)
47 ISTMN = ILB(JOBS,1)
48 DO 5 K = 1,JOB
49 JSQ(JOBS,1,K) = JSQ(JOB,NACTIV,K)

```

```

50      5 CONTINUE
      C
      C      BACK TRACKING
      C
51      1200 LV = LV-1
52          ITERM = 0
53          ND = JOBS + 1 - LV
54          DO 700 N = 1,ND
55              IF(ISTMIN-ILB(LV,N))700,700,710
56          700 CONTINUE
57              IF(LV.GT.1) GO TO 1200
58              IF(LV.EQ.1) GO TO 1300
59          710 LBX = ILB(LV,1)
60              NACTIV = 1
61              DO 730 NOD = 2,ND
62                  IF(LBX-ILB(LV,NOD))730,730,750
63          750 LBX = ILB(LV,NOD)
64              NACTIV = NOD
65          730 CONTINUE
66              ILB(LV,NACTIV) = 99999
67              CALL BRANCH (LV,JOBS,KONT,NACTIV,ITERM)
68              IF(ITERM.EQ.1) GO TO 1200
69              IF(ISTMIN-ILB(JOBS,1))760,760,770
70          770 ISTMIN = ILB(JOBS,1)
71              DO 771 K=1,JOB
72                  JSQ(JOBS,1,K)=JSQ(JOB,NACTIV,K)
73          771 CONTINUE
74          760 GO TO 1200
75      1300 WRITE(3,1516)
76          WRITE(3,1512) IB
77          DO 984 K=1,JOB
78              J(K)=JSQ(JOB,NACTIV,K)
79          984 CONTINUE
80              DO 985 K=1,JOBS
81              DO 986 KS = 1,JOB
82                  IF(K.EQ.J(KS)) GO TO 985
83          986 CONTINUE
84              JSQ(JOBS,1,JOBS)=K
85              GO TO 987
86          985 CONTINUE
87          987 CONTINUE
88              CALL INTIME(ETIME2)
89              COTIME = ( ETIME2-ETIME1 )/100.
90              WRITE(3,1600) ISTMIN,(JSQ(JOBS,1,K),K=1,JOBS)
91              WRITE(3,1518) KOUNT
92              WRITE(3,1511) COTIME
93              WRITE(3,1517) KONT
94              IF(IB.EQ.5) GO TO 982
95              IF(ICARD.EQ.0) GO TO 994
96              WRITE(2,1520) KOUNT,COTIME,KONT
97          994 CONTINUE
98              GO TO 16
99          982 WRITE(3,1513) KONTMB
100             WRITE(3,1514) KONTJB
101             WRITE(3,1515) KONTMJ
102             IF(ICARD.EQ.0) GO TO 995
103             WRITE(2,1521) KOUNT,COTIME,KONT,KONTMB,KONTJB,KONTMJ
104          995 CONTINUE
105          16 CONTINUE
106          15 CONTINUE

```

107
108
109

14 CONTINUE
STOP
END

105

```

110 SUBROUTINE BRANCH (LV,JOBS,KONT,NACTIV,ITERM)
111 COMMON IT(20,10),MACH,ISTMIN,KOUNT,IPRINT,IB
112 COMMON J(20),ILB(20,20),KONTMB,KONTJB,KONTMJ
113 COMMON NREPET,JSQ(20,20,20)
114 5000 FORMAT(1H-,5X,5HLEVEL,15X,4HNODE,10X,16HPARTIAL SEQUENCE)
115 5100 FORMAT(1H0,7X,I2,18X,I2,16X,20I2)
116 L=LV+1
117 JOB =JOBS-1
118 DO 10 LL = L,JOB
119 LLP=LL-1
120 NN=JOBS+1-LL
121 KOUNT = KOUNT + NN
122 IF(LL.GT.1) GO TO 1000

```

```

C
C FORMING THE PARTIAL SEQUENCES AT LEVEL 1 AND COMPUTING
C THE LOWER BOUND FOR EACH NODE.
C

```

```

123 DO 25 N = 1,NN
124 JSQ(LL,N,1) = N
125 IF(IPRINT) 26,26,27
126 27 WRITE(3,5000)
127 WRITE(3,5100) LL,N,JSQ(LL,N,1)
128 26 IF(IB.EQ.1) GO TO 701
129 IF(IB.EQ.2) GO TO 702
130 IF(IB.EQ.3) GO TO 703
131 IF(IB.EQ.4) GO TO 704
132 IF(IB.EQ.5) GO TO 705
133 701 CALL BOUND1 (NN,LL,JOBS,N)
134 GO TO 25
135 702 CALL BOUND2 (NN,LL,JOBS,N)
136 GO TO 25
137 703 CALL BOUND3 (NN,LL,JOBS,N)
138 GO TO 25
139 704 CALL BOUND4 ( NN,LL,JOBS,N)
140 GO TO 25
141 705 CALL BOUND5 ( NN,LL,JOBS,N)
142 GO TO 25
143 25 CONTINUE
144 GO TO 100

```

```

C
C FORMING THE PARTIAL SEQUENCES AT LEVEL LL ( LLIS GREATER
C THAN 1 ) AND COMPUTING THE LOWER BOUND FOR EACH NODE
C

```

```

145 1000 DO 50 K = 1,LLP
146 J(K)= JSQ(LLP,NACTIV,K)
147 50 CONTINUE
148 DO 60 K = LL,JOBS
149 KK = K-1
150 DO 70 JUNK = 1,JOBS
151 DO 80 I = 1,KK
152 IF(JUNK.EQ.J(I)) GO TO 70
153 80 CONTINUE
154 J(K) = JUNK
155 GO TO 60
156 70 CONTINUE
157 60 CONTINUE
158 KA = LL-1
159 DO 51 N = 1,NN
160 KA = KA + 1
161 JSQ(LL,N,LL) = J(KA)

```

```

162      51 CONTINUE
163      DO 52 N=1,NN
164      DO 53 K = 1,LLP
165      53 JSQ(LL,N,K) = J(K)
166      52 CONTINUE
167      DO 90 N = 1,NN
168      IF(IPRINT) 91,91,92
169      92 WRITE(3,5000)
170      WRITE(3,5100) LL,N,(JSQ(LL,N,K),K=1,LL)
171      91 IF(IB.EQ.1) GO TO 61
172      IF(IB.EQ.2) GO TO 62
173      IF(IB.EQ.3) GO TO 63
174      IF(IB.EQ.4) GO TO 64
175      IF(IB.EQ.5) GO TO 65
176      61 CALL BOUND1 (NN,LL,JOBS,N)
177      GO TO 90
178      62 CALL BOUND2 (NN,LL,JOBS,N)
179      GO TO 90
180      63 CALL BOUND3 (NN,LL,JOBS,N)
181      GO TO 90
182      64 CALL BOUND4 (NN,LL,JOBS,N)
183      GO TO 90
184      65 CALL BOUND5 (NN,LL,JOBS,N)
185      GO TO 90
186      90 CONTINUE

```

C
C
C

SEARCH FOR THE ACTIVE NODE AT LEVEL LL

```

187      100 LLB = ILB(LL,1)
188      NACTIV = 1
189      DO 30 N = 2,NN
190      IF(LLB-ILB(LL,N))30,30,40
191      40 LLB = ILB(LL,N)
192      NACTIV = N
193      30 CONTINUE
194      IF(ILB(LL,NACTIV)-ISTMIN)1100,1400,1400
195      1400 LV = LL
196      ITERM = 1
197      GO TO 15
198      1100 IF(LL.EQ.JOB) GO TO 35
199      ILB(LL,NACTIV) = 99999
200      GO TO 10
201      35 ILB(LL+1,1) = ILB(LL,NACTIV)
202      10 CONTINUE
203      LV = LL
204      KONT = KONT + 1
205      15 RETURN
206      END

```

```

207      SUBROUTINE BOUND1 (NN,LL,JOBS,N)
208      DIMENSION ITRR(10),ITRMM(10),ICT(20,20)
209      COMMON IT(20,10),MACH,ISTMIN,KOUNT,IPRINT,IB
210      COMMON J(20),ILB(20,20),KONTMB,KONTJB,KONTMJ
211      COMMON NREPET,JSQ(20,20,20)
212      1700 FORMAT(1H ,10X,'JOB',10X,'M1      M2      M3      M4      M5',
           1'      M6      M7      M8      M9      M10 ')
213      1710 FORMAT(1H ,10X,I2,6X,10I7)
214      1720 FORMAT(1H ,'      ***** COMPLETION TIME MATRIX *****')
215      1740 FORMAT(1H ,10X,'SECOND TERM',10X,'MACHINE')
216      1750 FORMAT(1H ,13X,I4,14X,I4)
217      1760 FORMAT(1H ,11X,'THIRD TERM',10X,'MACHINE')
218      1770 FORMAT(1H ,10X,'ON MACHINE ',I2,' LOWER BOUND IS ',I4)
219      1780 FORMAT(1H ,11HLOWER BOUND,15X,5HLEVEL,15X,4HNODE)
220      1790 FORMAT(1H ,4X,I5,19X,I2,18X,I2)
C
C
221      IF(IB.EQ.5)                      GO TO 155
222      DO 120 K = 1,LL
223      J(K) = JSQ(LL,N,K)
224      120 CONTINUE
C
C      SPLITTING THE JOBS WHICH ARE NOT INCLUDED IN THE
C      PARTIAL SEQUENCE
C
225      JU = LL+1
226      DO 160 K = JU,JOBS
227      KK = K-1
228      DO 150 JUSK = 1,JOBS
229      DO 130 I = 1,KK
230      IF(JUSK.EQ.J(I))                  GO TO 150
231      130 CONTINUE
232      J(K) = JUSK
233      GO TO 160
234      150 CONTINUE
235      160 CONTINUE
236      155 CONTINUE
C
C      FORMING THE COMPLETION TIME MATRIX FOR JOBS INCLUDED IN
C      THE PARTIAL SEQUENCE
C
237      DO 400 I=1,LL
238      JJ = J(I)
239      IF(I.GT.1)                        GO TO 430
240      DO 410 M = 1,MACH
241      IF(M.GT.1)                        GO TO 420
242      ICT(JJ,M) = IT(JJ,M)
243      ICTF = ICT(JJ,M)
244      GO TO 410
245      420 ICT(JJ,M) = ICTF + IT(JJ,M)
246      ICTF = ICT(JJ,M)
247      410 CONTINUE
248      GO TO 400
249      430 II = I-1
250      JP = J(II)
251      DO 500 M = 1,MACH
252      IF(M.GT.1)                        GO TO 510
253      ICT(JJ,M) = ICT(JP,M)+IT(JJ,M)
254      GO TO 500
255      510 MM = M-1

```

```

256      IF(ICT(JJ,MM).GE.ICT(JP,M))      GO TO 520
257      ICT(JJ,M) = ICT(JP,M)+IT(JJ,M)
258      GO TO 500
259      520 ICT(JJ,M) = ICT(JJ,MM)+IT(JJ,M)
260      500 CONTINUE
261      400 CONTINUE

C
C      PRINT THE COMPLETION TIME MATRIX IF IPRINT = 1
C
262      IF(IPRINT.EQ.0)      GO TO 105
263      WRITE(3,1720)
264      WRITE(3,1700)
265      DO 106 K = 1,LL
266      JK = J(K)
267      106 WRITE(3,1710) JK,(ICT(JK,M),M = 1,MACH)
268      105 CONTINUE

C
C      SECOND TERM IN THE BROWN AND LOMNICKI FORMULA
C
269      KU = LL + 1
270      DO 185 M = 1,MACH
271      ITR = 0
272      DO 180 I = KU,JOBS
273      K = J(I)
274      180 ITR = ITR + IT(K,M)
275      ITRR(M) = ITR
276      185 CONTINUE
277      IF(IPRINT.EQ.0)      GO TO 108
278      WRITE(3,1740)
279      DO 109 M = 1,MACH
280      109 WRITE(3,1750) ITRR(M),M
281      108 CONTINUE

C
C      THIRD TERM IN THE BROWN AND LOMNICKI FORMULA
C
282      MMM = MACH - 1
283      DO 250 M = 1,MMM
284      MA = M+1
285      DO 200 I = KU,JOBS
286      ITRM = 0
287      DO 190 MR = MA,MACH
288      K = J(I)
289      190 ITRM = ITRM + IT(K,MR)
290      IF(I.GT.KU)      GO TO 210
291      ITRMIN = ITRM
292      210 IF(ITRM-ITRMIN)220,200,200
293      220 ITRMIN = ITRM
294      200 CONTINUE
295      ITRMM(M) = ITRMIN
296      250 CONTINUE

C
C      PRINT THE THIRD TERM FOR ALL MACHINES , EXCEPT THE LAST.
C
297      IF(IPRINT.EQ.0)      GO TO 110
298      WRITE(3,1760)
299      DO 111 M = 1,MMM
300      111 WRITE(3,1750) ITRMM(M),M
301      110 CONTINUE

C
C      COMPUTATION OF LOWER BOUND

```

```

C
302      DO 600 M = 1,MACH
303      JL = J(LL)
304      IF(M.EQ.MACH)                GO TO 610
305      LB = ICT(JL,M) + ITRR(M) + ITRMM(M)
306      IF(M.GT.1)                  GO TO 620
307      ILB(LL,N) = LB
308      GO TO 112
309      610 LB = ICT(JL,M) + ITRR(M)
310      620 IF(LB-ILB(LL,N))112,112,630
311      630 ILB(LL,N) = LB

C
C      PRINT THE LOWER BOUNDS FOR EACH MACHINE AT LEVEL LL.
C
312      112 IF(IPRINT.EQ.0)          GO TO 600
313      WRITE(3,1770) M,LB
314      600 CONTINUE

C
C      PRINT THE LOWER BOUND AT LEVEL LL , IF ISKIP = 1.
C
315      IF(ISKIP.EQ.0)              GO TO 113
316      WRITE(3,1780)
317      WRITE(3,1790) ILB(LL,N),LL,N
318      113 CONTINUE
319      RETURN
320      END

```



```

321 SUBROUTINE BOUND2 (NN,LL,JOBS,N)
322 DIMENSION JOS(10,20),JPS(10,20),ICT(20,20),ITXMM(10)
323 COMMON IT(20,10),MACH,ISTMIN,KOUNT,IPRINT,IB
324 COMMON J(20),ILB(20,20),KONTMB,KONTJB,KONTMJ
325 COMMON NREPET,JSQ(20,20,20)
326 3000 FORMAT(1H,'SEQUENCE ON MACHINE',I2,'AND',I2,'IS',20I2)
327 3010 FORMAT(1H,'COMPLETION TIME MATRIX')
328 3020 FORMAT(1H,20X,'JOB',15X,'MACHINE',I2,15X,'MACHINE',I3)
329 3030 FORMAT(1H,20X,I2,17X,I4,21X,I4)
330 3040 FORMAT(1H,'SECOND TERM ON MACHINE',I2,'AND',I3,'=',I5)
331 3050 FORMAT(1H,'LOWER BOUND ON MACHINE',I2,'AND',I3,'IS',I5)
332 3060 FORMAT(1H,'LOWER BOUND AT LEVEL',I2,'FOR NODE',I2,'=',I5)

```

```

C
C FORMING THE SEQUENCE ON MACHINE M AND M+1 BY USING THE
C JOHNSON'S CRITERION.
C

```

```

333 IF(NREPET.EQ.1) GO TO 692
334 MM = MACH - 1
335 DO 690 M = 1,MM
336 DO 691 JE = 1,JOBS
337 691 JOS(M,JE) = 0
338 JX = JOBS + 1
339 JJ = 1
340 IJUMP = 0
341 DO 695 JD = 1,JOBS
342 MINT = 9999

```

```

C
C THIS PART COMPUTES THE MINIMUM PROCESSING TIME AND
C CORRESPONDING JOB ON MACHINE M
C

```

```

343 DO 700 JA = 1,JOBS
344 IF( IJUMP.EQ.0) GO TO 685
345 DO 680 JR = 1,JOBS
346 IF(JA.EQ.JOS(M,JR)) GO TO 700
347 680 CONTINUE
348 685 IF(IT(JA,M).LT.MINT) GO TO 705
349 GO TO 700
350 705 MINT = IT(JA,M)
351 JMTX = JA
352 700 CONTINUE
353 MIT = 9999

```

```

C
C THIS PART COMPUTES THE MINIMUM PROCESSING TIME AND THE
C CORRESPONDING JOB ON MACHINE M+1
C

```

```

354 DO 710 JB = 1,JOBS
355 IF( IJUMP.EQ.0) GO TO 675
356 DO 670 JQ = 1,JOBS
357 IF(JB.EQ.JOS(M,JQ)) GO TO 710
358 670 CONTINUE
359 675 IF(IT(JB,M+1).LT.MIT) GO TO 715
360 GO TO 710
361 715 MIT = IT(JB,M+1)
362 JMTY = JB
363 710 CONTINUE
364 IF(MINT.LE.MIT) GO TO 720
365 JX = JX - 1
366 JOS(M,JX) = JMTY
367 IJUMP = 1
368 IF(JX.EQ.1) GO TO 721

```

```

369      GO TO 695
370      720 JOS(M,JJ) = JMTX
371      IJUMP = 1
372      721 JJ = JJ + 1
373      695 CONTINUE
374      690 CONTINUE
375      NREPET = NREPET + 1
376      692 CONTINUE

C
C      PRINT THE SEQUENCE IF IPRINT = 1
C
377      IF(IPRINT.EQ.0)          GO TO 101
378      DO 102 M = 1,MM
379      MR = M + 1
380      102 WRITE(3,3000) M,MR,(JOS(M,JN),JN = 1,JOBS)

C
C      SPLITTING UP THE JOBS INCLUDED IN THE PARTIAL SEQUENCE
C
381      101 DO 731 K = 1,LL
382      J(K) = JSQ(LL,N,K)
383      731 CONTINUE

C
C      SPLITTING UP THE REMAINING JOBS FROM THE SEQUENCE
C      COMPUTED BY THE JOHNSON'S CRITERION.
C
384      JU = LL + 1
385      DO 733 M = 1,MM
386      KN = 1
387      DO 732 K = JU,JOBS
388      736 JUSK = JOS(M,KN)
389      DO 734 I = 1,LL
390      IF(JUSK.EQ.J(I))          GO TO 735
391      734 CONTINUE
392      JPS(M,K) = JUSK
393      KN = KN + 1
394      IF( KN.GT.JOBS)          KN = JOBS
395      GO TO 732
396      735 KN = KN + 1
397      IF( KN.GT.JOBS)          KN = JOBS
398      GO TO 736
399      732 CONTINUE
400      733 CONTINUE

C
C      FORMING THE COMPLETION TIME MATRIX
C
401      DO 750 M = 1,MM
402      MF = M + 1
403      DO 737 K = JU,JOBS
404      737 J(K) = JPS(M,K)
405      IF(MF.GT.2)          GO TO 742
406      DO 738 I = 1,JOBS
407      JJJ = J(I)
408      IF(I.GT.1)          GO TO 739
409      DO 740 MA = M,MF
410      IF(MA.GT.1)          GO TO 741
411      ICT(JJJ,MA) = IT(JJJ,MA)
412      ICTF = ICT(JJJ,MA)
413      GO TO 740
414      741 ICT(JJJ,MA) = ICTF + IT(JJJ,MA)
415      740 CONTINUE

```

```

416      GO TO 738
417 739 II = I-1
418      JP = J(II)
419      DO 743 MA = M,MF
420      IF(MA.GT.1) GO TO 745
421      ICT(JJJ,MA) = ICT(JP,MA) + IT(JJJ,MA)
422      GO TO 743
423 745 MN = MA - 1
424      IF(ICT(JJJ,MN).GE.ICT(JP,MA)) GO TO 746
425      ICT(JJJ,MA) = ICT(JP,MA) + IT(JJJ,MA)
426      GO TO 743
427 746 ICT(JJJ,MA) = ICT(JJJ,MN) + IT(JJJ,MA)
428 743 CONTINUE
429 738 CONTINUE
430      GO TO 104
431 758 CONTINUE
432      GO TO 602
433 742 DO 747 IR = 1,LL
434      JJJ = J(IR)
435      IF(IR.GT.1) GO TO 748
436      ICT(JJJ,MF) = ICT(JJJ,M) + IT(JJJ,MF)
437      GO TO 747
438 748 II = IR - 1
439      JJP = J(II)
440      IF(ICT(JJP,MF).GE.ICT(JJJ,M)) GO TO 751
441      ICT(JJJ,MF) = ICT(JJP,M) + IT(JJJ,MF)
442      GO TO 747
443 751 ICT(JJJ,MF) = ICT(JJP,MF) + IT(JJJ,MF)
444 747 CONTINUE
445      DO 752 K = JU,JOBS
446      JJ = J(K)
447      JR = J(K-1)
448 752 ICT(JJ,M) = ICT(JR,M) + IT(JJ,M)
449      DO 753 K = JU,JOBS
450      KR = J(K)
451      JN = J(K-1)
452      IF(ICT(KR,M).GE.ICT(JN,MF)) GO TO 754
453      ICT(KR,MF) = ICT(JN,MF) + IT(KR,MF)
454      GO TO 753
455 754 ICT(KR,MF) = ICT(KR,M) + IT(KR,MF)
456 753 CONTINUE

C
C      PRINT THE COMPLETION TIME MATRIX IF IPRINT = 1
C
457 104 IF(IPRINT.EQ.0) GO TO 759
458      WRITE (3,3010)
459      WRITE(3,3020) M,MF
460      DO 601 JM = 1,JOBS
461      JK = J(JM)
462 601 WRITE(3,3030) JK,ICT(JK,M),ICT(JK,MF)

C
C      FINDING THE MINIMUM OF THE SUMS OF PROCESSING TIMES
C      FOR JOBS NOT INCLUDED IN THE PARTIAL SEQUENCE ON
C      SUCCEEDING MACHINES.
C
463 759 MH = MF + 1
464      IF(M.NE.MM) GO TO 523
465      JJJ = J(JOBS)
466      LB = ICT(JJJ,MF)
467      IF(LB - ILB(LL,N))521,521,522

```

```

468 522 ILB(LL,N) = LB
469 521 GO TO 602
470 523 DO 760 KA = JU,JOBS
471     ITXM = 0
472     DO 761 MG = MH,MACH
473     KJ = J(KA)
474 761 ITXM = ITXM + IT(KJ,MG)
475     IF(KA.GT.JU) GO TO 762
476     ITXMIN = ITXM
477 762 IF(ITXM - ITXMIN)763,760,760
478 763 ITXMIN = ITXM
479 760 CONTINUE
480     ITXMM(M) = ITXMIN
481     IF(IPRINT.EQ.0) GO TO 524
482     WRITE(3,3040) M,MF,ITXMM(M)

```

C
C
C

COMPUTATION OF LOWER BOUND

```

483 524 JJJ = J(JOBS)
484     LB = ICT(JJJ,MF) + ITXMM(M)
485     ILB(LL,N) = LB
486     IF(M.EQ.1) GO TO 758
487 757 IF(LB - ILB(LL,N))602,602,765
488 765 ILB(LL,N) = LB
489 602 IF(IPRINT.EQ.0) GO TO 750
490     WRITE(3,3050) M,MF,LB
491 750 CONTINUE
492     IF(IPRINT.EQ.0) GO TO 603
493     WRITE(3,3060) LL,N,ILB(LL,N)
494 603 RETURN
495     END

```

```

496      SUBROUTINE BOUND3 (NN,LL,JOBS,N)
497      DIMENSION ICT(20,20),ITRR(10),ITRMM(10),IDT(20,20)
498      COMMON IT(20,10),MACH,ISTMIN,KOUNT,IPRINT,IB
499      COMMON J(20),ILB(20,20),KONTMB,KONTJB,KONTMJ
500      COMMON NREPET,JSQ(20,20,20)
501      3200 FORMAT(1H ,10X,'JOB',10X,'M1      M2      M3      M4      M5',
1'      M6      M7      M8      M9      M10 ')
502      3210 FORMAT(1H ,10X,I2,6X,10I7)
503      3220 FORMAT(1H ,'      ***** COMPLETION TIME MATRIX *****')
504      3230 FORMAT(1H ,' SOPHISTICATED COMPLETION TIME FOR THE LAST JOB IN THE
1 PARTIAL SEQUENCE.')
```

C
C SPLITTING THE JOBS INCLUDED IN THE PARTIAL SEQUENCE
C

```

511      DO 120 K = 1,LL
512      J(K) = JSQ(LL,N,K)
513      120 CONTINUE
```

C
C SPLITTING THE JOBS WHICH ARE NOT INCLUDED IN THE
C PARTIAL SEQUENCE
C

```

514      JU = LL+1
515      DO 160 K = JU,JOBS
516      KK = K-1
517      DO 150 JUSK = 1,JOBS
518      DO 130 I = 1,KK
519      IF(JUSK.EQ.J(I))          GO TO 150
520      130 CONTINUE
521      J(K) = JUSK
522      GO TO 160
523      150 CONTINUE
524      160 CONTINUE
```

C
C FORMING THE COMPLETION TIME MATRIX FOR JOBS INCLUDED IN
C THE PARTIAL SEQUENCE
C

```

525      DO 400 I=1,LL
526      JJ = J(I)
527      IF(I.GT.1)          GO TO 430
528      DO 410 M = 1,MACH
529      IF(M.GT.1)          GO TO 420
530      ICT(JJ,M) = IT(JJ,M)
531      ICTF = ICT(JJ,M)
532      GO TO 410
533      420 ICT(JJ,M) = ICTF + IT(JJ,M)
534      ICTF = ICT(JJ,M)
535      410 CONTINUE
536      GO TO 400
537      430 II = I-1
538      JP = J(II)
539      DO 500 M = 1,MACH
540      IF(M.GT.1)          GO TO 510
541      ICT(JJ,M) = ICT(JP,M)+IT(JJ,M)
542      GO TO 500
```

```

543      510 MM = M-1
544      IF(1CT(JJ,MM).GE.1CT(JP,M))      GO TO 520
545      1CT(JJ,M) = 1CT(JP,M)+1T(JJ,M)
546      GO TO 500
547      520 1CT(JJ,M) = 1CT(JJ,MM)+1T(JJ,M)
548      500 CONTINUE
549      400 CONTINUE
550      IF(1PRINT.EQ.0)      GO TO 105
551      WRITE(3,3220)
552      WRITE(3,3200)
553      DO 106 K = 1,LL
554      JK = J(K)
555      106 WRITE(3,3210) JK,(1CT(JK,M),M = 1,MACH)
556      105 CONTINUE
C
C      FINDING THE SOPHISTICATED COMPLETION TIME
C
557      DO 855 M = 1,MACH
558      JL = J(LL)
559      IF(M.GT.1)      GO TO 860
560      1DT(JL,M) = 1CT(JL,M)
561      GO TO 855
562      860 MG = M-1
563      1DT(JL,M) = 1CT(JL,M)
564      DO 865 MS = 1,MG
565      MINT = 9999
566      DO 875 K = JU,JOBS
567      JK = J(K)
568      1TIME = 0
569      DO 870 MX = MS,MG
570      870 1TIME = 1TIME + 1T(JK,MX)
571      IF(1TIME.GE.MINT)      GO TO 875
572      MINT = 1TIME
573      875 CONTINUE
574      1DTX = 1CT(JL,MS) + MINT
575      IF(1DT(JL,M).LT.1DTX)      GO TO 880
576      GO TO 865
577      880 1DT(JL,M) = 1DTX
578      865 CONTINUE
579      855 CONTINUE
C
C      PRINT THE SOPHISTICATED COMPLETION TIME FOR THE LAST
C      JOB IN THE PARTIAL SEQUENCE.
C
580      IF(1PRINT.EQ.0)      GO TO 107
581      WRITE(3,3230)
582      WRITE(3,3200)
583      WRITE(3,3210) JL,(1DT(JL,M),M = 1,MACH)
584      107 CONTINUE
C
C      SECOND TERM IN THE IGNALL & SCHRAGE LOWER BOUND
C
585      KU = LL + 1
586      DO 185 M = 1,MACH
587      ITR = 0
588      DO 180 I = KU,JOBS
589      K = J(I)
590      180 ITR = ITR + 1T(K,M)
591      1TRR(M) = ITR
592      185 CONTINUE

```

```

C
C      PRINT THE SECOND TERM FOR EACH MACHINE, IF IPRINT = 1.
C
593      IF(IPRINT.EQ.0)                GO TO 108
594      WRITE(3,3240)
595      DO 109 M = 1,MACH
596      109 WRITE(3,3250) ITRR(M),M
597      108 CONTINUE

C
C      THIRD TERM IN THE IGNALL & SCHRAGE LOWER BOUND
C
598      MMM = MACH - 1
599      DO 250 M = 1,MMM
600      MA = M+1
601      DO 200 I = KU,JOBS
602      ITRM = 0
603      DO 190 MR = MA,MACH
604      K = J(I)
605      190 ITRM = ITRM + IT(K,MR)                GO TO 210
606      IF(I.GT.KU)
607      ITRMIN = ITRM
608      210 IF(ITRM-ITRMIN)220,200,200
609      220 ITRMIN = ITRM
610      200 CONTINUE
611      ITRMM(M) = ITRMIN
612      250 CONTINUE

C
C      PRINT THE THIRD TERM FOR ALL MACHINES , EXCEPT THE LAST.
C
613      IF(IPRINT.EQ.0)                GO TO 110
614      WRITE(3,3260)
615      DO 111 M = 1,MMM
616      111 WRITE(3,3250) ITRMM(M),M
617      110 CONTINUE

C
C      COMPUTATION OF SOPHISTICATED LOWER BOUND
C
618      DO 600 M = 1,MACH
619      JL = J(LL)
620      IF(M.EQ.MACH)                GO TO 610
621      LB = IDT(JL,M) + ITRR(M) + ITRMM(M)
622      IF(M.GT.1)                GO TO 620
623      ILB(LL,N) = LB
624      GO TO 112
625      610 LB = IDT(JL,M) + ITRR(M)
626      620 IF(LB-ILB(LL,N))112,112,630
627      630 ILB(LL,N) = LB

C
C      PRINT THE LOWER BOUNDS FOR EACH MACHINE AT LEVEL LL.
C
628      112 IF(IPRINT.EQ.0)                GO TO 600
629      WRITE(3,3270) M,LB
630      600 CONTINUE

C
C      PRINT THE LOWER BOUND AT LEVEL LL .
C
631      IF(IPRINT.EQ.0)                GO TO 113
632      WRITE(3,3280)
633      WRITE(3,3290) ILB(LL,N),LL,N
634      113 CONTINUE

```

635
636

RETURN
END

118


```

637      SUBROUTINE BOUND4 (NN,LL,JOBS,N)
638      DIMENSION ICT(20,20)
639      COMMON IT(20,10),MACH,ISTMIN,KOUNT,IPRINT,IB
640      COMMON J(20),ILB(20,20),KONTMB,KONTJB,KONTMJ
641      COMMON NREPET,JSQ(20,20,20)
642      3500 FORMAT(1H ,10X,'LOWER BOUND ON MACHINE ',I2,' IS ',I4)
643      3510 FORMAT(1H ,10X,'LOWER BOUND AT LEVEL ',I2,' FOR NODE ',I2,' IS ',I
15)
644      3520 FORMAT(1H ,'      ***** COMPLETION TIME MATRIX *****')
645      3530 FORMAT(1H ,10X,'JOB',10X,'M1      M2      M3      M4      M5',
1'      M6      M7      M8      M9      M10 ')
646      3540 FORMAT(1H ,10X,I2,6X,10I7)
C
C      SPLITTING THE JOBS INCLUDED IN THE PARTIAL SEQUENCE
C
647      IF(IB.EQ.5)                      GO TO 155
648      DO 120 K = 1,LL
649      J(K) = JSQ(LL,N,K)
650      120 CONTINUE
C
C      SPLITTING THE JOBS WHICH ARE NOT INCLUDED IN THE
C      PARTIAL SEQUENCE
C
651      JU = LL+1
652      DO 160 K = JU,JOBS
653      KK = K-1
654      DO 150 JUSK = 1,JOBS
655      DO 130 I = 1,KK
656      IF(JUSK.EQ.J(I))                  GO TO 150
657      130 CONTINUE
658      J(K) = JUSK
659      GO TO 160
660      150 CONTINUE
661      160 CONTINUE
662      155 CONTINUE
C
C      FORMING THE COMPLETION TIME MATRIX FOR JOBS INCLUDED IN
C      THE PARTIAL SEQUENCE
C
663      DO 400 I=1,LL
664      JJ = J(I)
665      IF(I.GT.1)                        GO TO 430
666      DO 410 M = 1,MACH
667      IF(M.GT.1)                        GO TO 420
668      ICT(JJ,M) = IT(JJ,M)
669      ICTF = ICT(JJ,M)
670      GO TO 410
671      420 ICT(JJ,M) = ICTF + IT(JJ,M)
672      ICTF = ICT(JJ,M)
673      410 CONTINUE
674      GO TO 400
675      430 II = I-1
676      JP = J(II)
677      DO 500 M = 1,MACH
678      IF(M.GT.1)                        GO TO 510
679      ICT(JJ,M) = ICT(JP,M)+IT(JJ,M)
680      GO TO 500
681      510 MM = M-1
682      IF(ICT(JJ,MM).GE.ICT(JP,M))      GO TO 520
683      ICT(JJ,M) = ICT(JP,M)+IT(JJ,M)

```

```

684      GO TO 500
685      520 ICT(JJ,M) = ICT(JJ,MM)+IT(JJ,M)
686      500 CONTINUE
687      400 CONTINUE

C
C      PRINT THE COMPLETION TIME MATRIX.
C

688      IF(IPRINT.EQ.0)          GO TO 205
689      WRITE(3,3520)
690      WRITE(3,3530)
691      DO 206 K = 1,LL
692      JK = J(K)
693      206 WRITE(3,3540) JK,(ICT(JK,M),M = 1,MACH)
694      205 CONTINUE

C
C      SECOND TERM IN THE JOB BASED LOWER BOUND.
C

695      JP = LL + 1
696      DO 903 MJ = 1,MACH
697      MAX = 0
698      DO 900 K = JP,JOBS

C
C      PROCESSING TIME ON MACHINE 'MJ' AND ALL MACHINES
C      FOLLOWING MACHINE 'MJ' , FOR A UNSCHEDULED JOB .
C

699      IF(MJ.NE.MACH)          GO TO 905
700      DO 906 KQ = JP,JOBS
701      JQ = J(KQ)
702      906 MAX = MAX + IT(JQ,MACH)
703      GO TO 907
704      905 JH = J(K)
705      IPROC = 0
706      DO 901 M = MJ,MACH
707      901 IPROC = IPROC + IT(JH,M)

C
C      MINIMUM RUNNING TIME FOR THE REMAINING JOBSEXCLUDING
C      THE JOB CONSIDERED FOR NEXT SEQUENCE POSITION
C

708      IRUN = 0
709      DO 902 KS = JP,JOBS
710      JR = J(KS)
711      IF(JR.EQ.JH)          GO TO 902
712      IF(IT(JR,MJ).LE.IT(JR,MACH))  GO TO 904
713      IRUN = IRUN + IT(JR,MACH)
714      GO TO 902
715      904 IRUN = IRUN + IT(JR,MJ)
716      902 CONTINUE
717      LTERM = IPROC + IRUN
718      IF(LTERM.GT.MAX)      MAX = LTERM
719      900 CONTINUE

C
C      LOWER BOUND ON MACHINE 'MJ' .
C

720      907 JL = J(LL)
721      LB = ICT(JL,MJ) + MAX
722      IF(IPRINT.EQ.0)          GO TO 908
723      WRITE(3,3500)MJ,LB
724      908 IF(MJ.GT.1)          GO TO 909
725      ILB(LL,N) = LB
726      GO TO 903

```

727 909 IF(LB - ILB(LL,N))903,903,910
728 910 ILB(LL,N) = LB
729 903 CONTINUE
730 IF(IPRINT.EQ.0)
731 WRITE(3,3510) LL,N,ILB(LL,N)
732 911 RETURN
733 END

GO TO 911

```

734      SUBROUTINE BOUND5(NN,LL,JOBS,N)
735      COMMON IT(20,10),MACH,ISTMIN,KOUNT,IPRINT,IB
736      COMMON J(20),ILB(20,20),KONTMB,KONTJB,KONTMJ
737      COMMON NREPET,JSQ(20,20,20)

      C
      C      SPLITTING THE JOBS INCLUDED IN THE PARTIAL SEQUENCE
      C

738      DO 120 K = 1,LL
739      J(K) = JSQ(LL,N,K)
740      120 CONTINUE

      C
      C      SPLITTING THE JOBS WHICH ARE NOT INCLUDED IN THE
      C      PARTIAL SEQUENCE
      C

741      JU = LL+1
742      DO 160 K = JU,JOBS
743      KK = K-1
744      DO 150 JUSK = 1,JOBS
745      DO 130 I = 1,KK
746      IF(JUSK.EQ.J(I))          GO TO 150
747      130 CONTINUE
748      J(K) = JUSK
749      GO TO 160
750      150 CONTINUE
751      160 CONTINUE
752      CALL BOUND1(NN,LL,JOBS,N)
753      MBASED = ILB(LL,N)
754      CALL BOUND4(NN,LL,JOBS,N)
755      IF(MBASED.EQ.ILB(LL,N))    GO TO 983
756      IF(MBASED.GT.ILB(LL,N))    GO TO 980
757      KONTJB = KONTJB + 1
758      GO TO 981
759      980 ILB(LL,N) = MBASED
760      KONTMB = KONTMB + 1
761      GO TO 981
762      983 KONTMJ = KONTMJ + 1
763      981 RETURN
764      END

```

```
765 FUNCTION BANDNO(IY)
766 IY = IY*65627
767 IF(IY) 5,6,6
768 5 IY = IY + 2147483647 + 1
769 6 BANDNO = IY*.4656613E-9
770 RETURN
771 END
```

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ANALYSIS AND COMPARISON OF VARIOUS LOWER-BOUNDS ON
SCHEDULE TIMES FOR THE SOLUTION OF FLOW-SHOP PROBLEMS

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There exist several production situations in which a certain number of jobs have to be processed on various machines according to a specified technological requirement. The production scheduling problem consists of finding the sequence of jobs to be processed on all machines so as to optimize a certain criterion. This research is concerned with the solution to the flow shop problem in which all jobs have the same machine ordering. Various approaches to this problem are available; however, due to the combinatorial nature of the problem, these techniques are inefficient even for relatively small size problems.

The branch-and-bound technique is used in this research. This procedure involves generation of nodes that indicate partial sequences. A lower-bound on the schedule time is evaluated for each node in order to determine which node is to be explored. The number of explored nodes can be curtailed by a powerful bounding process which is imbedded in the branch-and-bound algorithm. Back-tracking process of the algorithm guarantees optimality of the solution.

The basic objective of this research is to analyze mathematically and empirically the five bounding procedures developed by several investigators. The basic concept of the branch-and-bound technique including branching, bounding and back-tracking processes are discussed. In order to study the merits of the various bounding procedures, several computational experiments were conducted. The comparison was based on both the number of nodes explored and the computation time spent in obtaining the optimal solution. Based on problems solved, the number of nodes explored and the computation time increase rapidly as the number of jobs increases. The ranks of the bounding procedures are tabulated according to the number of nodes explored and the computation time spent. It appears that LB I

ranks first in the computation time; however, its rank in the number of nodes is second.